

# 电子电路与系统基础I

理论课第六讲 等效电路法：线性二端口网络

（二端口网络的加压-加流测量法与戴维南-诺顿定理）

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# 二端口网络 Two-Port Network

- 二端口网络是电路中最常见的网络
  - 单入单出信号处理系统的基本模型
    - 一个输入端口，一个输出端口：激励信号或能量自输入端口进入，经二端口网络处理后自输出端口输出，形成对后级电路的激励

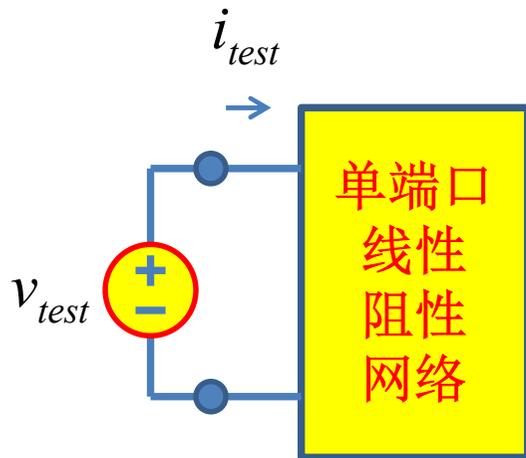


不做特别说明时，一般默认端口1为输入端口，端口2为输出端口

# 二端口线性网络等效电路法 大纲

- 加压求流/加流求压法
    - 从单端口网络等效到二端口网络等效
  - 二端口网络参量
    - 阻抗参量 $z$
    - 导纳参量 $y$
    - 混合参量 $h$
    - 逆混参量 $g$
    - 传输参量 $ABCD$ 
      - 逆传参量 $abcd$
  - 二端口网络连接分析
  - 传递函数分析
- 用加压-加流测量方法求线性二端口网络的等效电路
- 获得二端口线性网络的戴维南-诺顿定理

# 一、单端口网络等效基本方法

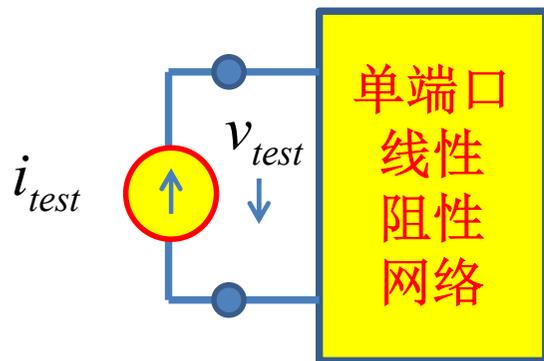
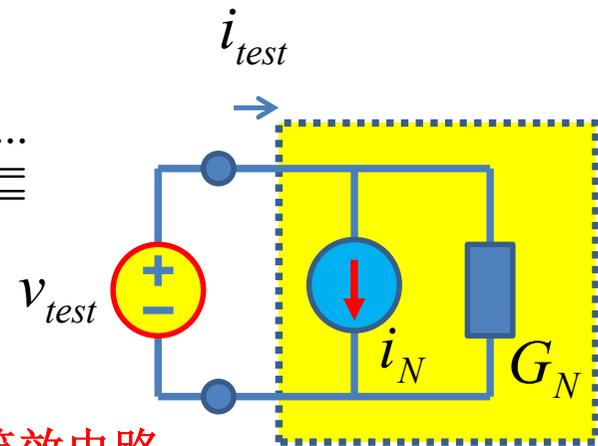


加压求流

$$i_{test} = \alpha_v \cdot v_{test} + \beta_v \cdot v_{s1} + \gamma_v \cdot i_{s2} + \dots$$

$$= G_N \cdot v_{test} + i_N$$

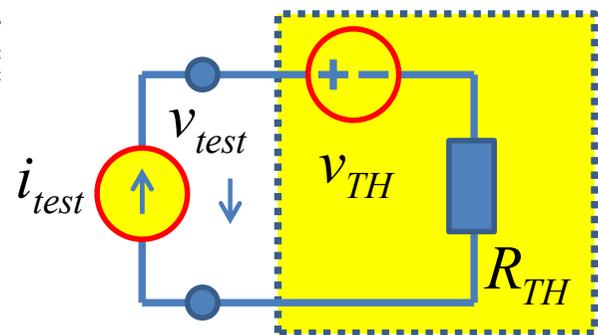
加压测试获得压控形式的等效电路  
加流测试获得流控形式的等效电路



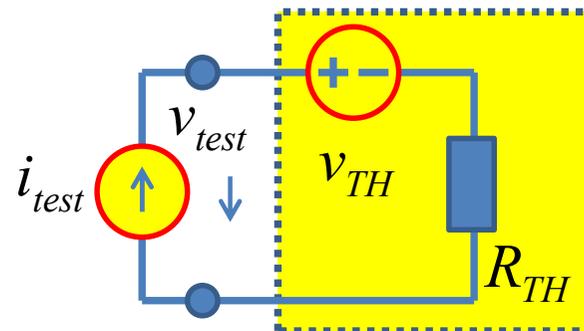
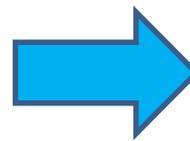
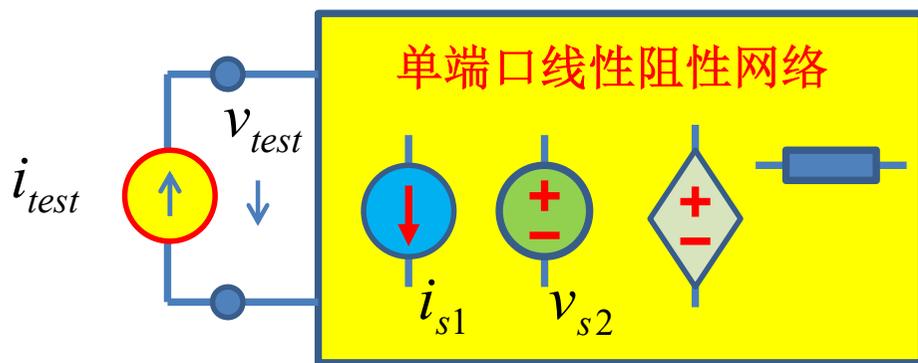
加流求压

$$v_{test} = \alpha_i \cdot i_{test} + \beta_i \cdot v_{s1} + \gamma_i \cdot i_{s2} + \dots$$

$$= R_{TH} \cdot i_{test} + v_{TH}$$



# 戴维南等效参量的含义



$$v_{test} = \alpha \cdot i_{test} + \lambda_1 \cdot i_{s1} + \lambda_2 \cdot v_{s2} + \dots$$

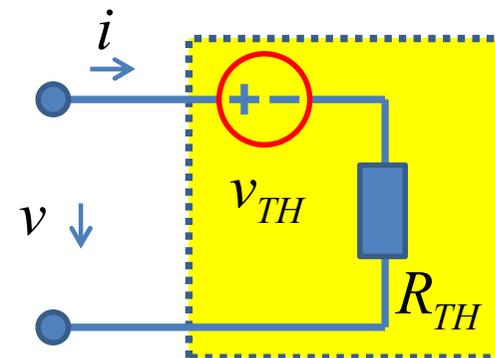
$$= R_{TH} \cdot i_{test} + v_{TH}$$

戴维南定理:

- (1) 端口开路电压  $v_{TH}$  为网络内部独立源在端口的表现
- (2)  $R_{TH}$  为网络内部独立源置零时的输入电阻

$$v_{TH} = v_{test} \Big|_{i_{test}=0}$$

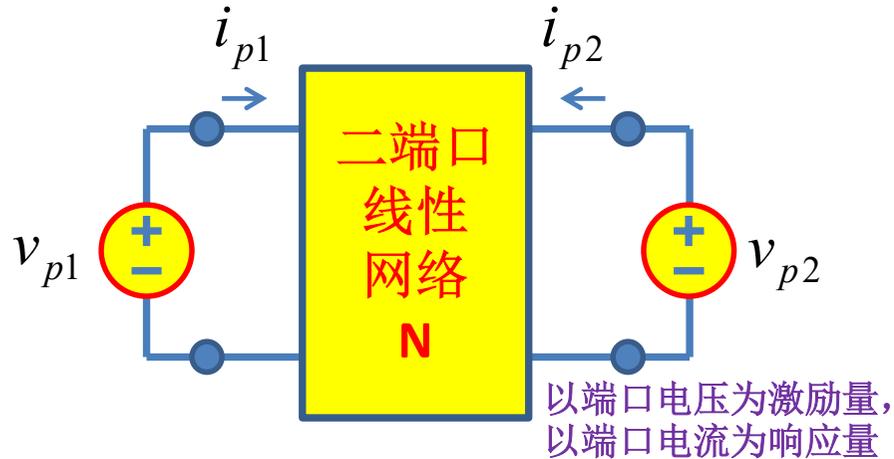
$$R_{TH} = \frac{v_{test}}{i_{test}} \Big|_{v_{TH}=0}$$



