

电子电路与系统基础I

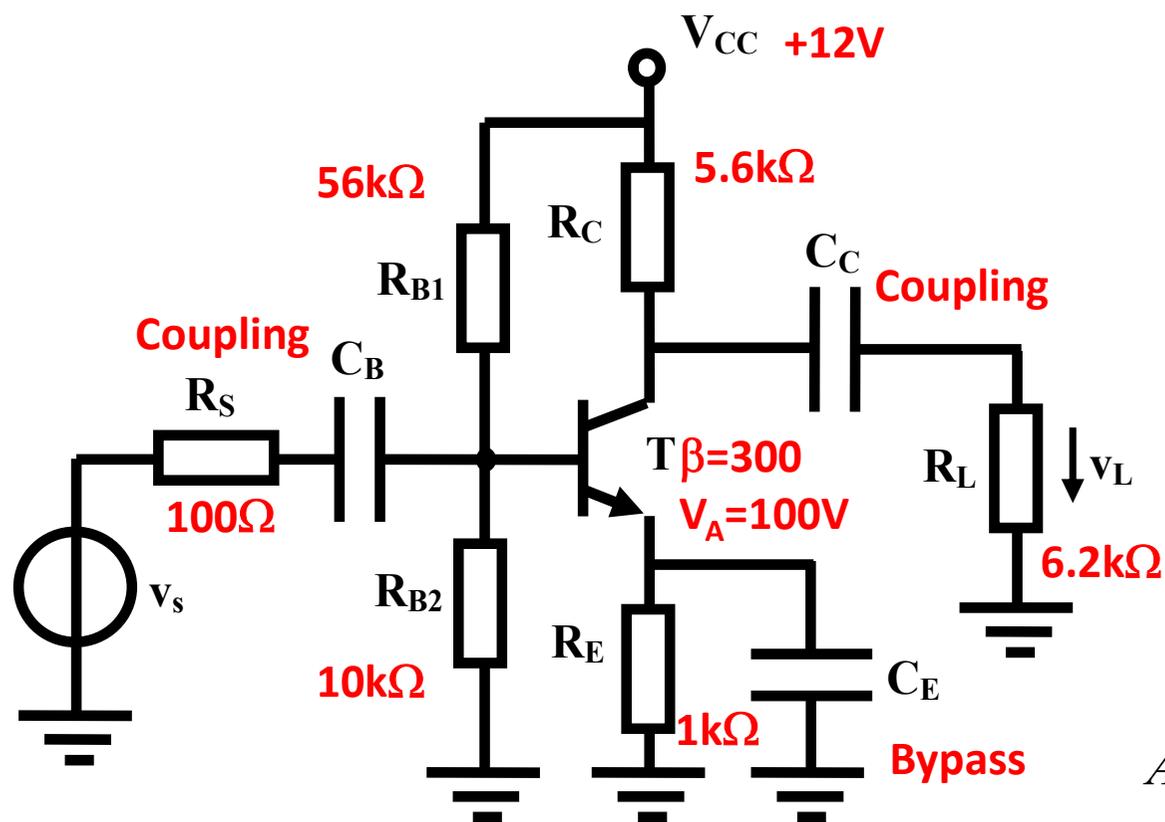
理论课第十二讲 晶体管放大器 负反馈与三种组态

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晶体管放大器 大纲

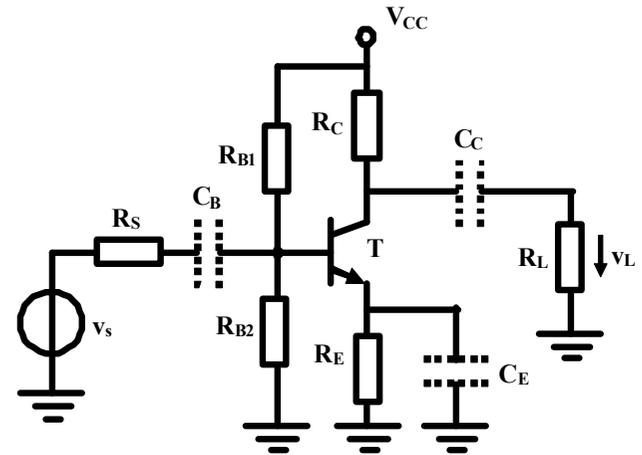
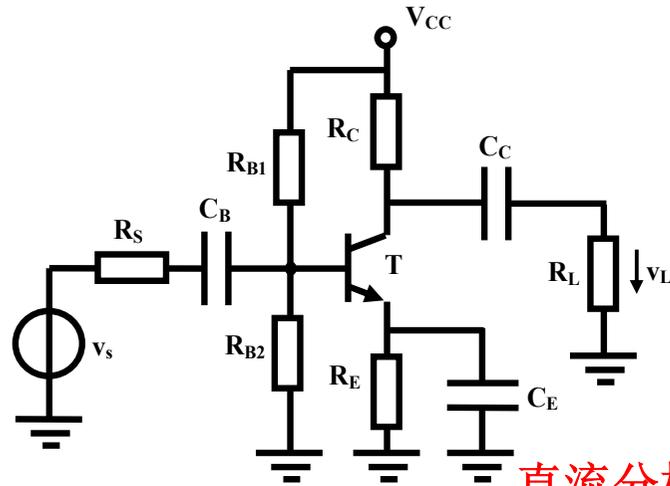
- 负反馈分析
 - **CE**组态放大器分析
 - 负反馈放大器的一般分析方法
 - 深度负反馈的实现
 - 高增益放大器
- 恒流区工作的晶体管的三种组态
 - **CE、CB、CC**组态特性及其简化等效电路
 - **CB**组态：放大器分析例
 - **CC**组态：电压缓冲器例

例3 NPN-BJT-CE放大器 (续)

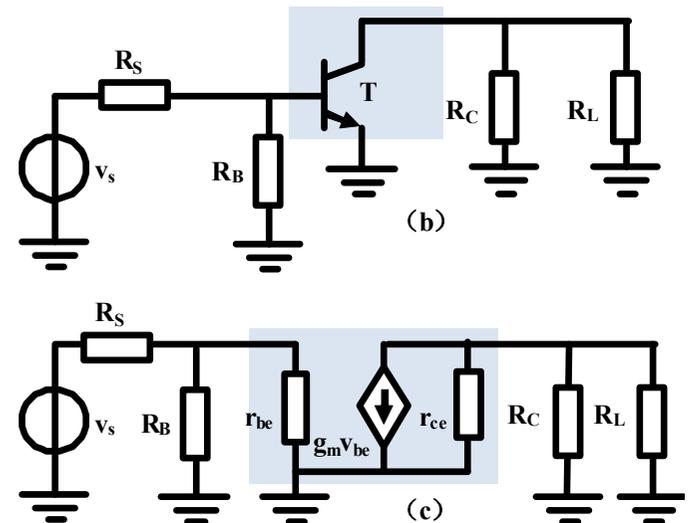
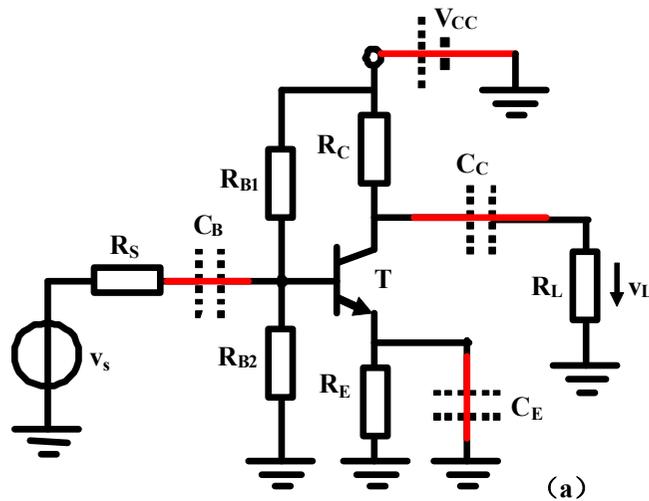


$$A_v = \frac{v_L}{v_s} = ?$$

直流分析和交流分析



直流分析：获得直流工作点
分段折线法

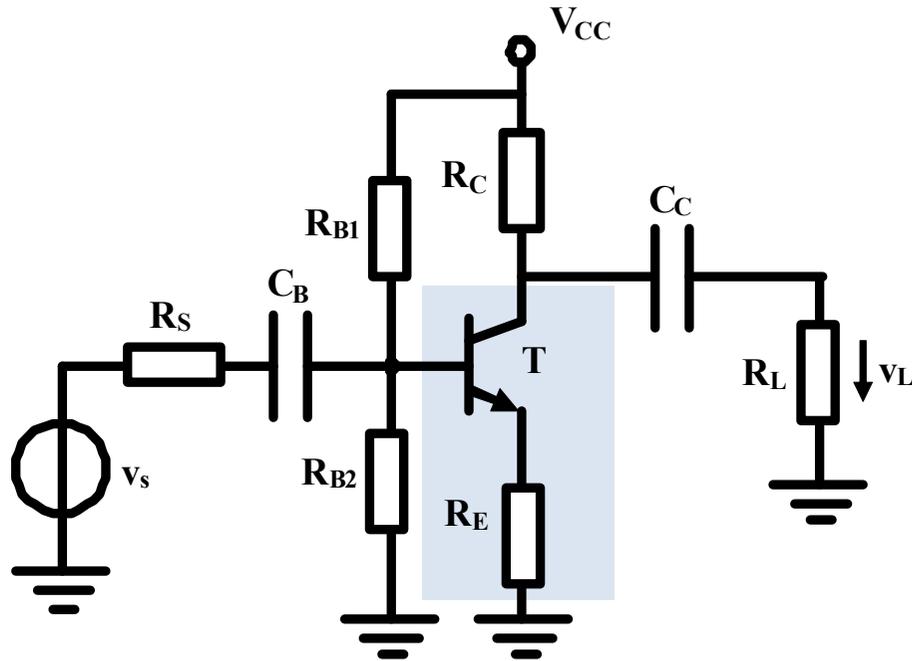


交流小信号分析：获得交流小信号电压放大倍数
局部线性化：线性电路分析

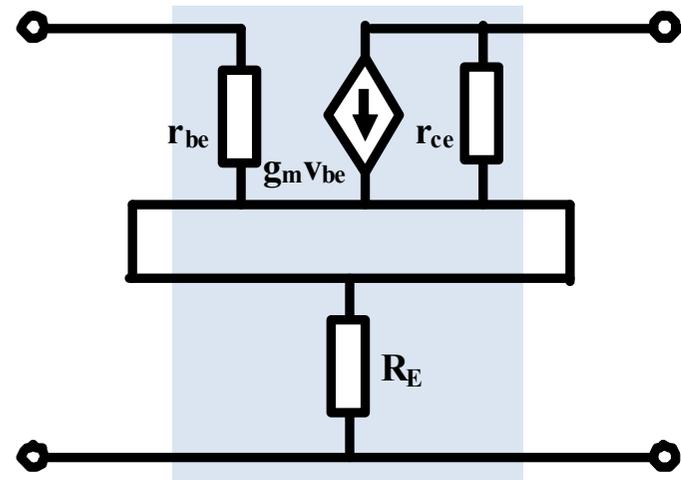
$$A_v = \frac{v_L}{v_S} = -115$$

如果没有旁路电容

发射极不是交流地：存在负反馈



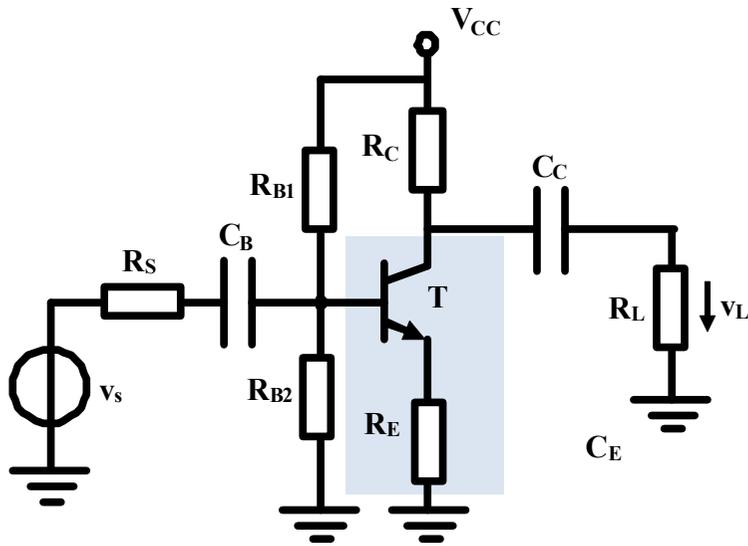
直流分析无影响



交流小信号分析

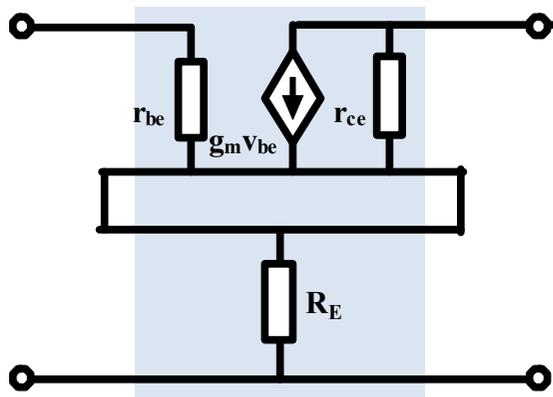
T 和 R_E 构成的二端口网络
是 T 和 R_E 的串串连接关系

串串连接z相加 数学操作



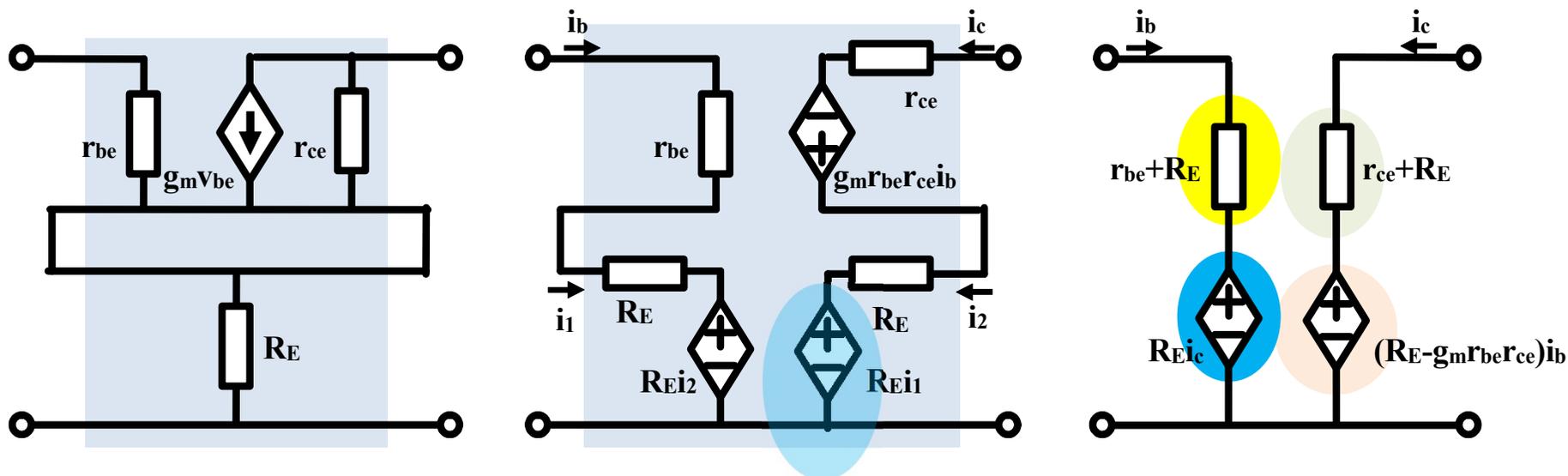
$$\mathbf{z}_T = \mathbf{y}_T^{-1} = \begin{bmatrix} g_{be} & 0 \\ g_m & g_{ce} \end{bmatrix}^{-1} = \begin{bmatrix} r_{be} & 0 \\ -g_m r_{be} r_{ce} & r_{ce} \end{bmatrix}$$

$$\mathbf{z}_E = \begin{bmatrix} R_E & R_E \\ R_E & R_E \end{bmatrix}$$



$$\begin{aligned} \mathbf{z} = \mathbf{z}_T + \mathbf{z}_E &= \begin{bmatrix} r_{be} & 0 \\ -g_m r_{be} r_{ce} & r_{ce} \end{bmatrix} + \begin{bmatrix} R_E & R_E \\ R_E & R_E \end{bmatrix} \\ &= \begin{bmatrix} r_{be} + R_E & R_E \\ -g_m r_{be} r_{ce} + R_E & r_{ce} + R_E \end{bmatrix} \end{aligned}$$

串串连接z相加的电路操作



$$\mathbf{Z} = \mathbf{Z}_T + \mathbf{Z}_E = \begin{bmatrix} r_{be} & 0 \\ -g_m r_{be} r_{ce} & r_{ce} \end{bmatrix} + \begin{bmatrix} R_E & R_E \\ R_E & R_E \end{bmatrix} = \begin{bmatrix} r_{be} + R_E & R_E \\ -g_m r_{be} r_{ce} + R_E & r_{ce} + R_E \end{bmatrix}$$

