

电子电路与系统基础(1)---线性电路---2020春季学期

# 第10讲：串联RLC时频分析

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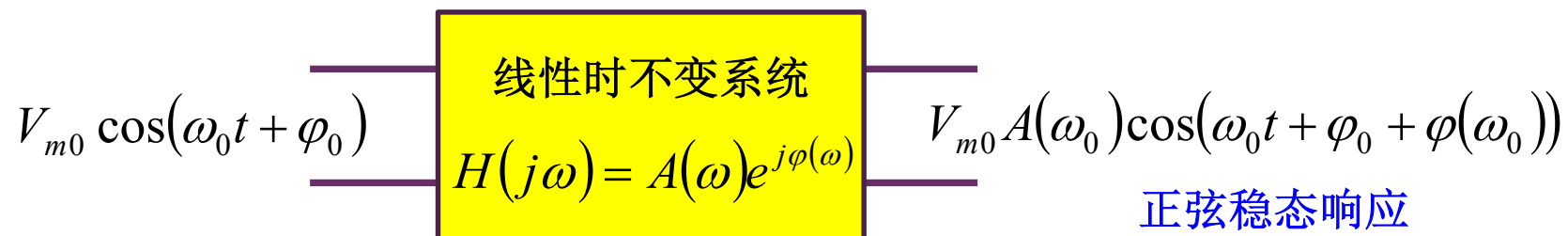
# B 班课程内容安排

第一学期：线性	序号	第二学期：非线性
电路定律	1	器件基础
电阻电源	2	二极管
电容电感	3	<b>MOSFET</b>
信号分析	4	<b>BJT</b>
分压分流	5	反相电路
正弦稳态	6	数字门
时频分析	7	放大器
期中复习	8	期中复习
<b>RLC</b> 二阶	9	负反馈
<b>二阶时频</b>	<b>10</b>	差分放大
受控源	11	频率特性
网络参量	12	正反馈
典型网络	13	振荡器
作业选讲	14	作业选讲
期末复习	15	期末复习

# 二阶滤波器时频分析 内容

- 阻容感分压电路和分流电路
  - 串联RLC分压分析：并联RLC分流分析属对偶分析
    - 时域分析：一般性分析
      - 五要素法
    - 理想滤波特性与实际滤波特性
      - 理想滤波特性
        - 通带内信号无失真传输，通带外信号完全滤除
      - 实际滤波特性
        - 通带内信号传输存在幅度失真和相位失真，通带外无法完全滤除
        - 实际滤波特性应尽可能逼近理想滤波特性
  - 二阶滤波器时频分析：以串联RLC电路为例
    - 低通/高通/带通/带阻
    - 幅频特性与相频特性波特图画法

# LTI系统频域分析



对线性时不变系统，用相量法很容易地  
直接获得正弦信号激励下的稳态响应

$$H(j\omega) = A(\omega)e^{j\varphi(\omega)}$$

传递函数

幅  
频  
特  
性

相  
频  
特  
性

# 理想低通滤波特性

理想低通系统：通带内传递函数

$$H(j\omega) = A_0 e^{-j\omega\tau_0}$$

假设输入信号频谱都在通带内

$$in = x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

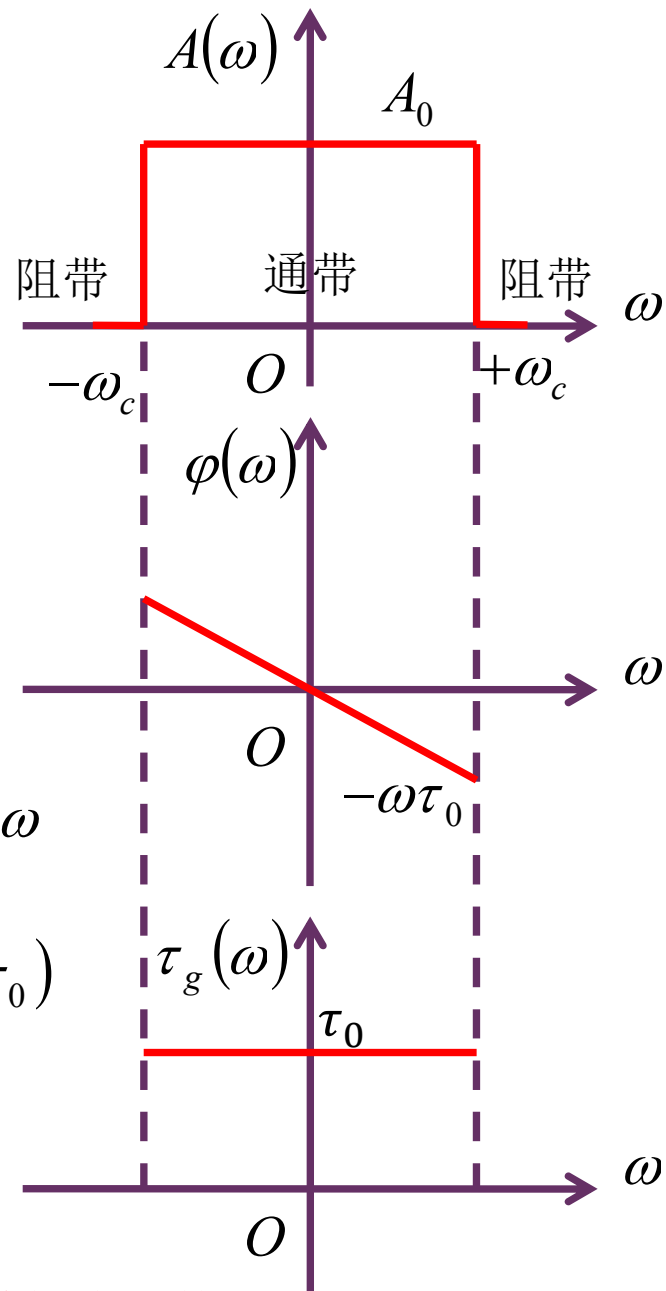
那么输出将仅是输入的比例放大和整体延时

$$\begin{aligned} out = y(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) X(\omega) e^{j(\omega t + \varphi(\omega))} d\omega \\ &= A_0 \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j(\omega(t - \tau_0))} d\omega = A_0 x(t - \tau_0) \end{aligned}$$

称之为无失真传输

$$\tau_g(\omega) = -\frac{d\varphi(\omega)}{d\omega} = \tau_0$$

群延时



理想滤波器通带内的幅频特性为常数，群延时特性为常数

# 实际滤波特性

理想滤波器可实现通带内信号的无失真传输，而通带外信号则全部被滤除

但理想低通系统不可实现，实际的低通系统为：

$$H(j\omega) = A(\omega)e^{j\varphi(\omega)}$$

其通带内幅度不是常数，群延时也不是常数；通带外信号也无法全部被衰减清零

$$in = x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$

即使输入所包含的频率分量全部都在通带内

$$out = y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega)X(\omega)e^{j(\omega t + \varphi(\omega))} d\omega$$

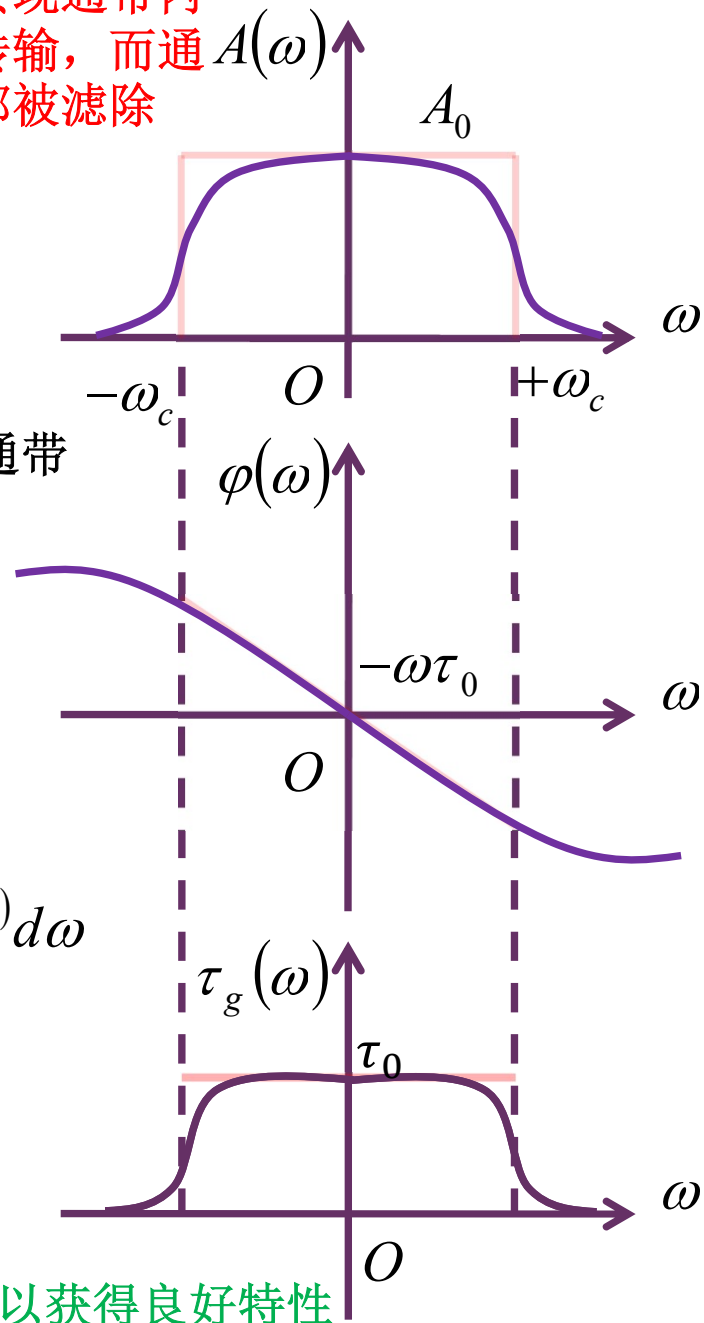
输出也会产生线性失真：幅度失真和相位失真

幅度失真：不同的频率分量有不同的增益

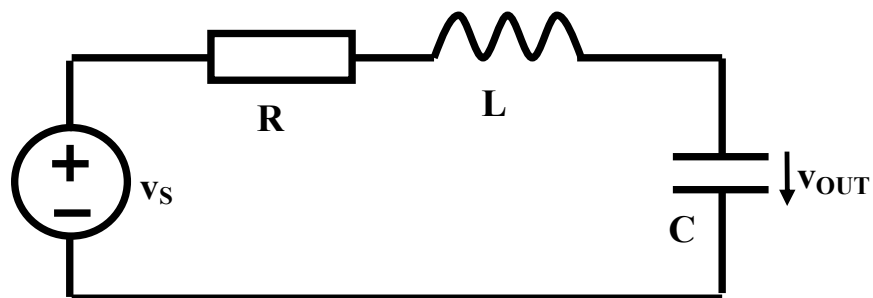
相位失真：不同的频率分量有不同的延时

失真：输出波形和输入波形形状不同

实际实现的滤波器应尽可能接近理想滤波器，以获得良好特性



# 二阶低通：电容分压



直观理解：

低频：电容开路，电感短路，  
信号通过

高频：电容短路，电感开路，  
信号不能通过

$$H(j\omega) = \frac{\dot{V}_C}{\dot{V}_S} = \frac{\frac{1}{j\omega C}}{R + j\omega L + \frac{1}{j\omega C}} = \frac{1}{(j\omega)^2 LC + j\omega RC + 1}$$

$$\stackrel{j\omega \rightarrow s}{=} \frac{1}{s^2 LC + sRC + 1} = \frac{\frac{1}{LC}}{s^2 + s\frac{R}{L} + \frac{1}{LC}} = H_0 \frac{\omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2}$$

二阶低通传函典型形式

$$H_0 = 1 \quad \omega_0 = \frac{1}{\sqrt{LC}} \quad \xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

# 幅频特性、相频特性、群延时特性

$$H(s) = \frac{\omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} \stackrel{s=j\omega}{=} \frac{\omega_0^2}{(\omega_0^2 - \omega^2) + j2\xi\omega_0\omega} = A(\omega)e^{j\varphi(\omega)}$$

$$A(\omega) = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}}$$

幅频特性

$$\varphi(\omega) = -\arctan \frac{2\xi\omega_0\omega}{\omega_0^2 - \omega^2}$$

相频特性

$$\tau_g(\omega) = -\frac{d\varphi(\omega)}{d\omega}$$

群延时特性

群延时：相频特性曲线的斜率  
一群信号通过该系统的延时大小

$$\tau_g(\omega) = \frac{2\xi\omega_0(\omega^2 + \omega_0^2)}{\omega^4 + 2(2\xi^2 - 1)\omega_0^2\omega^2 + \omega_0^4}$$

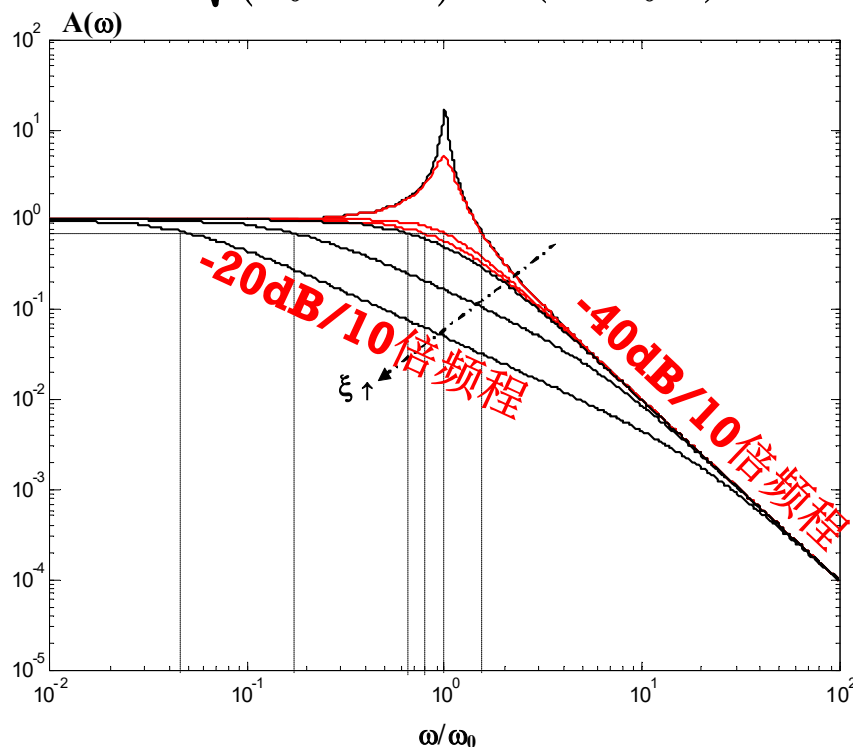


# 幅频特性

$$H(s) = \frac{\omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} = \frac{\omega_0^2}{(s - \lambda_1)(s - \lambda_2)}$$

$$A(\omega) = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}}$$

$$\lambda_{1,2} = (-\xi \pm \sqrt{\xi^2 - 1})\omega_0$$



$\xi=0.03, 0.1, 0.707, 0.866, 1, 3, 10$

$\xi > 1$  过阻尼，幅频特性明显可三段折线处理

$0.707 \leq \xi \leq 1$ ，幅频特性平坦，可两段折线处理

$\xi \ll 0.707$ ，自由振荡频点附近有谐振峰出现

# 过阻尼：幅频特性可三段折线

 $\xi > 1$ 

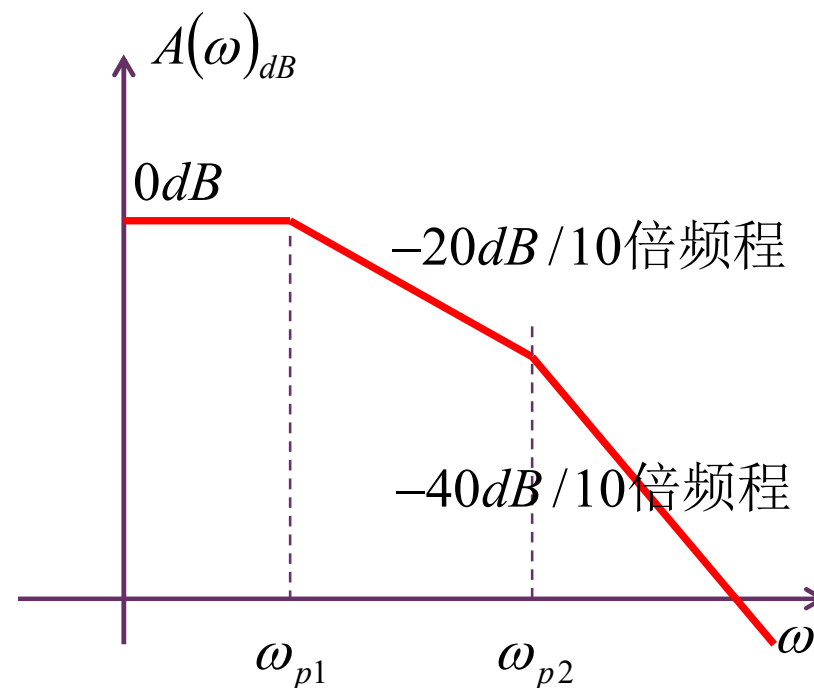
$$H(s) = \frac{\omega_0^2}{(s - \lambda_1)(s - \lambda_2)}$$

$$H(j\omega) = \frac{\omega_0^2}{(j\omega + \omega_{p1})(j\omega + \omega_{p2})}$$

$$= \frac{1}{\left(\frac{j\omega}{\omega_{p1}} + 1\right)\left(\frac{j\omega}{\omega_{p2}} + 1\right)}$$

$$\approx \begin{cases} 1 & \omega < \omega_{p1} \\ \frac{1}{j\omega} = \frac{\omega_{p1}}{j\omega} & \omega_{p1} < \omega < \omega_{p2} \\ \frac{1}{\frac{j\omega}{\omega_{p1}} \cdot \frac{j\omega}{\omega_{p2}}} = \frac{\omega_0^2}{-\omega^2} & \omega > \omega_{p2} \end{cases}$$

$$\begin{aligned} \lambda_{1,2} &= \left(-\xi \pm \sqrt{\xi^2 - 1}\right) \omega_0 \\ &= \begin{cases} -\left(\xi - \sqrt{\xi^2 - 1}\right) \omega_0 = -\omega_{p1} \\ -\left(\xi + \sqrt{\xi^2 - 1}\right) \omega_0 = -\omega_{p2} \end{cases} \end{aligned}$$



# 欠阻尼存在谐振峰的可能性

$$(0 < \xi < 1)$$

$$\lambda_{1,2} = \left( -\xi \pm j\sqrt{1-\xi^2} \right) \omega_0$$

$$H(s) = \frac{\omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} = \frac{\omega_0^2}{(s - \lambda_1)(s - \lambda_2)}$$

也可分解，但为复根分解

$$H(j0) = 1 \quad H(j\infty) = 0$$

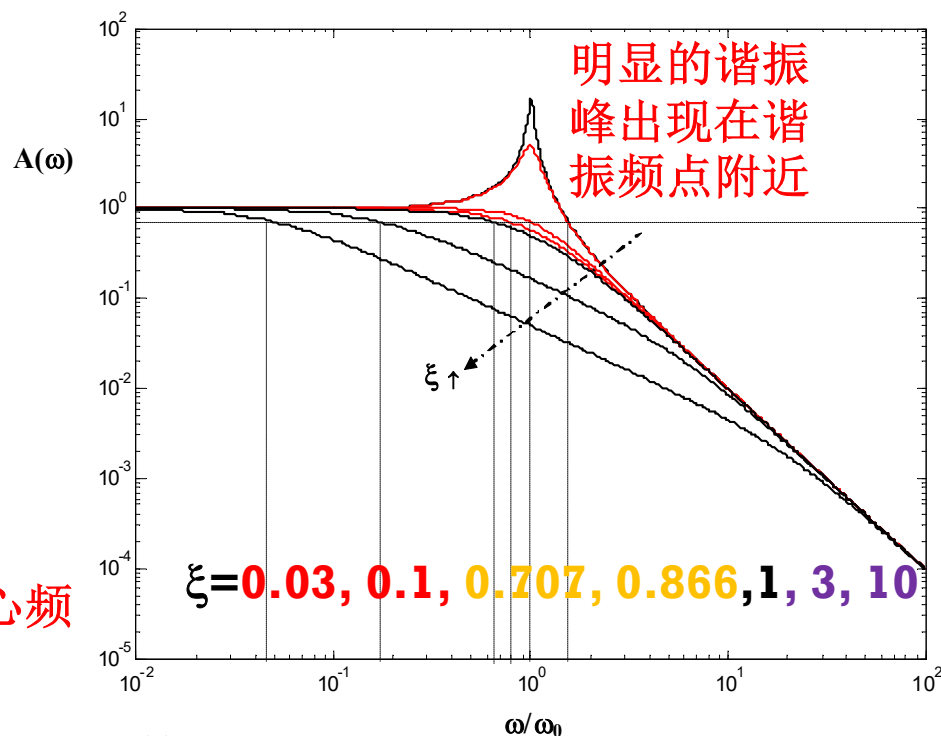
低通特性不会改变

$$H(j\omega_0) = \frac{\omega_0^2}{(j\omega_0)^2 + 2\xi\omega_0(j\omega_0) + \omega_0^2}$$

$$= -j \frac{1}{2\xi} = \frac{1}{2\xi} e^{-j\frac{\pi}{2}}$$

$$A(\omega_0) = \frac{1}{2\xi} \stackrel{\xi < 0.5}{>} 1 = A(0)$$

自由振荡频点 $\omega_0$ 附近幅值可以高于中心频点（零频点），这就是谐振现象



# 谐振峰在哪里？

$$\frac{dA(\omega)}{d\omega} = 0$$

$$= -\frac{1}{2} \frac{\omega_0^2}{\left( (\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2 \right)^{\frac{3}{2}}} \left[ 2(\omega_0^2 - \omega^2)(-2\omega) + 2(2\xi\omega_0\omega)2\xi\omega_0 \right]$$

$$= -\frac{\omega_0^2}{\left( (\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2 \right)^{\frac{3}{2}}} 2\omega \left[ \omega^2 + (2\xi^2 - 1)\omega_0^2 \right]$$

阻尼系数很小时，  
谐振峰确实出现在  
自由振荡频点，谐  
振峰高度近似为Q

$$\omega_e = \sqrt{1 - 2\xi^2} \omega_0 \quad (\xi < 0.707)$$

谐振峰频点

$$A(\omega_e) = \frac{1}{2\xi\sqrt{1-\xi^2}} \stackrel{\xi < 0.707}{>} 1 = A(0)$$

谐振峰高度

$$\omega_e = \sqrt{1 - 2\xi^2} \omega_0 \stackrel{\xi \ll 0.707}{\approx} \omega_0$$

$$A(\omega_e) = \frac{1}{2\xi\sqrt{1-\xi^2}}$$

$$\stackrel{\xi \ll 0.707}{\approx} \frac{1}{2\xi} = Q = A(\omega_0)$$

# 幅度最大平坦

$$\xi = 0.707$$

$$A(\omega) = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}}$$

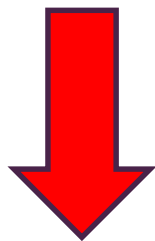
$$\left. \frac{dA(\omega)}{d\omega} \right|_{\omega=0} = 0$$

$$\left. \frac{d^2 A(\omega)}{d\omega^2} \right|_{\omega=0} = 0$$

$$\xi = \frac{\sqrt{2}}{2} = 0.707$$

$$A_2(\omega) \stackrel{\xi=0.707}{=} \frac{\omega_0^2}{\sqrt{\omega_0^4 + \omega^4}}$$

**Passband**的中心频点最大平坦



二阶低通系统的幅频特性具有最大平坦特性

此为最接近理想传输系统幅频特性的二阶低通系统：**最优**

$$A_n(\omega) \stackrel{\text{幅度最大平坦n阶滤波器}}{=} \frac{\omega_0^n}{\sqrt{\omega_0^{2n} + \omega^{2n}}}$$

理想传输系统幅频特性

$$A(\omega) = A_0 \quad \text{Passband绝对平坦}$$

$$\left. \frac{dA(\omega)}{d\omega} \right|_{\omega=0} = 0$$

$$\left. \frac{d^2 A(\omega)}{d\omega^2} \right|_{\omega=0} = 0$$

...

$$\left. \frac{d^n A(\omega)}{d\omega^n} \right|_{\omega=0} = 0$$

...