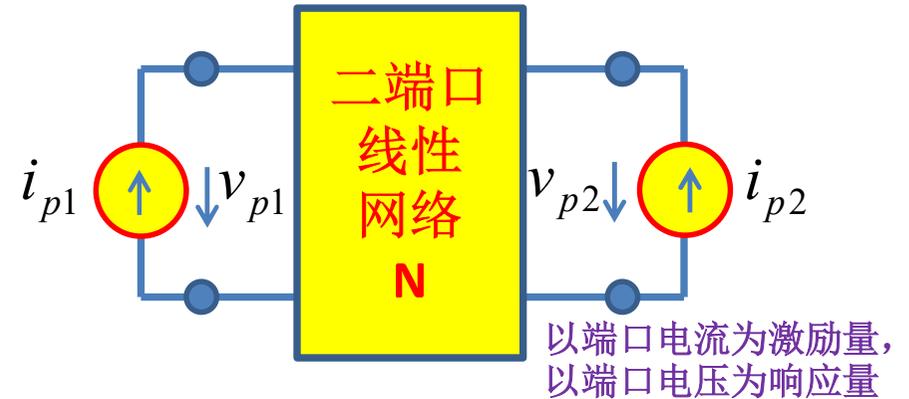
$$v = R_{TH} \cdot i + v_{TH}$$

# 端口加压、加流方法

## 对二端口网络的测量：4种基本测量手段

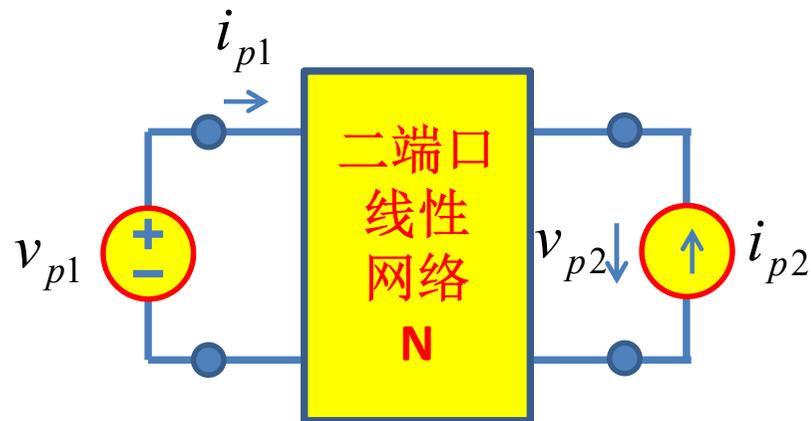


两个端口同时加独立变化的测试电压

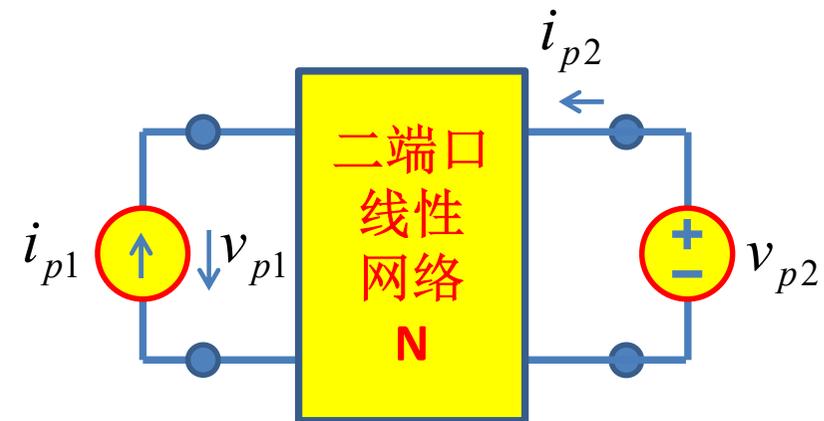


两个端口同时加独立变化的测试电流

端口1加测试电压同时端口2加测试电流

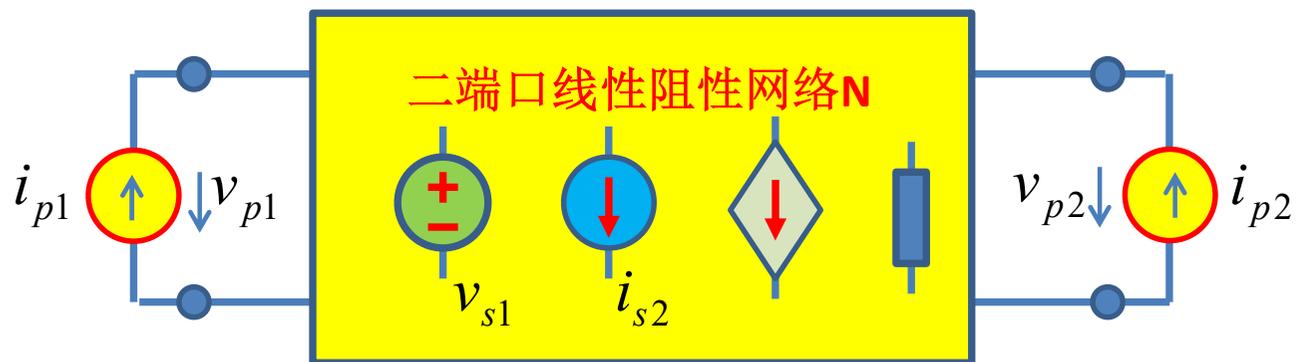


端口1加测试电流同时端口2加测试电压



## 2.1

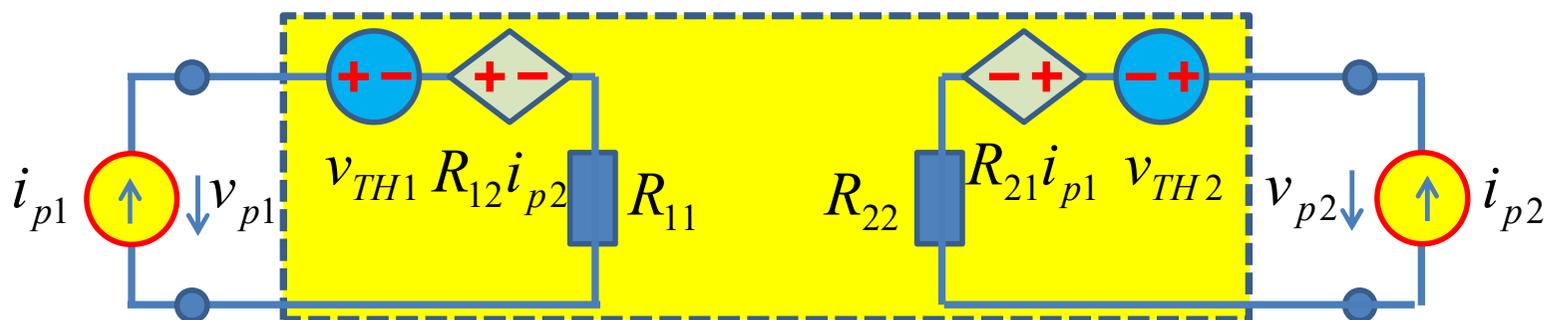
# 两个端口同时加流测试



$$v_{p1} = \alpha_{11}i_{p1} + \alpha_{12}i_{p2} + \lambda_{11}v_{s1} + \lambda_{12}i_{s2} + \dots = R_{11}i_{p1} + R_{12}i_{p2} + v_{TH1}$$

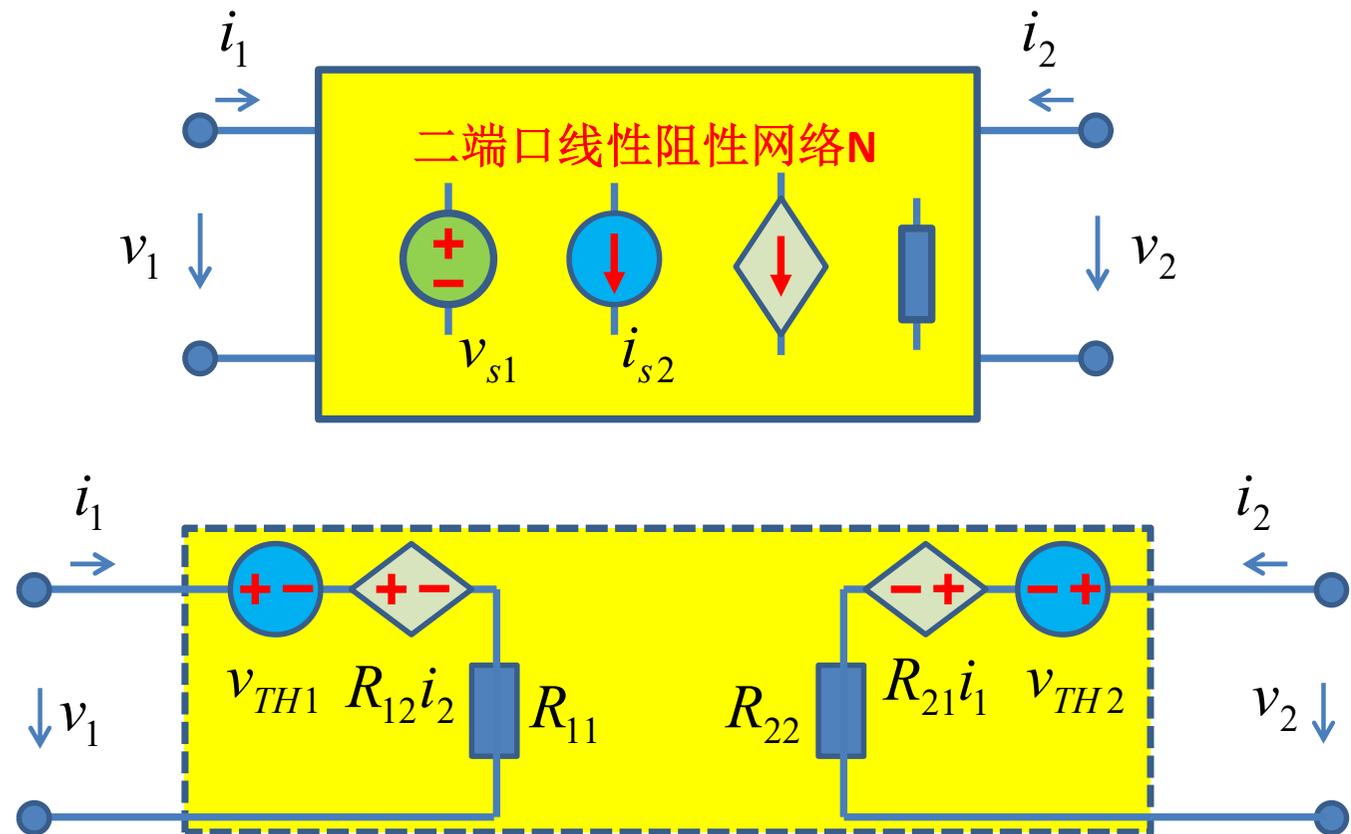
叠加定理

$$v_{p2} = \alpha_{21}i_{p1} + \alpha_{22}i_{p2} + \lambda_{21}v_{s1} + \lambda_{22}i_{s2} + \dots = R_{21}i_{p1} + R_{22}i_{p2} + v_{TH2}$$