影响可以忽略不计

开环与闭环

$$\begin{aligned}
 \mathbf{Z} &= \mathbf{Z}_T + \mathbf{Z}_E = \begin{bmatrix} r_{be} + R_E & R_E \\ -g_m r_{be} r_{ce} + R_E & r_{ce} + R_E \end{bmatrix} = \begin{bmatrix} r_{in} & R_F \\ -G_{m0} r_{in} r_{out} & r_{out} \end{bmatrix} \\
 &= \begin{bmatrix} r_{in} & 0 \\ -G_{m0} r_{in} r_{out} & r_{out} \end{bmatrix} + \begin{bmatrix} 0 & R_F \\ 0 & 0 \end{bmatrix} = \mathbf{Z}_{Ao} + \mathbf{Z}_F = \begin{bmatrix} g_{in} & 0 \\ G_{m0} & g_{out} \end{bmatrix}^{-1} + \begin{bmatrix} 0 & R_F \\ 0 & 0 \end{bmatrix}
 \end{aligned}$$

可能需要考虑输入端口负载效应

输入端口负载效应

反馈系数

影响可以忽略不计

输出端口负载效应

一般无需考虑反馈网络的前向作用

可能需要考虑输出端口负载效应

反馈系数由反馈网络提供

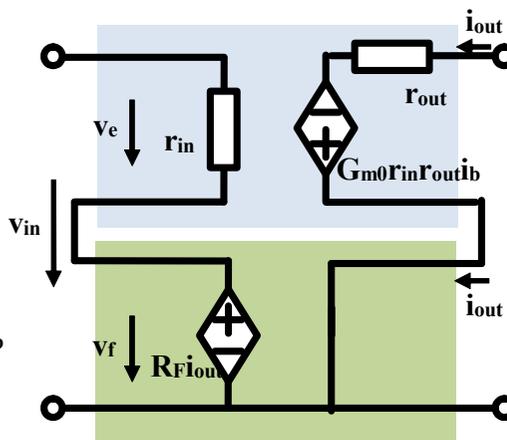
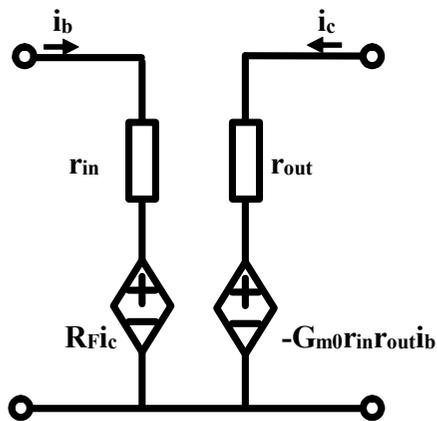
开环放大器
单向网络

理想反馈网络
单向网络

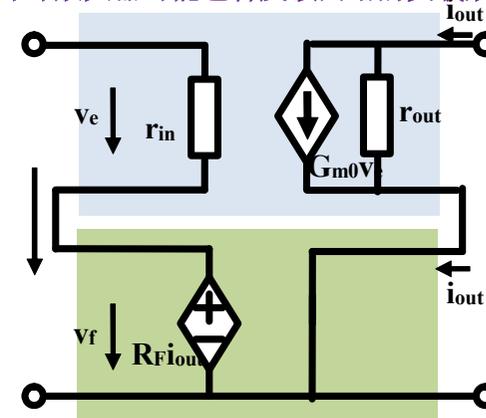
开环跨导放大器

输出对输入的反向作用
即反馈

消除输出对输入的反馈即开环：但反馈网络的阻抗关系仍然保留
称之为反馈网络的负载效应



开环放大器可能包含反馈网络的负载效应



而反馈系数纯由反馈网络提供

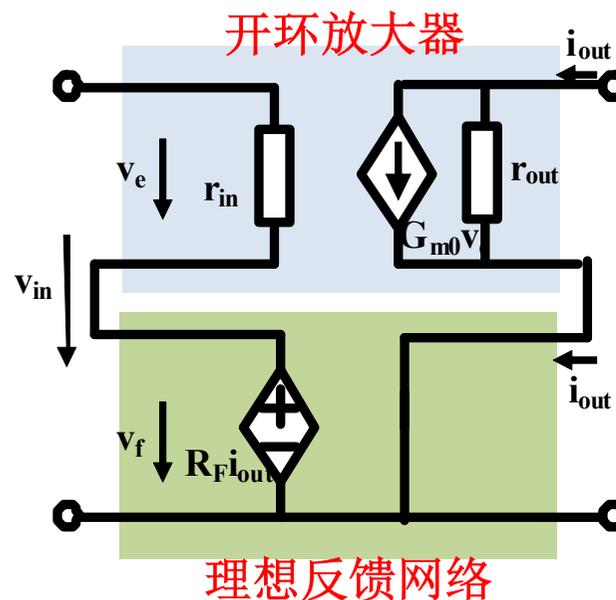
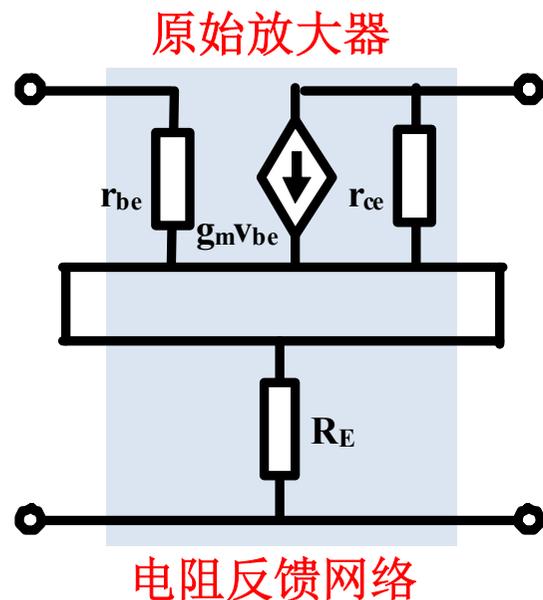
串串负反馈连接

检测输出电流，形成反馈电压

压控流源最适宜

$$\mathbf{Z} = \mathbf{Z}_T + \mathbf{Z}_E = \mathbf{Z}_{A0} + \mathbf{Z}_F$$

$$\mathbf{y} = \mathbf{z}^{-1}$$



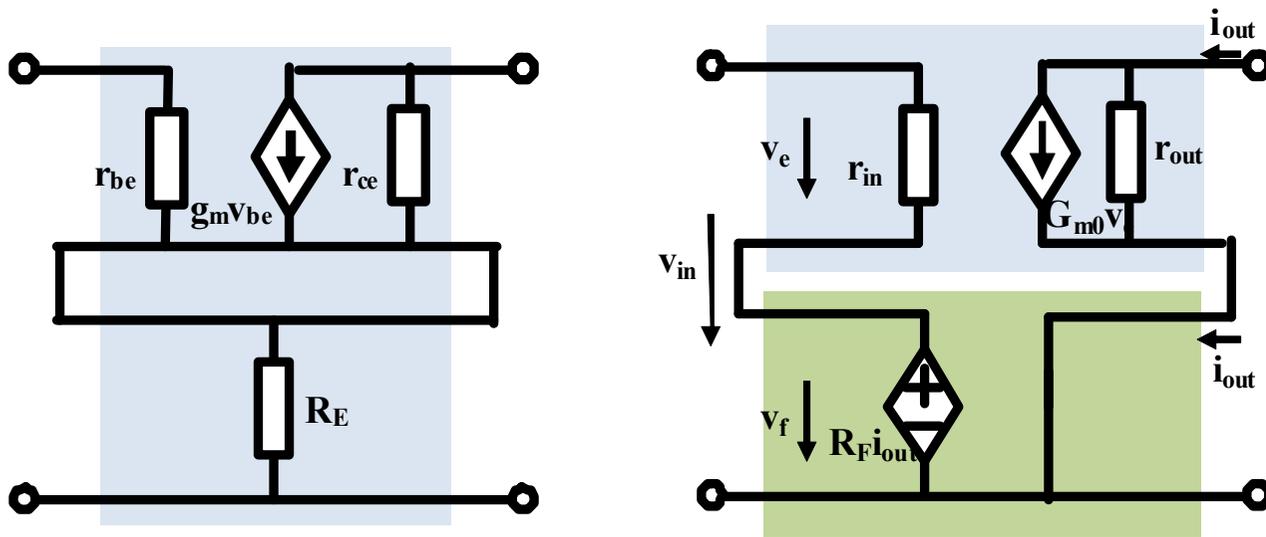
$$r_{in} = r_{be} + R_E \quad \text{负载效应}$$

$$r_{out} = r_{ce} + R_E \quad \text{负载效应}$$

$$G_{m0} = \frac{g_m r_{be} r_{ce} - R_E}{r_{in} r_{out}}$$

$$R_F = R_E$$

检测输出电流，形成反馈电压



$$r_{in} = r_{be} + R_E$$

$$r_{out} = r_{ce} + R_E$$

$$G_{m0} = \frac{g_m r_{be} r_{ce} - R_E}{r_{in} r_{out}}$$

$$R_F = R_E$$

压控流源 \mathbf{y} 最适

$$\mathbf{z} = \mathbf{z}_{A0} + \mathbf{z}_F = \begin{bmatrix} r_{in} & R_F \\ -G_{m0} r_{in} r_{out} & r_{out} \end{bmatrix}$$

$$\mathbf{y} = \mathbf{z}^{-1} = \frac{1}{1 + G_{m0} R_F} \begin{bmatrix} \frac{1}{r_{in}} & \frac{-R_F}{r_{in} r_{out}} \\ G_{m0} & \frac{1}{r_{out}} \end{bmatrix}$$

满足单向化条件

$$\approx \frac{1}{1 + G_{m0} R_F} \mathbf{y}_{OpenLoop}$$

$$\mathbf{y}_{OpenLoop} = \mathbf{z}_{OpenLoop}^{-1}$$

$$= \begin{bmatrix} r_{in} & 0 \\ -G_{m0} r_{in} r_{out} & r_{out} \end{bmatrix}^{-1}$$

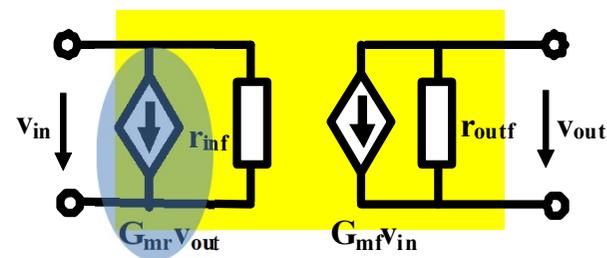
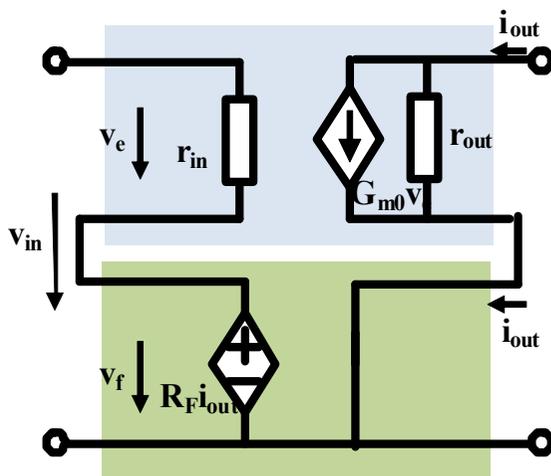
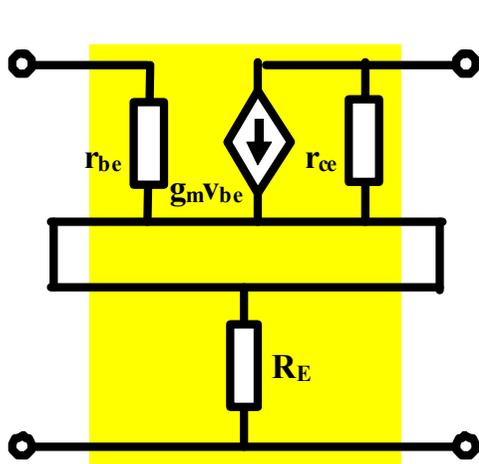
$$= \begin{bmatrix} \frac{1}{r_{in}} & 0 \\ G_{m0} & \frac{1}{r_{out}} \end{bmatrix}$$

这就是为什么分析开环放大器的原因：避免数学过程

闭环放大器

$$\mathbf{z} = \begin{bmatrix} r_{in} & R_F \\ -G_{m0}r_{in}r_{out} & r_{out} \end{bmatrix}$$

$$\mathbf{y} = \mathbf{z}^{-1} = \begin{bmatrix} \frac{1}{r_{inf}} & G_{mr} \\ G_{mf} & \frac{1}{r_{outf}} \end{bmatrix}$$



$$\mathbf{y} = \mathbf{z}^{-1} = \frac{1}{1 + G_{m0}R_F} \begin{bmatrix} \frac{1}{r_{in}} & \frac{-R_F}{r_{in}r_{out}} \\ G_{m0} & \frac{1}{r_{out}} \end{bmatrix}$$

G_{mr} 很小的数值，满足单向化条件则可忽略其影响

$$r_{inf} = r_{in} (1 + G_{m0}R_F)$$

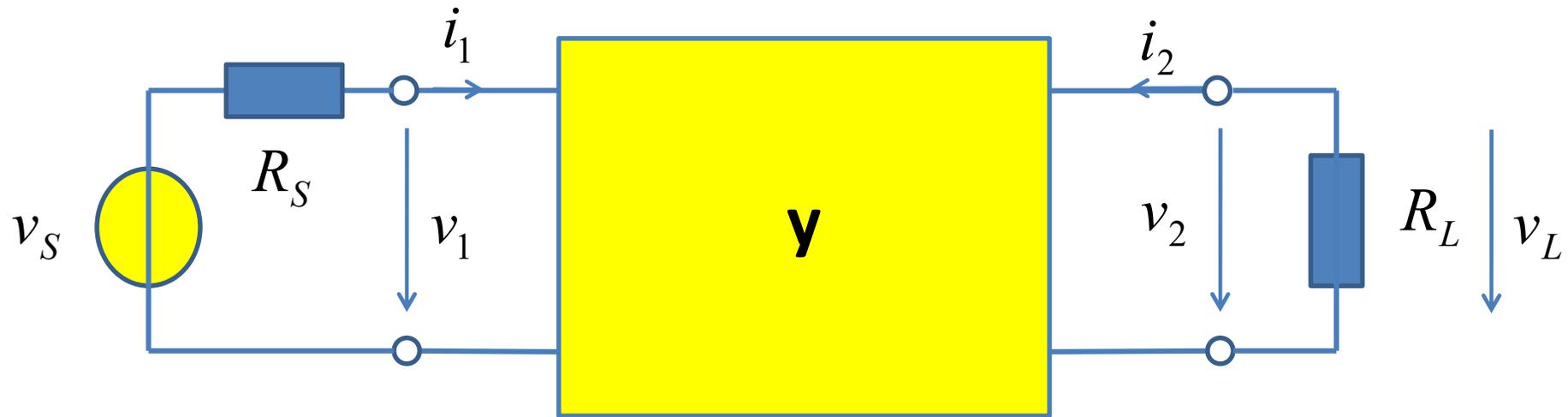
$$r_{outf} = r_{out} (1 + G_{m0}R_F)$$

$$G_{mf} = \frac{G_{m0}}{1 + G_{m0}R_F}$$

$$G_{mr} = \frac{-R_F}{r_{in}r_{out} (1 + G_{m0}R_F)}$$

$|G_{mr}G_{mf}| \ll \left(\frac{1}{r_{inf}} + G_S \right) \left(\frac{1}{r_{outf}} + G_L \right)$ R_S 和 R_L 不要过大即可视为单向放大网络

双向网络何时可视为单向网络？



$$H = \frac{v_L}{v_S} = \frac{y_{21}G_S}{y_{21}y_{12} - (y_{11} + G_S)(y_{22} + G_L)} \approx \frac{y_{21}G_S}{-(y_{11} + G_S)(y_{22} + G_L)}$$

双向网络传递函数

单向网络传递函数

$$|y_{21}y_{12}| \ll |(y_{11} + G_S)(y_{22} + G_L)|$$

单向化条件

$$|y_{21}y_{12}| \ll |(y_{11} + G_S)(y_{22} + G_L)|$$

见教材习题4.14分析

假设满足闭环单向化条件

$$R_S \ll r_{in} \text{ 或 } R_L \ll r_{out} \text{ 或 } R_S R_L \ll \frac{r_{inf} r_{outf}}{G_{m0} R_F} \approx r_{in} r_{out} G_{m0} R_F$$