## 3dB带宽

$$A(\omega_{3dB}) = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega_{3dB}^2)^2 + (2\xi\omega_0\omega_{3dB})^2}} = \frac{A(0)}{\sqrt{2}} = \frac{1}{\sqrt{2}}$$

$$\omega_{3dB}^4 + (4\xi^2\omega_0^2 - 2\omega_0^2)\omega_{3dB}^2 - \omega_0^4 = 0$$

$$\omega_{3dB}^2 = \frac{-4\xi^2\omega_0^2 + 2\omega_0^2 + \sqrt{(4\xi^2\omega_0^2 - 2\omega_0^2)^2 + 4\omega_0^4}}{2} = \left(-2\xi^2 + 1 + \sqrt{(2\xi^2 - 1)^2 + 1}\right)\omega_0^2$$

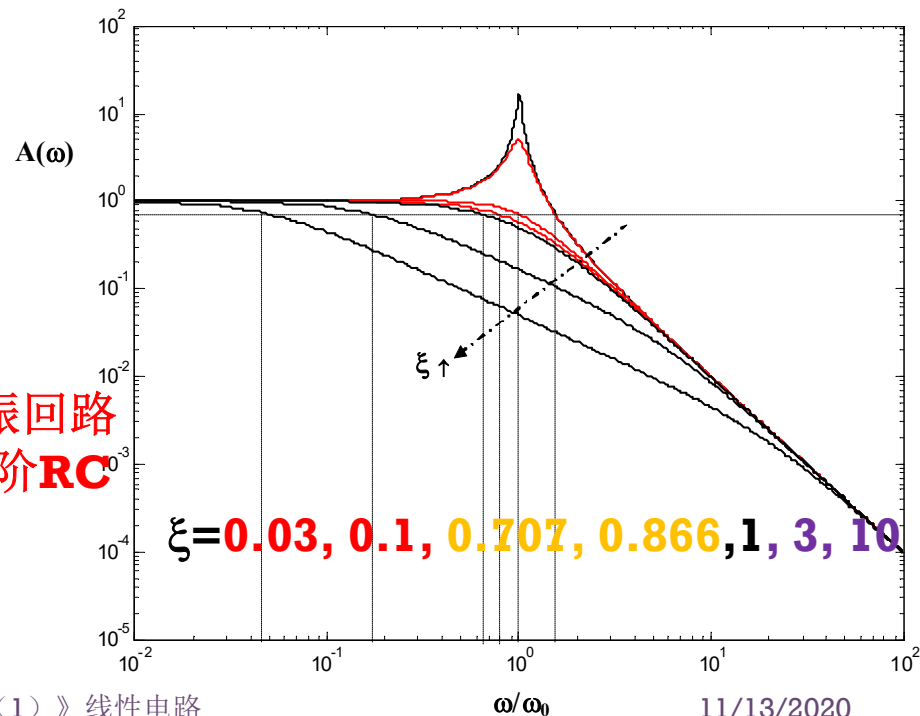
$$\omega_{3dB} = \omega_0 \sqrt{-2\xi^2 + 1 + \sqrt{(2\xi^2 - 1)^2 + 1}}$$

$$\omega_{3dB} \stackrel{\xi=0.707}{=} \omega_0$$

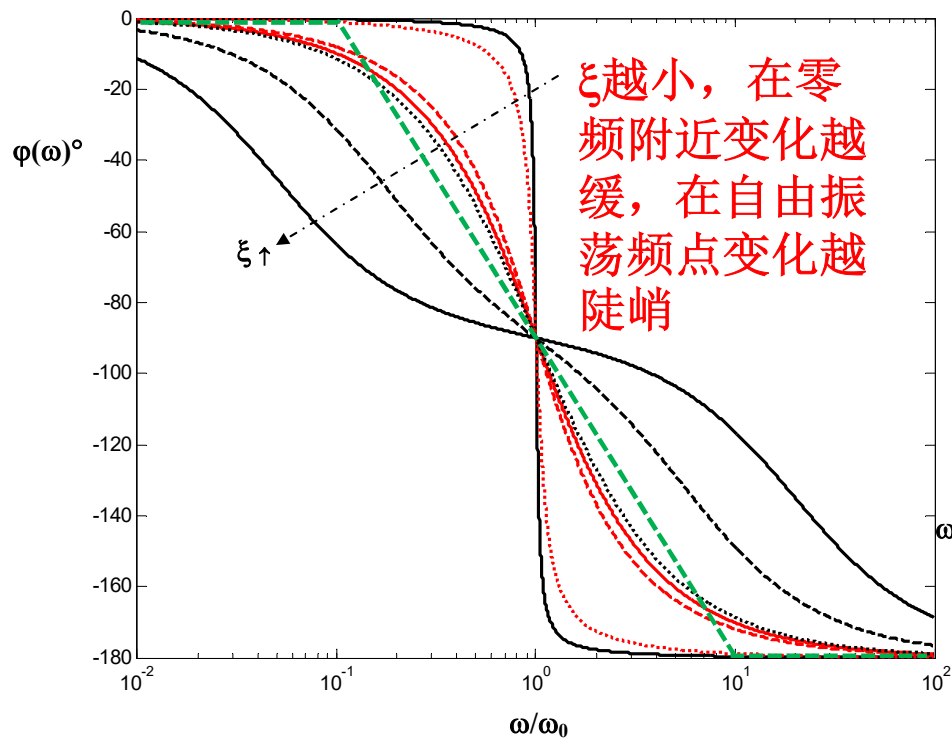
$$\omega_{3dB} \stackrel{\xi \gg 1}{\approx} \frac{1}{2\xi} \omega_0 \quad \text{=1/RC: RLC串联谐振回路}$$

**R很大时, 行为犹如一阶RC**

$$\omega_{3dB} \stackrel{\xi \ll 1}{\approx} \omega_0 \sqrt{1 + \sqrt{2}} = 1.554\omega_0$$



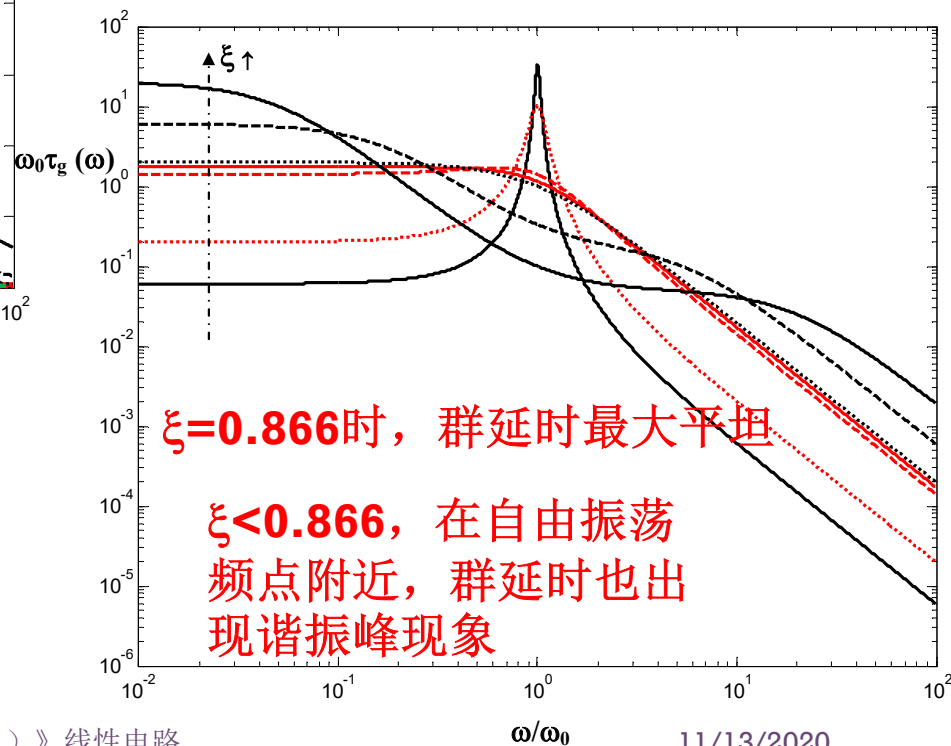
# 相频特性和群延时特性



$$\varphi(\omega) = -\arctan \frac{2\xi\omega_0\omega}{\omega_0^2 - \omega^2}$$

$$\xi = 0.03, 0.1, 0.707, 0.866, 1, 3, 10$$

$$\begin{aligned} \tau_g(\omega) &= -\frac{d\varphi(\omega)}{d\omega} \\ &= \frac{2\xi\omega_0(\omega^2 + \omega_0^2)}{\omega^4 + 2(2\xi^2 - 1)\omega_0^2\omega^2 + \omega_0^4} \end{aligned}$$



## 群延时最大平坦

$$\xi = 0.866$$

$$\tau_g(\omega) = \frac{2\xi\omega_0(\omega^2 + \omega_0^2)}{\omega^4 + 2(2\xi^2 - 1)\omega_0^2\omega^2 + \omega_0^4}$$

$$\left. \frac{d\tau_g(\omega)}{d\omega} \right|_{\omega=0} = 0$$

$$\left. \frac{d^2\tau_g(\omega)}{d\omega^2} \right|_{\omega=0} = 0$$

$$\xi = \frac{\sqrt{3}}{2} = 0.866$$



二阶低通系统的群延时特性具有最大平坦特性  
此为最接近理想传输系统群延时特性的二阶低通系统：最优

理想传输系统群延时特性

$$\tau_g(\omega) = \tau_0 \quad \text{passband}$$

$$\left. \frac{d\tau_g(\omega)}{d\omega} \right|_{\omega=0} = 0$$

$$\left. \frac{d^2\tau_g(\omega)}{d\omega^2} \right|_{\omega=0} = 0$$

...

$$\left. \frac{d^n\tau_g(\omega)}{d\omega^n} \right|_{\omega=0} = 0$$

...



# 最接近理想滤波器的二阶低通系统

$$\xi = \frac{\sqrt{2}}{2} = 0.707$$

二阶低通系统的幅频特性具有最大平坦特性（巴特沃思滤波器）  
此为最接近理想传输系统幅频特性的二阶低通系统：最优

$$\xi = \frac{\sqrt{3}}{2} = 0.866$$

二阶低通系统的群延时特性具有最大平坦特性（贝塞尔滤波器）  
此为最接近理想传输系统群延时特性的二阶低通系统：最优

$$\xi \in (0.707, 1)$$

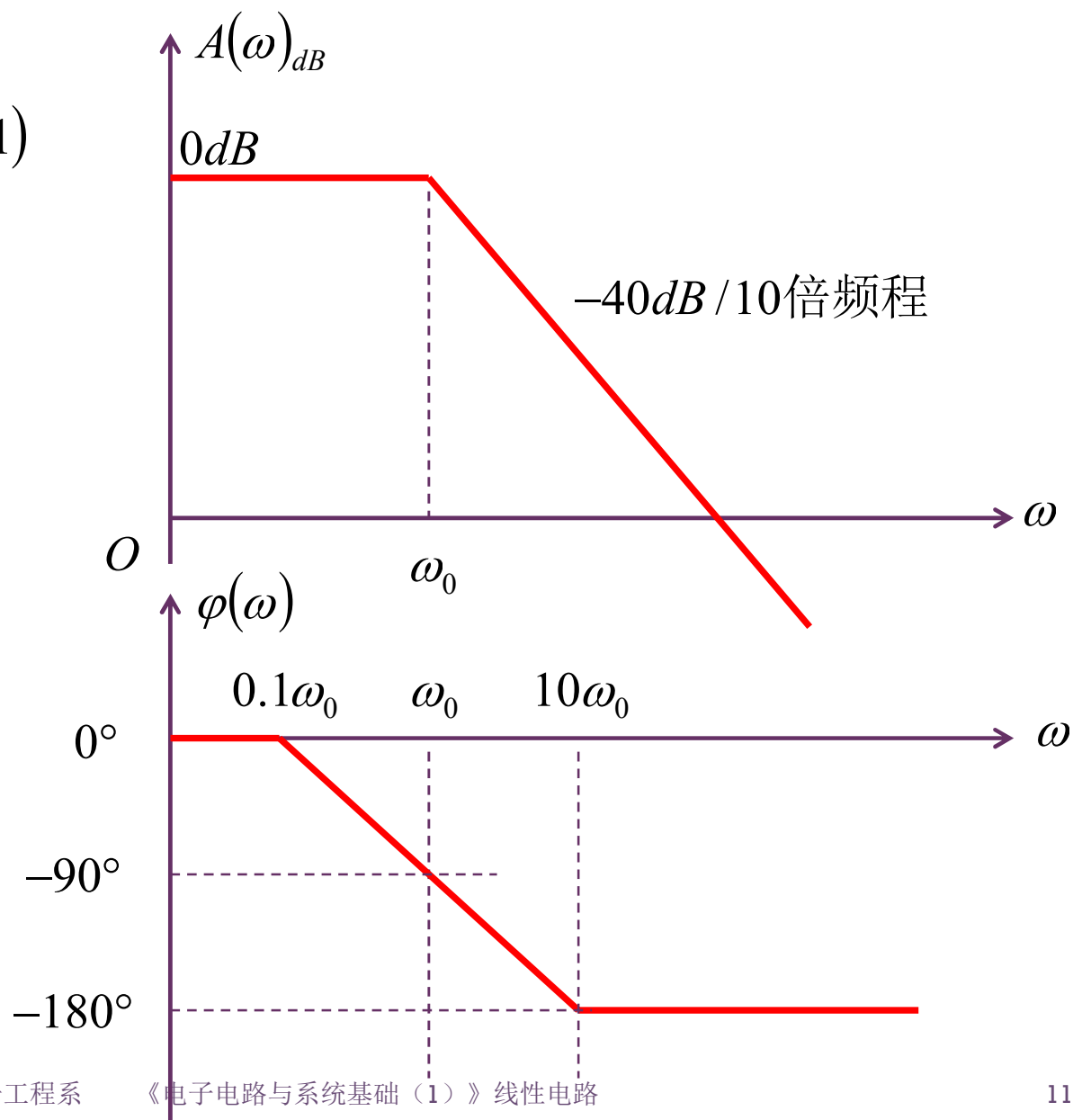
最优二阶低通系统：

频域：幅频特性、群延时特性相对平坦

时域：具有最快的阶跃响应（时域波形具有最小的线性失真）

# 最优二阶低通的波特图

$$\xi \in (0.707, 1)$$



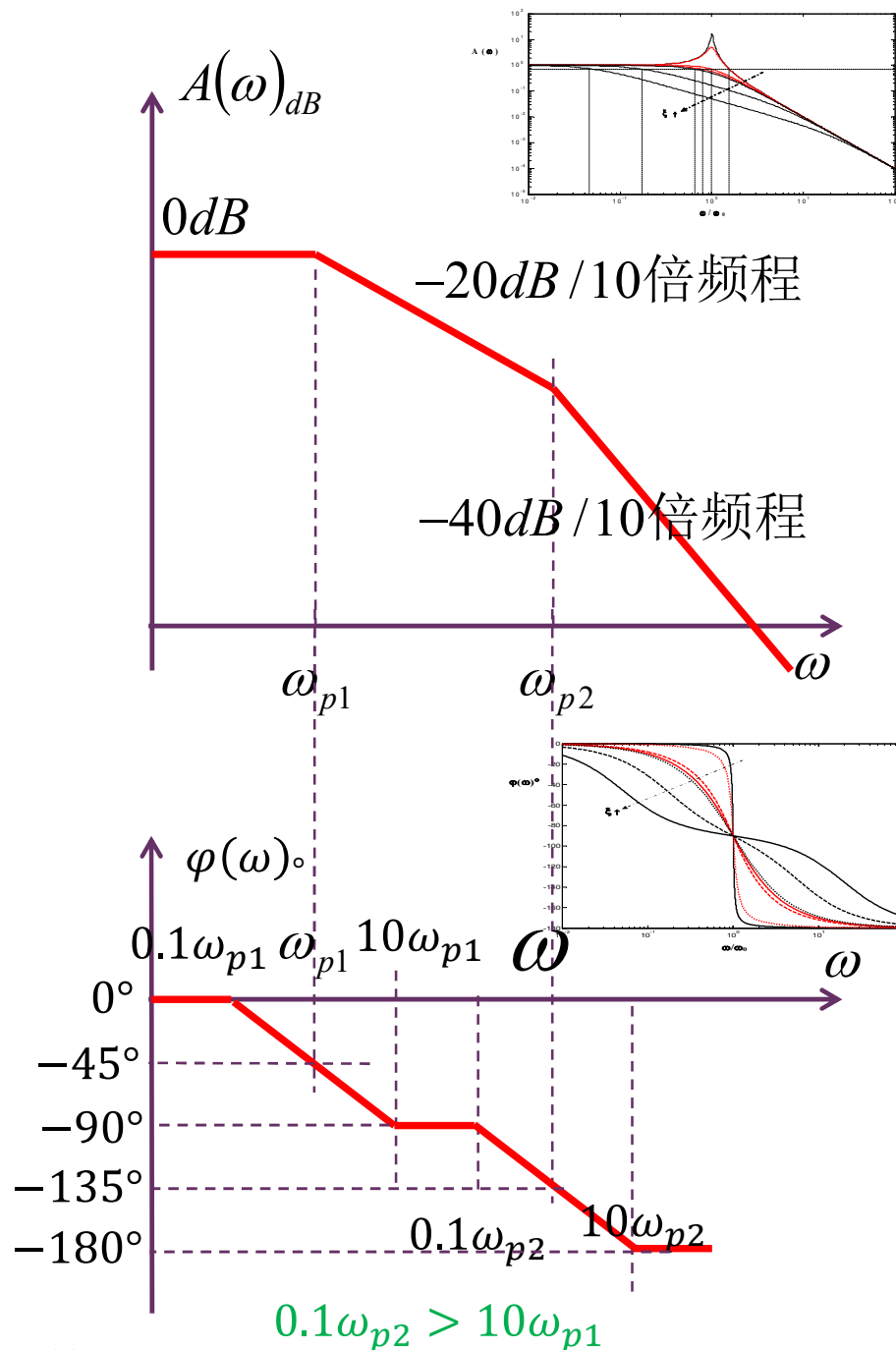
# 过阻尼的波特图

$$H(s) = \frac{\omega_0^2}{(s - \lambda_1)(s - \lambda_2)}$$

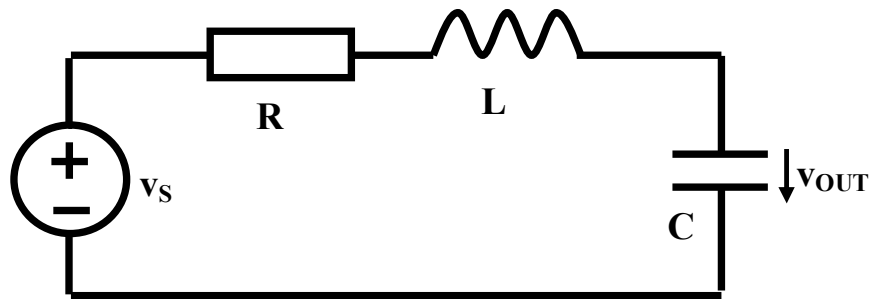
$$H(j\omega) = \frac{\omega_0^2}{(j\omega + \omega_{p1})(j\omega + \omega_{p2})}$$

$$= \frac{1}{\left(\frac{j\omega}{\omega_{p1}} + 1\right)\left(\frac{j\omega}{\omega_{p2}} + 1\right)}$$

$$\approx \begin{cases} 1 & \omega < \omega_{p1} \\ \frac{1}{j\omega} = \frac{\omega_{p1}}{j\omega} & \omega_{p1} < \omega < \omega_{p2} \\ \frac{1}{\frac{j\omega}{\omega_{p1}} \cdot \frac{j\omega}{\omega_{p2}}} = \frac{\omega_0^2}{-\omega^2} & \omega > \omega_{p2} \end{cases}$$