两个端口同时加流测量：阻抗参量，电阻参量

# 二端口线性网络的戴维南等效电路



$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

阻抗参量: impedance parameters

$\mathbf{v} = \mathbf{z} \cdot \mathbf{i} + \mathbf{v}_{TH}$       二端口网络的戴维南定理

$v = R_{TH} \cdot i + v_{TH}$       单端口网络的戴维南定理

# 二端口线性网络的戴维南等效参量

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

$$v_1 = R_{11}i_1 + R_{12}i_2 + v_{TH1}$$

$$v_2 = R_{21}i_1 + R_{22}i_2 + v_{TH2}$$

$$v_{TH1} = v_1 \Big|_{i_1=0, i_2=0}$$

端口1开路，端口2开路，端口1的开路电压

$$v_{TH2} = v_2 \Big|_{i_1=0, i_2=0}$$

端口1开路，端口2开路，端口2的开路电压

$$R_{11} = \frac{v_1}{i_1} \Big|_{i_2=0, v_{TH1}=0}$$

内部独立源置零  
端口2开路  
端口1看入电阻

$$R_{12} = \frac{v_1}{i_2} \Big|_{i_1=0, v_{TH1}=0}$$

内部独立源置零  
端口2电流对端口1  
开路电压的线性跨  
阻控制系数

输出端口对输入端口的反馈，有时可能起关键作用

$$R_{21} = \frac{v_2}{i_1} \Big|_{i_2=0, v_{TH2}=0}$$

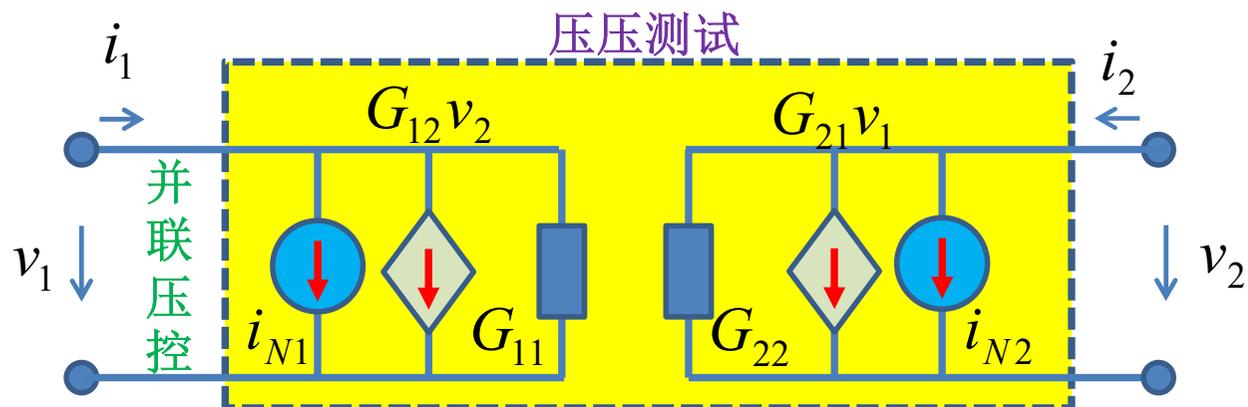
内部独立源置零  
端口1电流对端口2  
开路电压的线性跨  
阻控制系数

$$R_{22} = \frac{v_2}{i_2} \Big|_{i_1=0, v_{TH2}=0}$$

内部独立源置零  
端口1开路  
端口2看入电阻

1为输入端口，2为输出端口，最感兴趣的参量：代表了二端口网络处理器的功能：将输入电流转换为输出开路电压：跨阻传递系数

# 导纳、混合、逆混参量

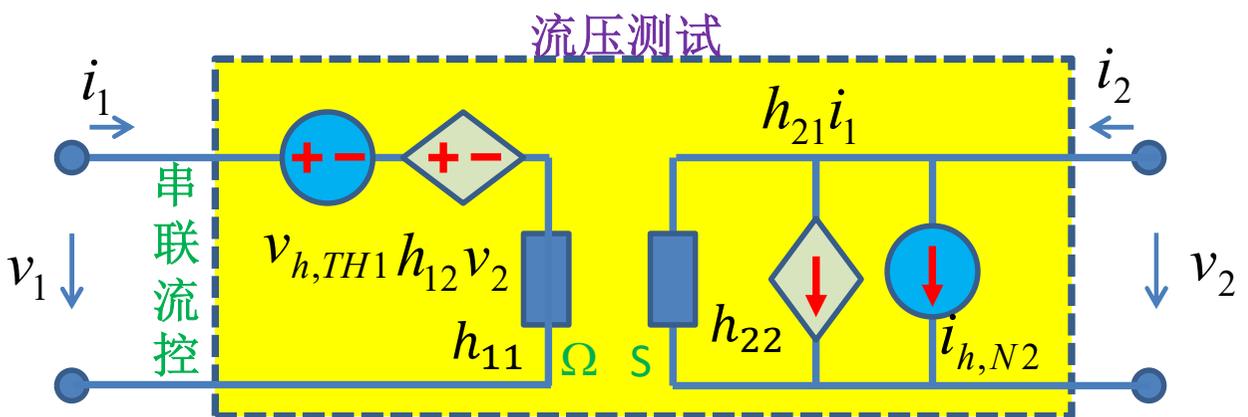


导纳参量: admittance parameters

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} i_{N1} \\ i_{N2} \end{bmatrix}$$

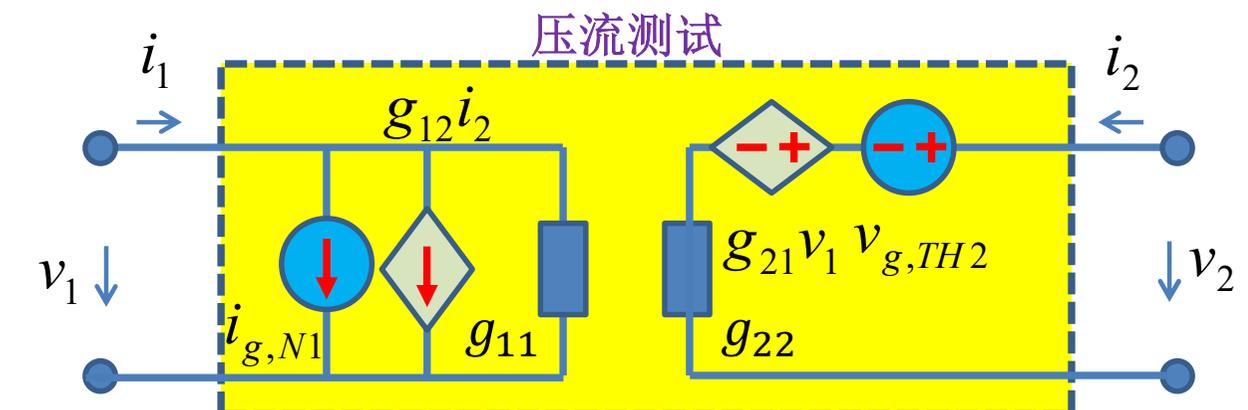
$\mathbf{i} = \mathbf{y} \cdot \mathbf{v} + \mathbf{i}_N$   
二端口网络的诺顿定理

$i = G_N \cdot v + i_N$   
单端口网络的诺顿定理



混合参量: hybrid parameters

$$\begin{bmatrix} v_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} v_{h,TH1} \\ i_{h,N2} \end{bmatrix}$$



逆混参量  
inverse hybrid parameters

$$\begin{bmatrix} i_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} i_{g,N1} \\ v_{g,TH2} \end{bmatrix}$$

# 两端口同时加压、加流测量参量

- 单端口线性网络

- 加流：流控表述：戴维南等效参量 ( $\mathbf{v}_{TH}$ ,  $\mathbf{R}_{TH}$ )
- 加压：压控表述：诺顿等效参量 ( $\mathbf{i}_N$ ,  $\mathbf{G}_N$ )

$$R_{TH} = G_N^{-1}$$

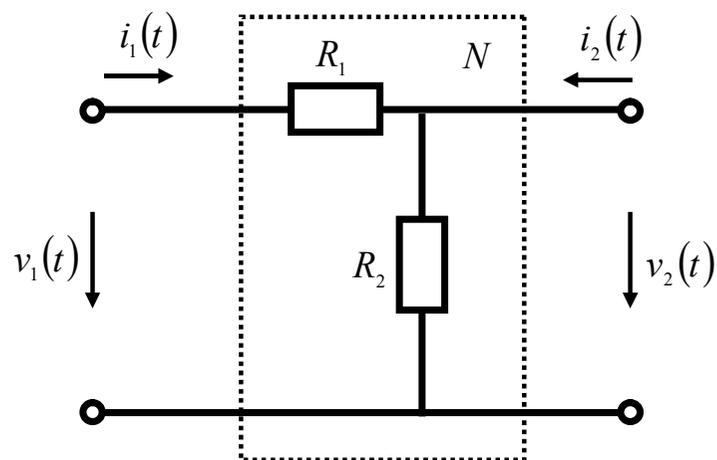
- 二端口线性网络

- **1**端口加流同时**2**端口加流：阻抗参量 $\mathbf{z}$
- **1**端口加压同时**2**端口加压：导纳参量 $\mathbf{y}$
- **1**端口加流同时**2**端口加压：混合参量 $\mathbf{h}$
- **1**端口加压同时**2**端口加流：逆混参量 $\mathbf{g}$

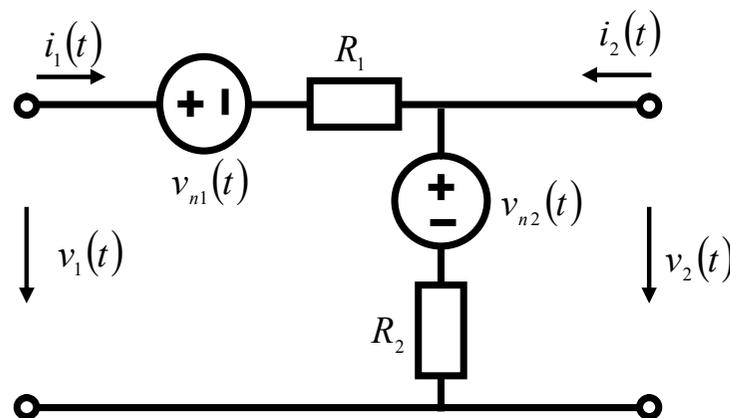
$$\mathbf{z} = \mathbf{y}^{-1}$$

$$\mathbf{h} = \mathbf{g}^{-1}$$

# 线性二端口网络等效电路例



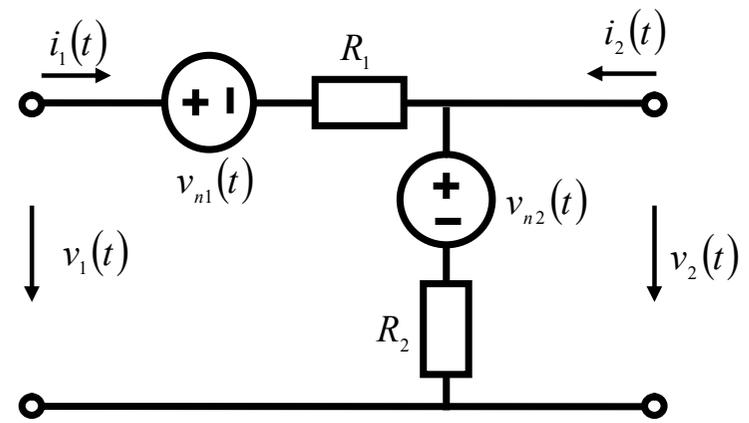
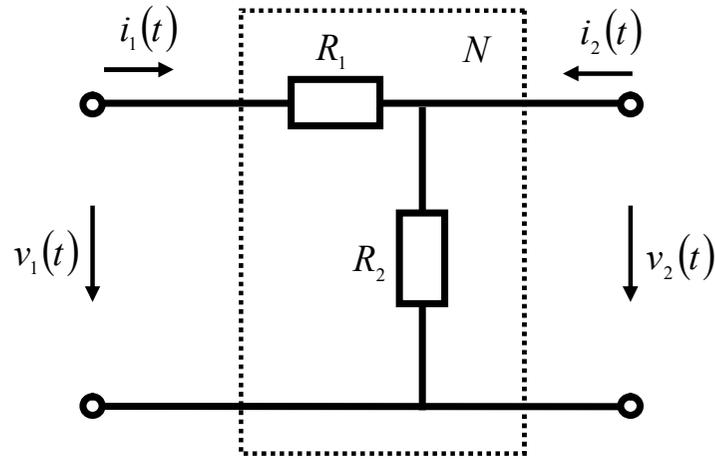
电阻网络



如果处理的信号比较微弱，  
则需考虑噪声影响

**z参量：戴维南等效：两个端口电流表述两个端口电压，测试电流为0则开路**

$$\begin{aligned}
 v_{TH1} &= v_1 \Big|_{i_1=0, i_2=0} = v_{n1} + v_{n2} & \overline{v_{n1}^2} &= 4kTR_1\Delta f & \overline{v_{TH1}^2} &= 4kT(R_1 + R_2)\Delta f \\
 v_{TH2} &= v_2 \Big|_{i_1=0, i_2=0} = v_{n2} & \overline{v_{n2}^2} &= 4kTR_2\Delta f & \overline{v_{TH2}^2} &= 4kTR_2\Delta f
 \end{aligned}$$