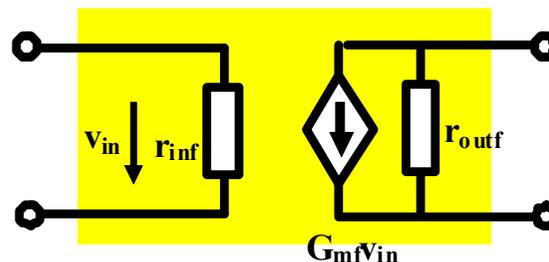
通常情况下，上述三个条件满足其一，则可单向化处理为单向跨导放大器

$$\mathbf{y} = \mathbf{z}^{-1} = \begin{bmatrix} \frac{1}{r_{in}(1+G_{m0}R_F)} & \frac{-R_F}{r_{in}r_{out}(1+G_{m0}R_F)} \\ \frac{G_{m0}}{1+G_{m0}R_F} & \frac{1}{r_{out}(1+G_{m0}R_F)} \end{bmatrix} \approx \begin{bmatrix} \frac{1}{r_{inf}} & 0 \\ G_{mf} & \frac{1}{r_{outf}} \end{bmatrix} = \frac{1}{1+G_{m0}R_F} \mathbf{y}_{OpenLoop}$$

$$r_{inf} = r_{in}(1+G_{m0}R_F)$$

$$r_{outf} = r_{out}(1+G_{m0}R_F)$$

$$G_{mf} = \frac{G_{m0}}{1+G_{m0}R_F} \approx \frac{1}{R_F}$$



这个结论使得我们在进行负反馈放大器分析时，只需分别分析获得反馈系数和开环放大器，即可获得闭环放大器的基本特性

深度负反馈条件： $T=G_{m0}R_F \gg 1$ ：负反馈放大器性能几乎由负反馈网络决定

数值计算

不稳定，不可靠

$$g_m = \frac{I_{C0}}{v_T} = \frac{1.08mA}{26mV} = 41.5mS$$

$$r_{be} = \beta \frac{1}{g_m} = 300 \times 24\Omega = 7.22k\Omega$$

$$r_{ce} = \frac{V_A}{I_{C0}} = \frac{100V}{1.08mA} = 92.6k\Omega$$

$$R_E = 1k\Omega$$

稳定，可靠

$$\mathbf{z} = \mathbf{z}_T + \mathbf{z}_E = \begin{bmatrix} r_{be} + R_E & R_E \\ -g_m r_{be} r_{ce} + R_E & r_{ce} + R_E \end{bmatrix} = \begin{bmatrix} 7.22 + 1 & 1 \\ -27778 + 1 & 92.6 + 1 \end{bmatrix} k\Omega = \begin{bmatrix} 8.22 & 1 \\ -27777 & 93.6 \end{bmatrix} k\Omega$$

$$\mathbf{y} = \mathbf{z}^{-1} = \begin{bmatrix} 3.28 & -0.0350 \\ 973 & 0.288 \end{bmatrix} \mu S \approx \begin{bmatrix} 3.28 & 0 \\ 973 & 0.288 \end{bmatrix} \mu S$$

也可以不走数学过程，直接给答案：

$$r_{inf} = \frac{1}{y_{11}} = 305k\Omega \approx r_{be}(1 + g_m R_E) = 307k\Omega$$

大得可视为无穷：可靠

$$r_{outf} = \frac{1}{y_{22}} = 3.47M\Omega \approx r_{ce}(1 + g_m R_E) = 3.94M\Omega$$

深度负反馈

$$G_{mf} = 973\mu S \approx \frac{1}{R_F} = 1mS$$

闭环增益几乎由反馈网络决定：可靠

是否可视为单向网络？

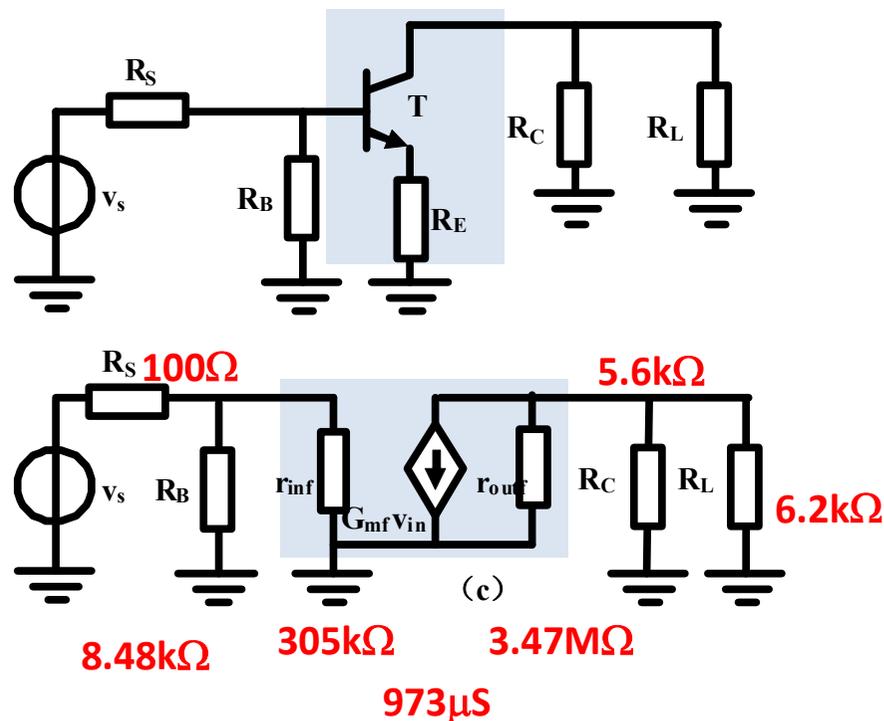
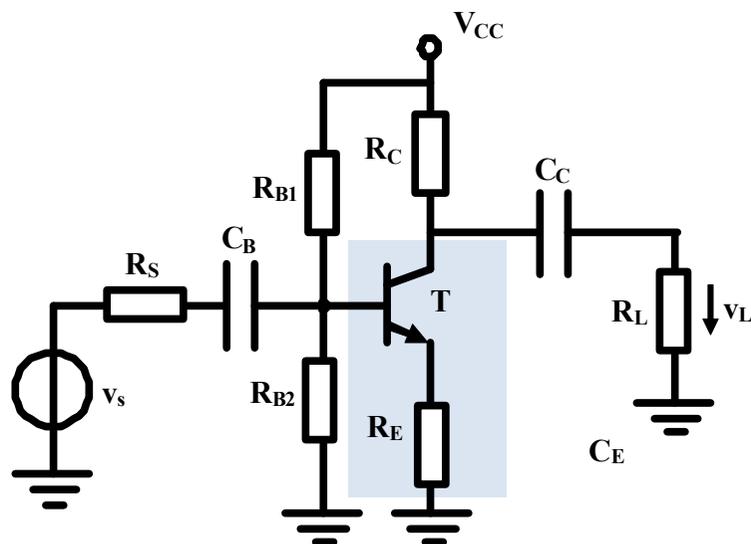
$$R_S = 100\Omega \ll r_{in} = 8.22k\Omega \text{ 或}$$

$$R'_L = R_L \parallel R_C = 2.94k\Omega \ll r_{out} = 93.6k\Omega \text{ 或}$$

$$R_S R'_L = 2.94 \times 10^5 (\Omega)^2 \ll \frac{r_{inf} r_{outf}}{G_{m0} R_F} = \frac{1}{|y_{12} y_{21}|} = 2.93 \times 10^{10} (\Omega)^2$$

视为单向网络毫无问题

没有旁路电容



$$A_v \approx -G_{mf} R'_L = -973 \mu S \times 2.94 k\Omega = -2.86 \sim -\frac{R'_L}{R_E} = -2.94$$

无旁路电容

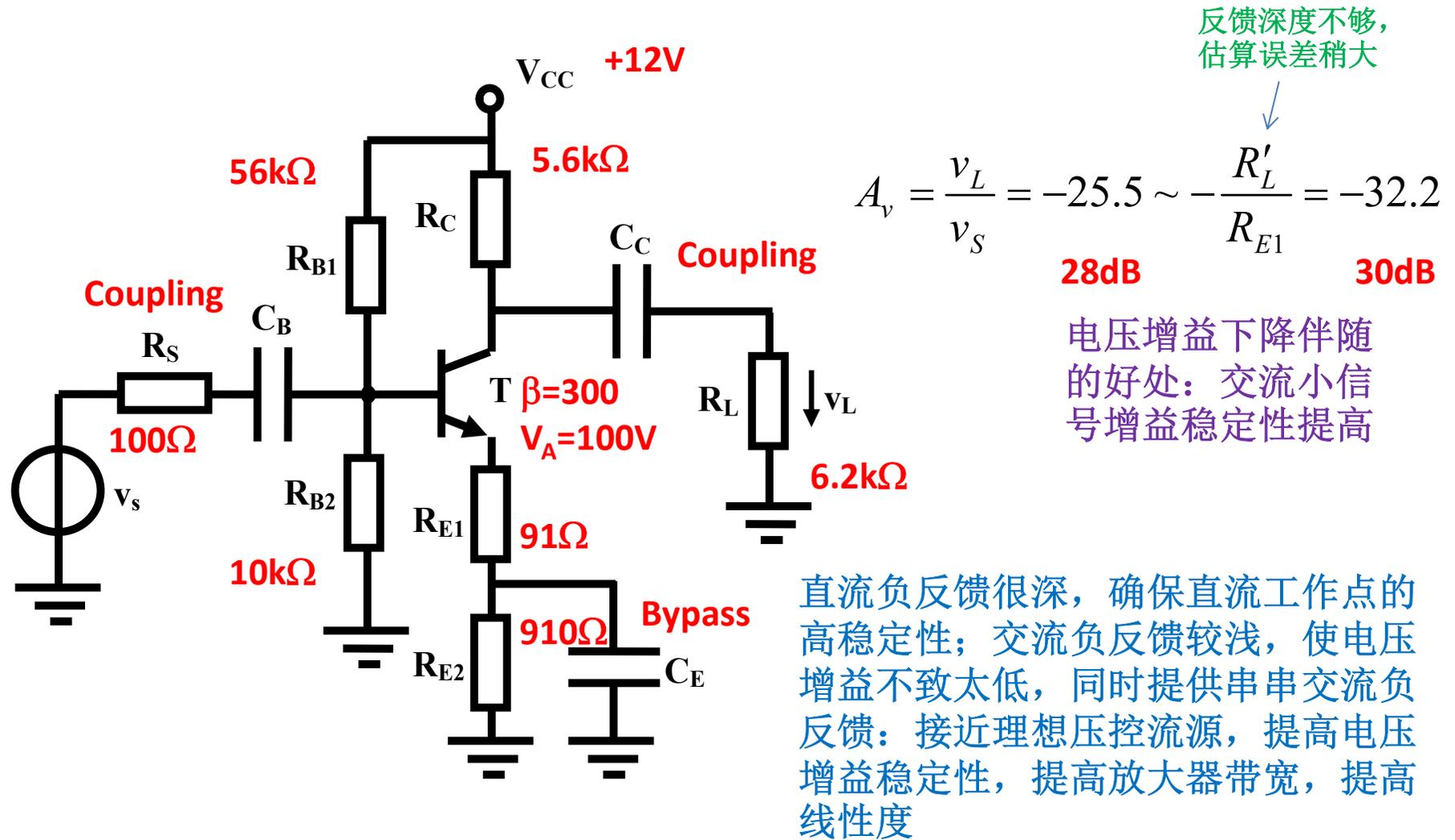
有旁路电容

$$A_v = \frac{v_L}{v_S} = -115 \sim -g_m R'_L = -122$$

9dB的反相电压增益：不令人满意
但温度敏感度低：令人满意

41dB的反相电压增益：令人满意
温度敏感度高：不令人满意

电路上的折中方案



负反馈的优点

$$T = G_{m0}R_F, R_{m0}G_F, A_{v0}F_v, A_{i0}F_i$$

环路增益 = 开环放大倍数 × 反馈系数

- 负反馈使得放大器接近理想受控源

- 输入电阻、输出电阻变得更大或更小

- 理想受控源输入电阻、输出电阻或无穷、或为零

- 串联则阻抗变大，并联则阻抗变小

$$r_{inf} = r_{in}(1+T), \frac{r_{in}}{1+T}$$

$$r_{ouf} = r_{out}(1+T), \frac{r_{out}}{1+T}$$

$$A_f = \frac{A_0}{1+A_0F} \stackrel{T=A_0F \gg 1}{\approx} \frac{1}{F}$$

$$G_{mf} = \frac{G_{m0}}{1+G_{m0}R_F} \stackrel{T=G_{m0}R_F \gg 1}{\approx} \frac{1}{R_F}$$

- 提高稳定性

- 提高线性度

- 提高带宽

实用的晶体管放大电路或多或少都存在着某种形式的负反馈结构

负反馈使得增益不再由放大网络单独决定
深度负反馈增益几乎完全由反馈网络决定，
等于反馈系数的倒数：反馈网络具有什么
特性，闭环放大器则具有什么特性

负反馈放大器拓展结论 (1)

$$g_m = 41.5\text{mS}$$

$$r_{be} = 7.22\text{k}\Omega$$

$$r_{ce} = 92.6\text{k}\Omega$$

$$R_{E1} = 91\Omega$$

• 晶体管串联负反馈简单估算公式

$$\mathbf{z} = \mathbf{z}_T + \mathbf{z}_E = \begin{bmatrix} r_{be} + R_{E1} & R_{E1} \\ -g_m r_{be} r_{ce} + R_{E1} & r_{ce} + R_{E1} \end{bmatrix} = \begin{bmatrix} r_{in} & R_F \\ -G_{m0} r_{in} r_{out} & r_{out} \end{bmatrix}$$

$$r_{in} = r_{be} + R_{E1} \approx r_{be}$$

$$r_{out} = r_{ce} + R_{E1} \approx r_{ce}$$

$$G_{m0} = \frac{g_m r_{be} r_{ce} - R_{E1}}{r_{in} r_{out}} \approx g_m$$

$$R_F = R_{E1}$$

晶体管自身为跨导放大器，串联负反馈形成的是理想跨导器，两者一致：反馈网络负载效应可以忽略不计，开环放大器近似为原始放大器

$$T = G_{m0} R_F \approx g_m R_{E1} = 3.78 \quad \text{反馈深度不深}$$

$$r_{inf} = r_{in} (1 + G_{m0} R_F) \approx r_{be} (1 + T) \approx 34.5\text{k}\Omega$$

$$r_{outf} = r_{out} (1 + G_{m0} R_F) \approx r_{ce} (1 + T) \approx 442\text{k}\Omega$$

$$G_{mf} = \frac{G_{m0}}{1 + G_{m0} R_F} \approx \frac{g_m}{1 + T} \approx 8.69\text{mS}$$

$$A_v = \frac{v_L}{v_S} \approx G_{mf} R'_L \approx 8.69\text{m} \times 2.94\text{k} = -25.5$$

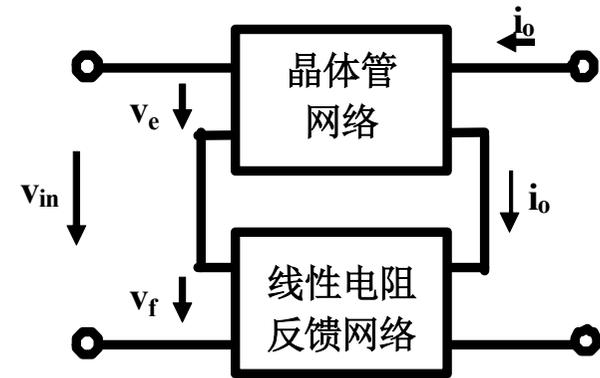
负反馈放大器 拓展研究 (2)

串串负反馈

(1) **原理**: 检测输出电流 i_o , 形成反馈电压 v_f , 从输入信号 v_{in} 中扣除, 形成误差电压 v_e , 作用到晶体管放大网络, 稳定输出电流 i_o 。故而串串负反馈形成接近理想的压控流源

(2) **分析**: 串串连接 \mathbf{z} 相加, \mathbf{z}_{12} 元素为理想反馈网络的反馈系数 R_F , 扣除反馈系数作用后的单向放大网络称之为开环放大器, 开环放大器输入电阻 $r_{in}=\mathbf{z}_{11}$, 输出电阻 $r_{out}=\mathbf{z}_{22}$, 开环跨导增益 $G_{m0}=-\mathbf{z}_{21}/(\mathbf{z}_{11}\mathbf{z}_{22})$ 。闭环放大器接近理想压控流源, 其最适参量矩阵为 \mathbf{y} 参量, 故而对 \mathbf{z} 求逆, $\mathbf{y}=\mathbf{z}^{-1}$ 。

(3) **结果**: 闭环放大器环路增益 $T=G_{m0}R_F$, 输入电阻变大 $r_{inf}=r_{in}(1+T)$, 输出电阻变大 $r_{outf}=r_{out}(1+T)$, 闭环跨导增益 $G_{mf}=G_{m0}/(1+T)$ 变得稳定了, 在深度负反馈条件 $T \gg 1$ 下, 闭环跨导增益几乎是反馈系数的倒数



串串负反馈

$$\mathbf{z} = \mathbf{z}_T + \mathbf{z}_E = \begin{bmatrix} r_{in} & R_F \\ -G_{m0}r_{in}r_{out} & r_{out} \end{bmatrix}$$