# 时域特性：冲激响应



$$\omega_0 = \frac{1}{\sqrt{LC}} \quad Z_0 = \sqrt{\frac{L}{C}}$$

$$\xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

$$v_C(0^+) = v_C(0^-) = 0$$

$$\frac{d}{dt} v_C(0^+) = \frac{i_C(0^+)}{C} = \frac{i_L(0^+)}{C} = \frac{V_{S0}}{Z_0 C} = \omega_0 V_{S0}$$

$$v_{C\infty}(t) = 0$$

$$v_S(t) = \frac{V_{S0}}{\omega_0} \cdot \delta(t)$$

$$i_L(0^-) = 0 \quad v_C(0^-) = 0$$

$$i_L(0^+) = i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} v_L(t) dt$$

$$= \frac{1}{L} \int_{0^-}^{0^+} \frac{V_{S0}}{\omega_0} \delta(t) dt = \frac{V_{S0}}{\omega_0 L} = \frac{V_{S0}}{Z_0}$$

$$x(t) = x_\infty(t) + (X_0 - X_{\infty 0}) e^{-\xi \omega_0 t} \cos \sqrt{1 - \xi^2} \omega_0 t + \left( \frac{\dot{X}_0 - \dot{X}_{\infty 0}}{\xi \omega_0} + X_0 - X_{\infty 0} \right) \frac{\xi}{\sqrt{1 - \xi^2}} e^{-\xi \omega_0 t} \sin \sqrt{1 - \xi^2} \omega_0 t \quad (t \geq 0)$$

$$v_{OUT}(t) = \frac{V_{S0}}{\sqrt{1 - \xi^2}} e^{-\xi \omega_0 t} \sin \left( \sqrt{1 - \xi^2} \omega_0 t \right) \cdot U(t)$$

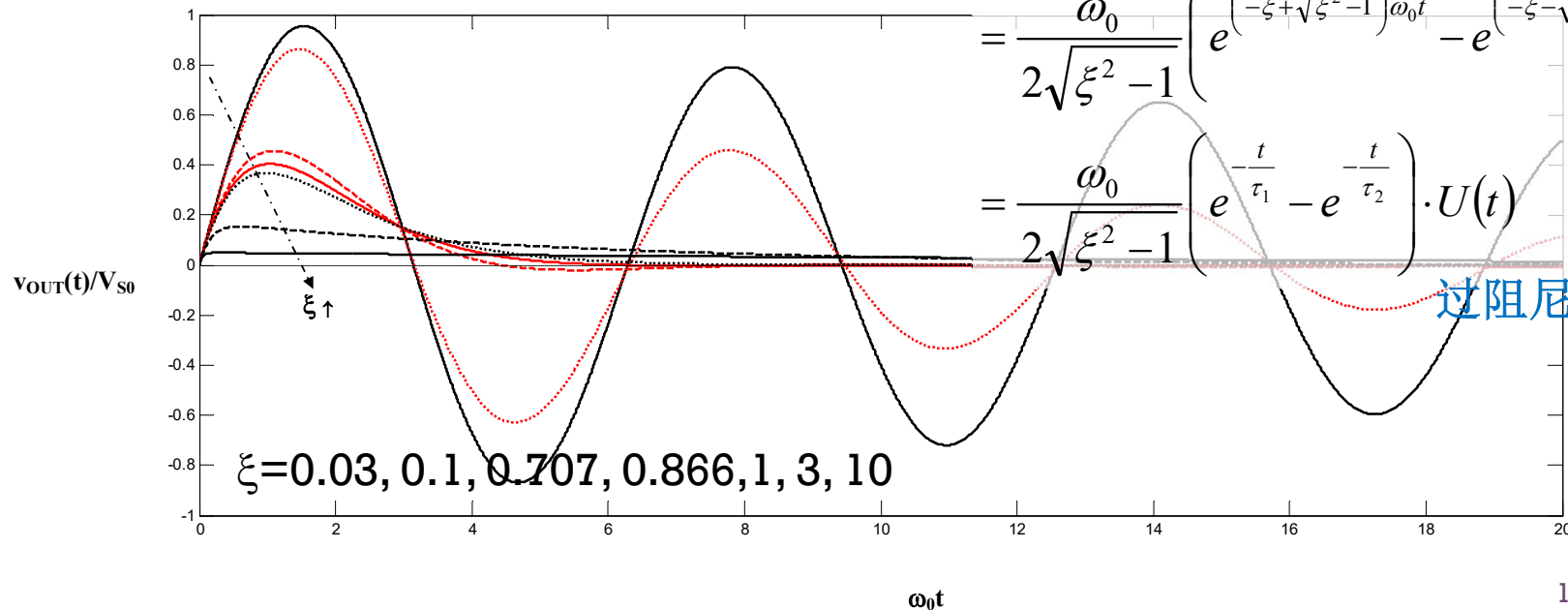
# 冲激响应时域波形

$$v_S(t) = \frac{V_{S0}}{\omega_0} \cdot \delta(t)$$

$$v_{OUT}(t) = \frac{V_{S0}}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin\left(\sqrt{1-\xi^2} \omega_0 t\right) \cdot U(t)$$

$$h(t) = \frac{\omega_0}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin\left(\sqrt{1-\xi^2} \omega_0 t\right) \cdot U(t)$$

欠阻尼：幅度指数衰减的正弦振荡



$$h(t) \stackrel{\xi=0}{=} \omega_0 \sin(\omega_0 t) \cdot U(t) \text{ 无阻尼：正弦振荡}$$

$$h(t) \stackrel{\xi>1}{=} \frac{\omega_0}{\sqrt{\xi^2-1}} e^{-\xi\omega_0 t} \sinh\left(\sqrt{\xi^2-1} \omega_0 t\right) \cdot U(t)$$

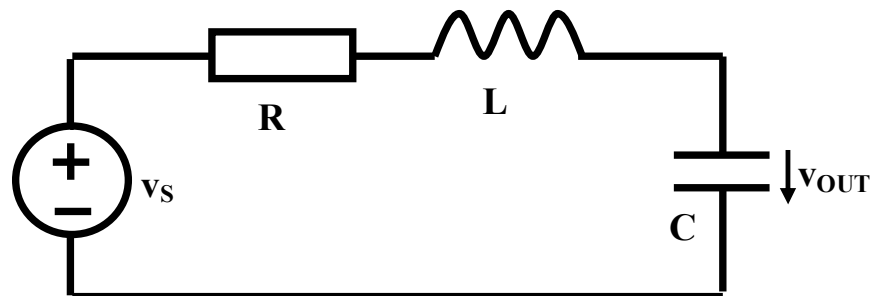
$$= \frac{\omega_0}{\sqrt{\xi^2-1}} e^{-\xi\omega_0 t} \frac{e^{\sqrt{\xi^2-1}\omega_0 t} - e^{-\sqrt{\xi^2-1}\omega_0 t}}{2} \cdot U(t)$$

$$= \frac{\omega_0}{2\sqrt{\xi^2-1}} \left( e^{(-\xi+\sqrt{\xi^2-1})\omega_0 t} - e^{(-\xi-\sqrt{\xi^2-1})\omega_0 t} \right) \cdot U(t)$$

$$= \frac{\omega_0}{2\sqrt{\xi^2-1}} \left( e^{-\frac{t}{\tau_1}} - e^{-\frac{t}{\tau_2}} \right) \cdot U(t)$$

过阻尼：指数衰减

# 阶跃响应



$$v_s(t) = V_{S0} \cdot U(t)$$

$$i_L(0^-) = 0 \quad v_C(0^-) = 0$$

$$\begin{aligned} i_L(0^+) &= i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} v_L(t) dt \\ &= i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} V_{S0} U(t) dt = i_L(0^-) = 0 \end{aligned}$$

$$\omega_0 = \frac{1}{\sqrt{LC}} \quad Z_0 = \sqrt{\frac{L}{C}}$$

$$\xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

$$v_C(0^+) = v_C(0^-) = 0$$

$$\frac{d}{dt} v_C(0^+) = \frac{i_C(0^+)}{C} = \frac{i_L(0^+)}{C} = 0$$

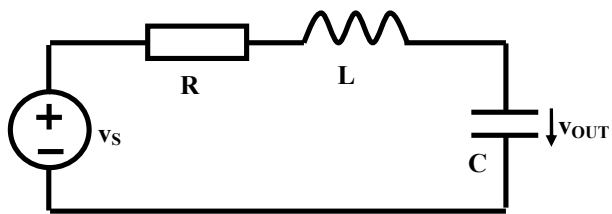
$$v_{C\infty}(t) = V_{S0}$$

$$\begin{aligned} x(t) &= x_\infty(t) + (X_0 - X_\infty) e^{-\xi\omega_0 t} \cos \sqrt{1-\xi^2} \omega_0 t \\ &+ \left( \frac{\dot{X}_0 - \dot{X}_\infty}{\xi\omega_0} + X_0 - X_\infty \right) \frac{\xi}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin \sqrt{1-\xi^2} \omega_0 t \end{aligned} \quad (t > 0)$$

$$v_{OUT}(t) = V_{S0} \left[ 1 - e^{-\xi\omega_0 t} \left( \cos \sqrt{1-\xi^2} \omega_0 t + \frac{\xi}{\sqrt{1-\xi^2}} \sin \sqrt{1-\xi^2} \omega_0 t \right) \right] \cdot U(t)$$

# 阶跃响应时域波形

$$v_S(t) = V_{S0} \cdot U(t)$$



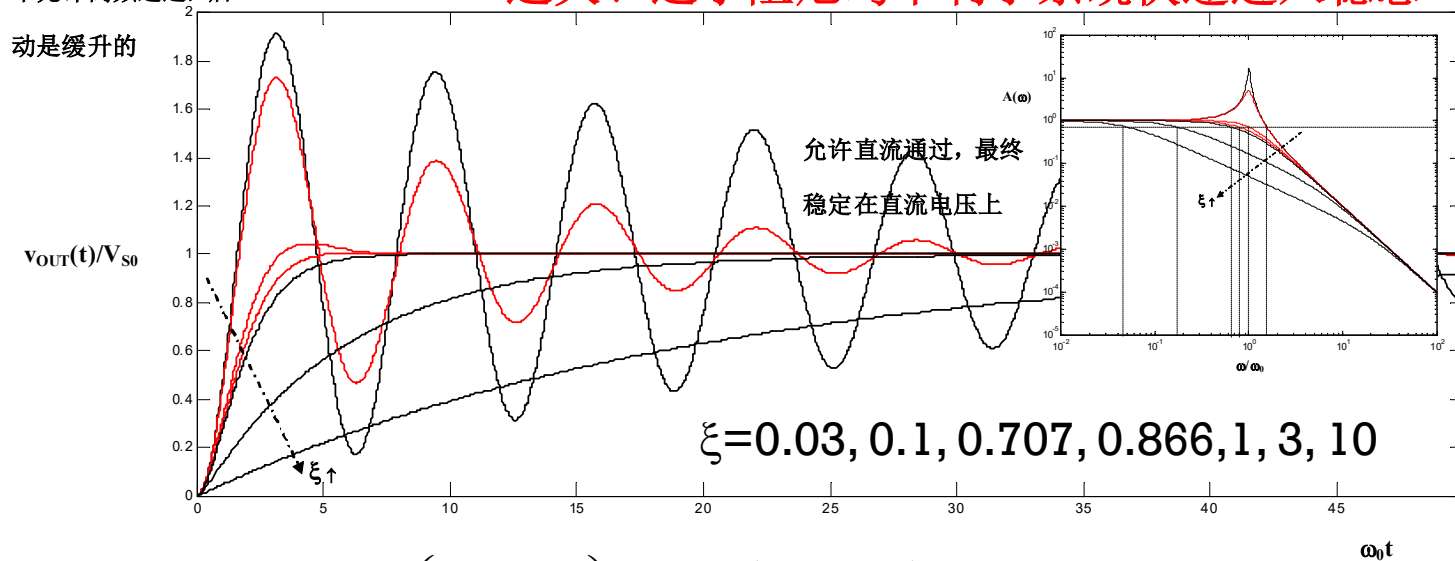
$$v_{OUT}(t) = V_{S0} \left( 1 - e^{-\xi\omega_0 t} \left( \cos\sqrt{1-\xi^2}\omega_0 t + \frac{\xi}{\sqrt{1-\xi^2}} \sin\sqrt{1-\xi^2}\omega_0 t \right) \right) \cdot U(t)$$

$$g(t) = \left( 1 - e^{-\xi\omega_0 t} \left( \cos\sqrt{1-\xi^2}\omega_0 t + \frac{\xi}{\sqrt{1-\xi^2}} \sin\sqrt{1-\xi^2}\omega_0 t \right) \right) \cdot U(t)$$

不允许高频通过，启动是缓升的

过大、过小阻尼均不利于系统快速进入稳态

$$\tau = \frac{1}{\xi\omega_0} \quad (0 < \xi < 1)$$



$$(\xi > 1)$$

$$\tau_1 = \frac{\xi + \sqrt{\xi^2 - 1}}{\omega_0}$$

长寿命

$$\tau_2 = \frac{1}{(\xi + \sqrt{\xi^2 - 1})\omega_0}$$

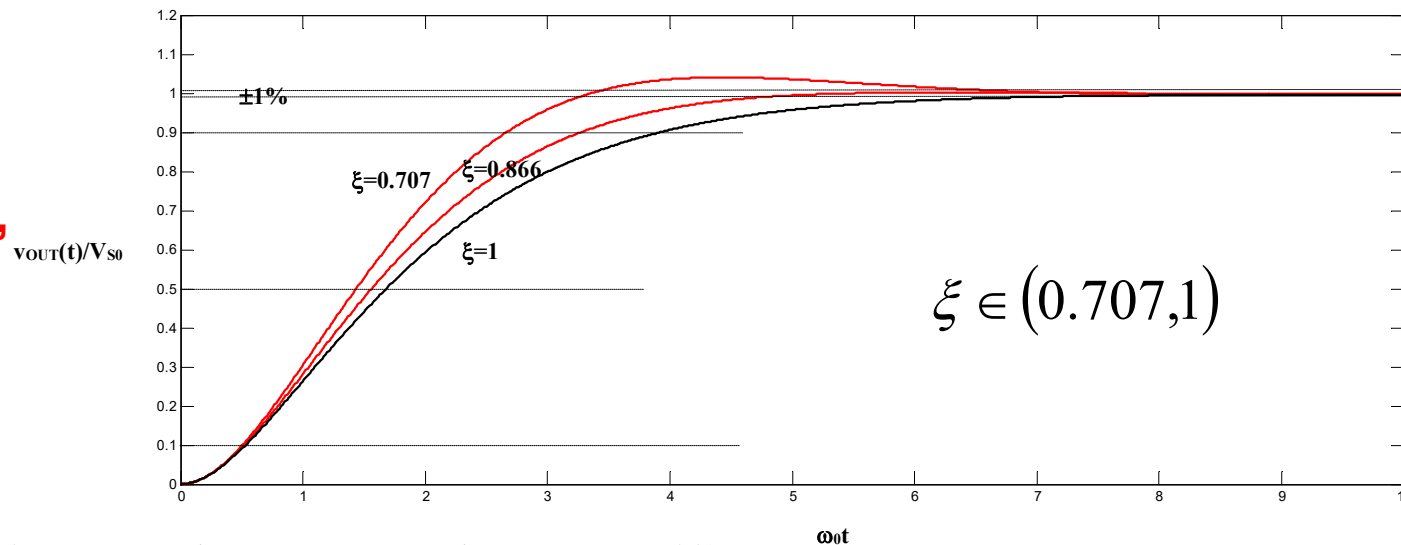
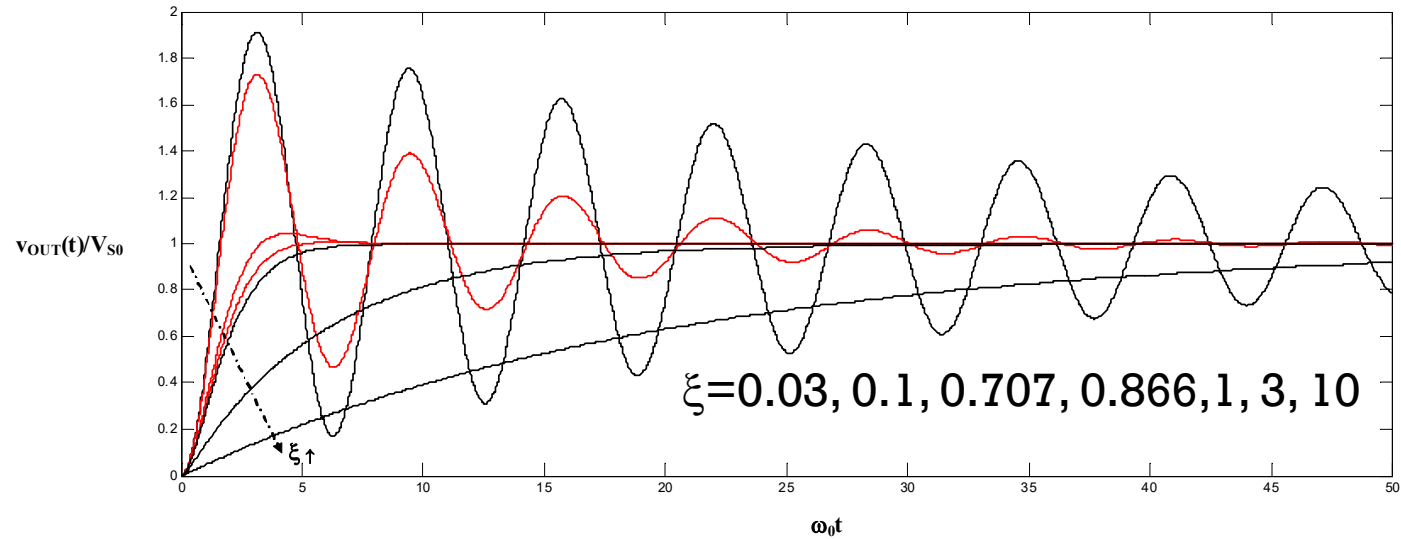
短寿命

$$g(t) \stackrel{\xi \text{极大时}}{\approx} \left( 1 - e^{-\frac{\omega_0 t}{2\xi}} \right) U(t) = \left( 1 - e^{-\frac{t}{RC}} \right) U(t)$$

**RLC在R很大时，犹如一阶RC**

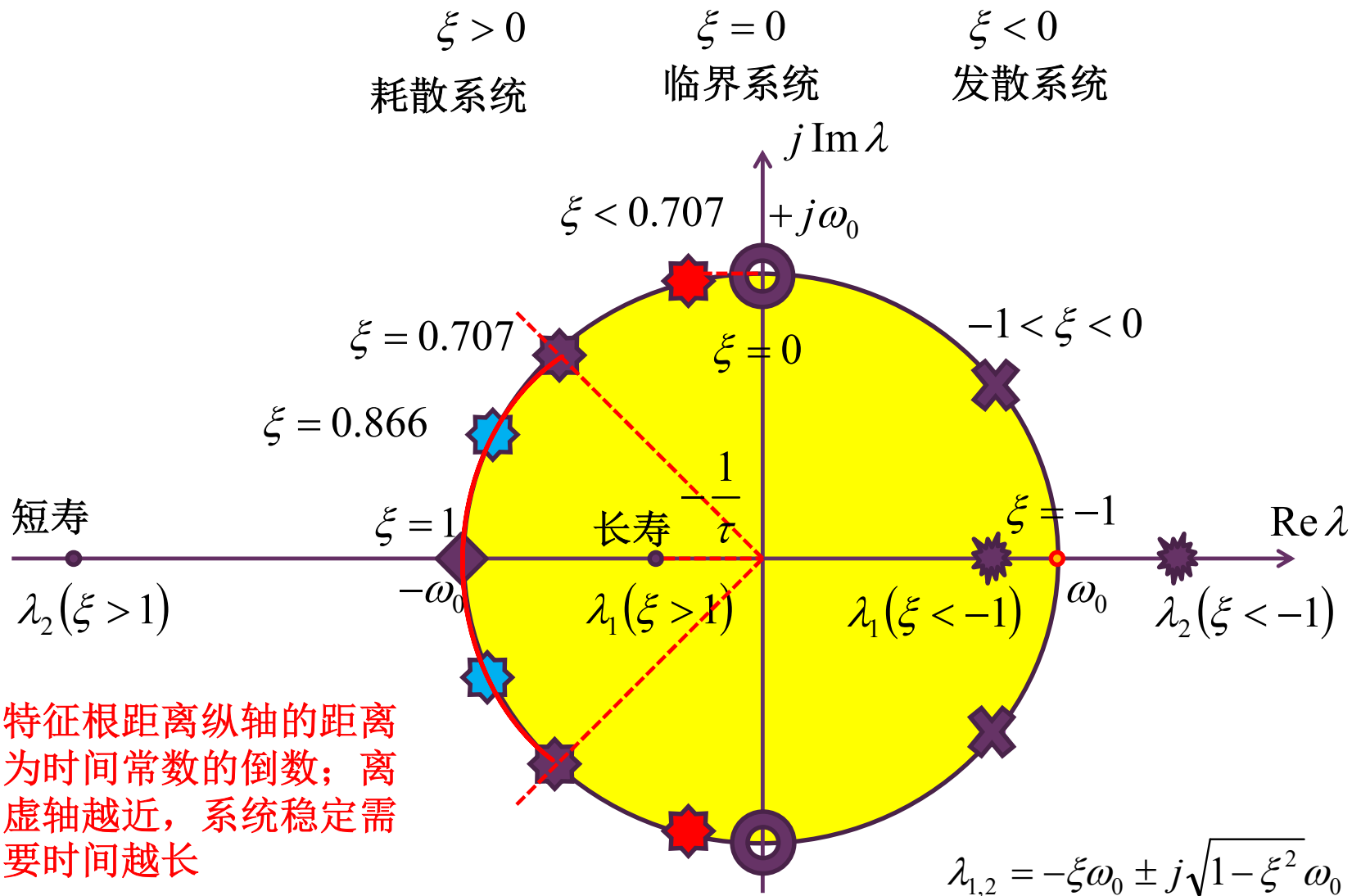
# 最优二阶低通的阶跃响应

阻尼系数在 **0.707-1** 之间时，系统进入稳态需要的时间最短：最优二阶低通系统，和一阶系统大体相当，大约  $5\tau$  ( **$1.5QT, 4.6\tau$** ) 时间进入偏离稳态 **1%** 误差范围，大约  $7\tau$  ( **$2.2QT, 6.9\tau$** ) 进入偏离稳态 **0.1%** 误差范围