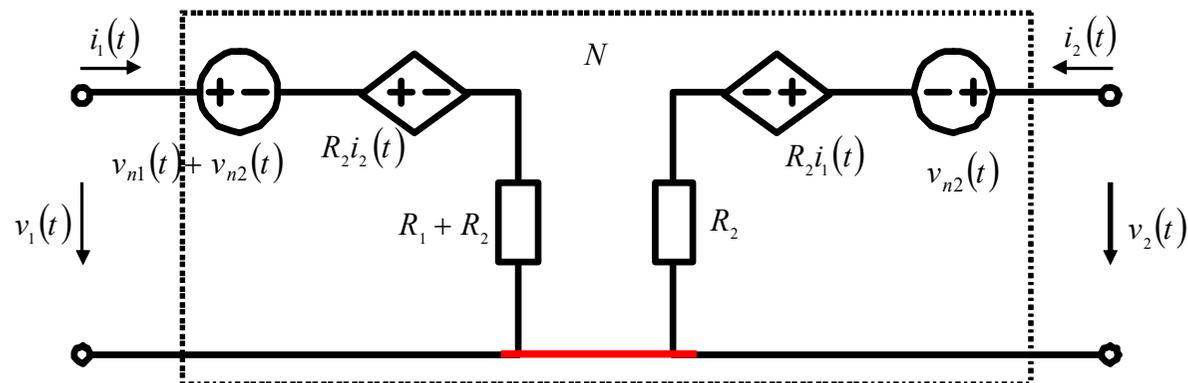
$$R_{11} = \left. \frac{v_1}{i_1} \right|_{i_2=0, v_{TH1}=0} = R_1 + R_2$$

$$R_{12} = \left. \frac{v_1}{i_2} \right|_{i_1=0, v_{TH1}=0} = R_2$$

$$R_{21} = \left. \frac{v_2}{i_1} \right|_{i_2=0, v_{TH2}=0} = R_2$$

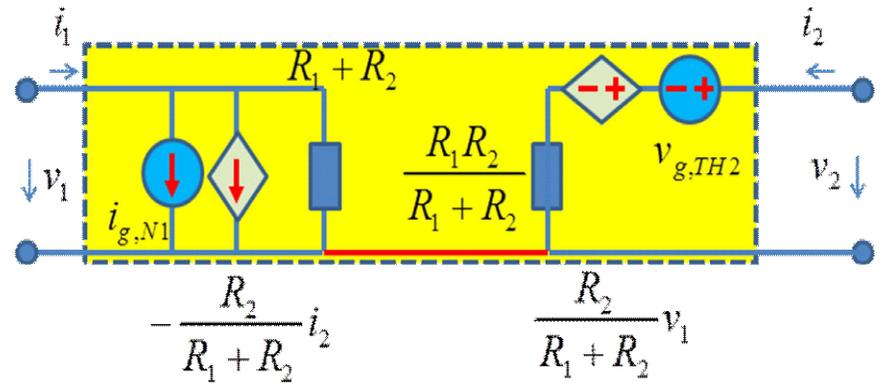
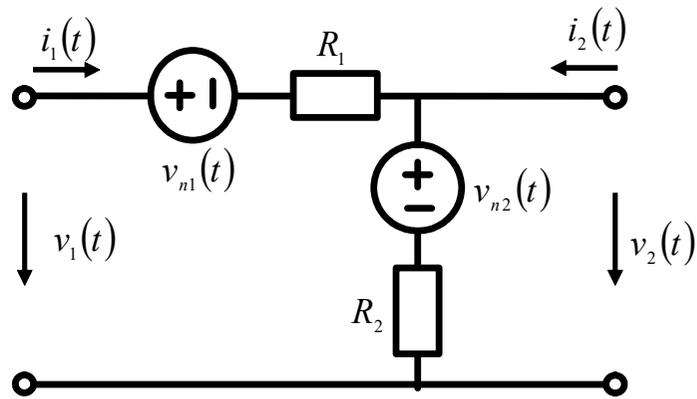
$$R_{22} = \left. \frac{v_2}{i_2} \right|_{i_1=0, v_{TH2}=0} = R_2$$

端口1等效噪声电压为端口1输入电阻产生的热噪声电压



端口2等效噪声电压为端口2输出电阻产生的热噪声电压：无源网络的热噪声分析均有此结论 <sup>13</sup>

诺顿戴维南等效物理意义更明确



端口1为输出则为对端口2电流的分流：分流器

$$\begin{bmatrix} i_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{R_1 + R_2} & -\frac{R_2}{R_1 + R_2} \\ \frac{R_2}{R_1 + R_2} & \frac{R_1 R_2}{R_1 + R_2} \end{bmatrix} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} -\frac{v_{n1} + v_{n2}}{R_1 + R_2} \\ \frac{R_1}{R_1 + R_2} v_{n2} - \frac{R_2}{R_1 + R_2} v_{n1} \end{bmatrix}$$

端口2为输出则为对端口1电压的分压：分压器

端口1等效噪声电流为端口1输入电导产生热噪声电流

$$\overline{i_{n,g,N}^2} = \overline{\left( -\frac{v_{n1} + v_{n2}}{R_1 + R_2} \right)^2} = \frac{\overline{v_{n1}^2} + \overline{v_{n2}^2}}{(R_1 + R_2)^2} = \frac{4kTR_1 \Delta f + 4kTR_2 \Delta f}{(R_1 + R_2)^2} = 4kT \frac{1}{R_1 + R_2} \Delta f = 4kT G_{in} \Delta f$$

端口2等效噪声电压为端口2看入电阻产生的热噪声电压

$$\overline{v_{n,g,TH}^2} = \overline{\left( \frac{R_1}{R_1 + R_2} v_{n2} - \frac{R_2}{R_1 + R_2} v_{n1} \right)^2} = \left( \frac{R_1}{R_1 + R_2} \right)^2 4kTR_2 \Delta f + \left( \frac{R_2}{R_1 + R_2} \right)^2 4kTR_1 \Delta f = 4kT \frac{R_1 R_2}{R_1 + R_2} \Delta f = 4kT R_{out} \Delta f$$

假设  
网络  
内部  
无独  
立源

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$

跨阻增益

可画  
出等  
效电  
路的  
四个  
网络  
参量

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

跨导增益

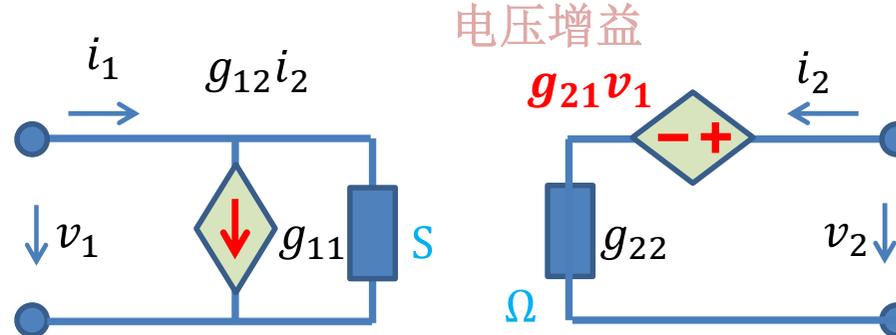
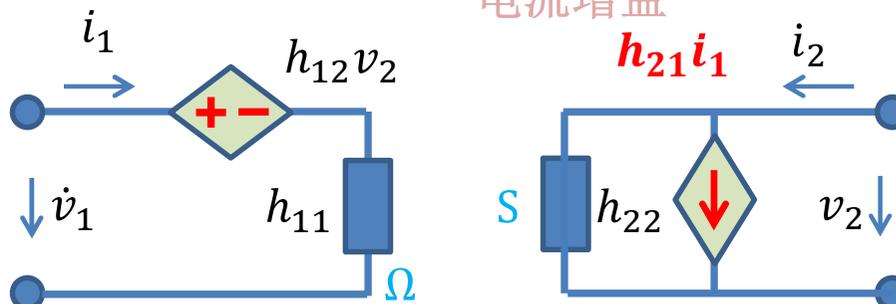
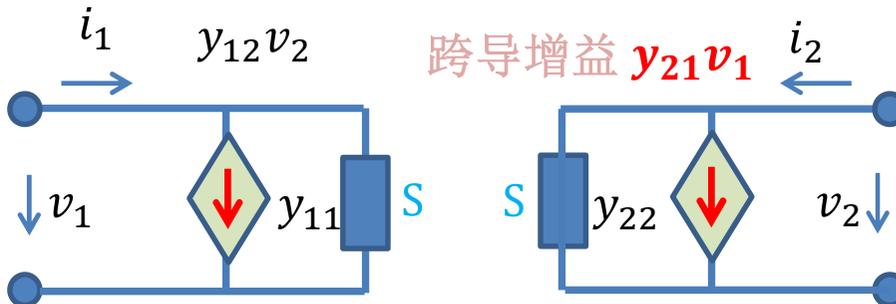
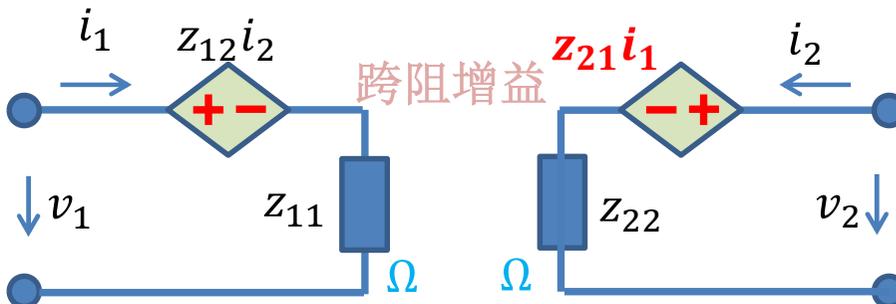
$$\begin{bmatrix} v_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ v_2 \end{bmatrix}$$

电流增益

记忆  
定义

$$\begin{bmatrix} i_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix}$$

电压增益



# 网络参量的6种表述方式

- 由于端口电压、端口电流可以任取两个作为自变量，剩下两个作为因变量，因而线性二端口网络有**6种**表述，**z、y、g、h**只是其中端口同时加压、加流获得的测量参量，还有两种不是端口同时加压、加流测量参量，而是一个端口加压加流获得的传输参量

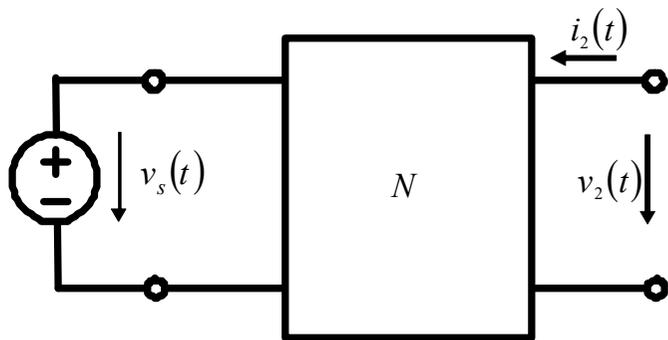
$$C_4^2 = 6$$

$v_1$   
 $v_2$   
 $i_1$   
 $i_2$

因变量	自变量	二端口网络参量
$v_1, v_2$	$i_1, i_2$	<b>z</b>
$i_1, i_2$	$v_1, v_2$	<b>y</b>
$v_1, i_2$	$i_1, v_2$	<b>h</b>
$i_1, v_2$	$v_1, i_2$	<b>g</b>
$v_1, i_1$	$v_2, i_2$	<b>ABCD T</b>
$v_2, i_2$	$v_1, i_1$	<b>abcd t</b>