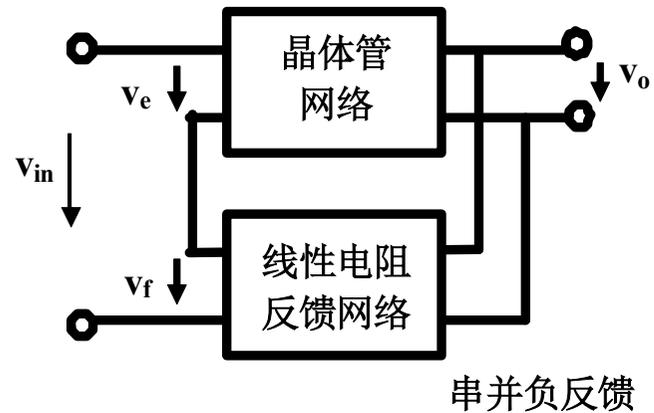
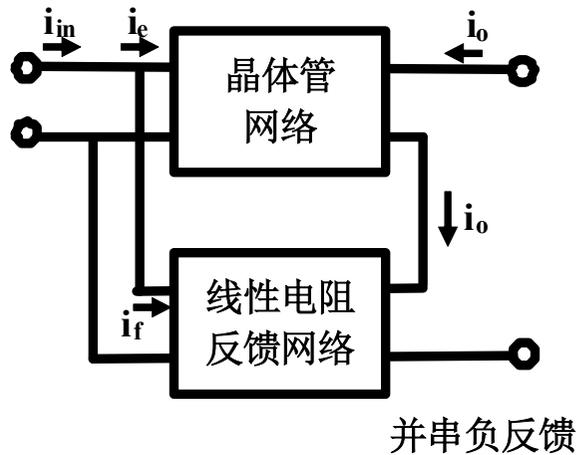
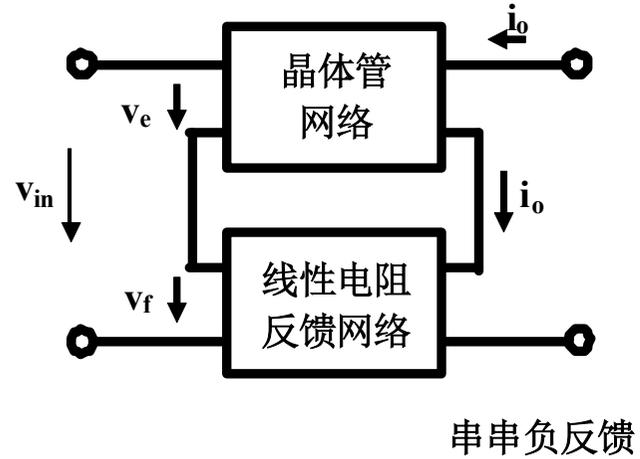
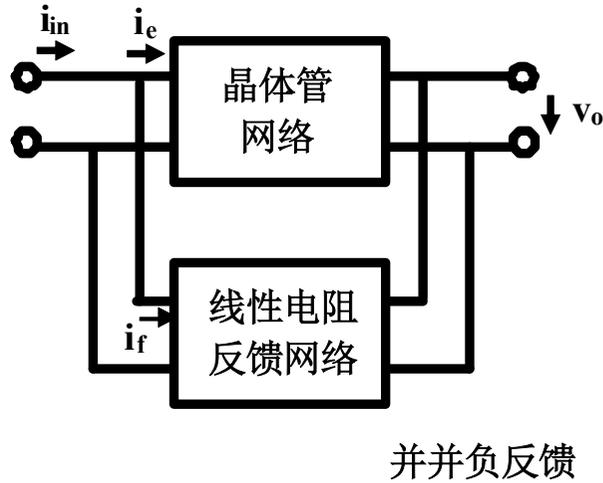
$$\mathbf{y} = \mathbf{z}^{-1} = \begin{bmatrix} \frac{1}{r_{in}(1+G_{m0}R_F)} & \frac{-R_F}{r_{in}r_{out}(1+G_{m0}R_F)} \\ \frac{G_{m0}}{1+G_{m0}R_F} & \frac{1}{r_{out}(1+G_{m0}R_F)} \end{bmatrix}$$

单向化条件满足

$$\approx \begin{bmatrix} \frac{1}{r_{inf}} & 0 \\ G_{mf} & \frac{1}{r_{outf}} \end{bmatrix}$$

$$G_{mf} = \frac{G_{m0}}{1+G_{m0}R_F} \stackrel{G_{m0}R_F \gg 1}{\approx} \frac{1}{R_F}$$

作业：三句话说清楚负反馈放大器



仿照上页串串负反馈格式，用相同的语式描述所有4种负反馈放大器：3句话，3个公式

深度负反馈

$$T = G_{m0}R_F, R_{m0}G_F, A_{v0}F_v, A_{i0}F_i$$

环路增益 = 开环放大倍数 × 反馈系数

- 如何获得稳定的接近理想的受控源？
 - 深度负反馈
 - 首先获得高增益但增益不太确定的放大网络，之后用稳定的反馈网络，由于增益为反馈系数的倒数，故而闭环增益稳定
 - 开环高增益可以是任意一种增益，如运放高增益为高电压增益

$$T \gg 1$$

串串负反馈: $G_{m0}R_F \gg 1$

并并负反馈: $R_{m0}G_F \gg 1$

串并负反馈: $A_{v0}F_v \gg 1$

并串负反馈: $A_{i0}F_i \gg 1$

串串负反馈: $G_{mf} = \frac{G_{m0}}{1 + G_{m0}R_F} \approx \frac{1}{R_F}$

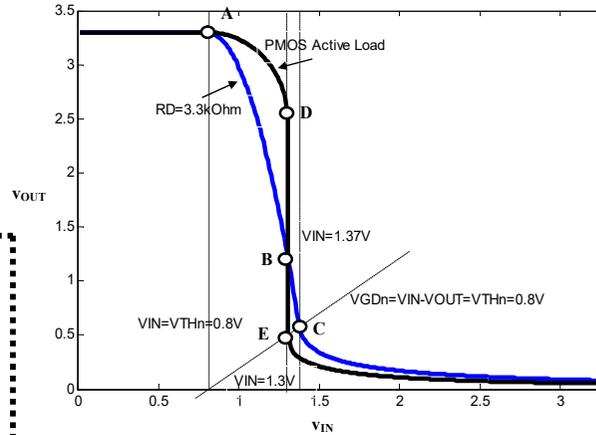
并并负反馈: $R_{mf} = \frac{R_{m0}}{1 + R_{m0}G_F} \approx \frac{1}{G_F}$

串并负反馈: $A_{vf} = \frac{A_{v0}}{1 + A_{v0}F_v} \approx \frac{1}{F_v}$

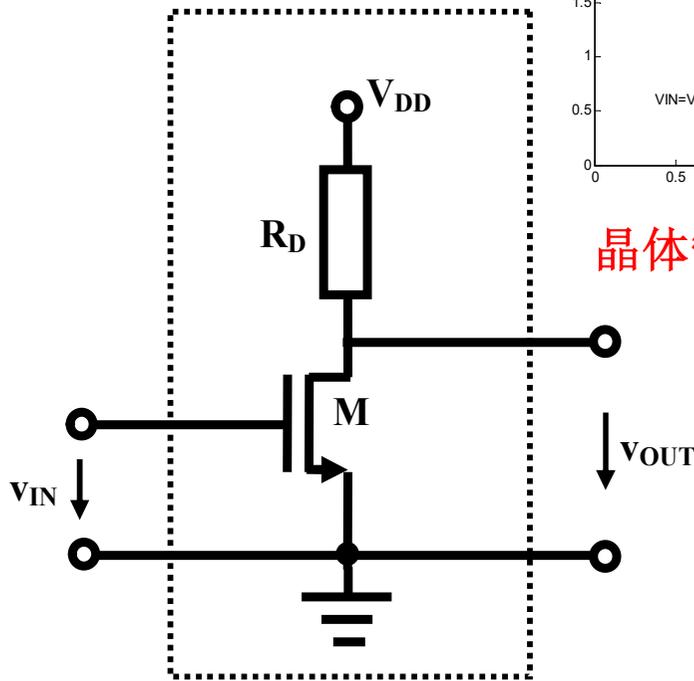
并串负反馈: $A_{if} = \frac{A_{i0}}{1 + A_{i0}F_i} \approx \frac{1}{F_i}$

高增益放大器实现方案 (1)

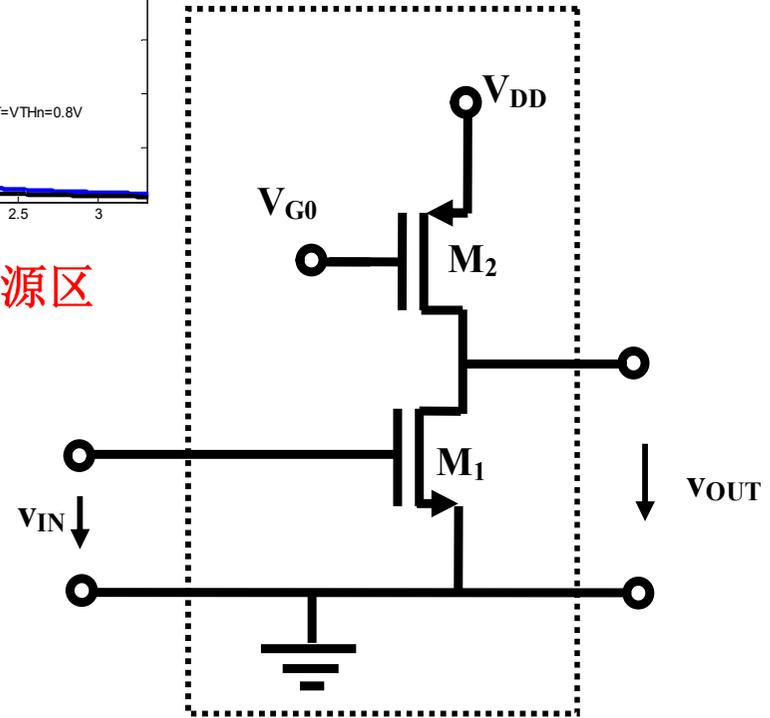
- 有源负载



晶体管都偏置在有源区

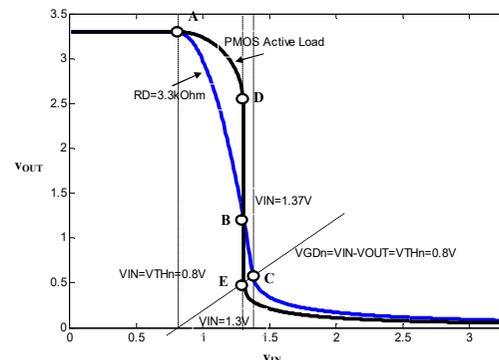
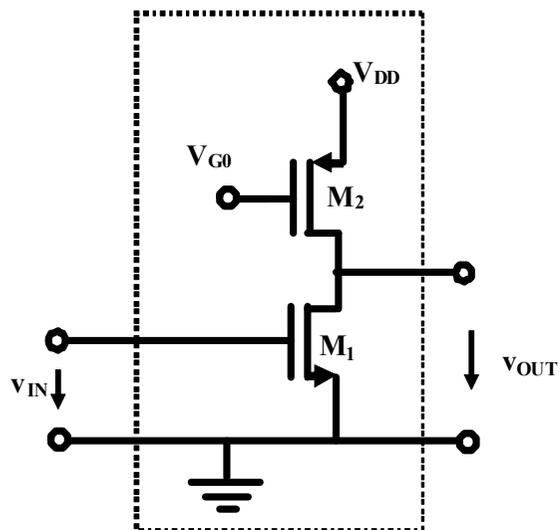


$$A_{v0} = -g_m (R_D \parallel r_{ds}) \approx -g_m R_D$$



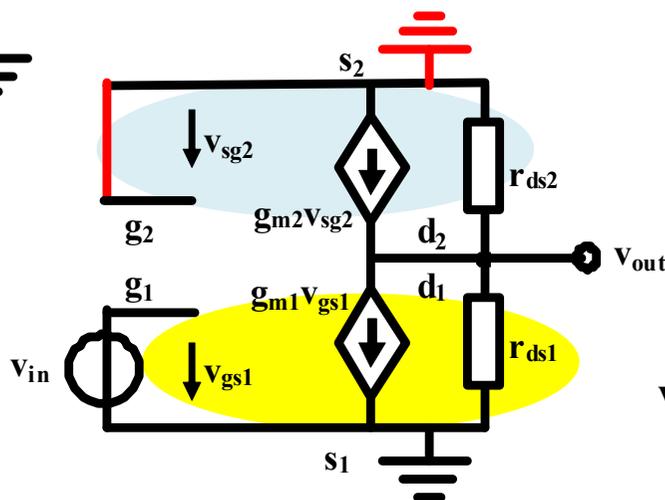
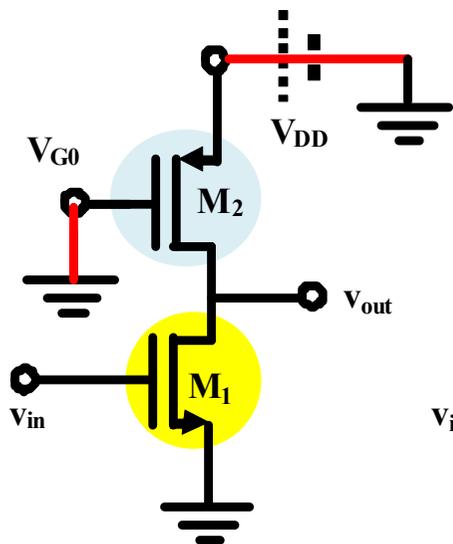
$$A_{v0} = -g_m (r_{ds1} \parallel r_{ds2})$$

有源负载

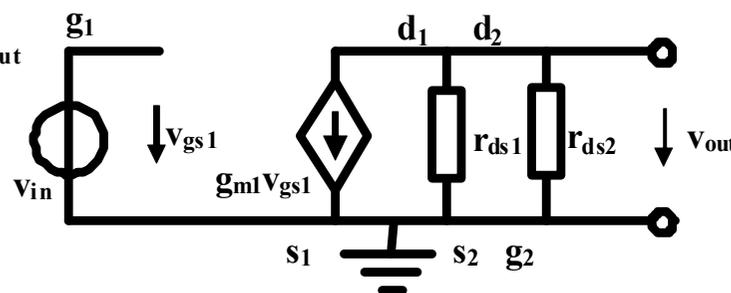


交流小信号分析时，直流电压源都短接（恒压源微分电阻为0）

有源负载很大，可以获得高电压增益，但跨导器是受控电流源输出，驱动重负载（小电阻，需要大电流的称之为重）时，电压增益变小



$$A_{v0} = -g_m (r_{ds1} \parallel r_{ds2})$$

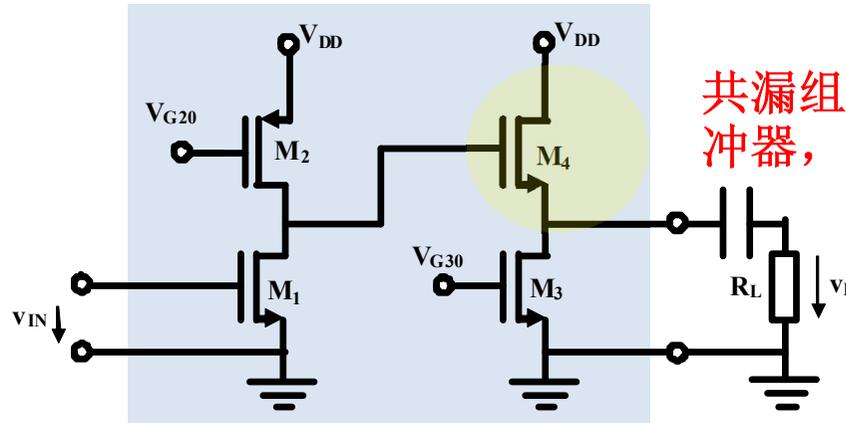


保留交流源，其他元件均用微分元件替代

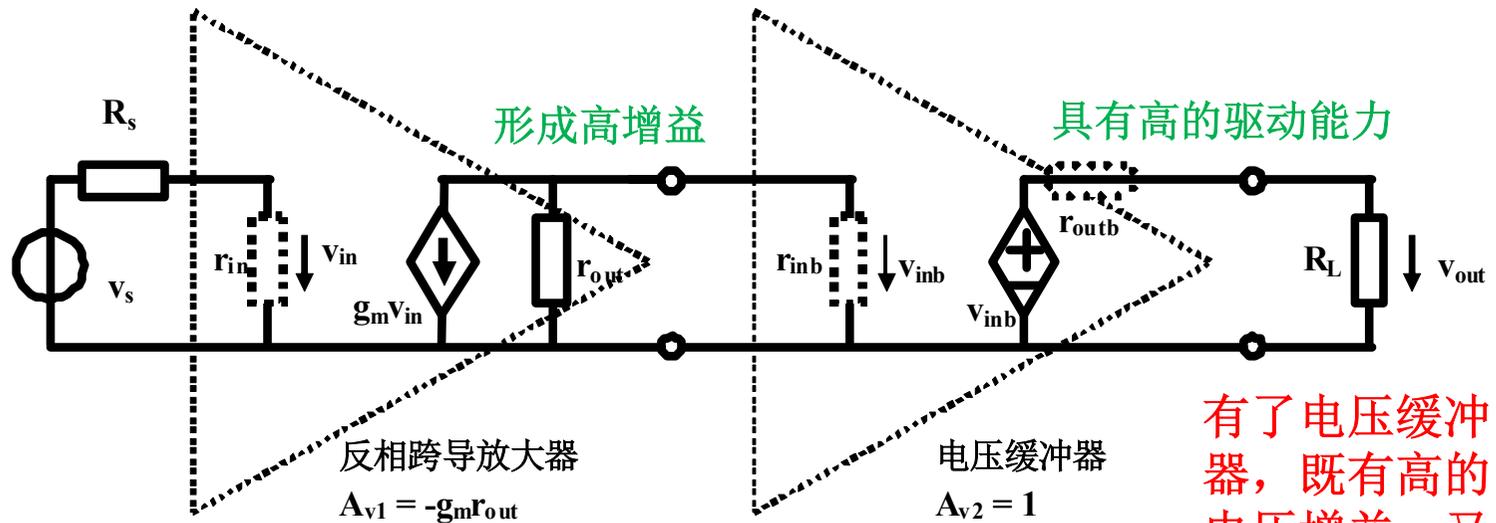
有源负载很大

高增益放大器实现方案 (2)