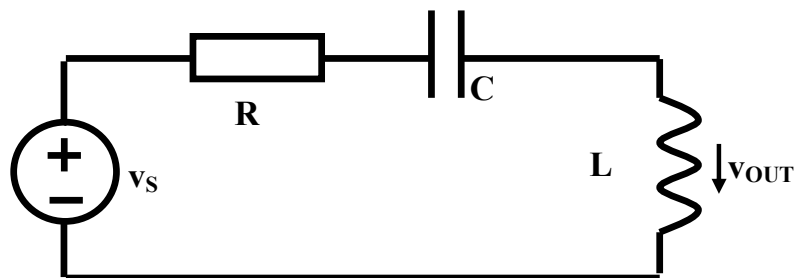




# 从特征根位置看最优响应为何是最快的



## 二阶高通：电感分压



直观理解：

低频：电容开路，电感短路，  
信号通不过

高频：电容短路，电感开路，  
信号全部通过

$$H(j\omega) = \frac{\dot{V}_L}{\dot{V}_S} = \frac{j\omega L}{R + j\omega L + \frac{1}{j\omega C}} = \frac{(j\omega)^2 LC}{(j\omega)^2 LC + j\omega RC + 1}$$

$$\stackrel{j\omega \rightarrow s}{=} \frac{s^2 LC}{s^2 LC + sRC + 1} = \frac{s^2}{s^2 + s\frac{R}{L} + \frac{1}{LC}} = H_0 \frac{s^2}{s^2 + 2\xi\omega_0 s + \omega_0^2}$$

二阶高通传函典型形式

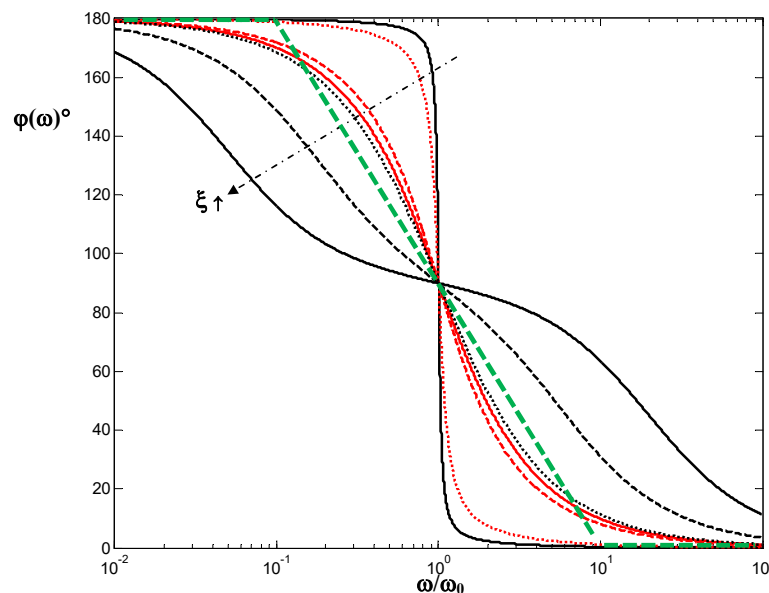
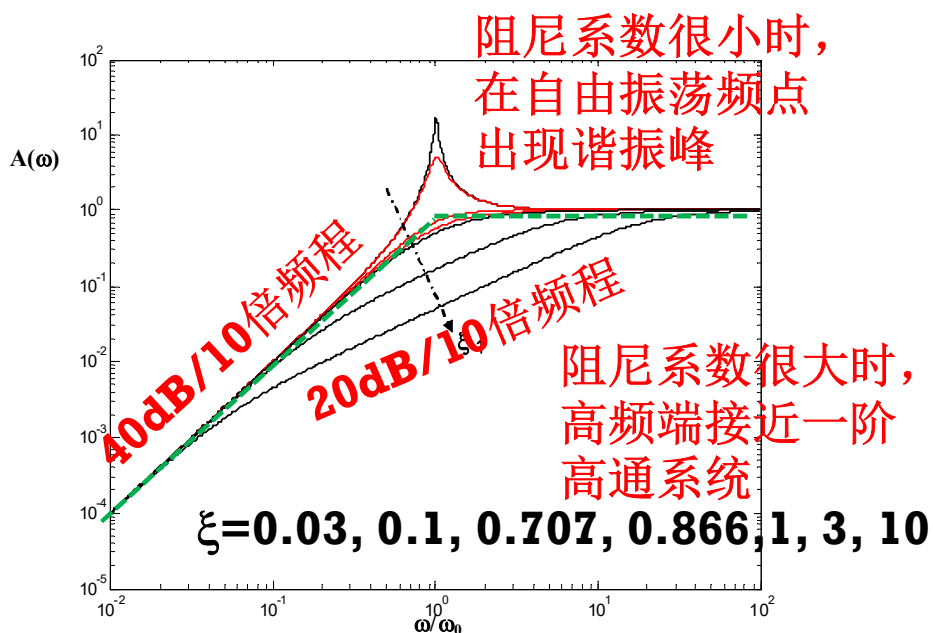
$$H_0 = 1 \quad \omega_0 = \frac{1}{\sqrt{LC}} \quad \xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

# 幅频特性、相频特性

$$H(s) = \frac{s^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} \stackrel{s=j\omega}{=} \frac{-\omega^2}{\omega_0^2 - \omega^2 + j2\xi\omega_0\omega} = A(\omega)e^{j\varphi(\omega)}$$

$$A(\omega) = \frac{\omega^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}}$$

$$\varphi(\omega) = \pi - \arctan \frac{2\xi\omega_0\omega}{\omega_0^2 - \omega^2}$$



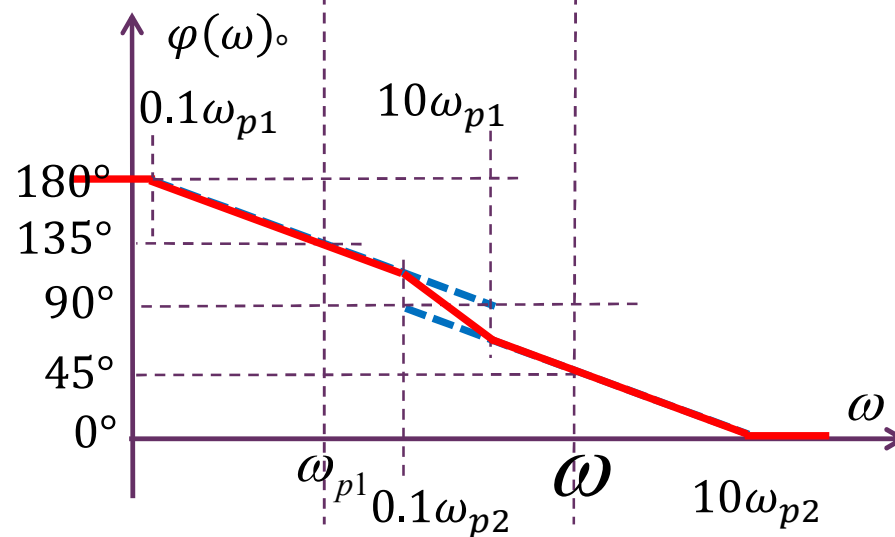
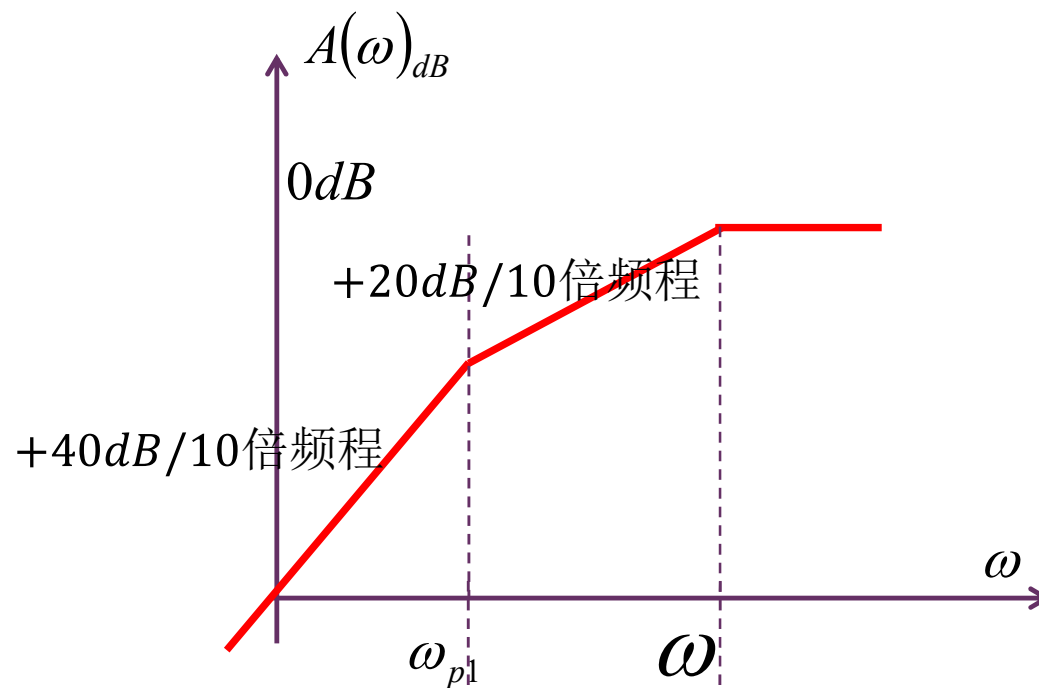
# 过阻尼的伯特图

$$H(s) = \frac{s^2}{(s - \lambda_1)(s - \lambda_2)}$$

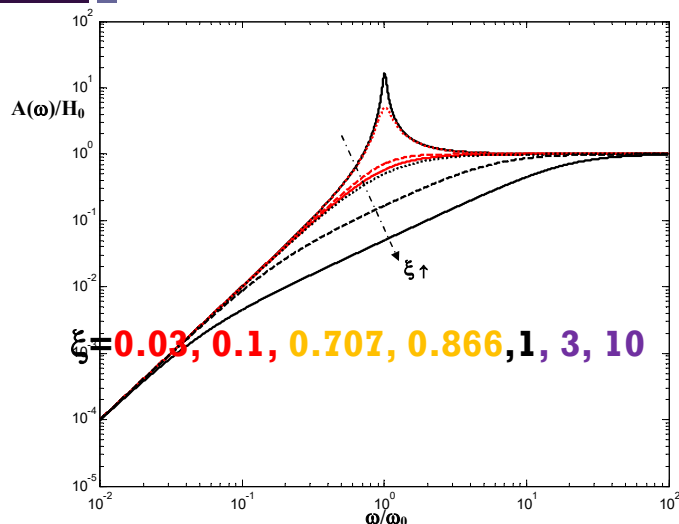
$$H(j\omega) = \frac{-\omega^2}{(j\omega + \omega_{p1})(j\omega + \omega_{p2})}$$

$$= \frac{1}{\left(1 + \frac{\omega_{p1}}{j\omega}\right)\left(1 + \frac{\omega_{p2}}{j\omega}\right)}$$

$$\approx \begin{cases} 1 & \omega > \omega_{p2} \\ \frac{1}{\frac{\omega_{p2}}{j\omega}} = \frac{j\omega}{\omega_{p2}} & \omega_{p2} > \omega > \omega_{p1} \\ \frac{1}{\frac{\omega_{p1}}{j\omega} \cdot \frac{\omega_{p2}}{j\omega}} = \frac{-\omega^2}{\omega_0^2} & \omega < \omega_{p1} \end{cases}$$



# 欠阻尼的谐振峰



阻尼系数很小时，谐振峰近似出现在自由振荡频点位置，谐振峰高度近似为Q

$$A(\omega) = \frac{\omega^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}}$$

$$\frac{dA(\omega)}{d\omega} = 0$$

$$= \frac{2\omega\omega_0^2}{\left((\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2\right)^{\frac{3}{2}}} \left[\omega_0^2 + (2\xi^2 - 1)\omega^2\right]$$

$$\omega_e = \frac{\omega_0}{\sqrt{1 - 2\xi^2}} \quad (\xi < 0.707)$$

$$A(\omega_e) = \frac{1}{2\xi\sqrt{1 - \xi^2}} \stackrel{\xi < 0.707}{>} 1 = A(\infty)$$

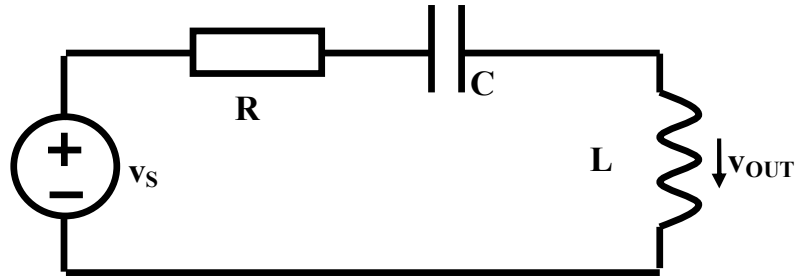
$$\omega_e = \frac{\omega_0}{\sqrt{1 - 2\xi^2}} \stackrel{\xi \ll 0.707}{\approx} \omega_0$$

$$A(\omega_e) = \frac{1}{2\xi\sqrt{1 - \xi^2}} \stackrel{\xi \ll 0.707}{\approx} \frac{1}{2\xi} = Q = A(\omega_0)$$

# 时域特性：冲激响应

$$\omega_0 = \frac{1}{\sqrt{LC}} \quad Z_0 = \sqrt{\frac{L}{C}}$$

$$\xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$



$$v_s(t) = \frac{V_{S0}}{\omega_0} \cdot \delta(t)$$

$$i_L(0^-) = 0 \quad v_C(0^-) = 0$$

$$i_L(0^+) = i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} v_L(t) dt$$

$$= \frac{1}{L} \int_{0^-}^{0^+} \frac{V_{S0}}{\omega_0} \delta(t) dt = \frac{V_{S0}}{\omega_0 L} = \frac{V_{S0}}{Z_0}$$

$$v_C(0^+) = v_C(0^-) = 0$$

$$v_L(0^+) = v_s(0^+) - v_R(0^+) - v_C(0^+)$$

$$= 0 - i_L(0^+)R - 0 = -2\xi V_{S0}$$

$$\frac{d}{dt} v_L(0^+) = \frac{d}{dt} v_s(0^+) - \frac{d}{dt} v_R(0^+) - \frac{d}{dt} v_C(0^+)$$

$$= 0 - R \frac{d}{dt} i_L(0^+) - \frac{i_C(0^+)}{C} = -\frac{R}{L} v_L(0^+) - \frac{i_L(0^+)}{C}$$

$$= -2\xi \omega_0 (-2\xi V_{S0}) - \frac{V_{S0}}{Z_0 C} = (4\xi^2 - 1) \omega_0 V_{S0}$$

$$v_{L\infty}(t) = 0$$

# 单位冲激响应

$$v_L(0^+) = -2\xi V_{S0} \quad \frac{d}{dt} v_L(0^+) = (4\xi^2 - 1)\omega_0 V_{S0}$$

$$v_L(0) = \frac{V_{S0}}{\omega_0} \cdot \delta(t)$$

$$v_{L\infty}(t) = 0$$

$$v_{L\infty}(t) = \frac{V_{S0}}{\omega_0} \delta(t)$$

t=0瞬间冲激电压加载到电感上

$$x(t) = x_\infty(t) + (X_0 - X_{\infty 0})e^{-\xi\omega_0 t} \cos\sqrt{1-\xi^2}\omega_0 t + \left( \frac{\dot{X}_0 - \dot{X}_{\infty 0}}{\xi\omega_0} + X_0 - X_{\infty 0} \right) \frac{\xi}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin\sqrt{1-\xi^2}\omega_0 t \quad (t > 0)$$

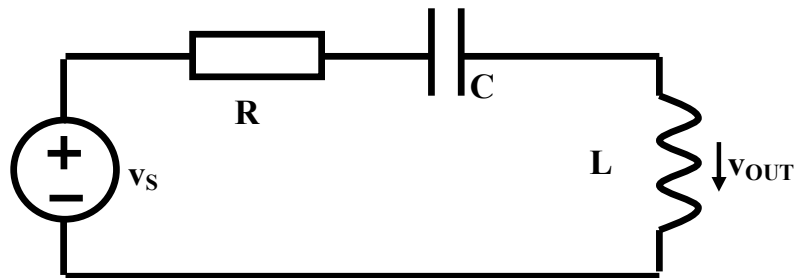
$$v_{OUT}(t) = \frac{V_{S0}}{\omega_0} \delta(t) + \left[ -2\xi V_{S0} e^{-\xi\omega_0 t} \cos\sqrt{1-\xi^2}\omega_0 t + \left( \frac{4\xi^2 - 1}{\xi} - 2\xi \right) V_{S0} \frac{\xi}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin(\sqrt{1-\xi^2}\omega_0 t) \right] \cdot U(t)$$

$$= \frac{V_{S0}}{\omega_0} \left[ \delta(t) - 2\xi\omega_0 e^{-\xi\omega_0 t} \cos\sqrt{1-\xi^2}\omega_0 t \cdot U(t) + \frac{2\xi^2 - 1}{\sqrt{1-\xi^2}} \omega_0 e^{-\xi\omega_0 t} \sin(\sqrt{1-\xi^2}\omega_0 t) \cdot U(t) \right]$$

$$v_S(t) = \frac{V_{S0}}{\omega_0} \cdot \delta(t)$$

$$h(t) = \delta(t) + \omega_0 e^{-\xi\omega_0 t} \left[ -2\xi \cos\sqrt{1-\xi^2}\omega_0 t + \frac{2\xi^2 - 1}{\sqrt{1-\xi^2}} \sin(\sqrt{1-\xi^2}\omega_0 t) \right] \cdot U(t)$$

# 阶跃响应



$$v_S(t) = V_{S0} \cdot U(t)$$

$$i_L(0^-) = 0 \quad v_C(0^-) = 0$$

$$i_L(0^+) = i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} v_L(t) dt$$

$$= i_L(0^-) + \frac{1}{L} \int_{0^-}^{0^+} V_{S0} U(t) dt$$

$$= i_L(0^-) = 0$$

$$v_{OUT}(t) = V_{S0} e^{-\xi \omega_0 t} \left( \cos \sqrt{1 - \xi^2} \omega_0 t - \frac{\xi}{\sqrt{1 - \xi^2}} \sin \sqrt{1 - \xi^2} \omega_0 t \right) \cdot U(t)$$

$$\omega_0 = \frac{1}{\sqrt{LC}} \quad \xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}} \quad Z_0 = \sqrt{\frac{L}{C}}$$

$$v_L(0^+) = V_{S0}$$

$$\begin{aligned} \frac{d}{dt} v_L(0^+) &= \frac{d}{dt} v_S(0^+) - \frac{d}{dt} v_R(0^+) - \frac{d}{dt} v_C(0^+) \\ &= 0 - R \frac{d}{dt} i_L(0^+) - \frac{i_C(0^+)}{C} = -\frac{R}{L} v_L(0^+) - \frac{i_L(0^+)}{C} \end{aligned}$$

$$= -2\xi \omega_0 V_{S0} - 0 = -2\xi \omega_0 V_{S0}$$

$$v_{L\infty}(t) = 0$$

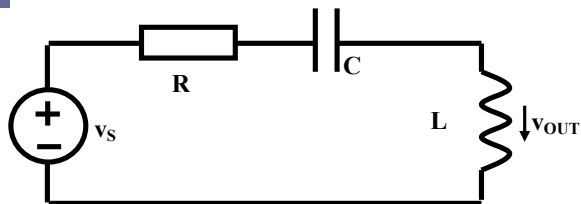
$$\begin{aligned} x(t) &= x_\infty(t) + (X_0 - X_\infty) e^{-\xi \omega_0 t} \cos \sqrt{1 - \xi^2} \omega_0 t \\ &+ \left( \frac{\dot{X}_0 - \dot{X}_\infty}{\xi \omega_0} + X_0 - X_\infty \right) \frac{\xi}{\sqrt{1 - \xi^2}} e^{-\xi \omega_0 t} \sin \sqrt{1 - \xi^2} \omega_0 t \end{aligned}$$

$$(t \geq 0)$$



# 阶跃响应时域波形

$$v_S(t) = V_{S0} \cdot U(t)$$

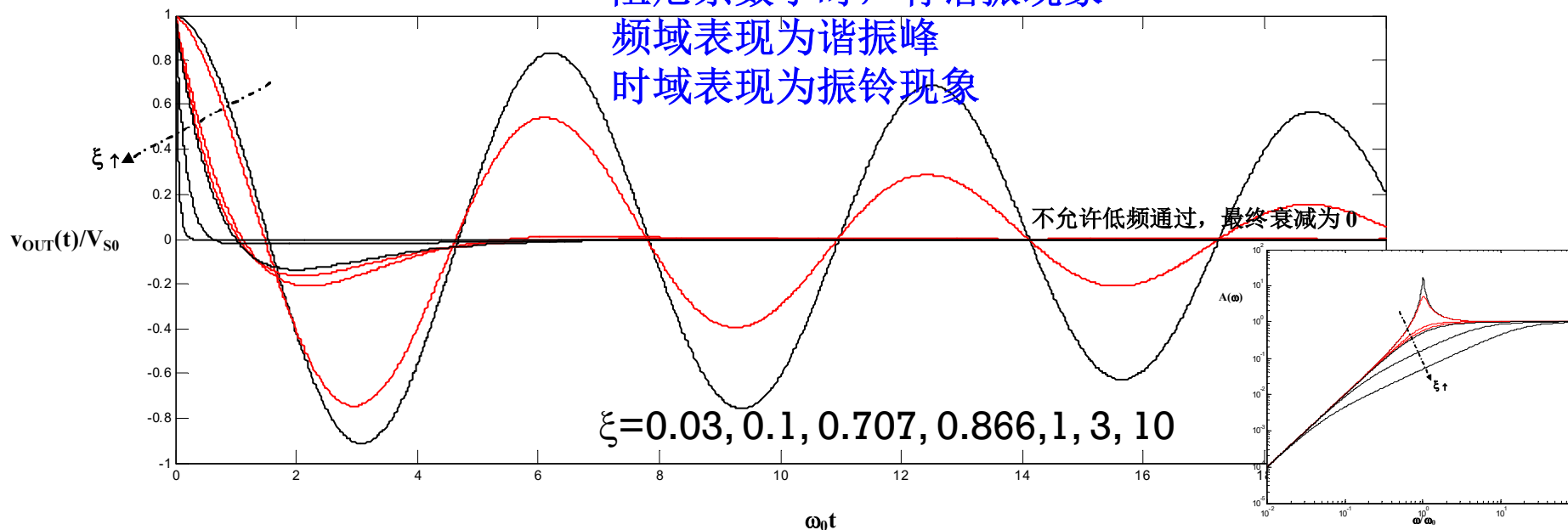


$$v_{OUT}(t) = V_{S0} e^{-\xi \omega_0 t} \left( \cos \sqrt{1-\xi^2} \omega_0 t - \frac{\xi}{\sqrt{1-\xi^2}} \sin \sqrt{1-\xi^2} \omega_0 t \right) \cdot U(t)$$