## 2.5 传输参量：单端加压加流测试

先假设内部独立源都置零：内部独立电压源短路，内部独立电流源开路



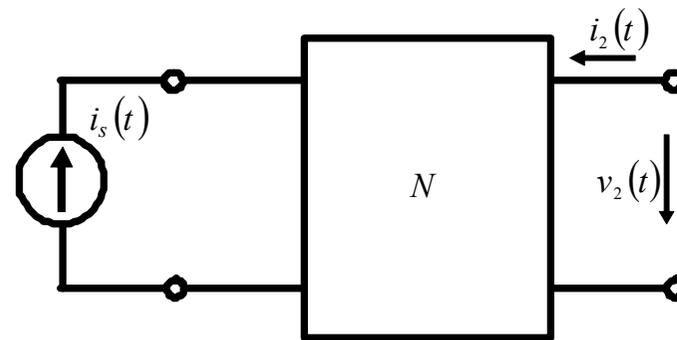
端口1加测试电压  
对端口2进行测量

端口2开路电压：电压传递系数

$$g_{21} = \frac{v_2}{v_1} \Big|_{i_2=0, \text{内部独立源置零}}$$

端口2短路电流：跨导传递系数

$$y_{21} = \frac{i_2}{v_1} \Big|_{v_2=0, \text{内部独立源置零}}$$



端口1加测试电流  
对端口2进行测量

端口2开路电压：跨阻传递系数

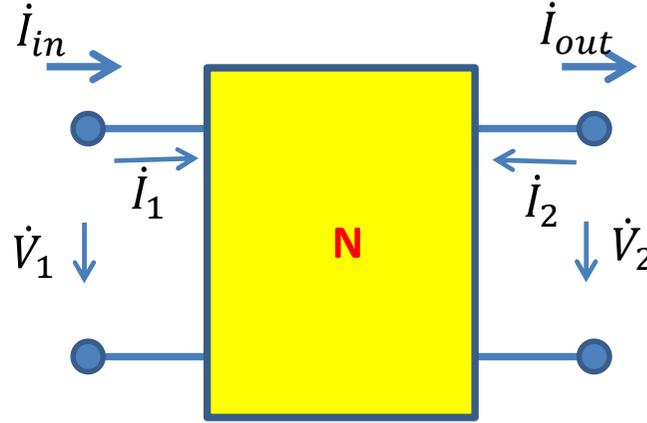
$$z_{21} = \frac{v_2}{i_1} \Big|_{i_2=0, \text{内部独立源置零}}$$

端口2短路电流：电流传递系数

$$h_{21} = \frac{i_2}{i_1} \Big|_{v_2=0, \text{内部独立源置零}}$$

# 传输参量

内部独立源已置零



$$A_{v0} = \left. \frac{v_{out}}{v_{in}} \right|_{i_{out} = 0} = g_{21}$$

本征电压增益

$$G_{m0} = \left. \frac{i_{out}}{v_{in}} \right|_{v_{out} = 0} = -y_{21}$$

本征跨导增益

$$R_{m0} = \left. \frac{v_{out}}{i_{in}} \right|_{i_{out} = 0} = z_{21}$$

本征跨阻增益

$$A_{i0} = \left. \frac{i_{out}}{i_{in}} \right|_{v_{out} = 0} = -h_{21}$$

本征电流增益

$$v_1 = Av_2 - Bi_2$$

$$A = \left. \frac{v_1}{v_2} \right|_{i_2 = 0} = \left. \frac{1}{\frac{v_2}{v_1}} \right|_{i_2 = 0} = \frac{1}{g_{21}}$$

端口2已经开路，激励源只能在端口1

$$B = \left. \frac{v_1}{-i_2} \right|_{v_2 = 0} = \left. \frac{1}{-\frac{i_2}{v_1}} \right|_{v_2 = 0} = \frac{1}{-y_{21}}$$

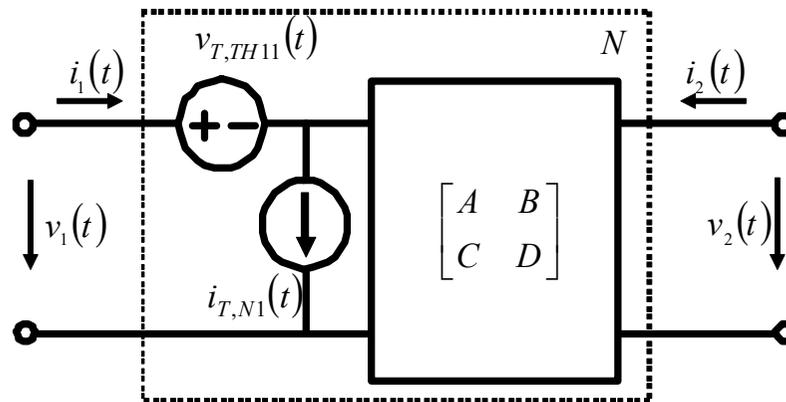
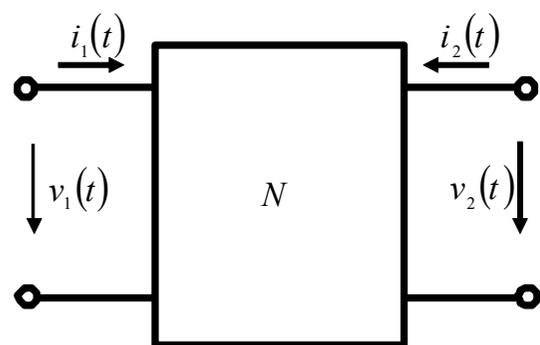
端口2已经短路，激励源只能在端口1

$$\begin{bmatrix} v_{in} \\ i_{in} \end{bmatrix} = \begin{bmatrix} v_1 \\ i_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{g_{21}} & \frac{1}{-y_{21}} \\ 1 & 1 \\ \frac{1}{z_{21}} & -h_{21} \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{A_{v0}} & \frac{1}{G_{m0}} \\ 1 & 1 \\ \frac{1}{R_{m0}} & \frac{1}{A_{i0}} \end{bmatrix} \begin{bmatrix} v_{out} \\ i_{out} \end{bmatrix}$$

形式上是用  $v_2, i_2$  表述  $v_1, i_1$ ，传输参量表述的其实是端口1到端口2的传输系数或本征增益

自变量在端口2，但激励量却是在端口1的测量方式：传输参量测量

# 传输参量的输入端口源等效



$$\begin{bmatrix} v_1 \\ i_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix} + \begin{bmatrix} v_{T,TH1} \\ i_{T,N1} \end{bmatrix}$$

$$v_1 = Av_2 - Bi_2 + v_{T,TH1}$$

$$i_1 = Cv_2 - Di_2 + i_{T,N1}$$

## Transmission Parameters

无法用电路元件描述，但 **ABCD** 参量包含了该二端口网络的所有端口信息，和 **z**、**y**、**h**、**g** 可以相互转换

端口**1**短路，端口**2**开路电压除以本征电压增益，折合到输入端的等效源电压

端口**1**开路，端口**2**开路电压除以本征跨阻增益，折合到输入端的等效源电流

$$v_{T,TH1} = -Av_2 \Big|_{v_1=0, i_2=0} = \frac{v_2 \Big|_{v_1=0, i_2=0}}{-A_{v0}}$$

$$i_{N1} = -Cv_2 \Big|_{i_1=0, i_2=0} = \frac{v_2 \Big|_{i_1=0, i_2=0}}{-R_{m0}}$$

# 传输参量 逆传参量



假设内部无独立源

$$\begin{bmatrix} v_1 \\ i_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix}$$

$$\begin{bmatrix} v_2 \\ i_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} v_1 \\ -i_1 \end{bmatrix}$$

abcd参量几乎没用

$$A = \left. \frac{v_1}{v_2} \right|_{i_2=0} \quad B = \left. \frac{v_1}{-i_2} \right|_{v_2=0}$$

$$a = \left. \frac{v_2}{v_1} \right|_{i_1=0} \quad b = \left. \frac{v_2}{-i_1} \right|_{v_1=0}$$

$$C = \left. \frac{i_1}{v_2} \right|_{i_2=0} \quad D = \left. \frac{i_1}{-i_2} \right|_{v_2=0}$$

$$c = \left. \frac{i_2}{v_1} \right|_{i_1=0} \quad d = \left. \frac{i_2}{-i_1} \right|_{v_1=0}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} A & -B \\ -C & D \end{bmatrix}^{-1}$$

测出任意一个网络参量，就代表了网络的端口特性，其他网络参量均可知

	<b>z</b>	<b>y</b>	<b>h</b>	<b>g</b>	<b>ABCD</b>	<b>abcd</b>
<b>z</b>	$\begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix}$	$\frac{1}{\Delta_y} \begin{bmatrix} y_{22} & -y_{12} \\ -y_{21} & y_{11} \end{bmatrix}$	$\frac{1}{h_{22}} \begin{bmatrix} \Delta_h & h_{12} \\ -h_{21} & 1 \end{bmatrix}$	$\frac{1}{g_{11}} \begin{bmatrix} 1 & -g_{12} \\ g_{21} & \Delta_g \end{bmatrix}$	$\frac{1}{C} \begin{bmatrix} A & \Delta_T \\ 1 & D \end{bmatrix}$	$\frac{1}{c} \begin{bmatrix} d & 1 \\ \Delta_t & a \end{bmatrix}$
<b>y</b>	$\frac{1}{\Delta_z} \begin{bmatrix} z_{22} & -z_{12} \\ -z_{21} & z_{11} \end{bmatrix}$	$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix}$	$\frac{1}{h_{11}} \begin{bmatrix} 1 & -h_{12} \\ h_{21} & \Delta_h \end{bmatrix}$	$\frac{1}{g_{22}} \begin{bmatrix} \Delta_g & g_{12} \\ -g_{21} & 1 \end{bmatrix}$	$\frac{1}{B} \begin{bmatrix} D & -\Delta_T \\ -1 & A \end{bmatrix}$	$\frac{1}{b} \begin{bmatrix} a & -1 \\ -\Delta_t & d \end{bmatrix}$
<b>h</b>	$\frac{1}{z_{22}} \begin{bmatrix} \Delta_z & z_{12} \\ -z_{21} & 1 \end{bmatrix}$	$\frac{1}{y_{11}} \begin{bmatrix} 1 & -y_{12} \\ y_{21} & \Delta_y \end{bmatrix}$	$\begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$	$\frac{1}{\Delta_g} \begin{bmatrix} g_{22} & -g_{12} \\ -g_{21} & g_{11} \end{bmatrix}$	$\frac{1}{D} \begin{bmatrix} B & \Delta_T \\ -1 & C \end{bmatrix}$	$\frac{1}{a} \begin{bmatrix} b & 1 \\ -\Delta_t & c \end{bmatrix}$
<b>g</b>	$\frac{1}{z_{11}} \begin{bmatrix} 1 & -z_{12} \\ z_{21} & \Delta_z \end{bmatrix}$	$\frac{1}{y_{22}} \begin{bmatrix} \Delta_y & y_{12} \\ -y_{21} & 1 \end{bmatrix}$	$\frac{1}{\Delta_h} \begin{bmatrix} h_{22} & -h_{12} \\ -h_{21} & h_{11} \end{bmatrix}$	$\begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix}$	$\frac{1}{A} \begin{bmatrix} C & -\Delta_T \\ 1 & B \end{bmatrix}$	$\frac{1}{d} \begin{bmatrix} c & -1 \\ \Delta_t & b \end{bmatrix}$
<b>AB CD</b>	$\frac{1}{z_{21}} \begin{bmatrix} z_{11} & \Delta_z \\ 1 & z_{22} \end{bmatrix}$	$-\frac{1}{y_{21}} \begin{bmatrix} y_{22} & 1 \\ \Delta_y & y_{11} \end{bmatrix}$	$-\frac{1}{h_{21}} \begin{bmatrix} \Delta_h & h_{11} \\ h_{22} & 1 \end{bmatrix}$	$\frac{1}{g_{21}} \begin{bmatrix} 1 & g_{22} \\ g_{11} & \Delta_g \end{bmatrix}$	$\begin{bmatrix} A & B \\ C & D \end{bmatrix}$	$\frac{1}{\Delta_t} \begin{bmatrix} d & b \\ c & a \end{bmatrix}$
<b>abcd</b>	$\frac{1}{z_{12}} \begin{bmatrix} z_{22} & \Delta_z \\ 1 & z_{11} \end{bmatrix}$	$-\frac{1}{y_{12}} \begin{bmatrix} y_{11} & 1 \\ \Delta_y & y_{22} \end{bmatrix}$	$\frac{1}{h_{12}} \begin{bmatrix} 1 & h_{11} \\ h_{22} & \Delta_h \end{bmatrix}$	$-\frac{1}{g_{12}} \begin{bmatrix} \Delta_g & g_{22} \\ g_{11} & 1 \end{bmatrix}$	$\frac{1}{\Delta_T} \begin{bmatrix} D & B \\ C & A \end{bmatrix}$	$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$\Delta_z = z_{11}z_{22} - z_{12}z_{21}$$