- 缓冲器



共漏组态晶体管为电压缓冲器，后面马上给予确认

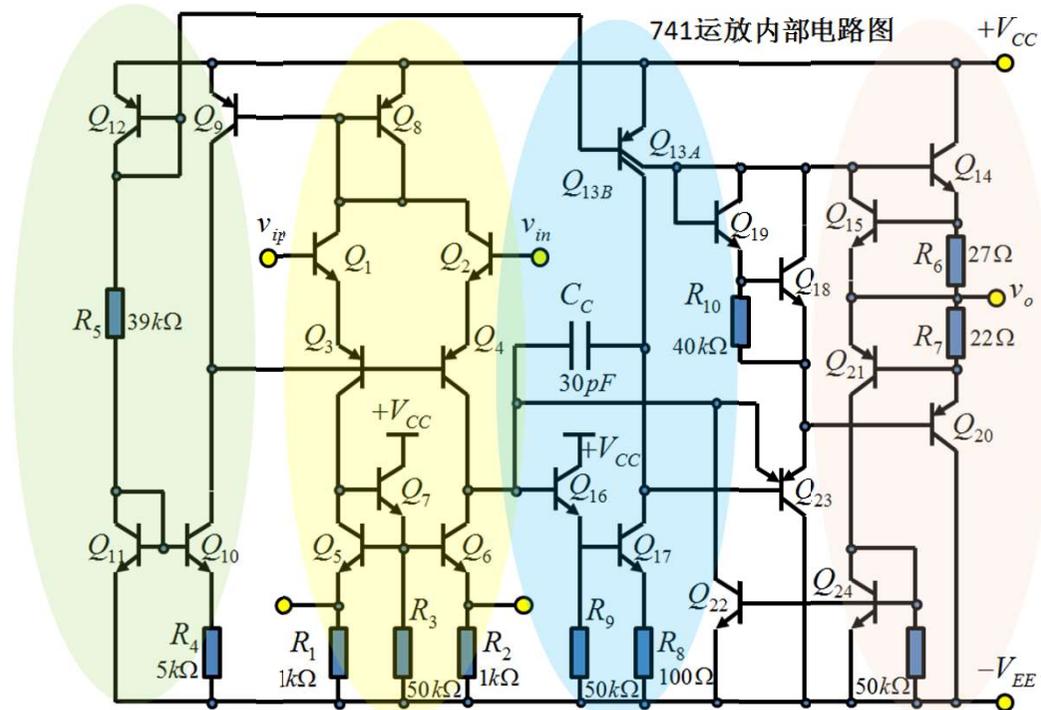


有了电压缓冲器，既有高的电压增益，又能驱动重负载

$$A_{v0} = A_{v1} A_{v2} = -g_m r_{out} \cdot 1 = -g_m (r_{ds1} \parallel r_{ds2})$$

高增益放大器实现方案 (3)

- 级联+缓冲



提供偏置
的参考电
流源

第一级
跨导放大器

第二级
跨导放大器

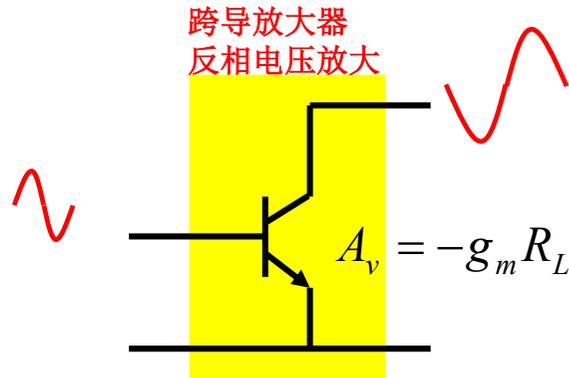
第三级
电压缓冲器

$$A_{v0} = A_{v1} A_{v2} A_{v3} = g_{m1} r_{out1} g_{m2} r_{out2} \sim 200000$$

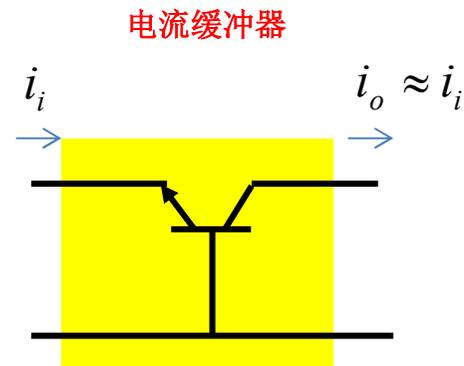
$$r_{in} = r_{in1} \sim 2M\Omega$$

$$r_{out} = r_{out3} \sim 75\Omega$$

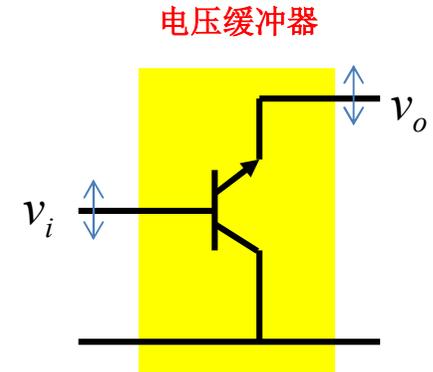
二、晶体管的三种组态



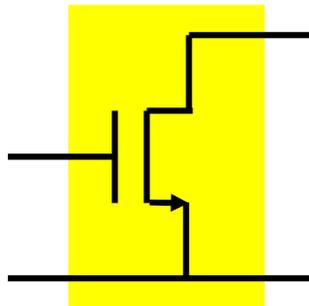
Common Emitter
CE: 共射组态



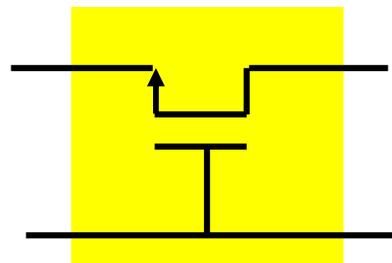
Common Base
CB: 共基组态



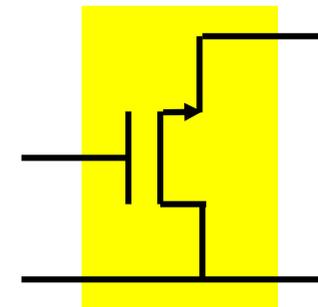
Common Collector
CC: 共集组态



Common Source
CS: 共源组态

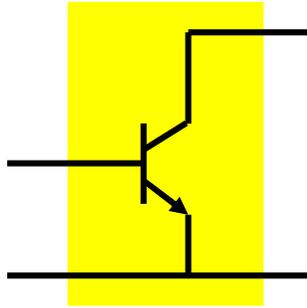


Common Gate
CG: 共栅组态

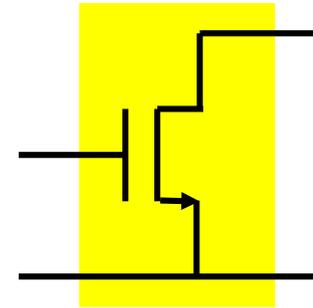


Common Drain
CD: 共漏组态

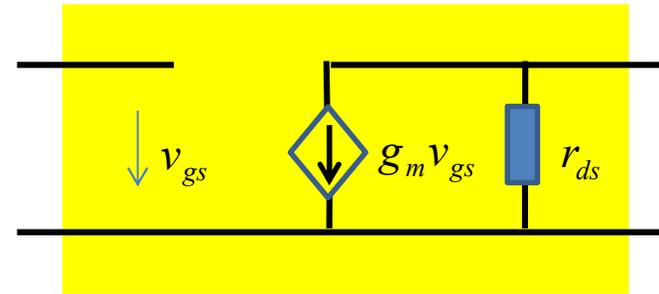
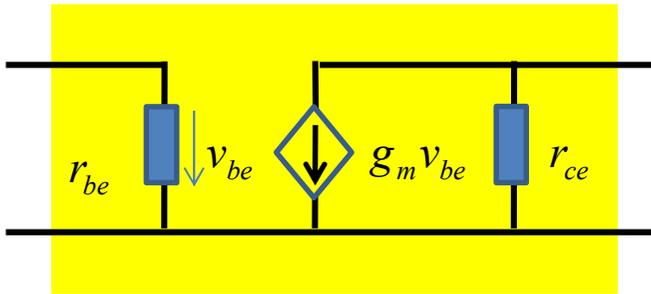
2.1 CE/CS组态跨导放大器



CE



CS



$$r_{in} = r_{be} = \beta \frac{v_T}{I_{C0}}$$

$$Z_{01} = r_{be} \quad Z_{02} = r_{ce}$$

$$r_{in} \rightarrow \infty$$

$$r_{out} = r_{ce} = \frac{V_A}{I_{C0}}$$

$$G_{pmax} = \frac{1}{(\sqrt{AD} + \sqrt{BC})^2}$$

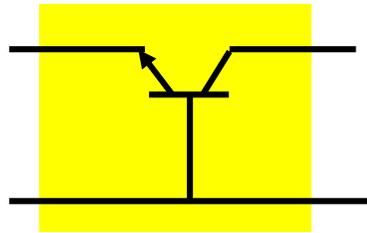
$$= \frac{1}{4AD} = \frac{1}{4} g_m^2 r_{be} r_{ce}$$

$$r_{out} = r_{ds} = \frac{V_E}{I_{D0}}$$

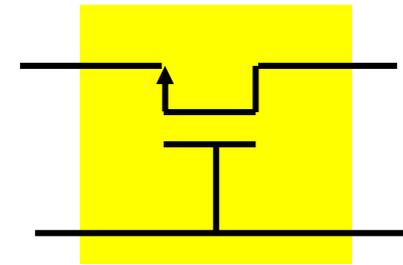
$$g_m = \frac{I_{C0}}{v_T}$$

$$g_m = \frac{2I_{D0}}{V_{GS0} - V_{TH}} = \frac{2I_{D0}}{V_{od}}$$

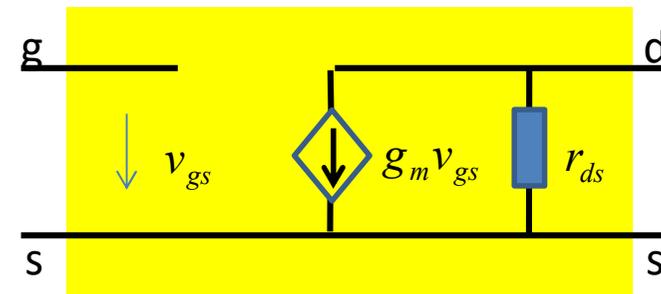
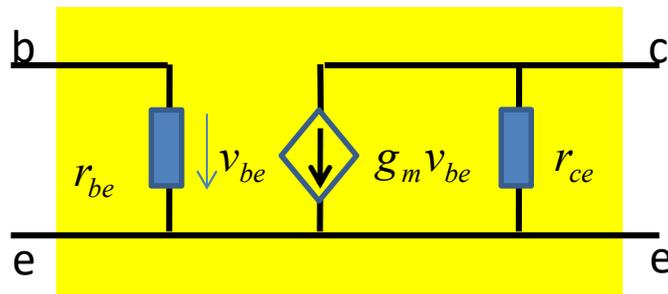
2.2 CB/CG组态



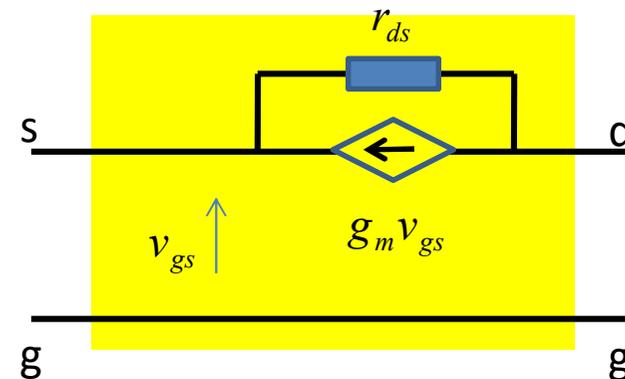
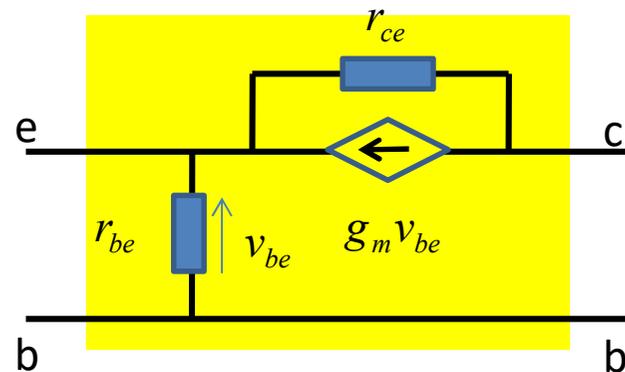
CB



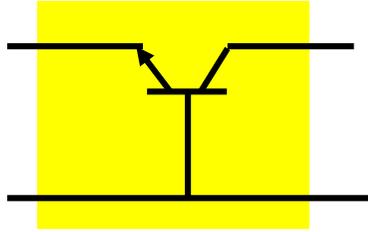
CG



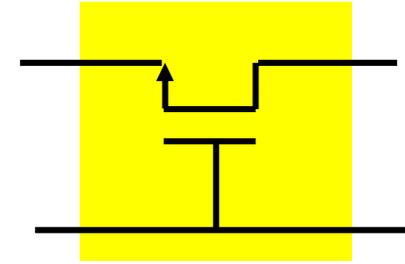
上节课建立交流小信号模型时，没有考虑任何组态问题，因而跨导器模型对任意组态都是可用的



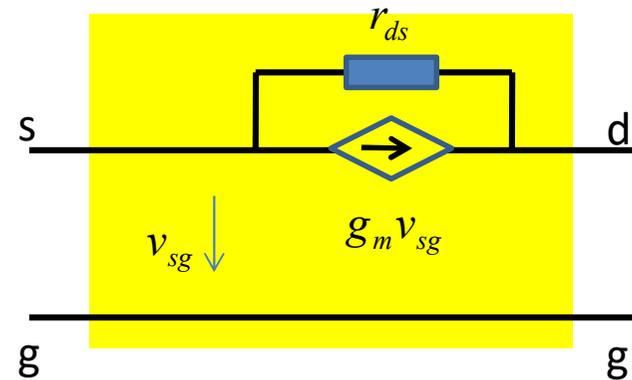
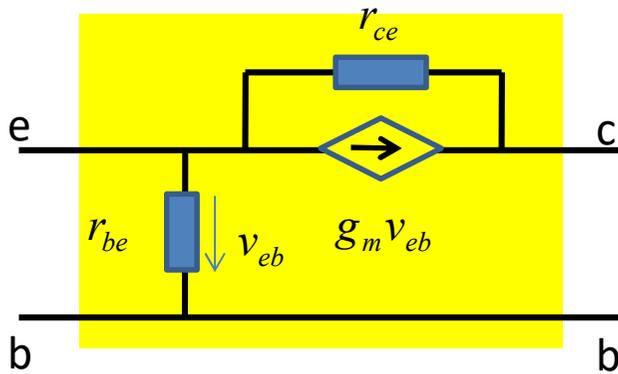
CB/CG组态 输入阻抗