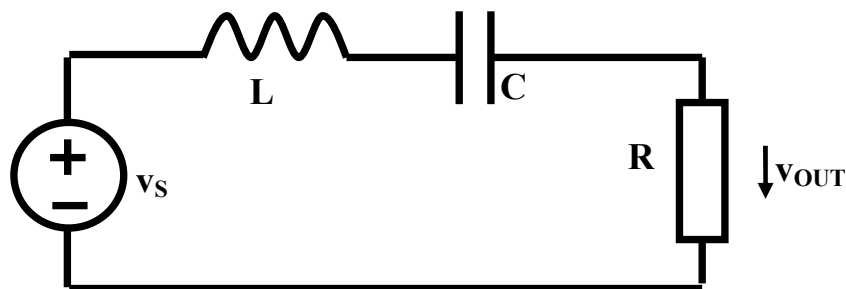
$$g(t) = e^{-\xi \omega_0 t} \left( \cos \sqrt{1-\xi^2} \omega_0 t - \frac{\xi}{\sqrt{1-\xi^2}} \sin \sqrt{1-\xi^2} \omega_0 t \right) \cdot U(t)$$

允许高频通过，瞬间跳变

阻尼系数小时，有谐振现象  
频域表现为谐振峰  
时域表现为振铃现象



# 二阶带通：电阻分压



直观理解：

低频：电容开路，电感短路，信号通不过

高频：电容短路，电感开路，信号通不过

自由振荡频点：电容电抗 $-jZ_0$ 和电感电抗 $+jZ_0$ 抵消，犹如短路，信号通过

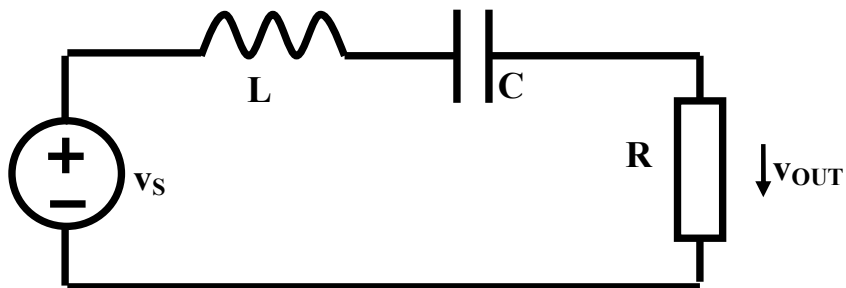
$$H(j\omega) = \frac{\dot{V}_R}{\dot{V}_S} = \frac{R}{R + j\omega L + \frac{1}{j\omega C}} = \frac{j\omega RC}{(j\omega)^2 LC + j\omega RC + 1}$$

$$\stackrel{j\omega \rightarrow s}{=} \frac{sRC}{s^2 LC + sRC + 1} = \frac{s \frac{R}{L}}{s^2 + s \frac{R}{L} + \frac{1}{LC}} = H_0 \frac{2\xi\omega_0 s}{s^2 + 2\xi\omega_0 s + \omega_0^2}$$

二阶带通传函典型形式

$$H_0 = 1 \quad \omega_0 = \frac{1}{\sqrt{LC}} \quad \xi = \frac{R}{2Z_0} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

# 考察带通习惯用Q值

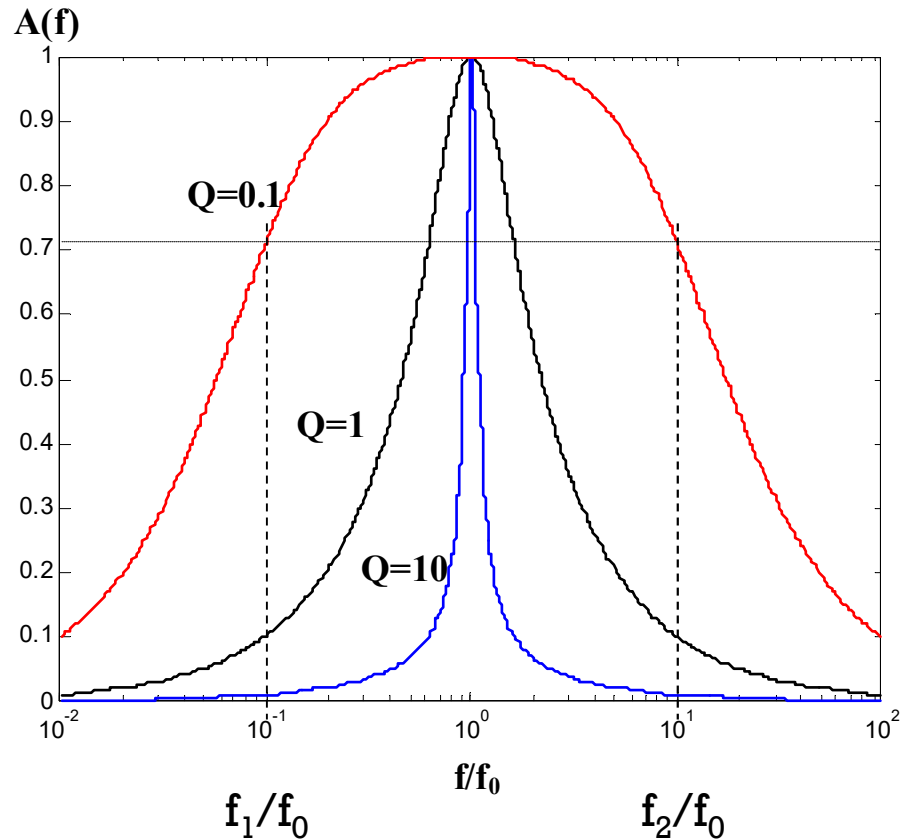


$$Q = \frac{1}{R} \sqrt{\frac{L}{C}} = \frac{Z_0}{R} = \frac{\omega_0 L}{R} = \frac{1}{2\xi}$$

品质因数：系统储能与耗能之比

$$\begin{aligned}
 H(j\omega) &= \frac{2\xi\omega_0 s}{s^2 + 2\xi\omega_0 s + \omega_0^2} = \frac{\frac{\omega_0}{Q} s}{s^2 + \frac{\omega_0}{Q} s + \omega_0^2} \stackrel{s=j\omega}{=} \frac{j\frac{\omega_0}{Q}\omega}{-\omega^2 + j\frac{\omega_0}{Q}\omega + \omega_0^2} \\
 &= \frac{1}{1 + jQ\left(\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega}\right)} = \frac{1}{\sqrt{1 + Q^2\left(\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega}\right)^2}} e^{-j\arctan Q\left(\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega}\right)} = A(\omega)e^{j\varphi(\omega)}
 \end{aligned}$$

# 幅频特性：带通选频特性



$$f_0 = \frac{1}{2\pi\sqrt{LC}}$$

$$A(f) = \frac{1}{\sqrt{1 + Q^2 \left( \frac{f}{f_0} - \frac{f_0}{f} \right)^2}}$$

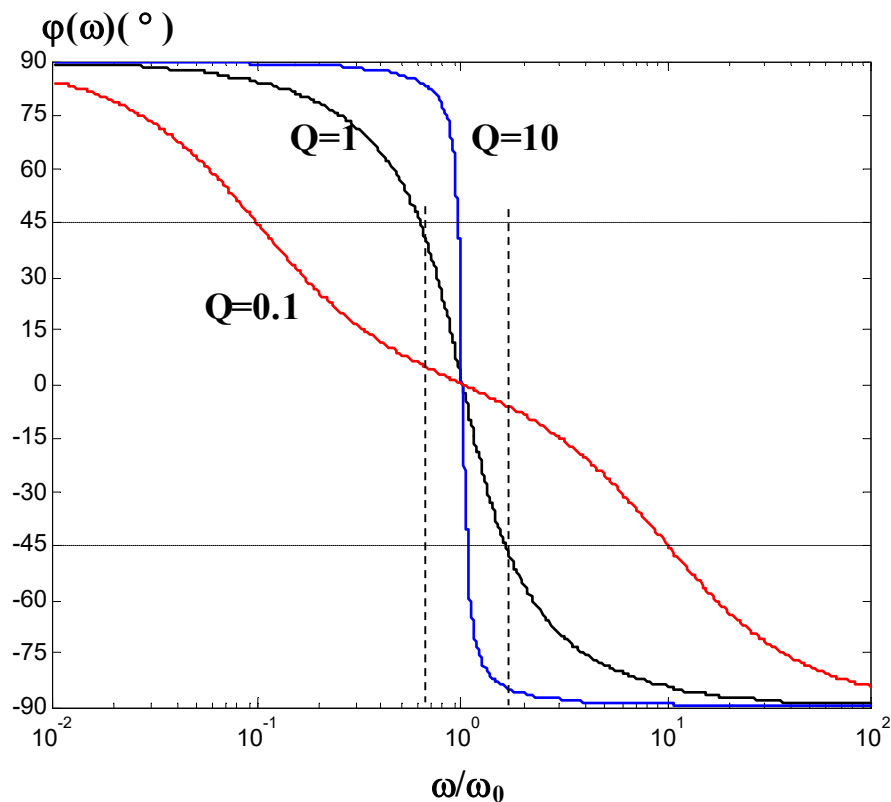
$$\text{3dB通频带: } Q \left( \frac{f}{f_0} - \frac{f_0}{f} \right) = \pm 1$$

$$\Rightarrow f_{1,2} = \dots$$

$$\Rightarrow BW_{3dB} = f_2 - f_1 = \frac{f_0}{Q}$$

$$f_0 = \sqrt{f_1 f_2}$$

# 相频特性



$$BW_{3dB} \cdot \tau_{g0} = \frac{f_0}{Q} \cdot \frac{2Q}{2\pi f_0} = \frac{1}{\pi} = 0.32$$

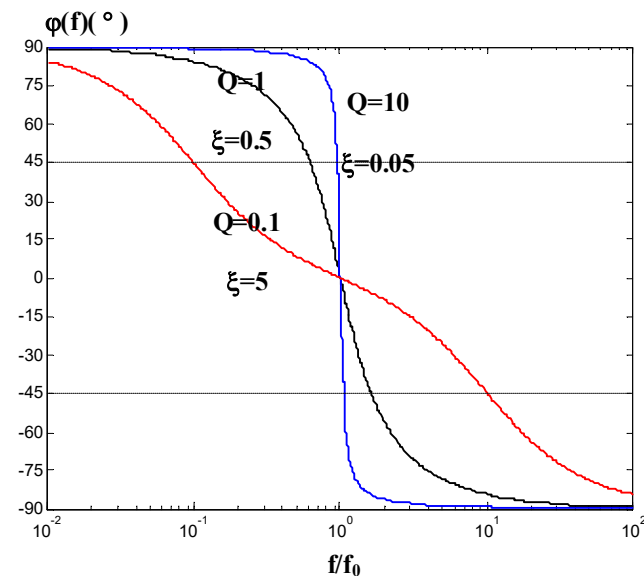
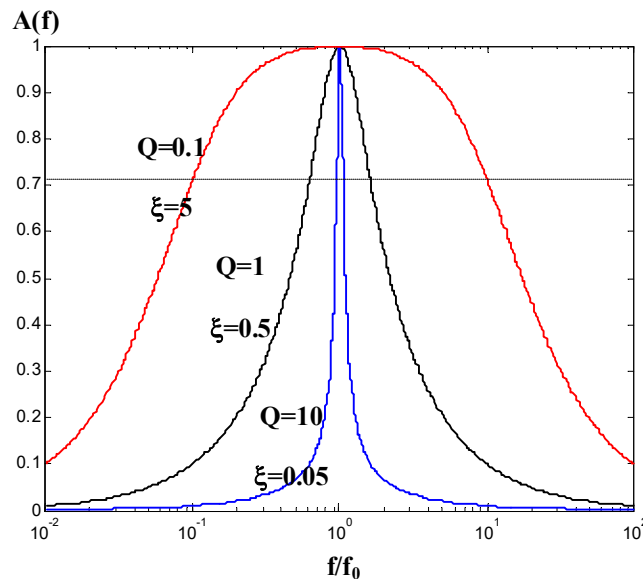
带宽越窄，信号延时越大：带通、低通均成立的结论

$$\varphi(\omega) = -\arctan Q \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right)$$

$$\tau_{g0} = - \left. \frac{d\varphi_i}{d\omega} \right|_{\omega=\omega_0} = \frac{2Q}{\omega_0}$$

$$\begin{aligned} \varphi(\omega) &\approx -Q \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) \\ &= -Q \left( \frac{(\omega - \omega_0)(\omega + \omega_0)}{\omega_0 \omega} \right) \\ &\approx -2Q \frac{(\omega - \omega_0)}{\omega_0} = -(\omega - \omega_0) \tau_{g0} \end{aligned}$$

# 谐振频点的疑问？



$$H(j\omega) = \frac{\dot{V}_R}{\dot{V}_S} = A(\omega)e^{j\varphi(\omega)}$$

$$v_S(t) = V_{Sm} \cos \omega t$$

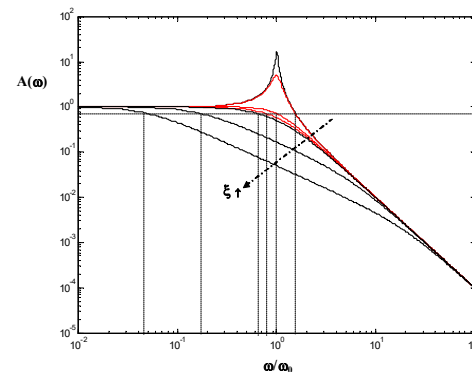
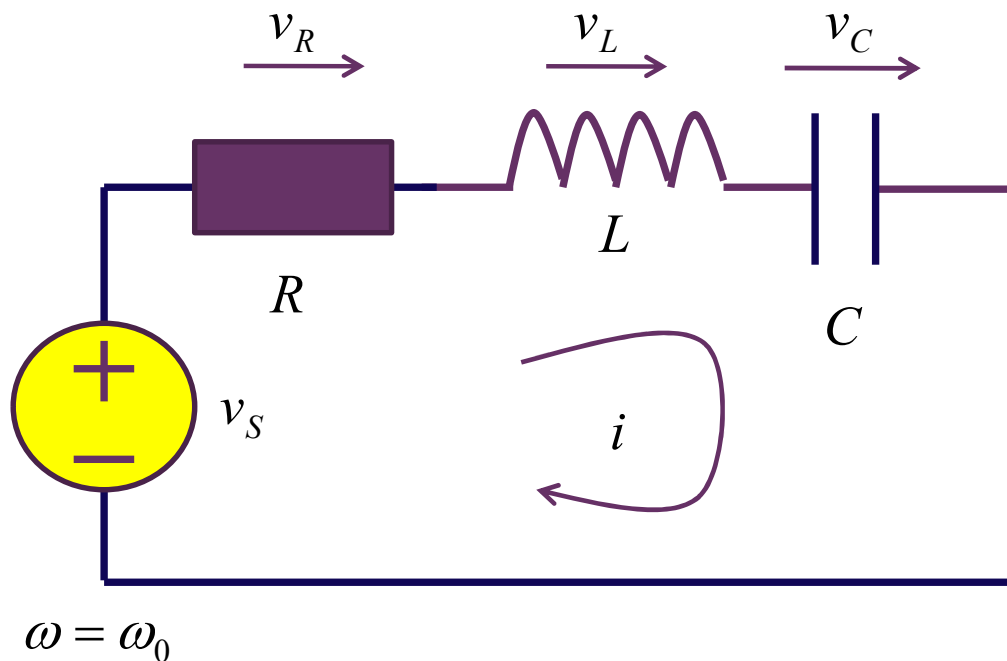
$$V_{R\infty}(t) = V_{Sm} A(\omega) \cos(\omega t + \varphi(\omega))$$

$$v_S(t) = V_{Sm} \cos \omega_0 t$$

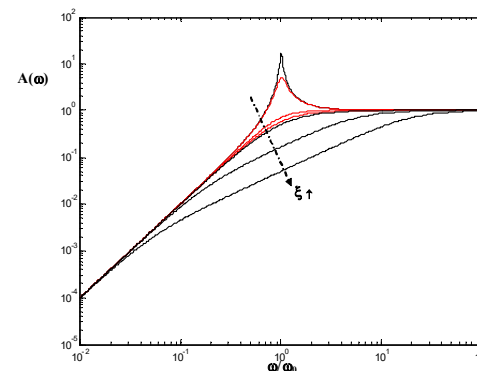
$$v_R(t) = V_{Sm} \cos \omega_0 t$$

显然：在谐振频点位置，电阻获得全部输入电压？？？  
难道电容、电感没有分压？

# 串联谐振为电压谐振



$$A(\omega_0) = \frac{1}{2\xi} = Q$$



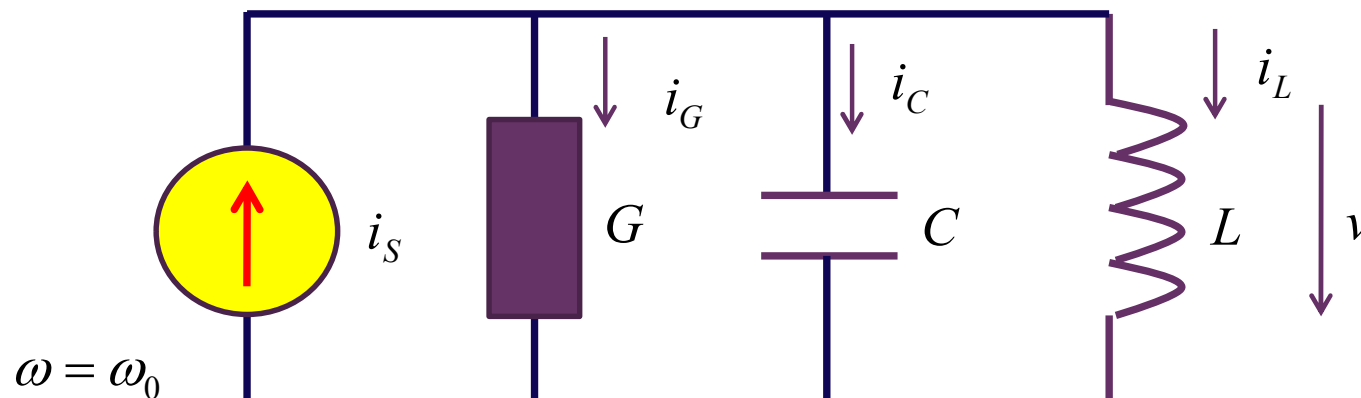
$$\dot{V}_R = \dot{V}_S$$

$$\dot{V}_L = j\omega_0 L \dot{I} = j \frac{\omega_0 L}{R} \dot{V}_S = j \frac{Z_0}{R} \dot{V}_S = jQ \dot{V}_S$$

$$\dot{I} = \frac{\dot{V}_R}{R} = \frac{\dot{V}_S}{R}$$

$$\dot{V}_C = \frac{\dot{I}}{j\omega_0 C} = -j \frac{1}{\omega_0 CR} \dot{V}_S = -j \frac{Z_0}{R} \dot{V}_S = -jQ \dot{V}_S$$

# 并联谐振为电流谐振



$$\begin{aligned} \dot{I}_G &= \dot{I}_S & \dot{I}_C &= j\omega_0 C \dot{V} = j \frac{\omega_0 C}{G} \dot{I}_S = j \frac{Y_0}{G} \dot{I}_S = jQ \dot{I}_S \\ \dot{V} &= \frac{\dot{I}_G}{G} = \frac{\dot{I}_S}{G} & \dot{I}_L &= \frac{\dot{V}}{j\omega_0 L} = -j \frac{1}{\omega_0 L G} \dot{I}_S = -j \frac{Y_0}{G} \dot{I}_S = -jQ \dot{I}_S \end{aligned}$$