$$\Delta_y = y_{11}y_{22} - y_{12}y_{21}$$

$$\Delta_h = h_{11}h_{22} - h_{12}h_{21}$$

$$\Delta_g = g_{11}g_{22} - g_{12}g_{21}$$

$$\Delta_T = AD - BC$$

$$\Delta_t = ad - bc$$

$g = h^{-1}$     只需记定义，随时可推导     $y = z^{-1}$

$h = g^{-1}$      $abcd = A\bar{B}\bar{C}D^{-1}$      $ABCD = a\bar{b}\bar{c}d^{-1}$      $z = y^{-1}$

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \quad \rightarrow \quad \begin{bmatrix} v_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ v_2 \end{bmatrix}$$

$$i_1 = y_{11}v_1 + y_{12}v_2$$

$$i_2 = y_{21}v_1 + y_{22}v_2$$

$$\frac{1}{y_{11}}i_1 = v_1 + \frac{y_{12}}{y_{11}}v_2$$

$$v_1 = \frac{1}{y_{11}}i_1 - \frac{y_{12}}{y_{11}}v_2$$

$$i_2 = y_{21} \left( \frac{1}{y_{11}}i_1 - \frac{y_{12}}{y_{11}}v_2 \right) + y_{22}v_2$$

$$= \frac{y_{21}}{y_{11}}i_1 + \left( y_{22} - \frac{y_{21}y_{12}}{y_{11}} \right) v_2$$

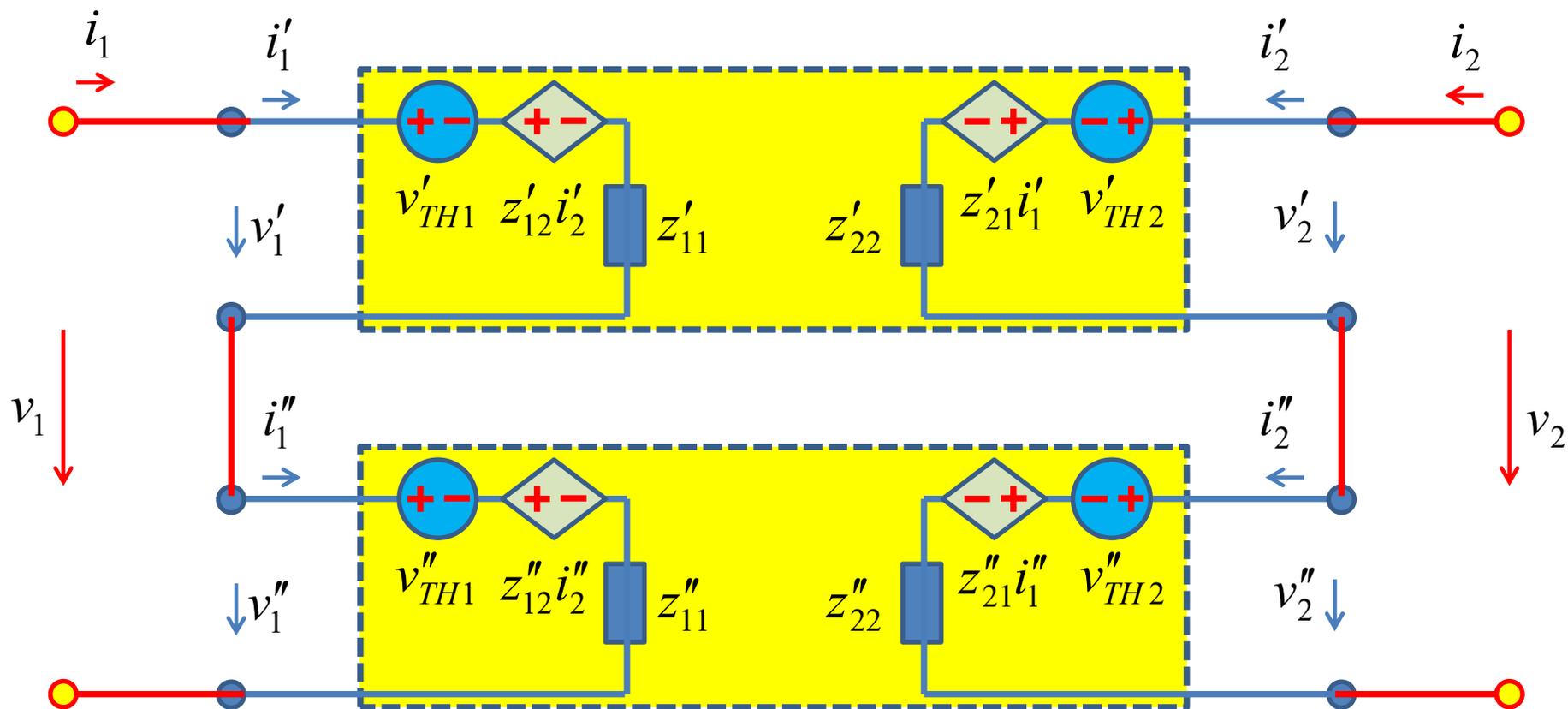
有些网络参量可能不存在

# 二端口线性网络等效电路法 大纲

- 加压求流/加流求压法
  - 从单端口网络等效到二端口网络等效
- 二端口网络参量
  - $z$ 、 $y$ 、 $h$ 、 $g$ 、 $ABCD$ 、 $abcd$
- 网络连接
  - 串串连接
  - 并并连接
  - 串并连接
  - 并串连接
  - 级联
- 传递函数

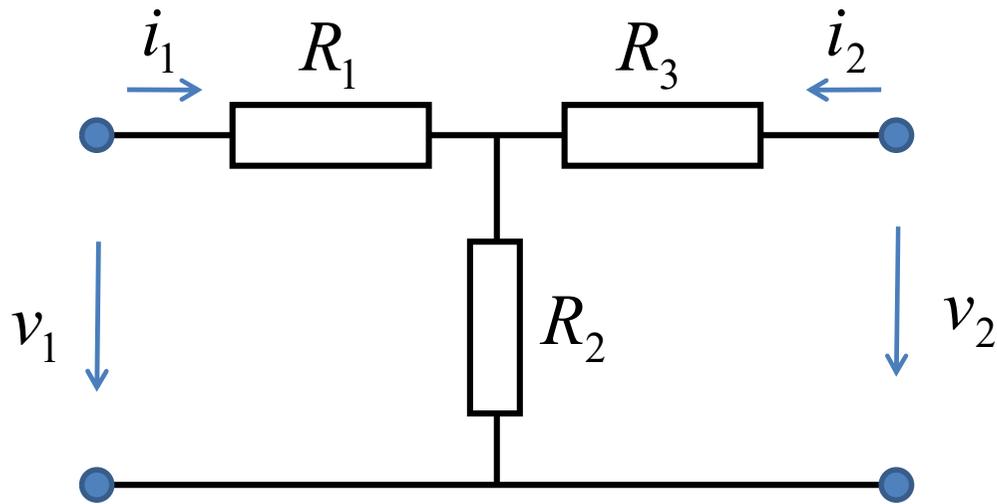
# 网络串联

Series-series connection



$$\mathbf{v} = \mathbf{v}' + \mathbf{v}'' = \mathbf{z}'\mathbf{i}' + \mathbf{v}'_{TH} + \mathbf{z}''\mathbf{i}'' + \mathbf{v}''_{TH} = \underline{\underline{(\mathbf{z}' + \mathbf{z}'')}}\mathbf{i} + (\mathbf{v}'_{TH} + \mathbf{v}''_{TH}) = \underline{\underline{\mathbf{z}}}\mathbf{i} + \mathbf{v}_{TH}$$

# 例：根据定义求z参量



$$\mathbf{z} = \begin{bmatrix} R_1 + R_2 & R_2 \\ R_2 & R_2 + R_3 \end{bmatrix}$$

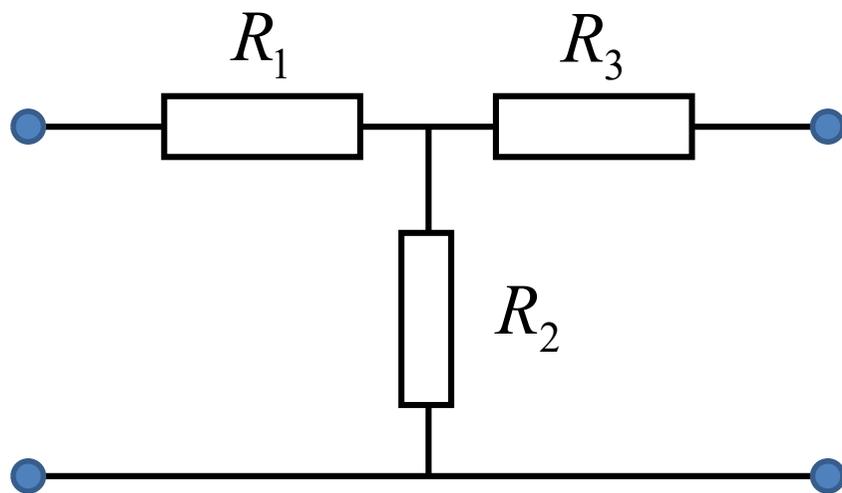
$$z_{11} = \left. \frac{v_1}{i_1} \right|_{i_2=0} = R_1 + R_2$$