CB



CG



$$r_{in} = r_{be} \parallel \frac{R_L + r_{ce}}{1 + g_m r_{ce}}$$

$$Z_{01} \approx \frac{r_{be}}{\sqrt{\beta}}$$

$$r_{in} = \frac{R_L + r_{ds}}{1 + g_m r_{ds}}$$

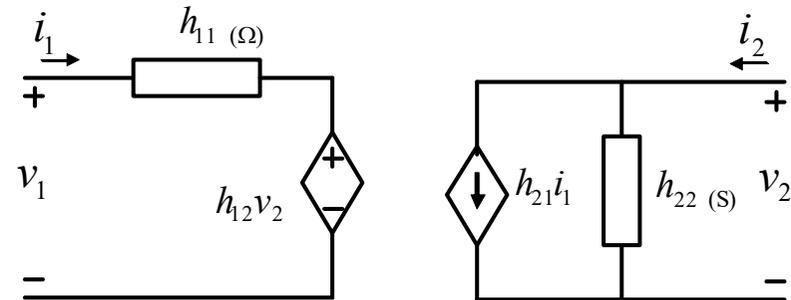
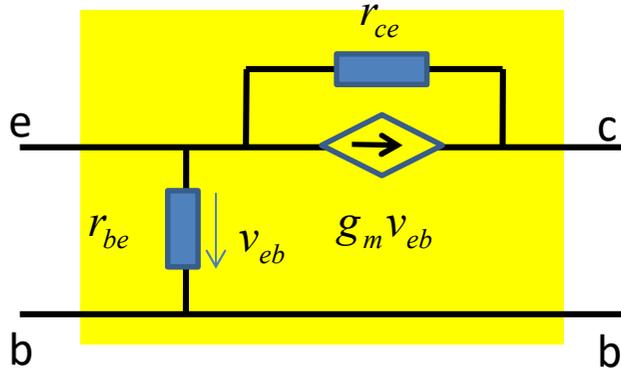
$$r_{out} = r_{be} \parallel R_S + r_{ce} + g_m (r_{be} \parallel R_S) r_{ce}$$

$$Z_{02} \approx \sqrt{\beta} r_{ce}$$

$$r_{out} = R_S + r_{ds} + g_m R_S r_{ds}$$

$$G_{pmax} = \frac{1}{(\sqrt{AD} + \sqrt{BC})^2} \approx \frac{1}{AD} \approx \frac{1}{A} \approx g_m r_{ce}$$

CB组态： 电流缓冲器？



$$\mathbf{h}_{CB} = \begin{bmatrix} \frac{1}{g_m + g_{be} + g_{ce}} & \frac{g_{ce}}{g_m + g_{be} + g_{ce}} \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be} g_{ce}}{g_m + g_{be} + g_{ce}} \end{bmatrix}$$

$$\mathbf{h} = \begin{bmatrix} 24.9314\Omega & 0.0002493 \\ -0.9975 & 0.02493\mu\text{S} \end{bmatrix}$$

$$g_m = 40\text{mS}, r_{be} = 10\text{k}\Omega, r_{ce} = 100\text{k}\Omega$$

CB 组态单向化条件

$$\mathbf{h}_{CB} = \begin{bmatrix} \frac{1}{g_m + g_{be} + g_{ce}} & \frac{g_{ce}}{g_m + g_{be} + g_{ce}} \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be}g_{ce}}{g_m + g_{be} + g_{ce}} \end{bmatrix}$$

$$|h_{12}h_{21}| \ll |(R_S + h_{11})(G_L + h_{22})|$$

$$(g_m + g_{ce})g_{ce} \ll (R_S(g_m + g_{be} + g_{ce}) + 1)(G_L(g_m + g_{be} + g_{ce}) + g_{be}g_{ce})$$

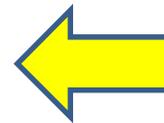


$g_m \gg g_{be}, g_{ce}$ 自然满足

$$g_m g_{ce} \ll (R_S g_m + 1)(G_L g_m + g_{be} g_{ce})$$



$$(R_S g_m + 1) \left(\frac{r_{ce}}{R_L} + \frac{1}{\beta} \right) \gg 1$$



$R_L \ll r_{ce}$
充分而非必要条件



教材习题
4.14分析

CB组态单向化

$R_L \ll r_{ce}$ 充分条件

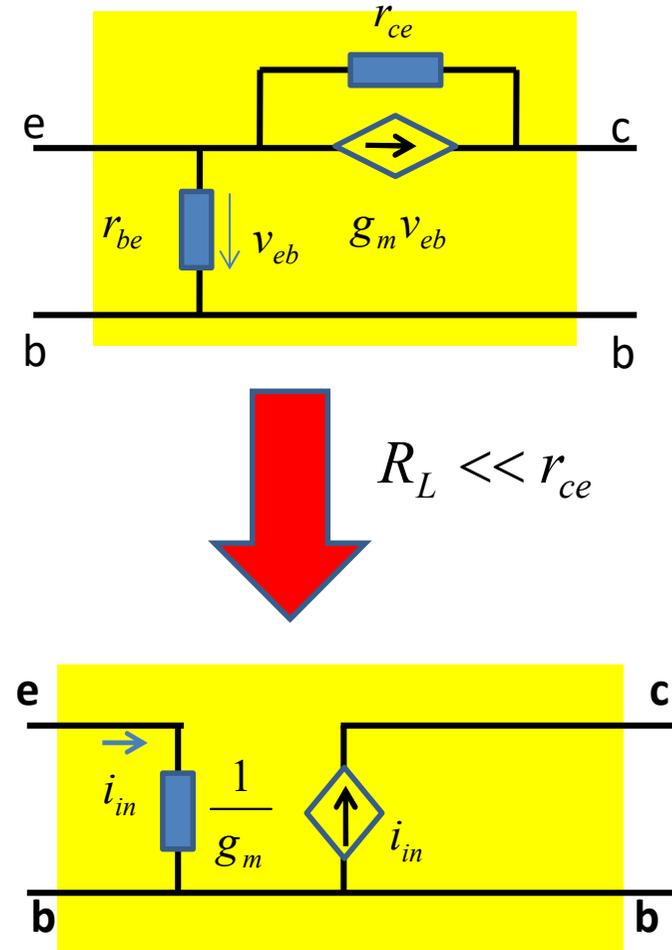
$$\mathbf{h}_{CB} = \begin{bmatrix} \frac{1}{g_m + g_{be} + g_{ce}} & \frac{g_{ce}}{g_m + g_{be} + g_{ce}} \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be}g_{ce}}{g_m + g_{be} + g_{ce}} \\ \frac{1}{g_m + g_{be} + g_{ce}} & \frac{g_{ce}}{g_m + g_{be} + g_{ce}} \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be}g_{ce}}{g_m + g_{be} + g_{ce}} \end{bmatrix}$$

$$\underset{R_L \ll r_{ce}}{\approx} \begin{bmatrix} \frac{1}{g_m + g_{be} + g_{ce}} & 0 \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be}g_{ce}}{g_m + g_{be} + g_{ce}} \\ \frac{1}{g_m + g_{be} + g_{ce}} & \frac{g_{ce}}{g_m + g_{be} + g_{ce}} \\ -\frac{g_m + g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{g_{be}g_{ce}}{g_m + g_{be} + g_{ce}} \end{bmatrix}$$

$$\approx \begin{bmatrix} \frac{1}{g_m} & 0 \\ -1 & 0 \end{bmatrix}$$

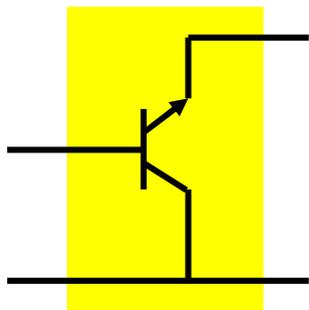
$$r_{out} = r_{be} + r_{ce} + g_m r_{be} r_{ce}$$

40MΩ极大：可认为开路

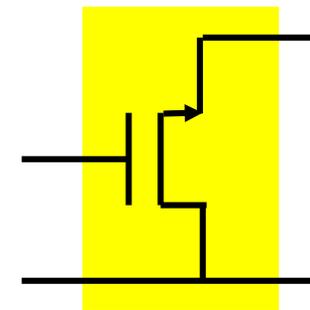


电流缓冲器模型

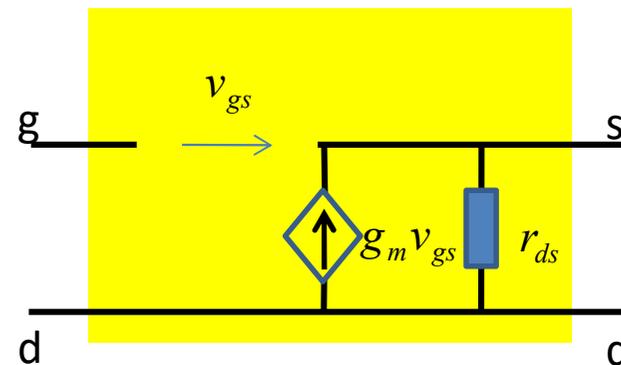
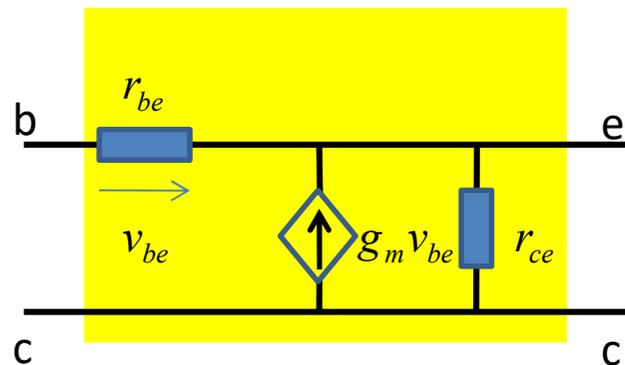
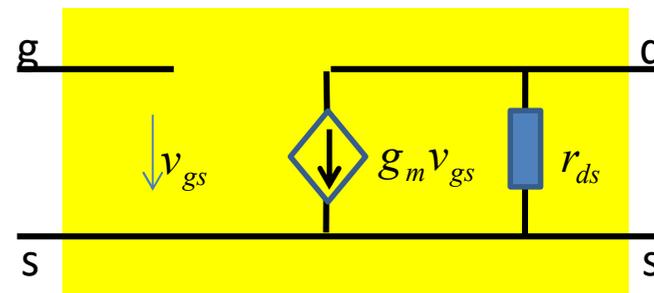
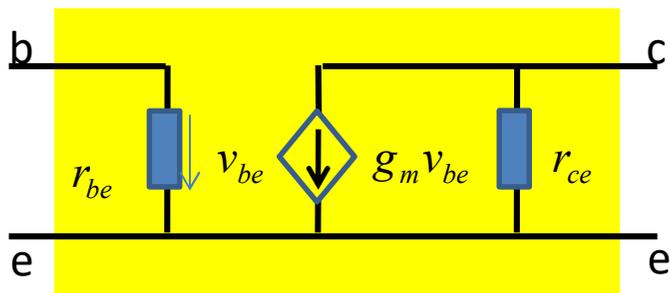
2.3 CC/CD组态



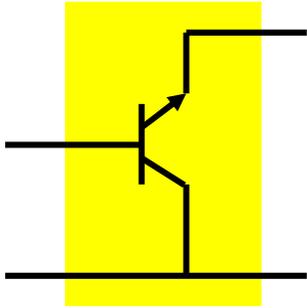
CC



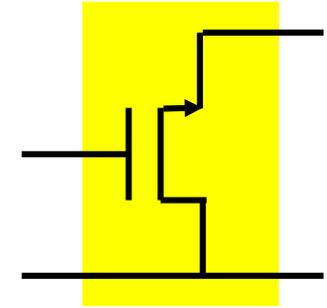
CD



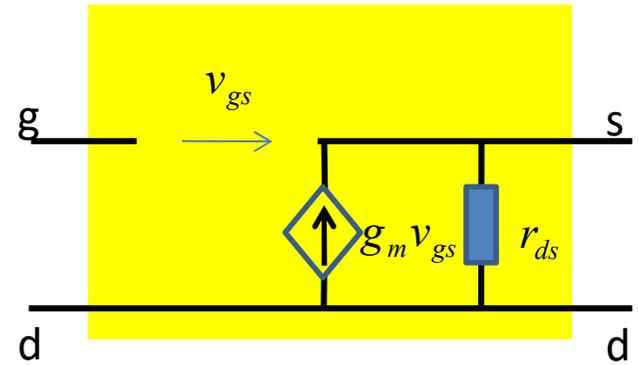
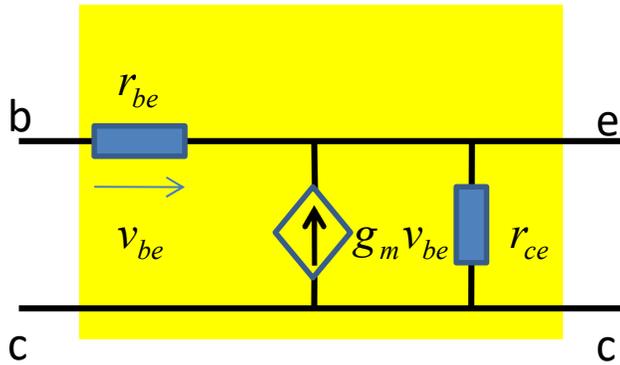
CC/CD组态 输入阻抗



CC



CD



$$r_{in} = r_{be} + r_{ce} \parallel R_L + g_m r_{be} (r_{ce} \parallel R_L)$$

$$Z_{01} \approx \sqrt{A_{v0}} r_{be}$$

$$R_{in} \rightarrow \infty$$

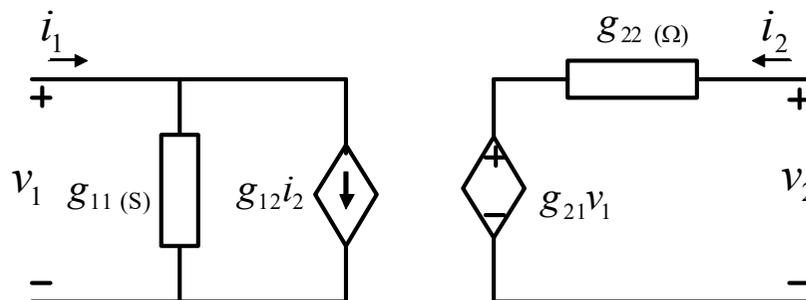
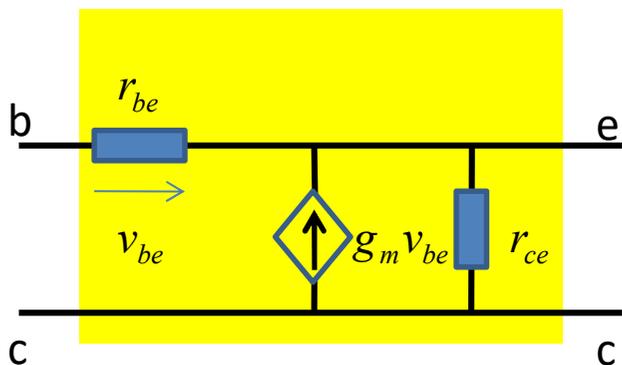
$$R_{out} = r_{ce} \parallel \frac{r_{be} + R_S}{1 + g_m r_{be}}$$

$$Z_{02} \approx \frac{r_{ce}}{\sqrt{A_{v0}}}$$

$$R_{out} = ? r_{ds} \parallel \frac{1}{g_m}$$

$$G_{pmax} = \frac{1}{(\sqrt{AD} + \sqrt{BC})^2} \approx \frac{1}{AD} \approx \frac{1}{D} \approx g_m r_{be}$$

CC组态：电压缓冲器？



$$[g]_{CC} = \begin{bmatrix} \frac{g_{be} g_{ce}}{g_m + g_{be} + g_{ce}} & \frac{-g_{be}}{g_m + g_{be} + g_{ce}} \\ \frac{g_m + g_{be}}{g_m + g_{be} + g_{ce}} & 1 \\ g_m + g_{be} + g_{ce} & g_m + g_{be} + g_{ce} \end{bmatrix}$$

$$g = \begin{bmatrix} 0.0249 \mu\text{S} & -0.00249 \\ 0.9998 & 24.9314 \Omega \end{bmatrix}$$

$$g_m = 40 \text{ mS}, \quad r_{be} = 10 \text{ k}\Omega, \quad r_{ce} = 100 \text{ k}\Omega$$

练习题 CC组态电压缓冲器模型

- (1) 分析g参量矩阵应用的单向化条件
- (2) 确认CC组态晶体管的单向化条件
 - 可以是充分非必要条件
- (3) 说明在满足该单向化条件情况下，CC组态为电压缓冲器模型