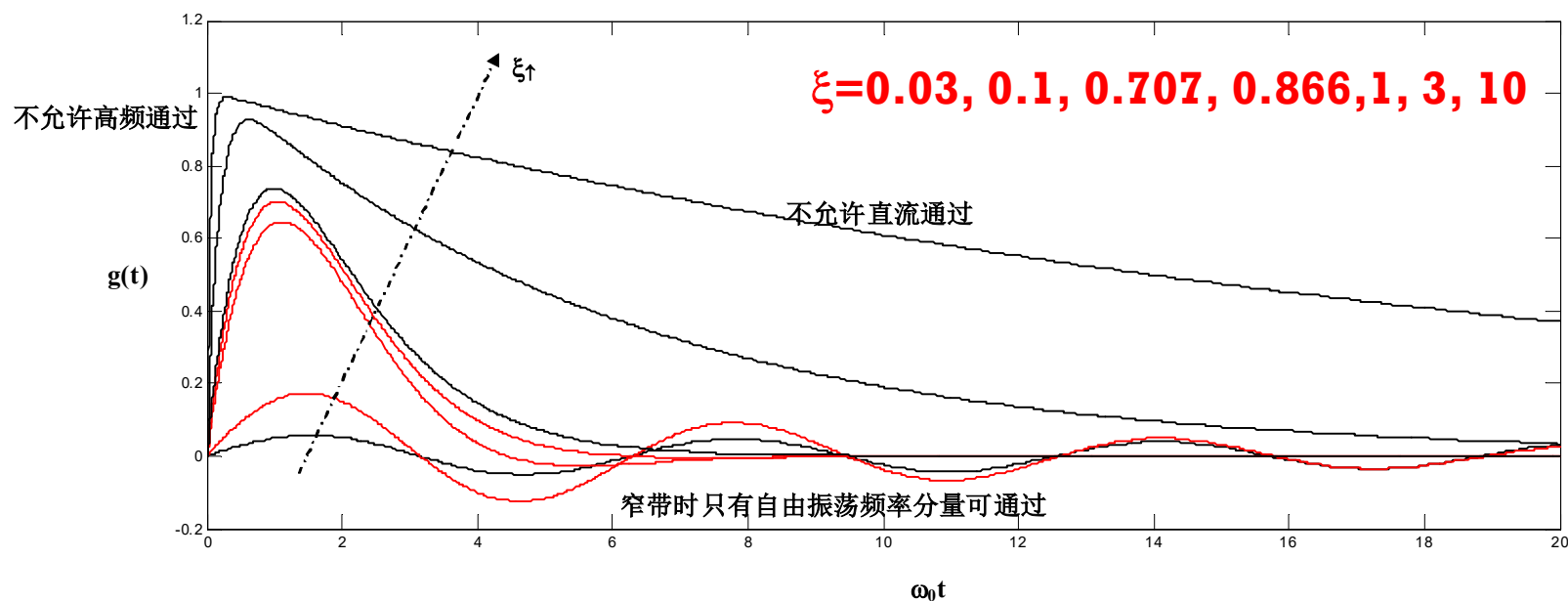


# 冲激响应和阶跃响应

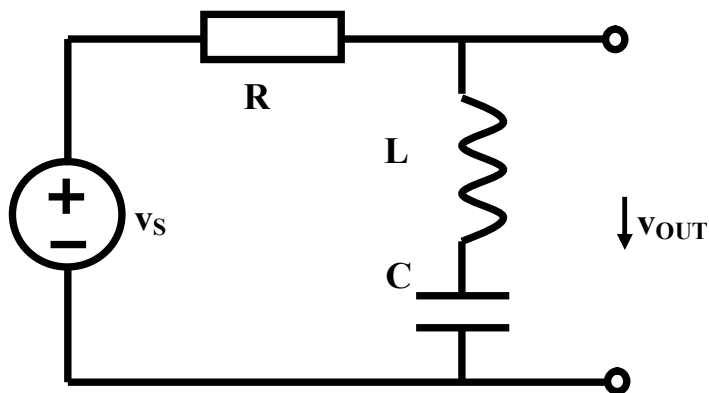
留作作业：用五要素法证明

$$h(t) = 2\xi\omega_0 e^{-\xi\omega_0 t} \left( \cos \sqrt{1-\xi^2} \omega_0 t - \frac{\xi}{\sqrt{1-\xi^2}} \sin \sqrt{1-\xi^2} \omega_0 t \right) \cdot U(t)$$

$$g(t) = \frac{2\xi}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin \sqrt{1-\xi^2} \omega_0 t \cdot U(t)$$



## 二阶带阻：LC分压



直观理解：

低频：电容开路，电感短路，信号全过

高频：电容短路，电感开路，信号全过

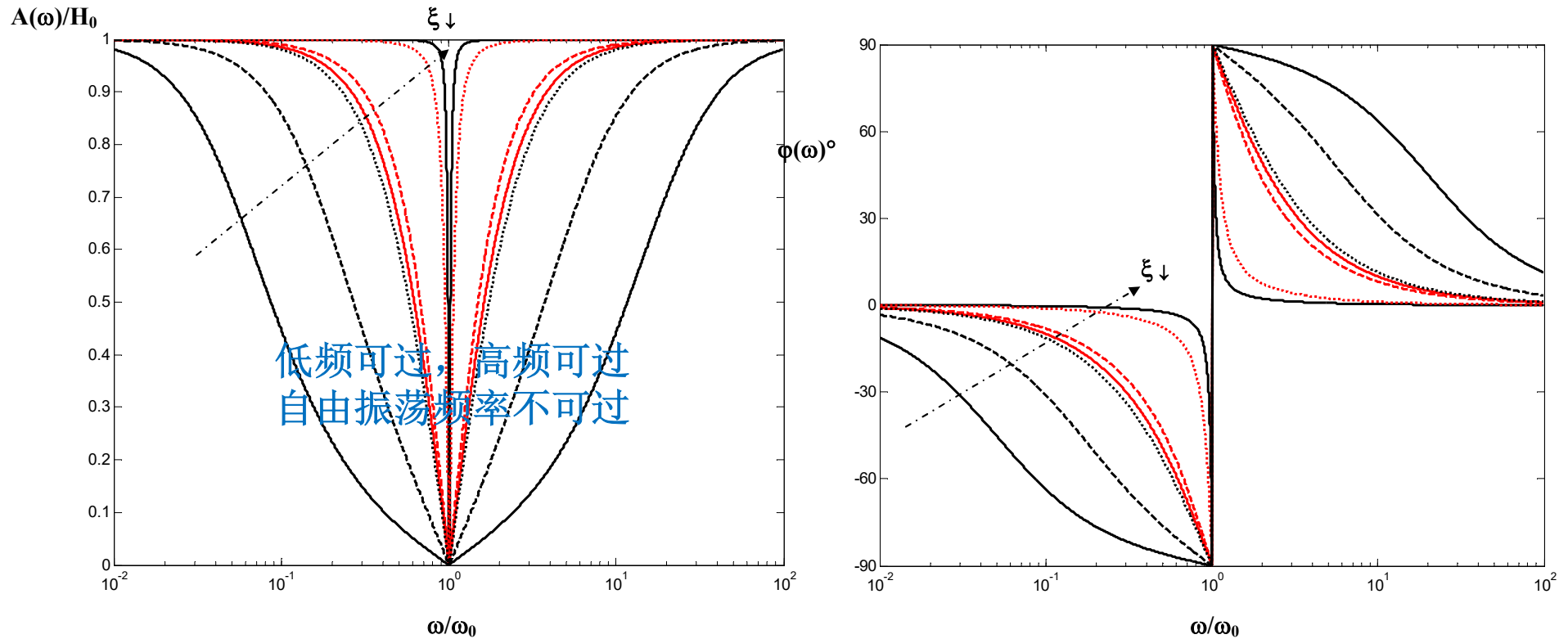
自由振荡频点：电容电抗和电感电抗抵消，犹如短路，输出为**0**，信号通不过

$$H(j\omega) = \frac{\dot{V}_L + \dot{V}_C}{\dot{V}_S} = H_0 \frac{s^2 + \omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} \Big|_{s=j\omega}$$

二阶带阻滤波器传函的一般形式

$$A(\omega) = H_0 \frac{|\omega_0^2 - \omega^2|}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\xi\omega_0\omega)^2}} \quad \varphi(\omega) = \begin{cases} -\arctan \frac{2\xi\omega_0\omega}{\omega_0^2 - \omega^2} & \omega < \omega_0 \\ \pi - \arctan \frac{2\xi\omega_0\omega}{\omega_0^2 - \omega^2} & \omega > \omega_0 \end{cases}$$

# 幅频特性、相频特性



在谐振频点，信号通不过，传函为**0**，该位置出现相位**180°**跳变

只有传函为**0**的点允许相位出现**180°**跳变，其他位置相位均连续

# 时域特性：冲激响应

## 电容电压

$$h_{LP}(t) = \frac{\omega_0}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin(\sqrt{1-\xi^2}\omega_0 t) \cdot U(t)$$

## 电感电压

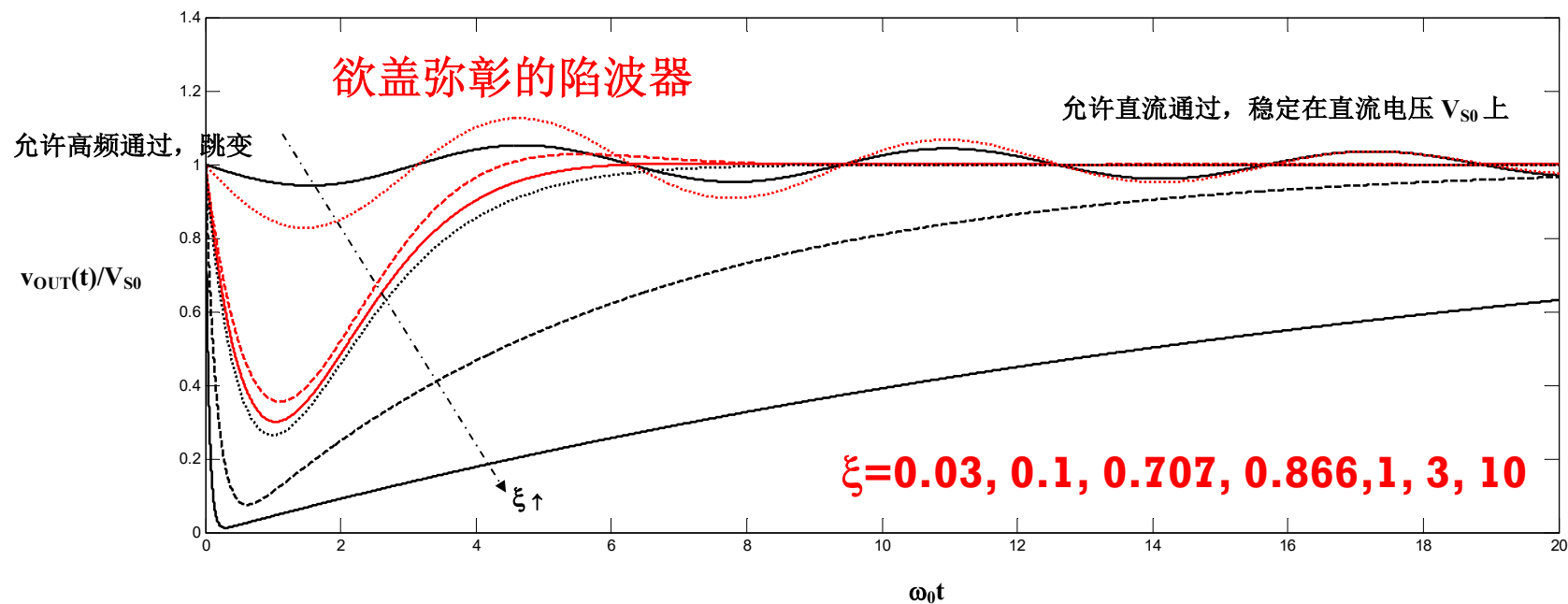
$$h_{HP}(t) = \delta(t) + \omega_0 e^{-\xi\omega_0 t} \left[ -2\xi \cos \sqrt{1-\xi^2} \omega_0 t + \frac{2\xi^2 - 1}{\sqrt{1-\xi^2}} \sin(\sqrt{1-\xi^2}\omega_0 t) \right] \cdot U(t)$$

## 电感电压+电容电压

$$\begin{aligned} h_{BS}(t) &= \delta(t) - 2\xi\omega_0 e^{-\xi\omega_0 t} \left[ \cos \sqrt{1-\xi^2} \omega_0 t - \frac{\xi}{\sqrt{1-\xi^2}} \sin(\sqrt{1-\xi^2}\omega_0 t) \right] \cdot U(t) \\ &= \delta(t) - h_{BP}(t) \end{aligned}$$

# 阶跃响应波形

$$g_{BS,2}(t) = U(t) - \frac{2\xi}{\sqrt{1-\xi^2}} e^{-\xi\omega_0 t} \sin \sqrt{1-\xi^2} \omega_0 t \cdot U(t)$$



以单频正弦波为输入， $\omega_0$  频率分量无法通过

# 本节内容小结

- RLC串联谐振电路，电容分压具有典型的二阶低通特性，电感分压具有典型的二阶高通特性，电阻分压具有典型的二阶带通特性，LC总分压具有典型的二阶带阻特性
- 当阻尼系数 $\xi \in [0.707, 1]$ 时，二阶低通系统具有接近理想低通系统的系统特性
  - 频域看：幅频特性足够平坦，群延时特性足够平坦
  - 时域看：具有最快的响应速度，最快进入稳态
- 过阻尼系数很大时，串联RLC电路行为犹如一阶RC电路行为
  - 过阻尼系数很大时，并联RLC电路行为犹如一阶RL电路行为
- 欠阻尼系数很小时，振铃十分严重，需要 $1.5Q$ 个振铃周期后，振铃才会消失
  - 幅度指数衰减为初始值的1%以内

# 伯特图画法小结

- 1) 记 $j\omega$ 为 $s$ ，以 $s$ 为自变量，重新表述传递函数为实系数有理多项式

$$H(s) = A_0 \frac{s^m + \beta_{m-1}s^{m-1} + \dots + \beta_0}{s^n + \alpha_{n-1}s^{n-1} + \dots + \alpha_0}$$

- (2) 因式分解

$$H(s) = A_0 \frac{(s + \omega_{z1})(s + \omega_{z2}) \dots (s + \omega_{zm})}{(s + \omega_{p1})(s + \omega_{p2}) \dots (s + \omega_{pn})}$$

这里假设只有实根  
共轭复根暂不考虑

# 极点和零点

$$H(s) = A_0 \frac{(s + \omega_{z1})(s + \omega_{z2}) \dots (s + \omega_{zm})}{(s + \omega_{p1})(s + \omega_{p2}) \dots (s + \omega_{pn})}$$

- 传递函数分母多项式的根称为极点，分子多项式的根称为零点
  - 稳定系统（滤波器，放大器，…）的极点（特征根）一定位于左半平面
  - 零点可正可负，可左可右

$$s_p = -\omega_{p1}, -\omega_{p2}, \dots, -\omega_{pn} < 0$$

出现右半平面极点  
（特征根），系统则  
不稳定，或者趋于无  
穷（进入非线性饱和  
区），或者自激振荡  
（变成振荡器）

不稳定系统没有传递  
函数，也没有波特图

$$s_z = -\omega_{z1}, -\omega_{z2}, \dots, -\omega_{zm}$$



# 波特图画法规则

$$H(s) = A_0 \frac{(s + \omega_{z1})(s + \omega_{z2}) \dots (s + \omega_{zm})}{(s + \omega_{p1})(s + \omega_{p2}) \dots (s + \omega_{pn})}$$

- 零极点按大小排序，其数值和频率比，随着频率的上升，...

## ■ 幅频特性

- 碰到极点-20，碰到零点+20；

- 每个极点都将导致20dB/10倍频程的幅频特性的下降，每个零点都将导致20dB/10倍频程的幅频特性的上升

$$\begin{aligned} H(s) &= H_0 \frac{\left(1 + \frac{s}{\omega_{z1}}\right) \left(1 + \frac{s}{\omega_{z2}}\right) \dots \left(1 + \frac{s}{\omega_{zm}}\right)}{\left(1 + \frac{s}{\omega_{p1}}\right) \left(1 + \frac{s}{\omega_{p2}}\right) \dots \left(1 + \frac{s}{\omega_{pn}}\right)} \end{aligned}$$

$$\stackrel{s=j\omega}{=} H_0 \frac{\left(1 + \frac{j\omega}{\omega_{z1}}\right) \left(1 + \frac{j\omega}{\omega_{z2}}\right) \dots \left(1 + \frac{j\omega}{\omega_{zm}}\right)}{\left(1 + \frac{j\omega}{\omega_{p1}}\right) \left(1 + \frac{j\omega}{\omega_{p2}}\right) \dots \left(1 + \frac{j\omega}{\omega_{pn}}\right)}$$

## ■ 相频特性

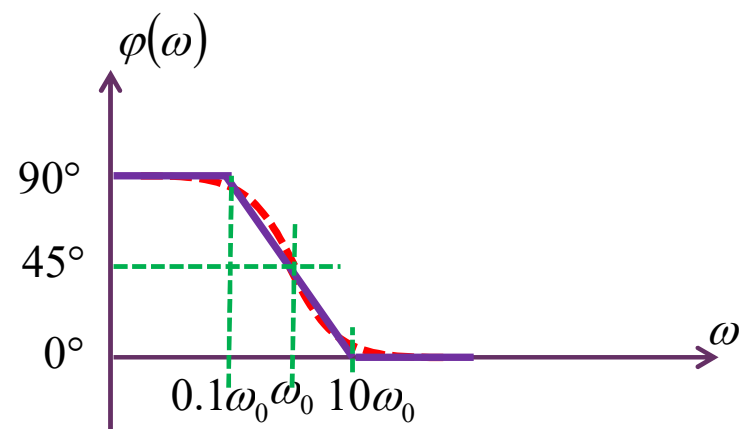
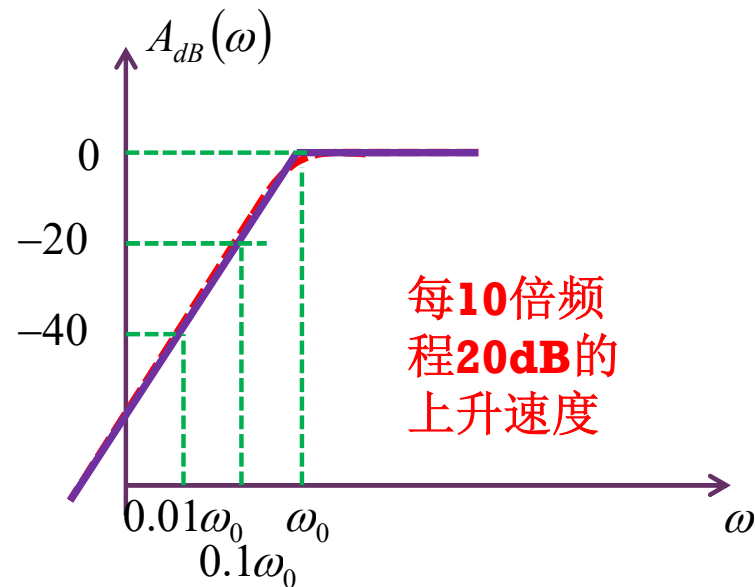
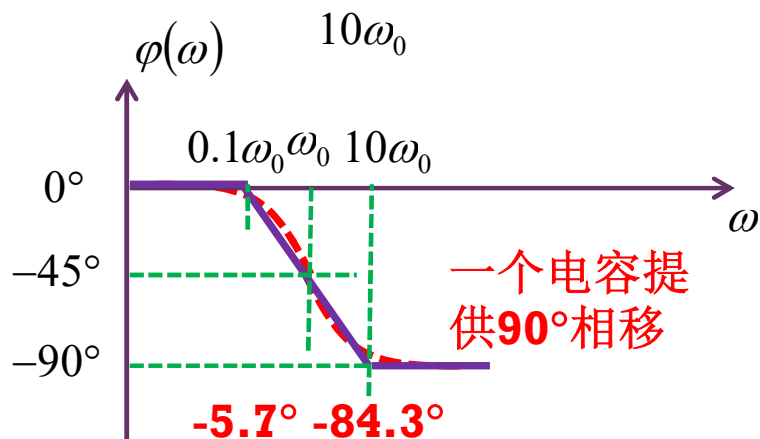
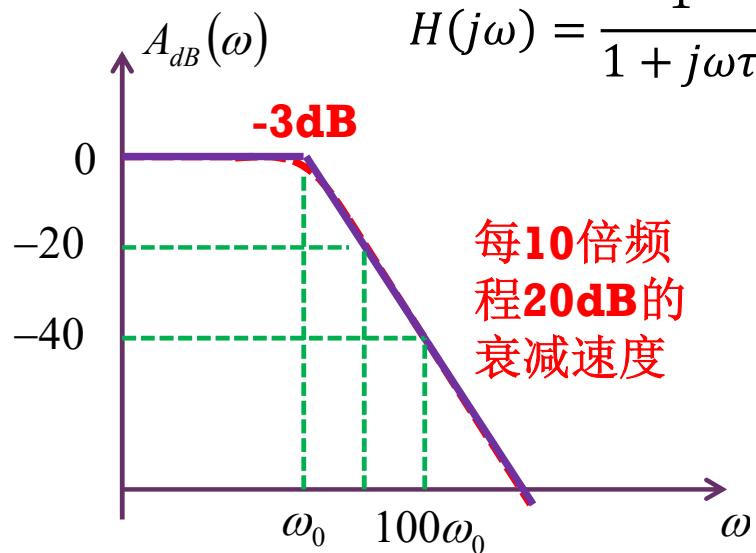
- 极点滞后90°，零点看左右，左超前右滞后90°

