清华大学本科生考试试题专用纸

考试课程

Linear Algebra (English) 2022 Fall Final Exam 2023.1.5 Exam Duration: 3 Hours

Name:

年 月 日

Student ID:

This exam includes 6 pages (including this page) and 5 problems. Please check to see if there is any missing page, and then write down your name and student ID number on this page and the first page of your answer sheets. Also write down the initials of your name on the top of every page of your answer sheets, in case they are scattered.

This exam is open book. You are allowed to consult your textbook and notes, and elementary calculators are fine (those that cannot instantly multiply matrices). Plagerism of all kinds are strictly forbidden and will be severly punished.

Please write down your answers to the problems in the **SEPARATE ANSWER SHEETS**, and follow the following rules:

- Always explain your answer. You should always explain your answers. Any problem answered with nothing but a single answer would receive no credit.
- Write cleanly and legible. Make sure that you writings can be read. The graders are NOT re sponsible to decipher illegible writings.
- Partial credits will be given.
- Blank spaces are provided in the exams. Feel free to use them as scratch papers. However, your formal answer has to be written in the **SEPARATE ANSWER SHEETS**, as required by the University.
- The total score of the exam is 50. If your total score exceeds 50 (there are 54 points in total), it will be recorded as 50.

al- ed	Problem	Points	Score
no	1	13	
ur	2	11	
e-	3	10	
	4	11	
ee or-	5	9	
E er-	Total:	54	



2. Suppose we are trying to solve a linear equation $A\mathbf{x} = \mathbf{0}$, where $A = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 2 & -2 & 1 & 1 \\ -1 & 1 & 3 & 3 \end{bmatrix}$. Surprisingly, for some rotation matrix B (real orthogonal with determinant one)

Surprisingly, for some rotation matrix R (real orthogonal with determinant one), $A\mathbf{x} = \mathbf{0}$ and $AR\mathbf{x} = \mathbf{0}$ have the same solution set! We also know that $R^2 - I$ is invertible, but $R^4 - I = 0$. What does it mean?

(a) (2 points) Find a basis for the subspaces $\operatorname{Ran}(A), \operatorname{Ker}(A), \operatorname{Ran}(A^{\mathrm{T}}), \operatorname{Ker}(A^{\mathrm{T}}).$

(b) (3 points) Among the subspaces $\operatorname{Ran}(A)$, $\operatorname{Ker}(A)$, $\operatorname{Ran}(A^{\mathrm{T}})$, $\operatorname{Ker}(A^{\mathrm{T}})$, which of them are *R*-invariant? Show why and why not. (We say *W* is *R*-invariant if for all $\boldsymbol{w} \in W$, we have $R\boldsymbol{w} \in W$.)

(c) (2 points) For each R-invariant subspace in the last sub-problem, find the orthogonal projection to it. Find the sum of all these orthogonal projections.

(d) (4 points) Find all eigenvalues of R counting algebraic multiplicities, and find all possible R.

3. (Imagine we want to solve the differential equation f'(x) = xf'(x+1). Not easy, right? But maybe we can study it by finding some eigenvectors.)

Let V be the space of polynomials of degree at most 3. Let $L: V \to V$ such that f(x) is sent to xf'(x+1). We shall see that L is diagonalizable. Let polynomials p_1, p_2, p_3, p_4 be the eigenvectors of L for eigenvalues $\lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \lambda_4$. Say we scale them so that they are all polynomials with leading coefficient 1. (So the coefficient for the largest degree term is 1.)

- (a) (2 points) Let $\mathcal{B} = (1, x, x^2, x^3)$ be the basis. Find the matrix for L under this basis.
- (b) (3 points) Find the characteristic polynomial of L, and all its eigenvalues. Find the eigen-polynomials p_1, p_2, p_3, p_4 . (I want to see the polynomials, not the coordinate vectors.)
- (c) (2 points) We have a basis $C = (p_1, p_2, p_3, p_4)$. If a polynomial has coordinates $\begin{bmatrix} 1\\1\\1\\1\\1 \end{bmatrix}$ under C, what are its coordinates under \mathcal{B} .
- 0 240 26 (d) (2 points) Suppose a linear transformation T has matrix un-0 30 0 50 0 100 der basis \mathcal{B} . Find the matrix for the same linear transformation under basis

der basis \mathcal{B} . Find the matrix for the same linear transformation under basis \mathcal{C} .

(e) (1 point) Can you write out an abstract description of T in terms of polynomials? (E.g., an abstract description of L is that it sends f(x) to xf'(x+1).

- 5. For each real number x, we define a corresponding matrix $A_x = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & x & 1 & x \\ 1 & 1 & x & x \\ 1 & x & x & 1 \end{bmatrix}$.
 - (a) (3 points) Find the LDL^{T} decomposition of A_x and the determinant of A_x . For what x is A_x invertible?

(b) (2 points) When x < 1, find the QR-decomposition of A_x . (Note that R need to have positive diagonal entries.)

(c) (2 points) How many eigenvalues of A_x are positive, depending on x?

(d) (2 points) Find two linearly independent eigenvectors of A_x independent of x. What are their eigenvalues? (The eigenvalues depend on x.) (Maybe try some specific values of x first? Or stare at A really hard.)

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