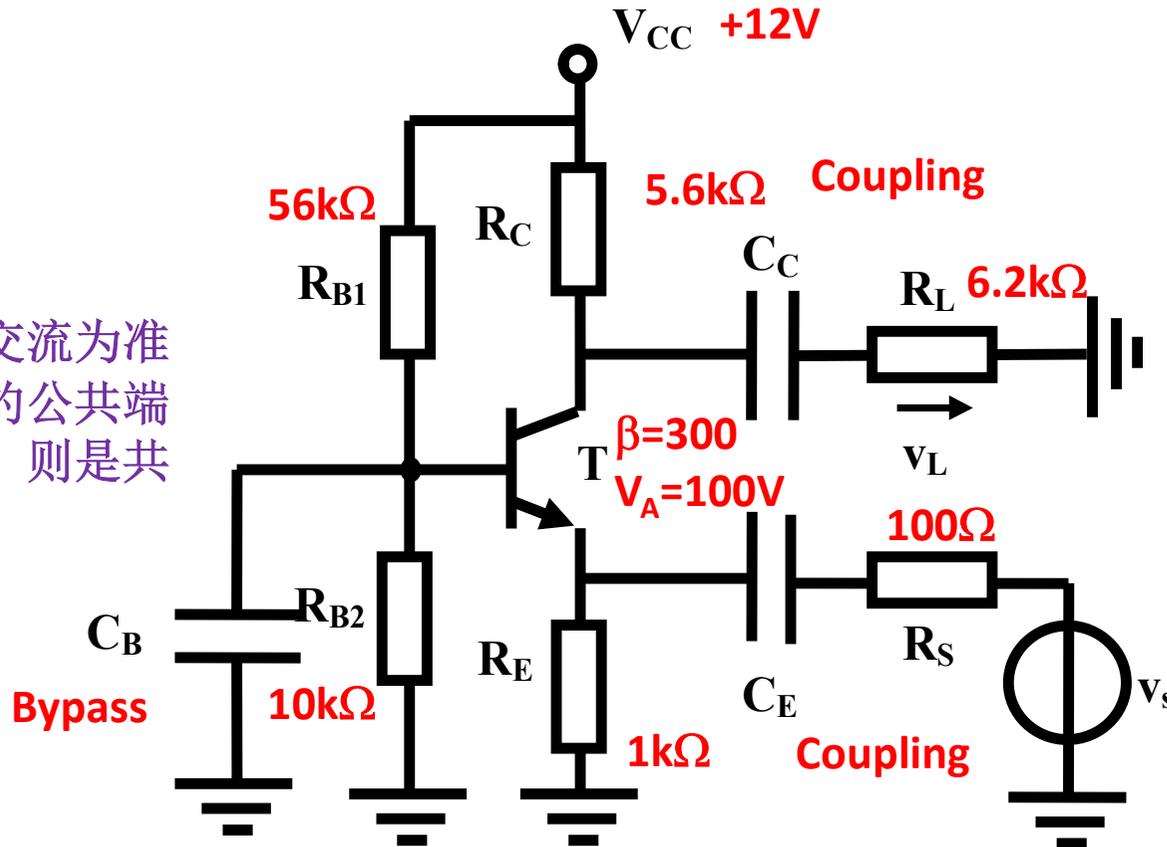


2.4 BJT组态总结

	CE	CB	CC
输入阻抗	r_{be}	$r_{be} \parallel \frac{R_L + r_{ce}}{1 + g_m r_{ce}}$	$r_{be} + r_{ce} \parallel R_L + g_m r_{be} (r_{ce} \parallel R_L)$
输出阻抗	r_{ce}	$r_{be} \parallel R_S + r_{ce} + g_m (r_{be} \parallel R_S) r_{ce}$	$r_{ce} \parallel \frac{r_{be} + R_S}{1 + g_m r_{be}}$
最大功率增益	$\frac{1}{4} g_m r_{ce} \cdot \beta$	$\sim \prec g_m r_{ce}$	$\sim \prec \beta = g_m r_{be}$
理想模型	反相跨导 $G_{m0} = -g_m$	电流缓冲 $A_{i0} = 1$	电压缓冲 $A_{v0} = 1$
输入输出阻抗	r_{be} r_{ce}	$r_{in} \approx 1/g_m$	$r_{out} \approx 1/g_m$
单向化条件		$R_L \ll r_{ce}$ 充分非必要	$R_S \ll r_{be}$

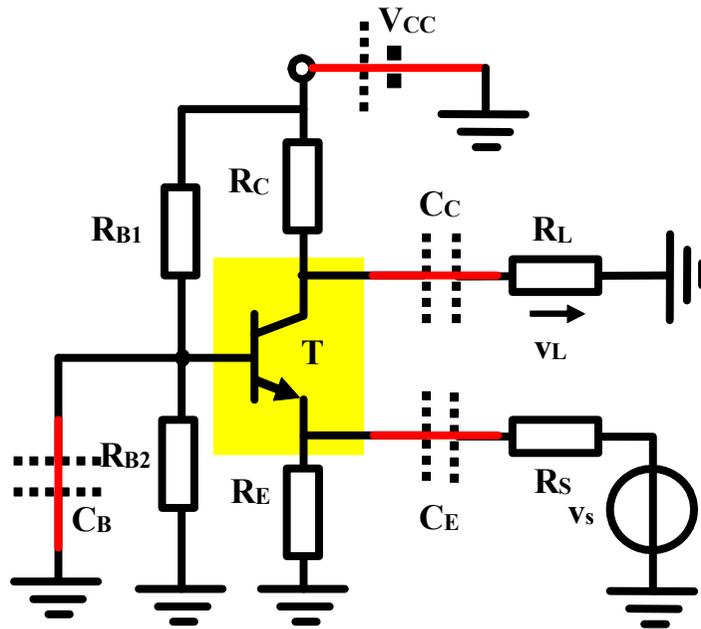
例4 CB组态交流小信号放大器分析

组态是以交流为准
交流分析的公共端
点是基极，则是共
基组态

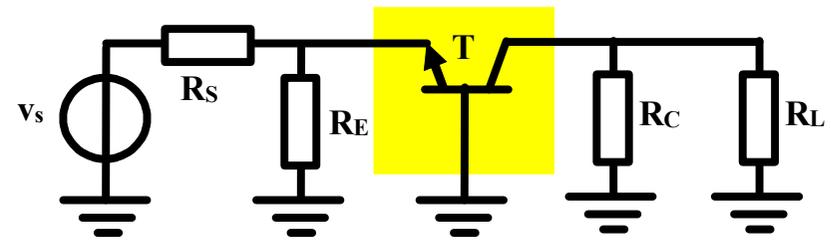


$$A_v = \frac{v_L}{v_S} = ?$$

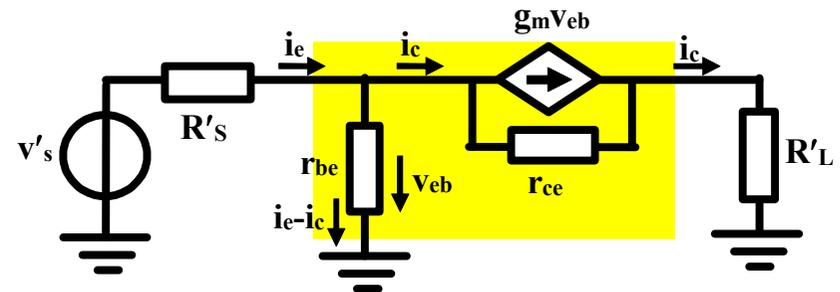
交流小信号线性分析



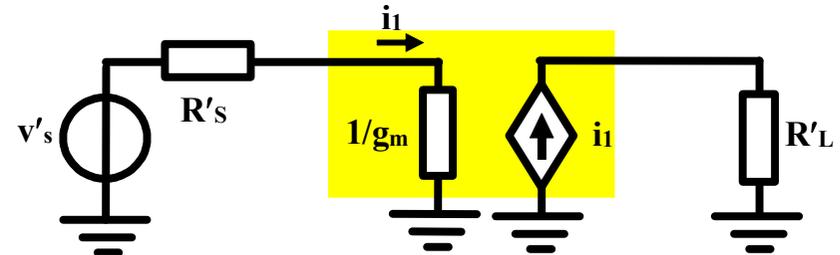
(a) 耦合电容、直流偏置电压源交流短路



(b) 交流小信号分析电路



(c) 晶体管采用通用跨导器模型



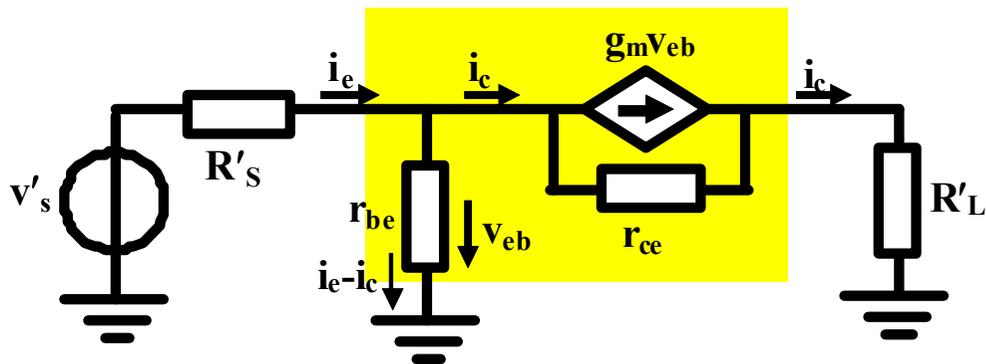
(d) 晶体管采用 CB 组态电流缓冲器模型

$$v'_s = \frac{R_E}{R_E + R_S} v_s = \frac{1k}{1k + 0.1k} v_s = 0.909v_s$$

$$R'_S = R_S \parallel R_E = \frac{R_E R_S}{R_E + R_S} = \frac{1k \times 0.1k}{1k + 0.1k} = 90.9\Omega$$

$$R'_L = R_L \parallel R_C = 6.2k\Omega \parallel 5.6k\Omega = 2.94k\Omega$$

晶体管用 y 参量电路模型



跨导器模型

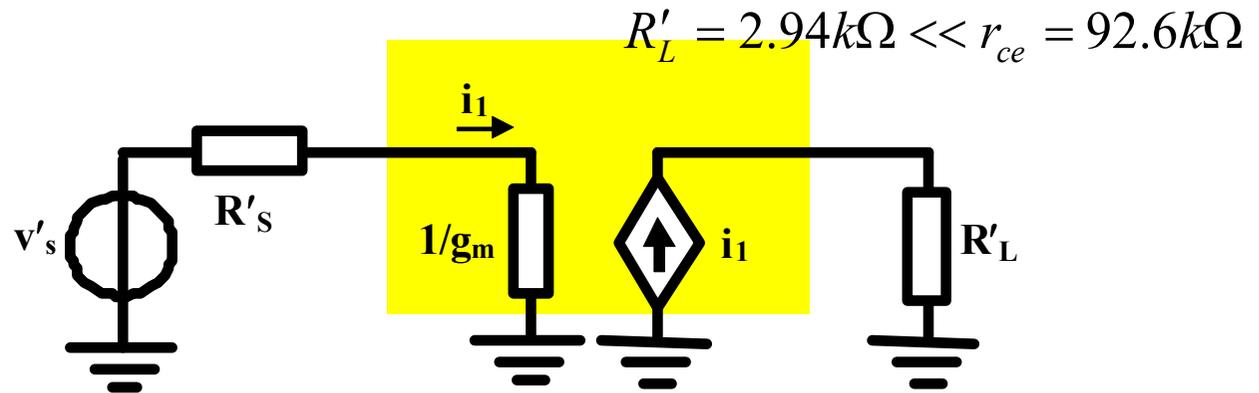
$$v'_s = R'_S i_e + (i_e - i_c) r_{be}$$

$$v'_s = R'_S i_e + (i_c - g_m (i_e - i_c) r_{be}) r_{ce} + i_c R'_L$$

$$\begin{aligned} v_L = i_c R'_L &= \frac{(1 + g_m r_{ce}) r_{be} R'_L}{R'_S (r_{be} + r_{ce} + g_m r_{be} r_{ce} + R'_L) + r_{be} (r_{ce} + R'_L)} v'_s \\ &= \frac{(1 + 41.5m \times 92.6k) \times 7.22k \times 2.94k}{90.9 \times (7.22k + 92.6k + 41.5m \times 7.22k \times 92.6k + 2.94k) + 7.22k \times (92.6k + 2.94k)} v'_s \\ &= 25.3 \times v'_s = 25.3 \times 0.909 v_s = 23 v_s \end{aligned}$$

同相电压放大
27.2dB

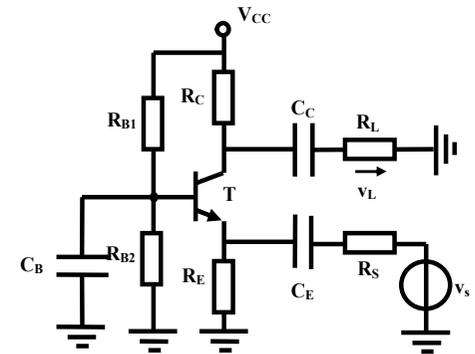
晶体管采用CB电流缓冲器模型



$$i_1 = \frac{v'_s}{R'_S + \frac{1}{g_m}} = \frac{g_m}{1 + g_m R'_S} v'_s = g_{mf} v'_s$$

$$v_L = i_1 R'_L = \frac{g_m R'_L}{1 + g_m R'_S} v'_s = g_{mf} R'_L v'_s$$

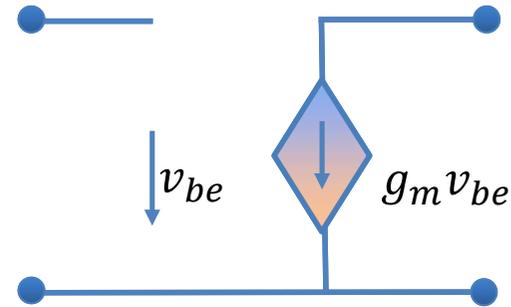
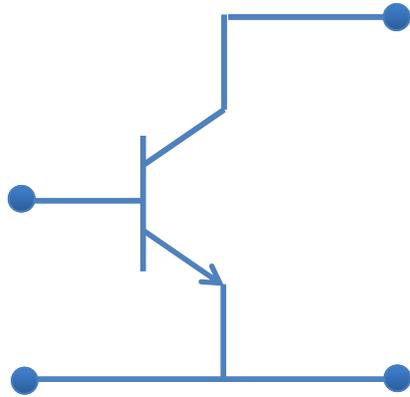
$$= \frac{41.5m \times 2.94k}{1 + 41.5m \times 0.091k} \times 0.909 v_s = \frac{122}{1 + 3.77} \times 0.909 v_s = 23.2$$



27.3dB的同相电压放大

我们总是喜欢简单模型：结论简洁，易于记忆

作业1 理想晶体管



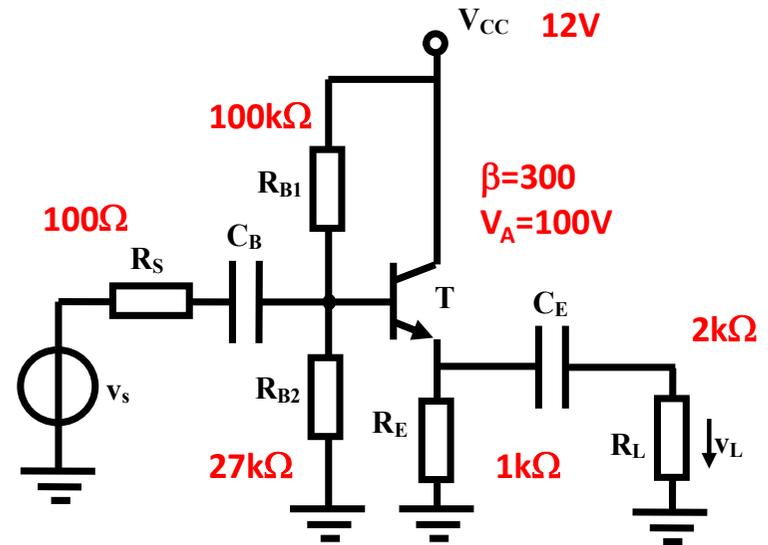
理想晶体管模型为理想压控流源。

- 1) 列写含有串反馈电阻的**CE**组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 2) 列写**CB**组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 3) 列写**CC**组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 4) 前述三个二端口网络，端口**1**对接戴维南源 (v_s , R_s)，端口**2**对接负载电阻 R_L ，分析电压增益 $A_v = v_L / v_s$

作业2

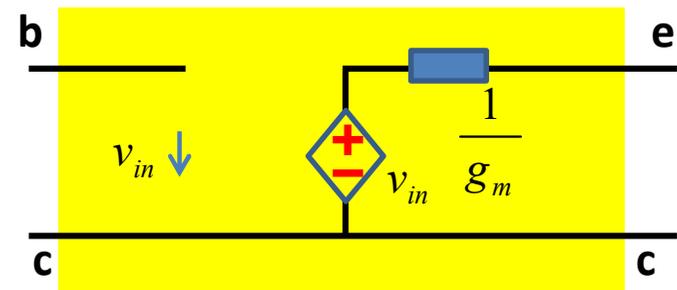
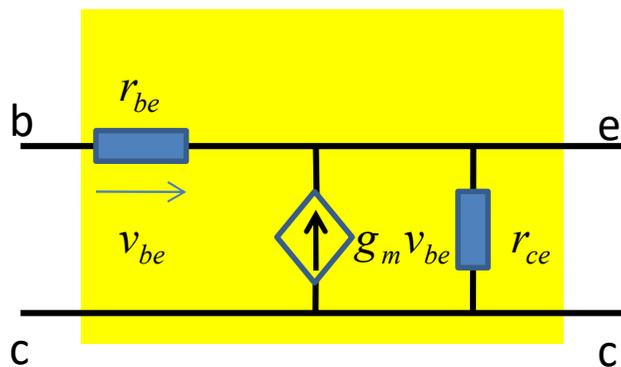
CC组态放大器