- 极点只能是左半平面极点，每个极点将导致一个90°相位滞后；左半平面零点导致一个90°相位超前，右半平面零点导致一个90°相位滞后

# 一阶低通和一阶高通

$$H(j\omega) = \frac{j\omega\tau}{1 + j\omega\tau} = \frac{s}{s + \omega_0}$$

$$H(j\omega) = \frac{1}{1 + j\omega\tau} = \frac{\omega_0}{s + \omega_0}$$



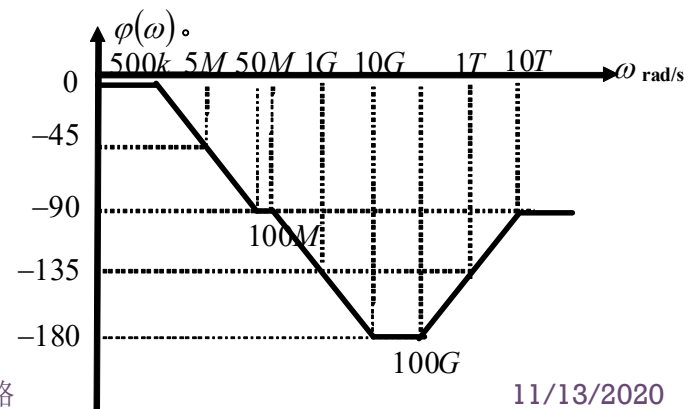
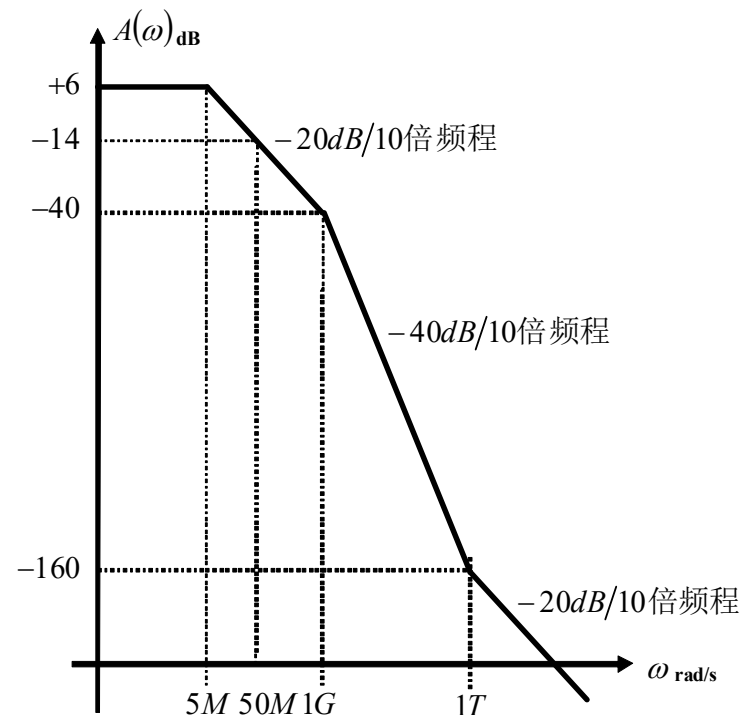
$$H(j\omega) = 10000 \frac{(j\omega + 1 \times 10^{12})}{(j\omega + 5 \times 10^6)(j\omega + 1 \times 10^9)}$$

$$= 2 \frac{\left(1 + \frac{j\omega}{1 \times 10^{12}}\right)}{\left(1 + \frac{j\omega}{5 \times 10^6}\right)\left(1 + \frac{j\omega}{1 \times 10^9}\right)}$$

$$5 \times 10^6$$

$$1 \times 10^9$$

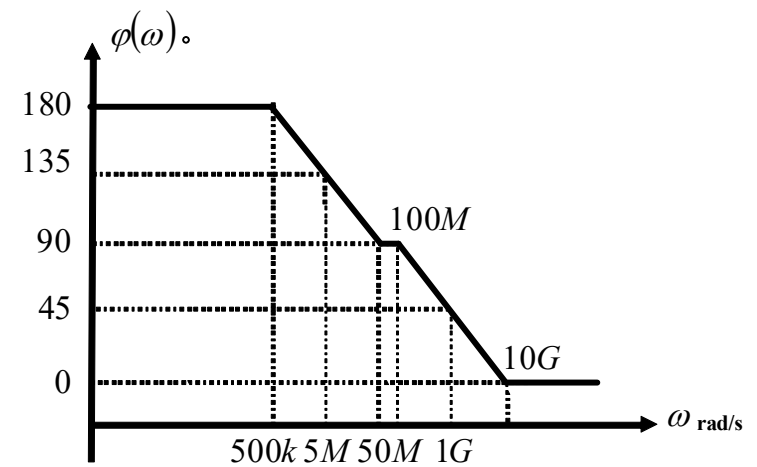
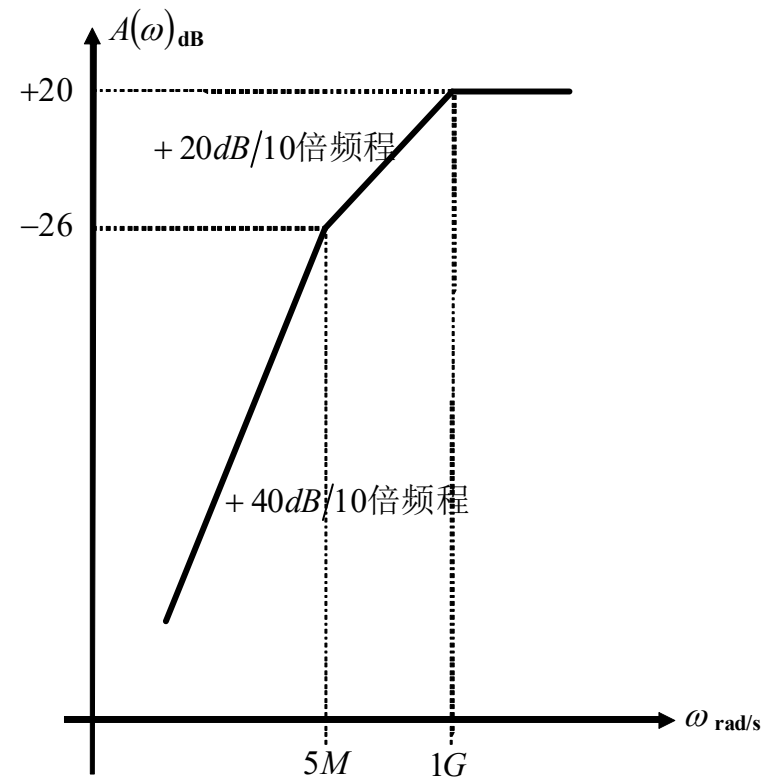
$$1 \times 10^{12}$$



$$H(j\omega) = 10 \frac{(j\omega)^2}{(j\omega + 5 \times 10^6)(j\omega + 1 \times 10^9)}$$

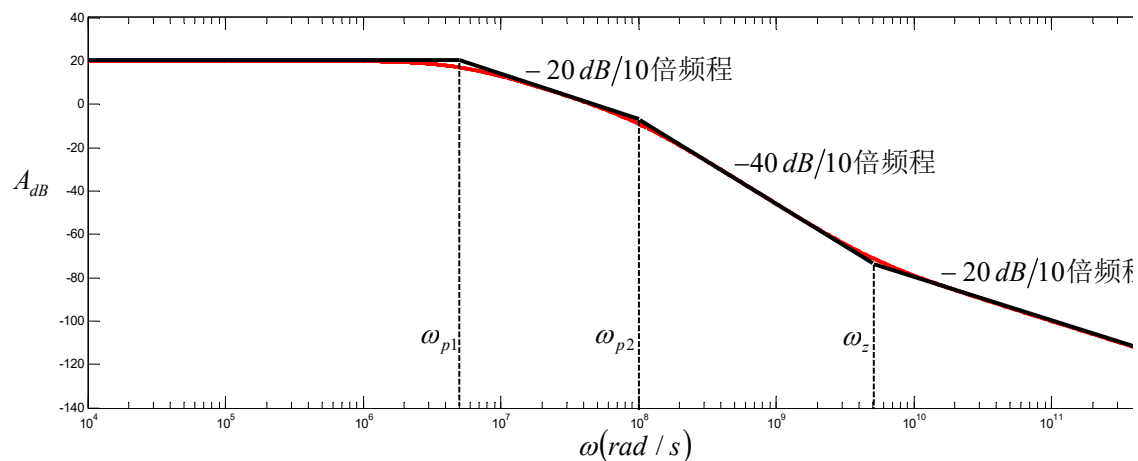
0

0

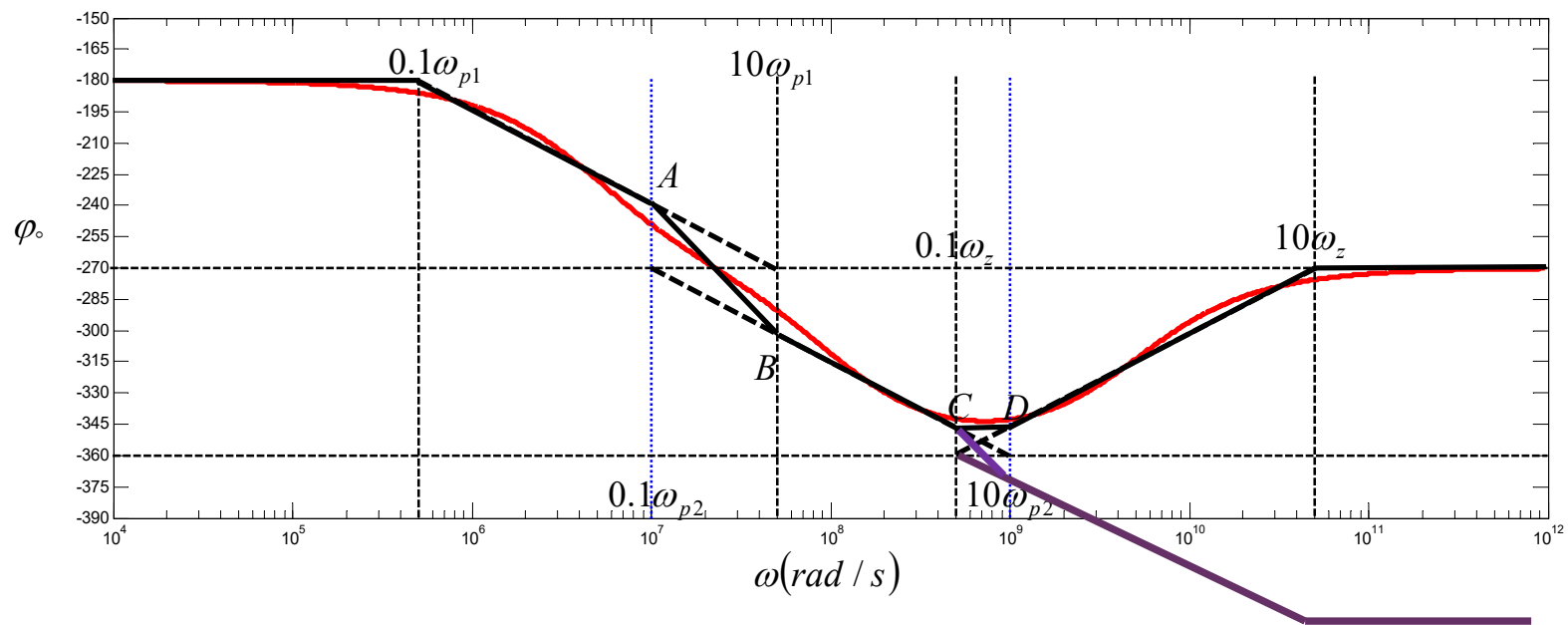
 $5 \times 10^6$  $1 \times 10^9$ 

$$H(j\omega) = -10^6 \frac{j\omega + 5 \times 10^9}{(j\omega + 5 \times 10^6)(j\omega + 1 \times 10^8)}$$

$$= -10 \frac{1 + \frac{j\omega}{5 \times 10^9}}{\left(1 + \frac{j\omega}{5 \times 10^6}\right) \left(1 + \frac{j\omega}{1 \times 10^8}\right)}$$



$$5 \times 10^6 \quad 1 \times 10^8 \quad 5 \times 10^9$$

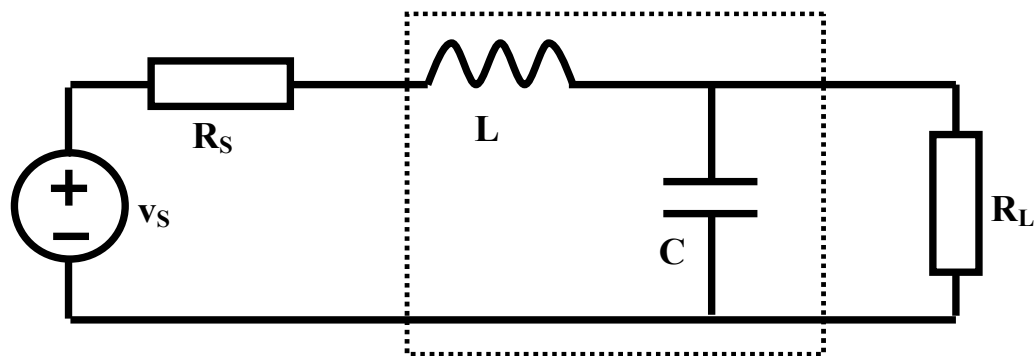


# 作业1 画波特图

- 自学P640-648内容，学会画波特图
  - 波特图：幅频特性和相频特性的分段折线描述
- 练习8.3.20 画出如下传递函数的波特图

$$H(j\omega) = -10 \frac{1 + \frac{j\omega}{5 \times 10^9}}{\left(1 + \frac{j\omega}{5 \times 10^6}\right) \left(1 + \frac{j\omega}{1 \times 10^8}\right) \left(1 + \frac{j\omega}{5 \times 10^{10}}\right)} = A(\omega)e^{j\phi(\omega)}$$

# 作业2 二阶低通滤波器设计



$$\xi = \sqrt{3}/2$$

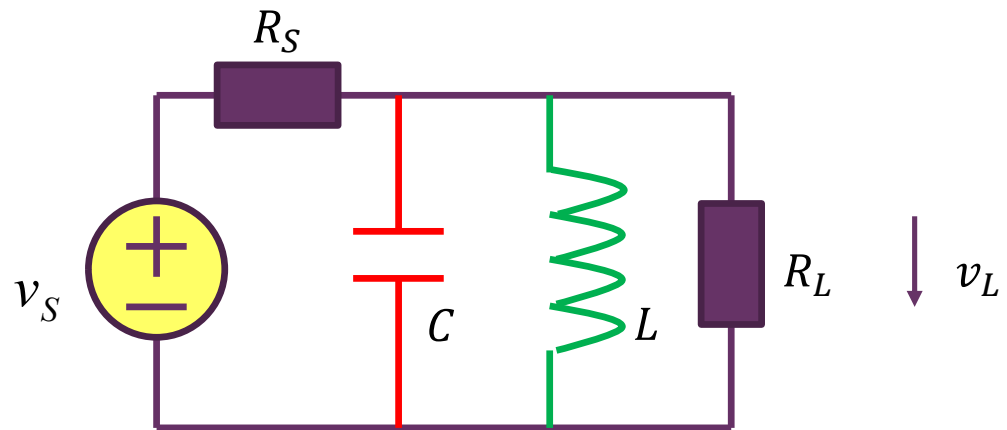
相频特性最接近理想直线，  
相位失真最小

$$\xi = \sqrt{2}/2$$

幅频特性最接近理想平直，  
幅度失真最小

- 如图所示，已知信源内阻为 $50\Omega$ ，负载电阻也是 $50\Omega$ ，请设计一个阻尼系数为 $0.866(= \sqrt{3}/2)$ 的二阶低通LC滤波器，其3dB带宽为1MHz，请给出虚框表示的LC低通滤波器中电感和电容的具体数值（选作：仿真确认带宽设计正确）

# 作业3 带通滤波



## ■ 频域分析

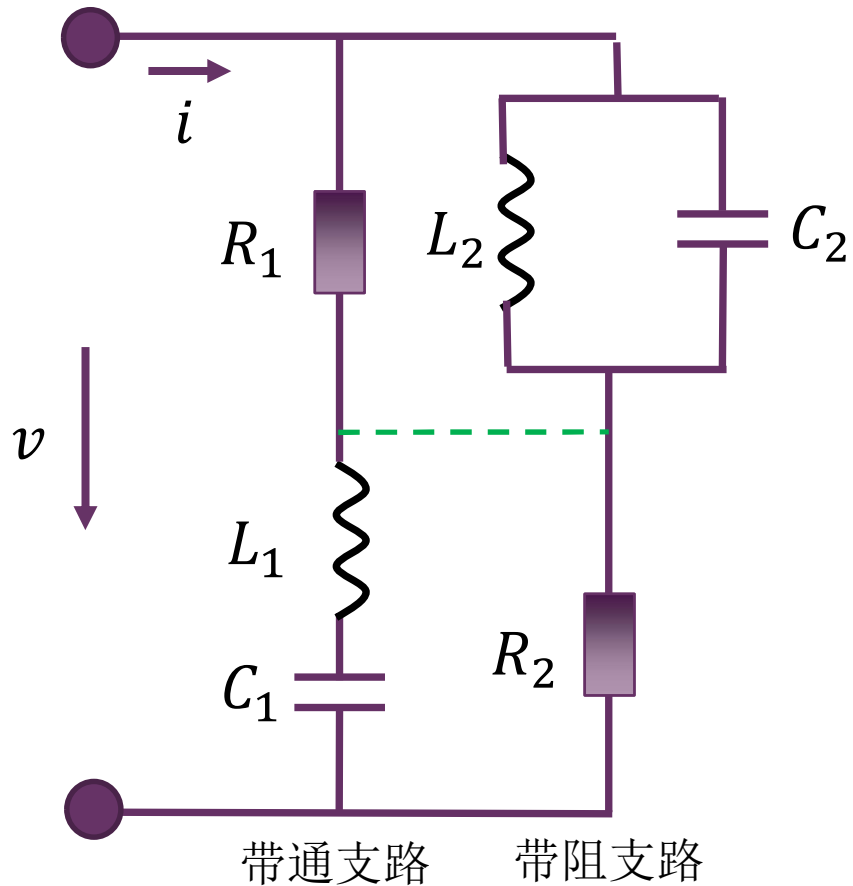
- 给出传递函数表达式
- 说明这是一个典型带通滤波器传递函数，并给出相应的Q值、自由振荡频率 $\omega_0$ ，3dB带宽 $BW_{3dB}$

## ■ 时域分析

- 用五要素法给出该系统的单位冲激响应和单位阶跃响应



# 作业4 带通带阻互补为直通

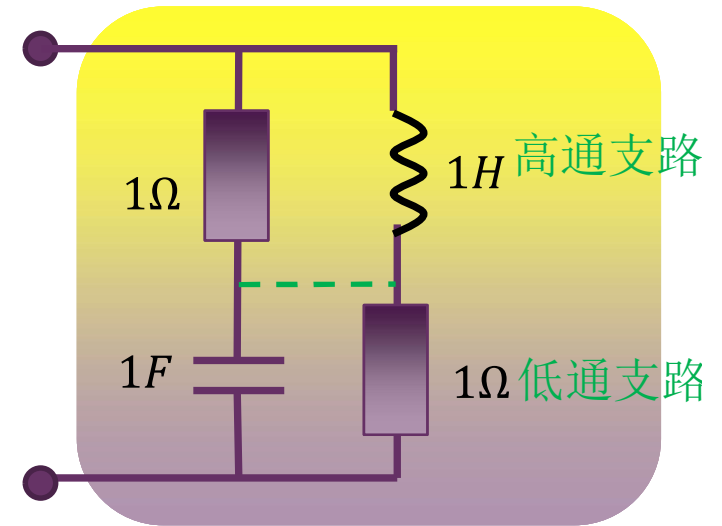


带通支路

带阻支路

$$R \frac{2\xi\omega_0 s}{s^2 + 2\xi\omega_0 s + \omega_0^2} + R \frac{s^2 + \omega_0^2}{s^2 + 2\xi\omega_0 s + \omega_0^2} = R$$

二阶带通和二阶带阻互补



高通支路

低通支路

低通+高通=直通

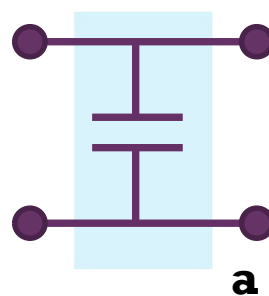
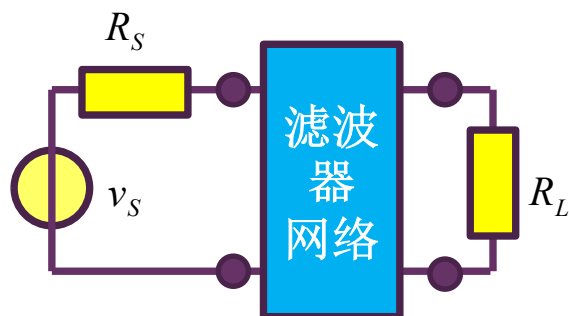
$$R \frac{\omega_0}{s + \omega_0} + R \frac{s}{s + \omega_0} = R$$