$$z_{12} = \left. \frac{v_1}{i_2} \right|_{i_1=0} = R_2$$

$$z_{21} = \left. \frac{v_2}{i_1} \right|_{i_2=0} = R_2$$

$$z_{22} = \left. \frac{v_2}{i_2} \right|_{i_1=0} = R_2 + R_3$$

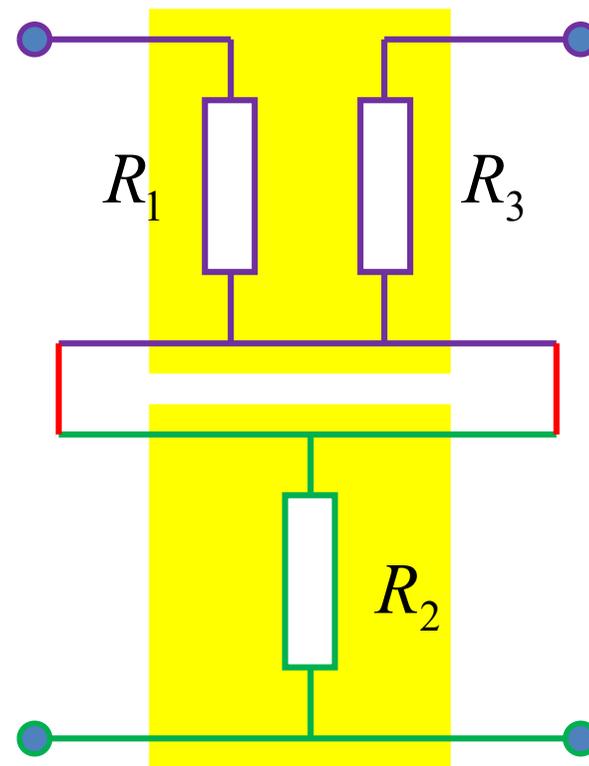
# 串串连接 $\mathbf{z}$ 相加



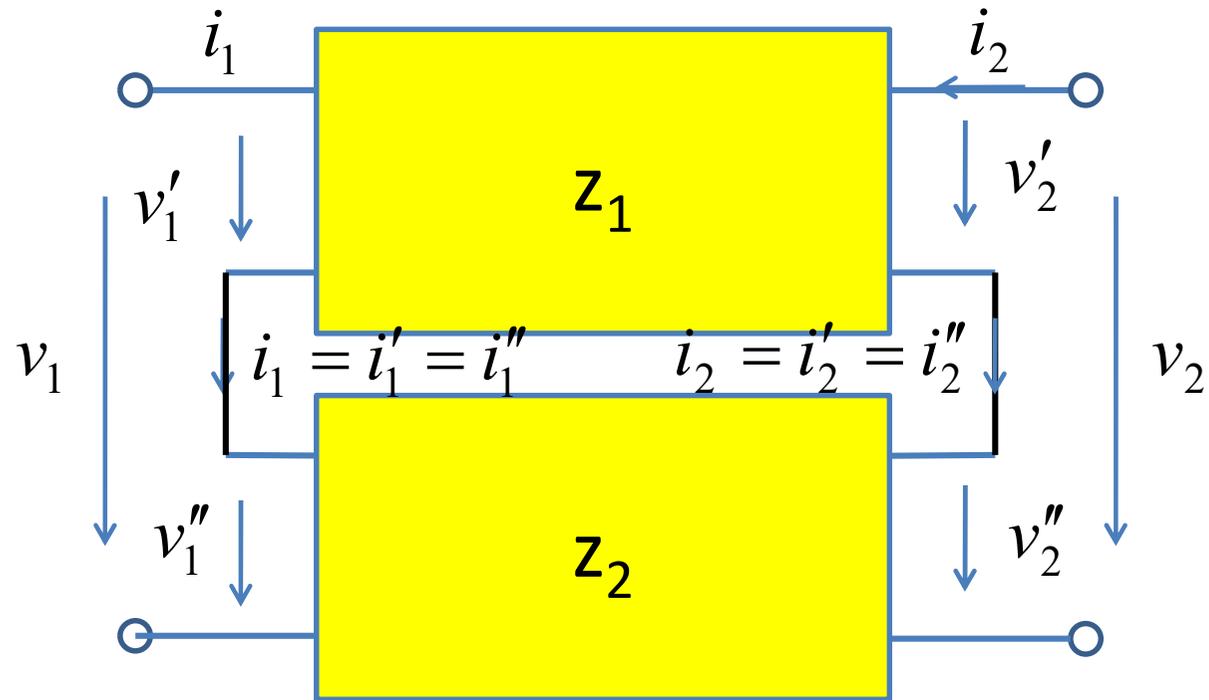
$$\mathbf{z}_1 = \begin{bmatrix} R_1 & 0 \\ 0 & R_3 \end{bmatrix}$$

$$\mathbf{z}_2 = \begin{bmatrix} R_2 & R_2 \\ R_2 & R_2 \end{bmatrix}$$

$$\mathbf{z} = \mathbf{z}_1 + \mathbf{z}_2 = \begin{bmatrix} R_1 + R_2 & R_2 \\ R_2 & R_2 + R_3 \end{bmatrix}$$



# 网络连接不能破坏端口条件



$$\begin{aligned} \mathbf{v} &= \mathbf{v}' + \mathbf{v}'' = \mathbf{z}_1 \mathbf{i}' + \mathbf{z}_2 \mathbf{i}'' \\ &= \mathbf{z}_1 \mathbf{i} + \mathbf{z}_2 \mathbf{i} = (\mathbf{z}_1 + \mathbf{z}_2) \mathbf{i} = \mathbf{z} \mathbf{i} \end{aligned}$$

$$\mathbf{i}' = \mathbf{i}'' = \mathbf{i}$$

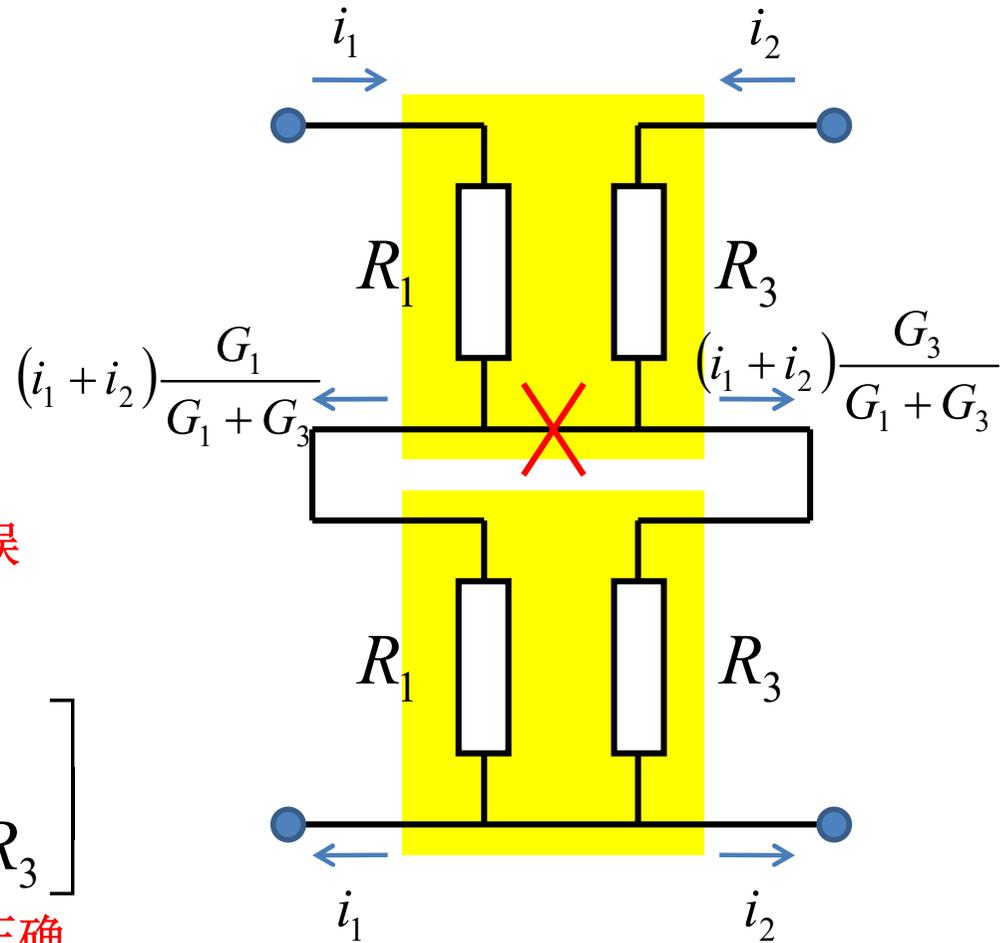
$$\mathbf{z} = \mathbf{z}_1 + \mathbf{z}_2$$

# 端口条件破坏，则不能随意运用网络参量连接公式计算

$$\mathbf{z}_1 = \mathbf{z}_2 = \begin{bmatrix} R_1 & 0 \\ 0 & R_3 \end{bmatrix}$$

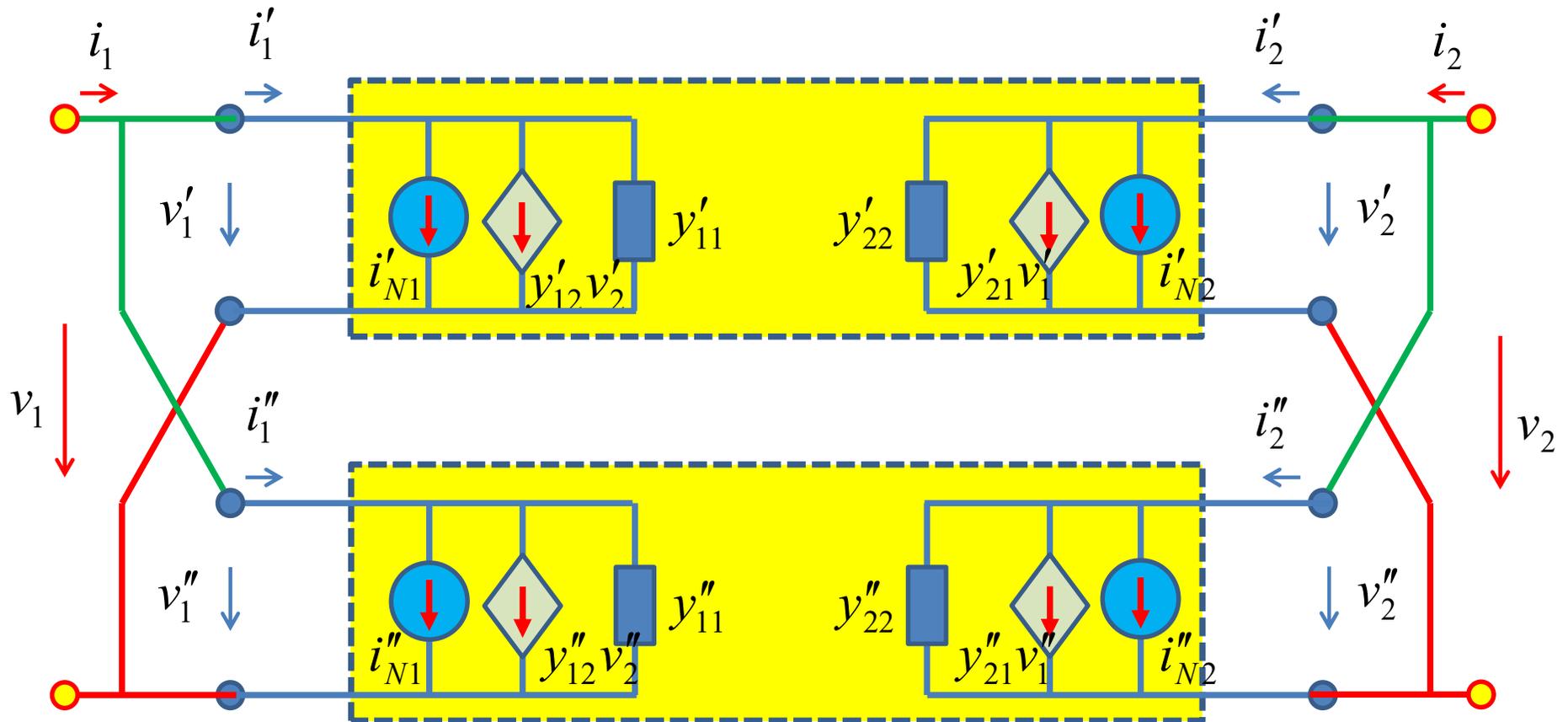
$$\mathbf{z} = \mathbf{z}_1 + \mathbf{z}_2 = \begin{bmatrix} 2R_1 & 0 \\ 0 & 2R_3 \end{bmatrix} \quad \text{错误}$$

$$\mathbf{z} = \begin{bmatrix} R_1 + R_1 \parallel R_3 & R_1 \parallel R_3 \\ R_1 \parallel R_3 & R_3 + R_1 \parallel R_3 \end{bmatrix} \quad \text{正确}$$