- (1) 直流分析
- (2) 交流分析
 - 采用y参量跨导器模型分析
 - 采用CC电压缓冲器模型分析



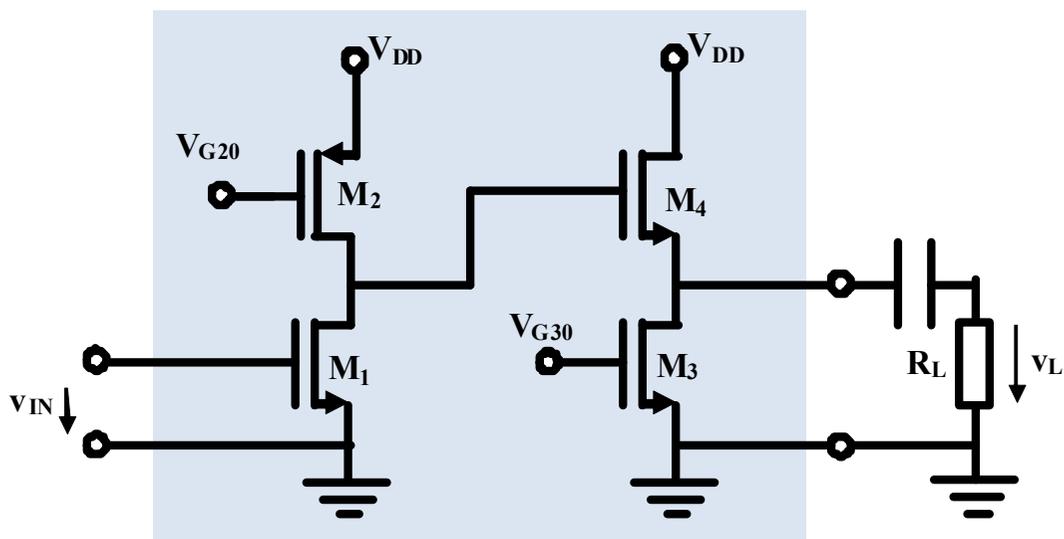
$$A_v = \frac{v_L}{v_S} = ?$$

$$A_i = \frac{i_L}{i_S} = \frac{i_L}{G_S v_S} = ?$$

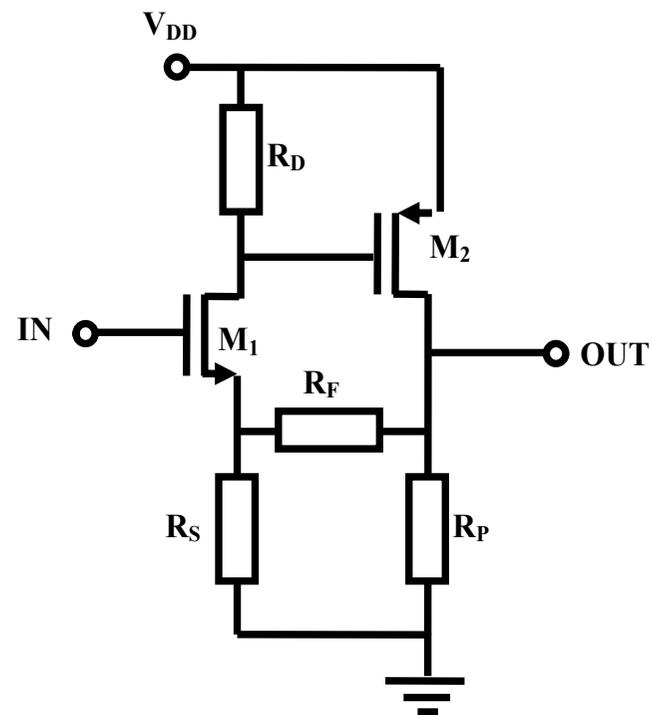


作业3

- 请画出图示电路的交流小信号分析电路模型，求电压放大倍数，输入电阻、输出电阻，及源端到负载端二端口等效电路
 - 假设晶体管工作在恒流区，交流分析用 y 参量微分元件替代
 - 二端口总网络用电压放大器最适 g 参量描述

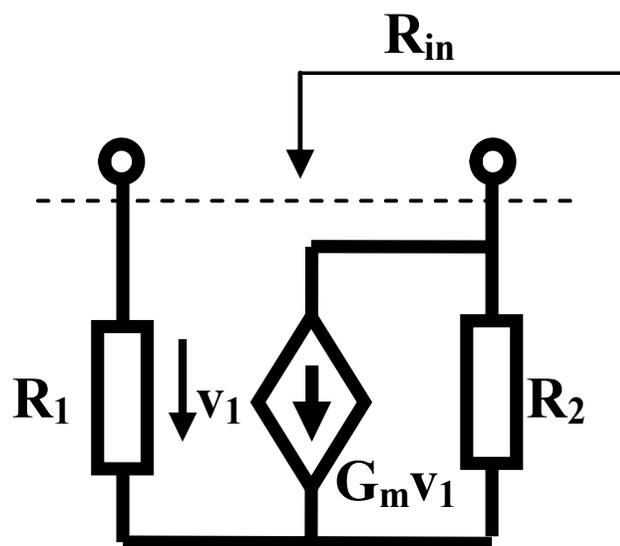


作业4、5



- 4、p20: 三句话说清楚负反馈放大器
 - 数学分析过程和结论
 - 具有将上述数学操作转换为电路操作的能力
- 5、对负反馈放大器分析的具体电路操作
- 习题4.23 一个负反馈放大器的分析：对于如图E4.8.25所示负反馈放大电路。
 - (1) 找到负反馈闭合环路并加以描述，说明闭环上某一点电压的波动，环路一周后其波动被抑制，从而说明这是一个负反馈连接形式。
 - (2) 判定其负反馈连接方式，说明该负反馈连接方式决定的受控源类型，进而获得反馈系数表达式，并给出深度负反馈情况下的闭环增益表达式。
 - (3) 假设两个晶体管在恒流区的交流小信号电路模型为理想压控流源，其跨导增益分别为 g_{m1} 和 g_{m2} ，请给出开环增益表达式。

作业6 bc端等效电阻



用加流求压法证明:

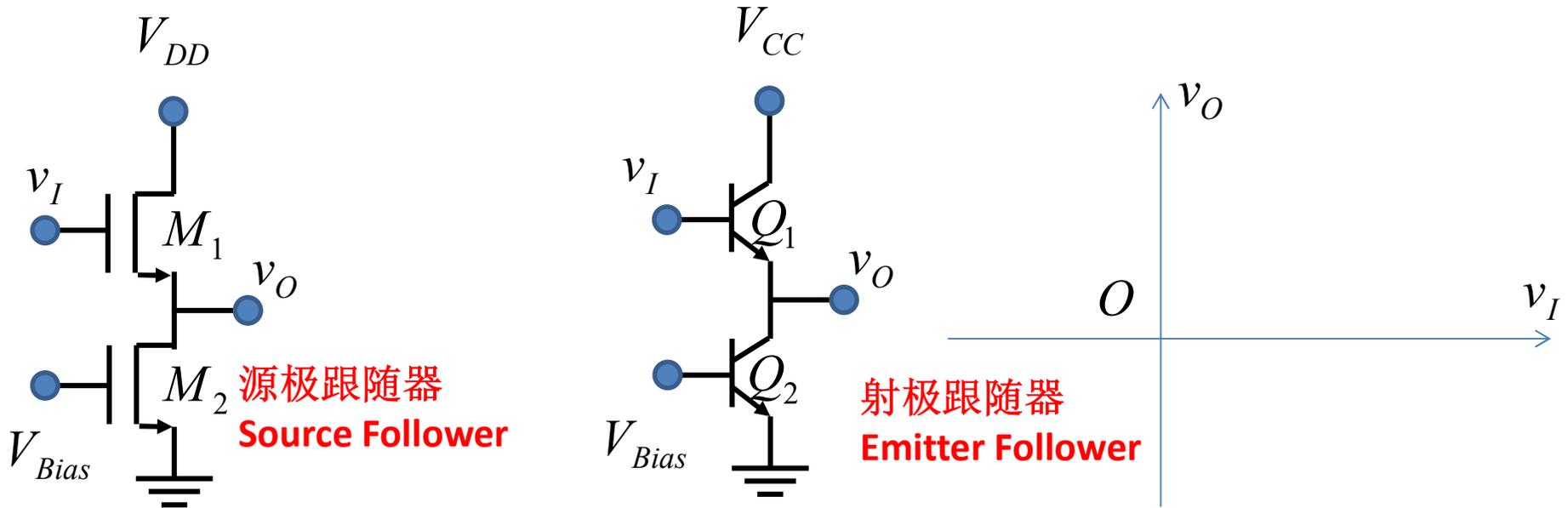
$$R_{in} = R_1 \langle G_m \rangle R_2 = R_1 + R_2 + G_m R_1 R_2$$

对于BJT晶体管, 则有

$$\begin{aligned} r_{bc,in} &= r_{be} \langle g_m \rangle r_{ce} \\ &= r_{be} + r_{ce} + g_m r_{be} r_{ce} \\ &\approx g_m r_{be} r_{ce} \end{aligned}$$

牢记这个结论: 经常会用

作业7 射极跟随器



假设所有晶体管均位于有源区，证明：
$$r_o \approx \frac{1}{g_{m1}}$$

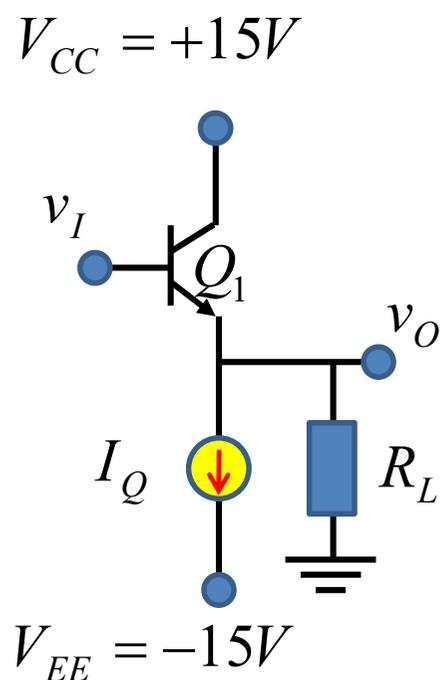
用分段折线模型，分析射极跟随器的输入输出电压转移特性曲线
问输入直流电压为多大时，跟随器线性度最高

作业8

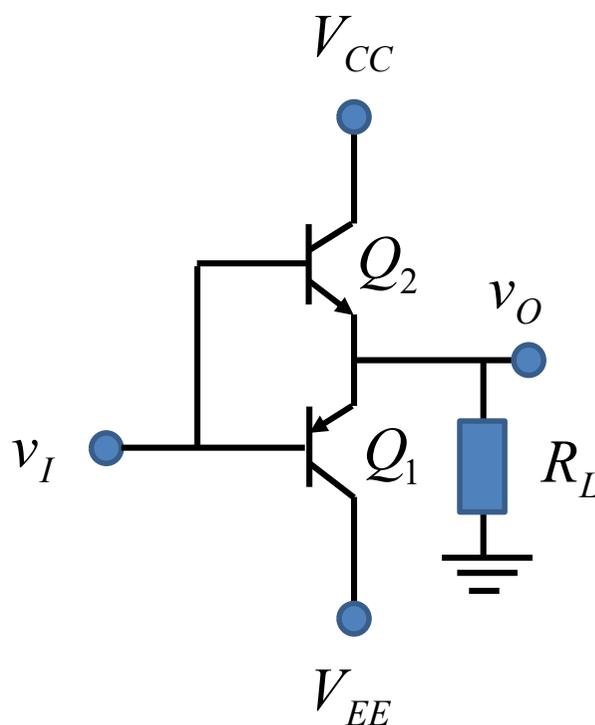
输出级

- 这里有三个转移特性曲线，试分析这三条转移特性曲线分别对应哪种输出级，说明为什么会形成这样的转移特性曲线，并将正确的表达式列写于图上问号位置

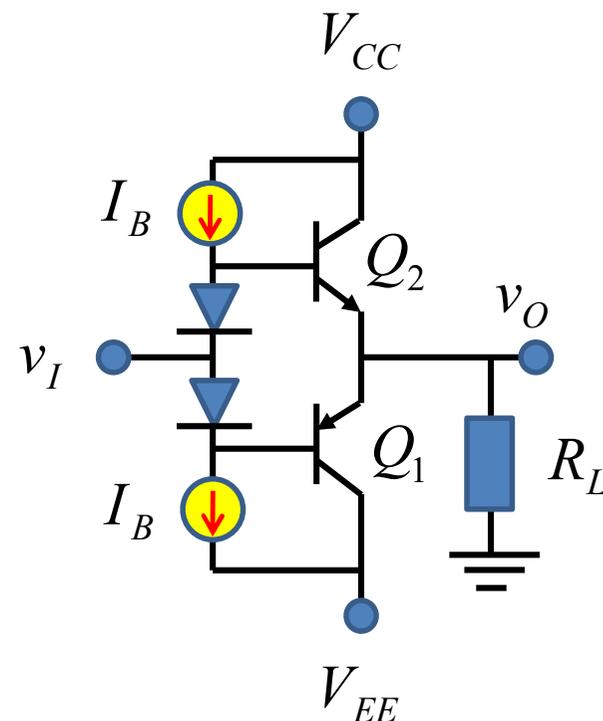
- A类射极跟随器
- B类推挽结构
- AB类推挽结构



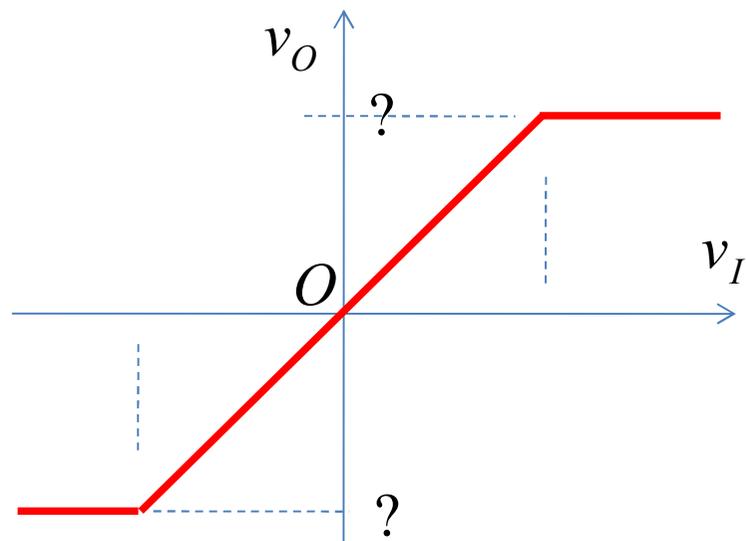
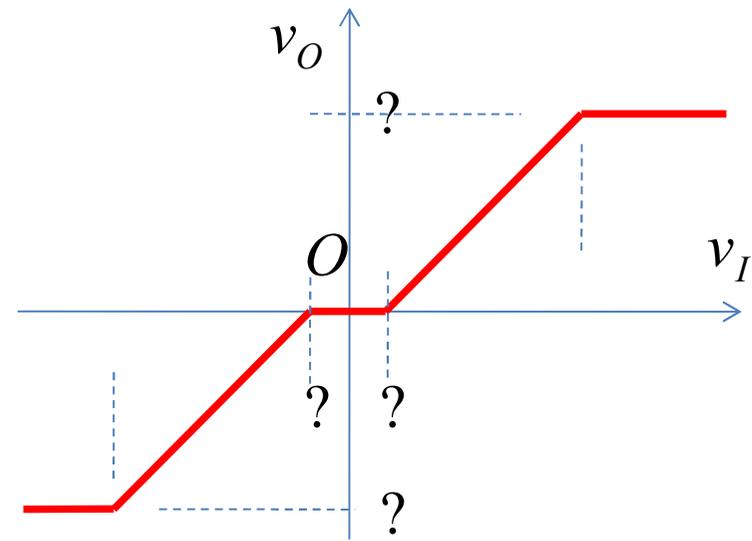
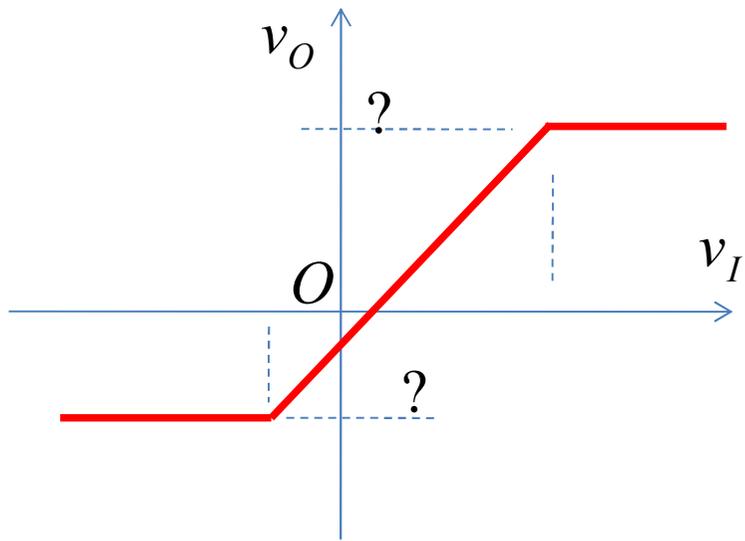
A类射极跟随器



B类推挽



AB类推挽



CAD作业

- 对作业8进行仿真，给出输入输出转移特性曲线，和理论分析结果进行比对
 - 库中如果没有BJT，选用MOS，思考如何给出AB类的微微导通偏置电压？