一阶低通和一阶高通互补

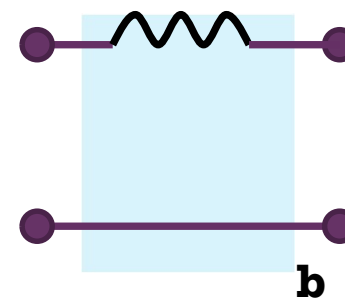
- 求电路中6个元件值满足什么关系时，总端口看入阻抗为纯阻？

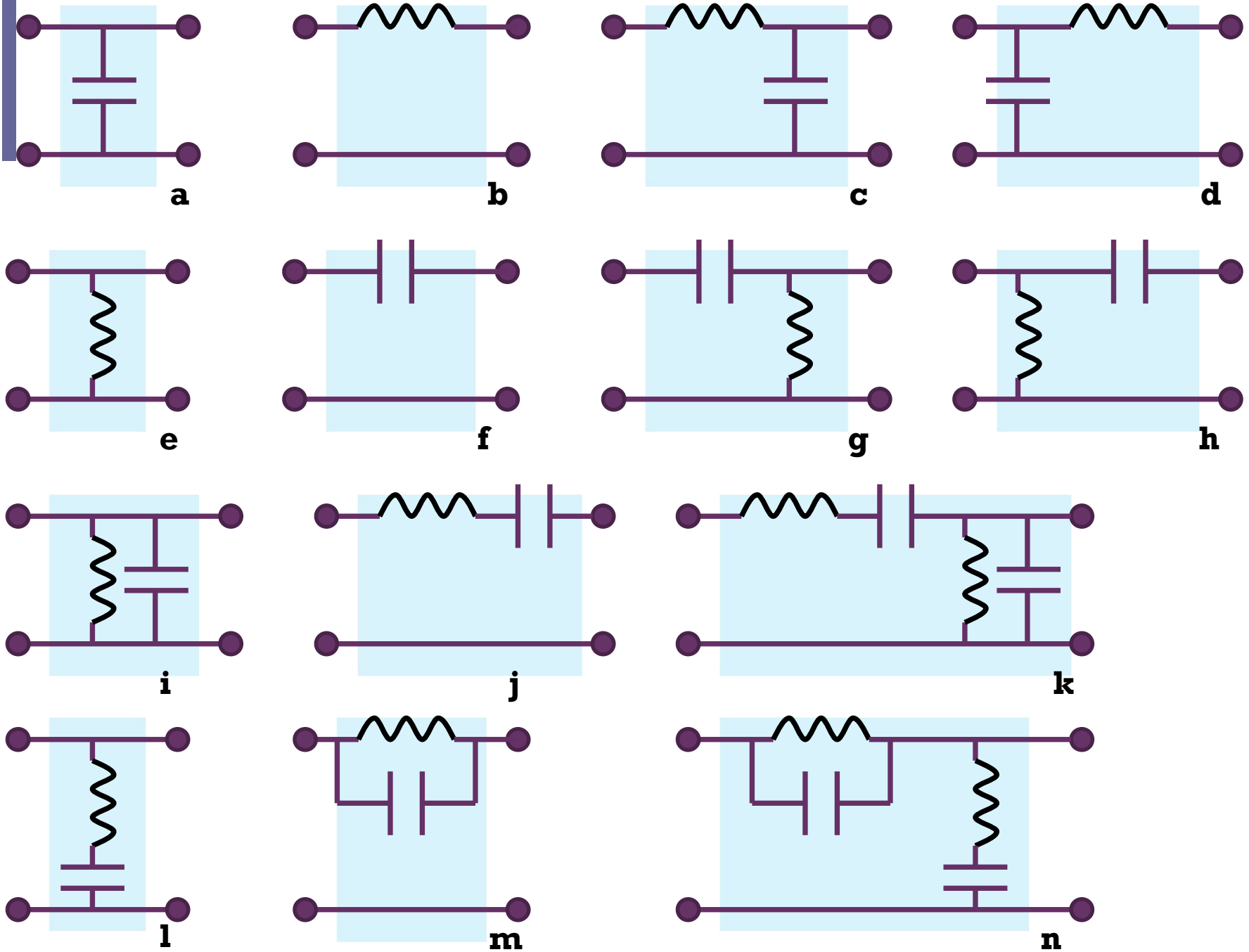
# 作业5 滤波器类型判定

- 电容和电感的记忆能力或者积分效应，导致时域上的延时和频域上的选频特性
- 常见滤波器分类
  - 低通、高通、带通、带阻
  - 请给出正确的滤波器分类



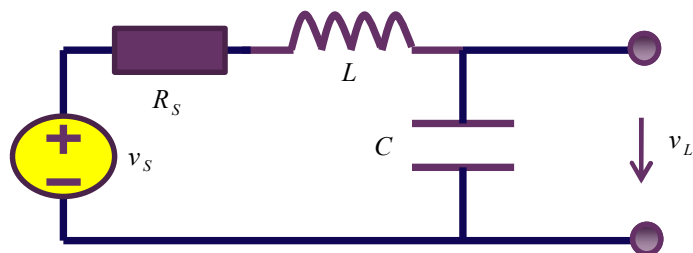
一阶低通





# CAD选作

- 用串联RLC电路，设计 $\xi = 0.1$ ， $0.866$ ， $10$ 三种情况下的低通滤波器，仿真其阶跃响应，说明 $\xi = 0.866$ 的阶跃响应最优



- 提供matlab代码，供同学运行考察不同阻尼系数滤波器的优劣

```
RS=50; %信源内阻为50欧姆
f3dB=1E6; %3dB带宽为1MHz
```

```
kesai=[0.1 sqrt(3)/2 10]; %三种阻尼系数情况
```

```
Dt=1E-9;
```

```
timenum=20000;
```

```
f0=f3dB/5; %方波的基波频率
```

```
w0=2*pi*f0;
```

```
T=1/f0;
```

```
for j=1:timenum
```

```
    t(j)=(j-1000)*Dt;
```

```
    if j<1000
```

```
        vs1(j)=0;
```

```
        vs2(j)=0;
```

```
    else
```

```
        vs1(j)=1; %信号1为阶跃信号
```

```
        vs2(j)=0.5+2/pi*cos(w0*(t(j)-0.3*T))-2/3/pi*cos(3*w0*(t(j)-0.3*T))+2/5/pi*cos(5*w0*(t(j)-0.3*T));
```

%信号2为方波信号取傅立叶展开前4项，设定为数字信号

```
        vs2n(j)=vs2(j)+0.3*sin(50*w0*t(j)+0.5*randn)+0.6*sin(52*w0*t(j)+0.5*randn)+0.3*sin(54*w0*t(j)+0.5*randn)+0.5*randn;
```

```
    end
```

```
end
```

```
figure(1)
```

```
hold on
```

```
plot(t,vs1,'k')
```

```
figure(2)
```

```
hold on
```

```
plot(t,vs2,'k')
```

```
plot(t,vs2n,'b')
```

数字信号+噪声：通带外10倍位置的干扰+随机噪声

```
for k=1:3
```

```
    %串联RLC取值
```

```
    L(k)=RS*sqrt(-2*kesai(k)^2+1+sqrt((1-2*kesai(k)^2)^2+1))/(2*kesai(k)*2*pi*f3dB);
```

```
    C(k)=2*kesai(k)*sqrt(-2*kesai(k)^2+1+sqrt((1-2*kesai(k)^2)^2+1))/(RS*2*pi*f3dB);
```

```
    RCD=Dt/C(k);
```

```
    GLD=Dt/L(k);
```

```
    A=[1 -RCD; GLD 1+GLD*RS];
```

```
    invA=inv(A);
```

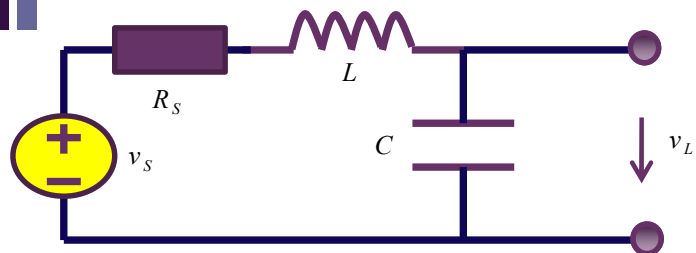
根据**3dB**带宽、阻尼系数、  
信源内阻计算电容、电感

$$L = \frac{R_S \sqrt{-2\xi^2 + 1 + \sqrt{(-2\xi^2 + 1)^2 + 1}}}{2\xi\omega_{3dB}}$$

$$C = \frac{2\xi \sqrt{-2\xi^2 + 1 + \sqrt{(-2\xi^2 + 1)^2 + 1}}}{R_S\omega_{3dB}}$$

$$\begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} = \begin{bmatrix} 1 & -R_{C\Delta} \\ G_{L\Delta} & 1 + G_{L\Delta}R_S \end{bmatrix}^{-1} \left( \begin{bmatrix} v_C(t_k) \\ i_L(t_k) \end{bmatrix} + \begin{bmatrix} 0 \\ G_{L\Delta} \end{bmatrix} v_s(t_{k+1}) \right)$$

# 时域特性数值仿真



$$v_s = v_R + v_L + v_C = i_L R_S + L \frac{di_L}{dt} + v_C$$

$$i_L = i_C = C \frac{dv_C}{dt}$$

$$\frac{dv_C}{dt} = \frac{1}{C} i_L$$

$$\frac{di_L}{dt} = \frac{1}{L} v_s - \frac{1}{L} v_C - \frac{R_S}{L} i_L$$

$$\frac{d}{dt} \begin{bmatrix} v_C(t) \\ i_L(t) \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{C} \\ -\frac{1}{L} & -\frac{R_S}{L} \end{bmatrix} \begin{bmatrix} v_C(t) \\ i_L(t) \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{L} \end{bmatrix} v_s(t)$$

状态方程

$$\frac{d}{dt} \mathbf{x}(t) = \mathbf{f}(\mathbf{x}(t), t)$$

$$\begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} - \begin{bmatrix} v_C(t_k) \\ i_L(t_k) \end{bmatrix} \approx \left( \begin{bmatrix} 0 & \frac{1}{C} \\ -\frac{1}{L} & -\frac{R_S}{L} \end{bmatrix} \begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{L} \end{bmatrix} v_s(t_{k+1}) \right) \Delta t$$

$$\begin{aligned} & \mathbf{x}(t_{k+1}) - \mathbf{x}(t_k) \\ &= \int_{t_k}^{t_{k+1}} \mathbf{f}(\mathbf{x}(t), t) dt \\ &\approx \mathbf{f}(\mathbf{x}(t_{k+1}), t_{k+1}) \Delta t \end{aligned}$$

$(t_k, t_{k+1})$  区间内积分

积分面积用时间离散化后的矩形面积替代

矩形高度取  $\mathbf{k}+1$  时刻，为后向欧拉法，收敛算法  
取  $\mathbf{k}$  时刻则为前向欧拉法，迭代可能不收敛

$$\begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} - \begin{bmatrix} v_C(t_k) \\ i_L(t_k) \end{bmatrix} \approx \begin{bmatrix} 0 & \frac{\Delta t}{C} \\ -\frac{\Delta t}{L} & -\frac{\Delta t R_S}{L} \end{bmatrix} \begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{\Delta t}{L} \end{bmatrix} v_s(t_{k+1})$$

%时域特性1: 阶跃响应

```
vC(1)=0;
```

```
iL(1)=0;
```

```
x=[vC(1);iL(1)];
```

```
for j=2:timenum
```

```
    x=invA*(x+[0; GLD*vs1(j)]);
```

```
    vC(j)=x(1);
```

```
    iL(j)=x(2);
```

```
end
```

```
figure(1)
```

```
hold on
```

```
plot(t,vC)
```

阶跃激励产生的阶跃响应

%时域特性2: 噪声滤波

```
vC(1)=0;
```

```
iL(1)=0;
```

```
x=[vC(1);iL(1)];
```

```
for j=2:timenum
```

```
    x=invA*(x+[0; GLD*vs2n(j)]);
```

```
    vC(j)=x(1);
```

```
    iL(j)=x(2);
```

```
end
```

```
figure(5+k)
```

```
hold on
```

```
plot(t,vs2,'k')
```

```
plot(t,vC,'b')
```

数字信号带噪声，滤波器应当将噪声滤除

$$\begin{bmatrix} v_C(t_{k+1}) \\ i_L(t_{k+1}) \end{bmatrix} = \begin{bmatrix} 1 & -R_{C\Delta} \\ G_{L\Delta} & 1 + G_{L\Delta}R_S \end{bmatrix}^{-1} \left( \begin{bmatrix} v_C(t_k) \\ i_L(t_k) \end{bmatrix} + \begin{bmatrix} 0 \\ G_{L\Delta} \end{bmatrix} v_s(t_{k+1}) \right)$$



%频率特性

```

freqstart=f3dB/100;
freqstop=f3dB*10000;
freqnum=10000;
freqstep=10^(log10(freqstop/freqstart)/(freqnum-1));
freq=freqstart/freqstep;
taog(1)=0;
for j=1:freqnum
    freq=freq*freqstep;
    f(j)=freq;
    s=i*2*pi*freq;
    ks=0.5*RS*sqrt(C(k)/L(k));
    w0=1/sqrt(L(k)*C(k));
    H=w0^2/(s^2+2*ks*w0*s+w0^2);
    absH(j)=20*log10(abs(H));
    angH(j)=angle(H)/pi*180;
    if j>1
        taog(j)=-((angH(j)-angH(j-1)))/(f(j)-f(j-1))/360;
    end
end
taog(1)=taog(2);
end

```

figure(3)

hold on

plot(f,absH) %幅频特性

figure(4)

hold on

plot(f,angH) %相频特性

figure(5)

hold on

plot(f,taog) %群延时特性

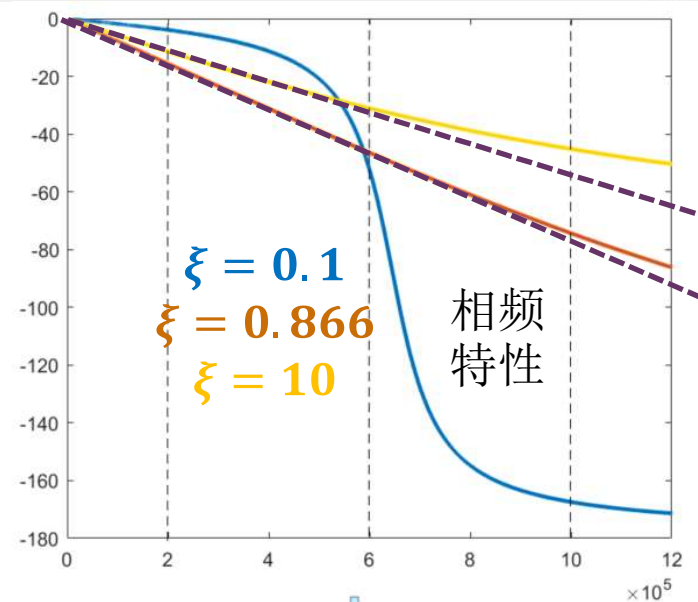
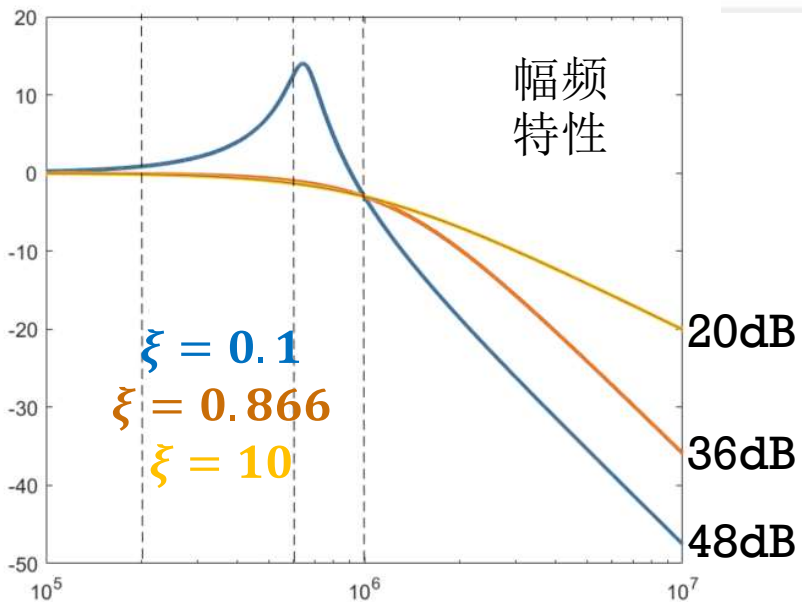
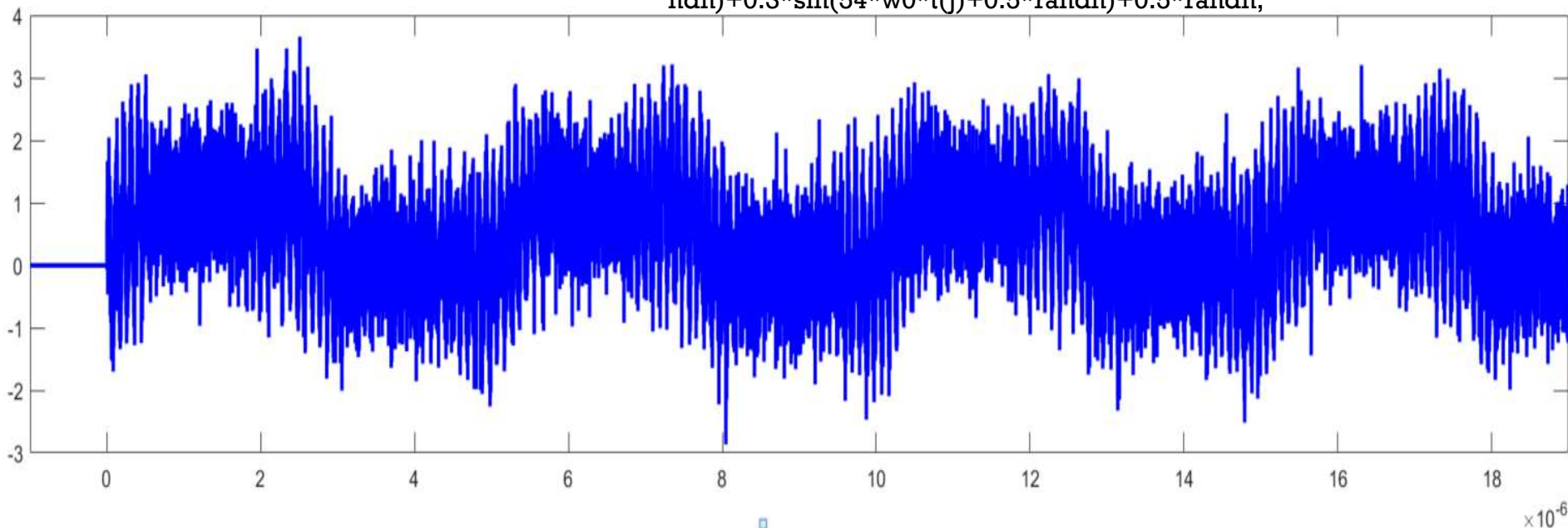
$$H(s) = \frac{\omega_0^2}{s^2 + 2\xi\omega_0s + \omega_0^2}$$

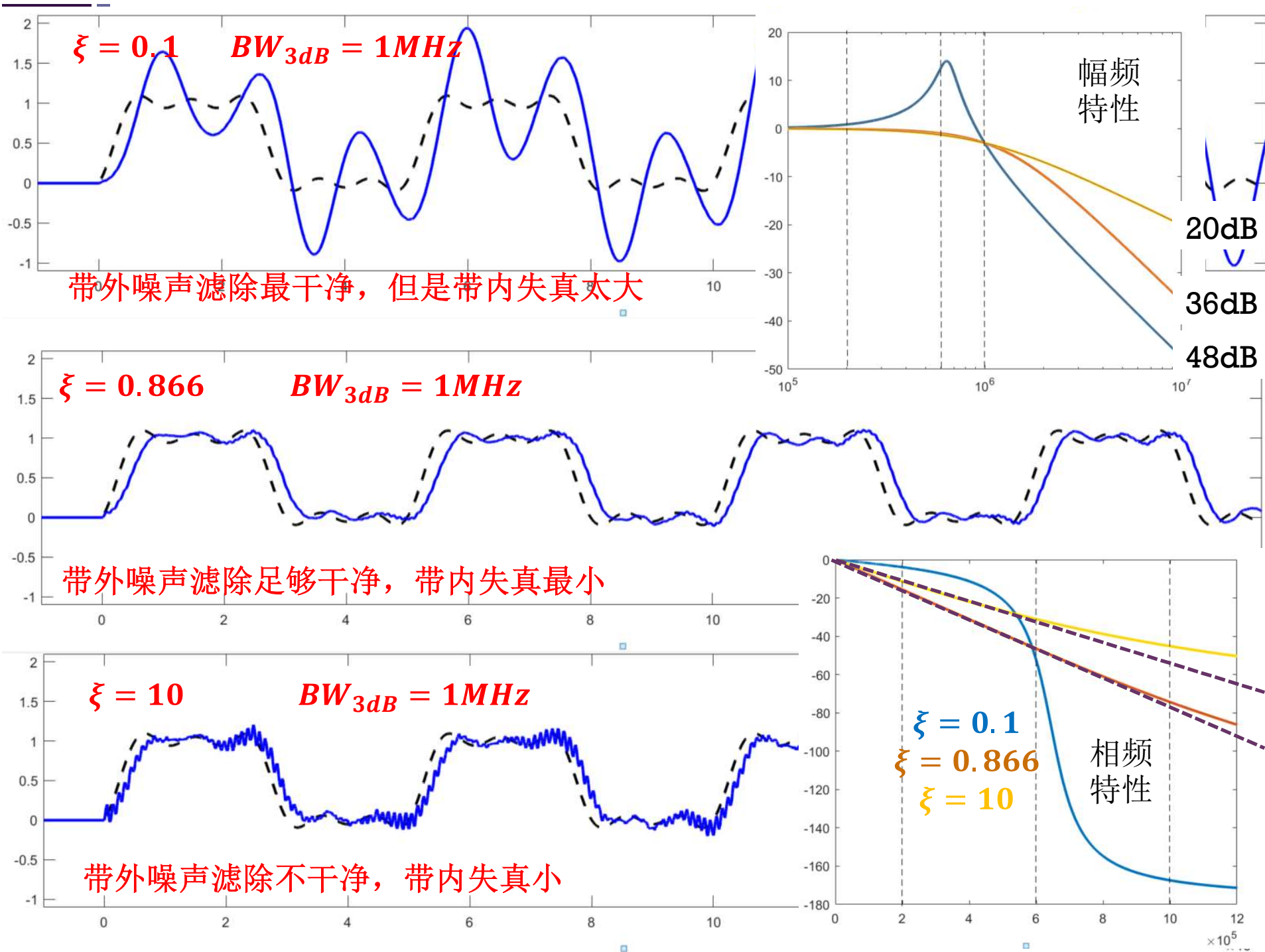
$$\xi = \frac{R_S}{2} \sqrt{\frac{C}{L}} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

# 滤波特性

$$vs2(j) = 0.5 + \frac{2}{\pi} \cos(\omega_0(t(j) - 0.3T)) - \frac{2}{3\pi} \cos(3\omega_0(t(j) - 0.3T)) + \frac{2}{5\pi} \cos(5\omega_0(t(j) - 0.3T));$$

$$vs2n(j) = vs2(j) + 0.3 \sin(50\omega_0 t(j) + 0.5 \text{randn}) + 0.6 \sin(52\omega_0 t(j) + 0.5 \text{randn}) + 0.3 \sin(54\omega_0 t(j) + 0.5 \text{randn}) + 0.5 \text{randn};$$





# 本节课内容在教材中的章节对应

- P780-807: 二阶滤波器