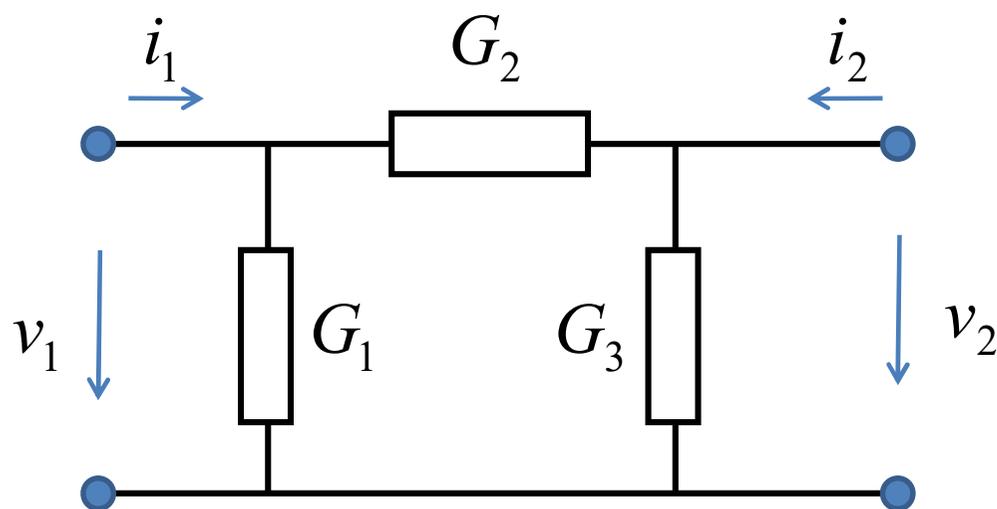
# 网络并联

Parallel-parallel connection



$$\mathbf{i} = \mathbf{i}' + \mathbf{i}'' = \mathbf{y}'\mathbf{v}' + \mathbf{i}'_{\mathbf{N}} + \mathbf{y}''\mathbf{v}'' + \mathbf{i}''_{\mathbf{N}} = \underline{\underline{(\mathbf{y}' + \mathbf{y}'')}}\mathbf{v} + (\mathbf{i}'_{\mathbf{N}} + \mathbf{i}''_{\mathbf{N}}) = \underline{\underline{\mathbf{y}}}\mathbf{v} + \underline{\underline{\mathbf{i}_{\mathbf{N}}}}$$

# 例：根据定义求 $\mathbf{y}$ 参量



$$\mathbf{y} = \begin{bmatrix} G_1 + G_2 & -G_2 \\ -G_2 & G_2 + G_3 \end{bmatrix}$$

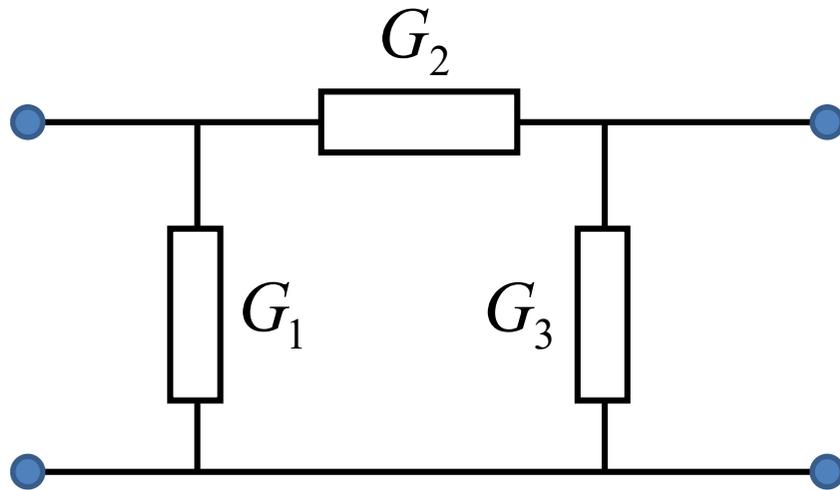
$$y_{11} = \left. \frac{i_1}{v_1} \right|_{v_2=0} = G_1 + G_2$$

$$y_{12} = \left. \frac{i_1}{v_2} \right|_{v_1=0} = -G_2$$

$$y_{21} = \left. \frac{i_2}{v_1} \right|_{v_2=0} = -G_2$$

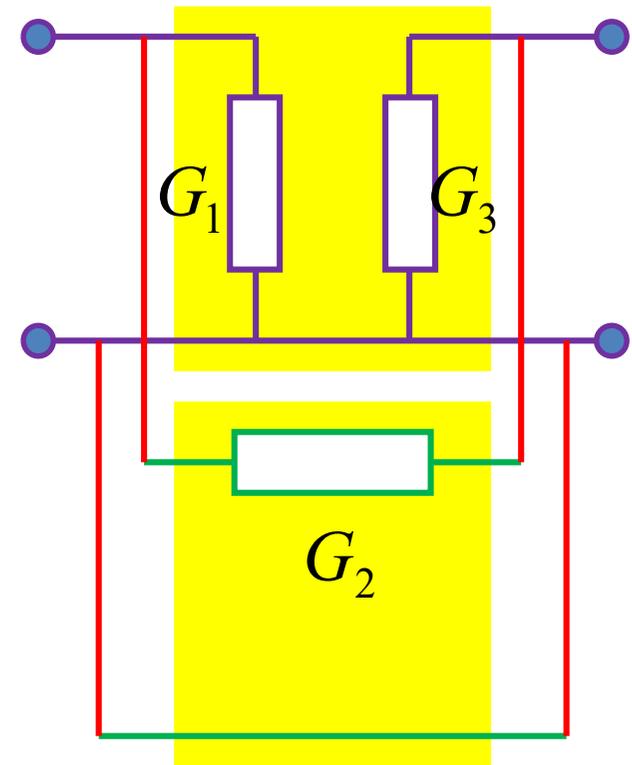
$$y_{22} = \left. \frac{i_2}{v_2} \right|_{v_1=0} = G_2 + G_3$$

# 并并连接 $\mathbf{y}$ 相加



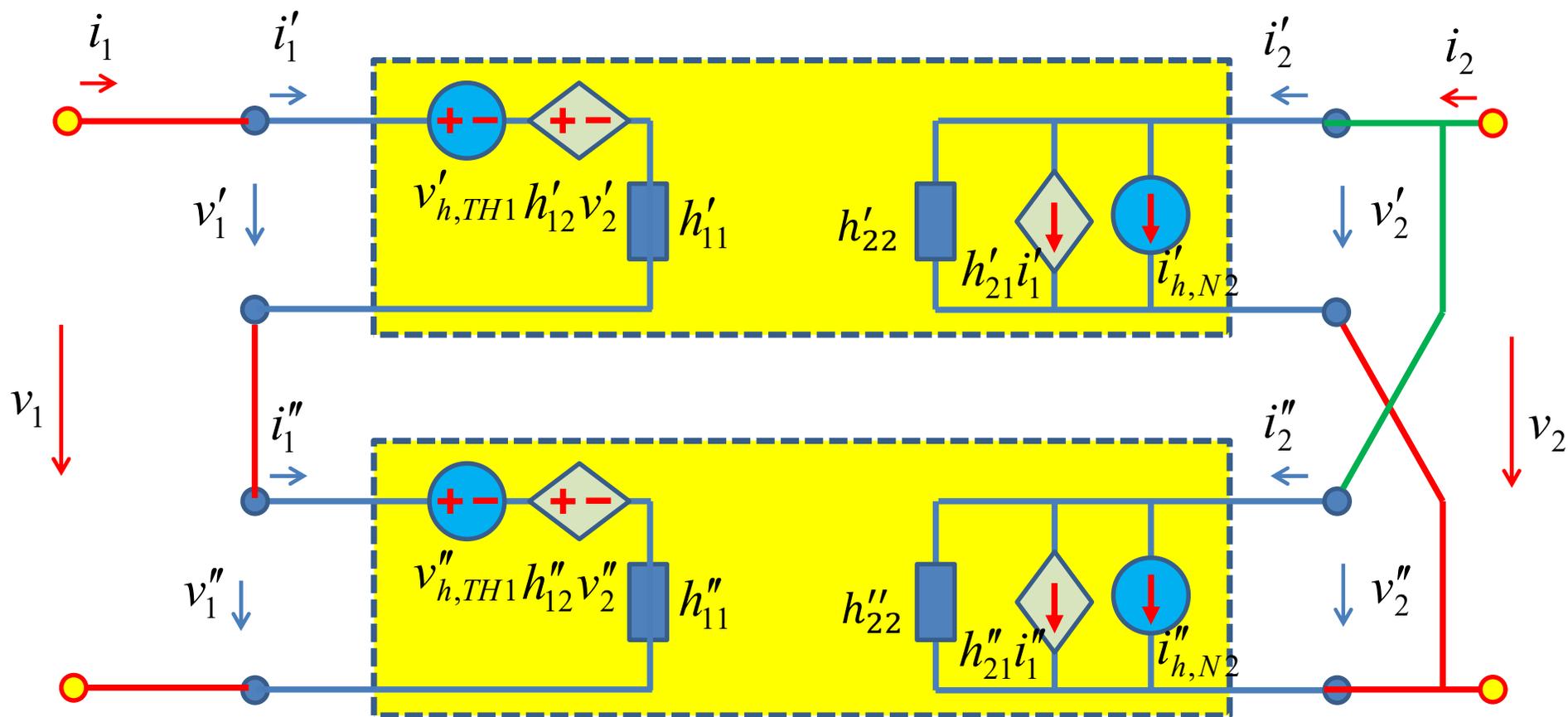
$$\mathbf{y}_1 = \begin{bmatrix} G_1 & 0 \\ 0 & G_3 \end{bmatrix} \quad \mathbf{y}_2 = \begin{bmatrix} G_2 & -G_2 \\ -G_2 & G_2 \end{bmatrix}$$

$$\mathbf{y} = \mathbf{y}_1 + \mathbf{y}_2 = \begin{bmatrix} G_1 + G_2 & -G_2 \\ -G_2 & G_2 + G_3 \end{bmatrix}$$



# 串并连接

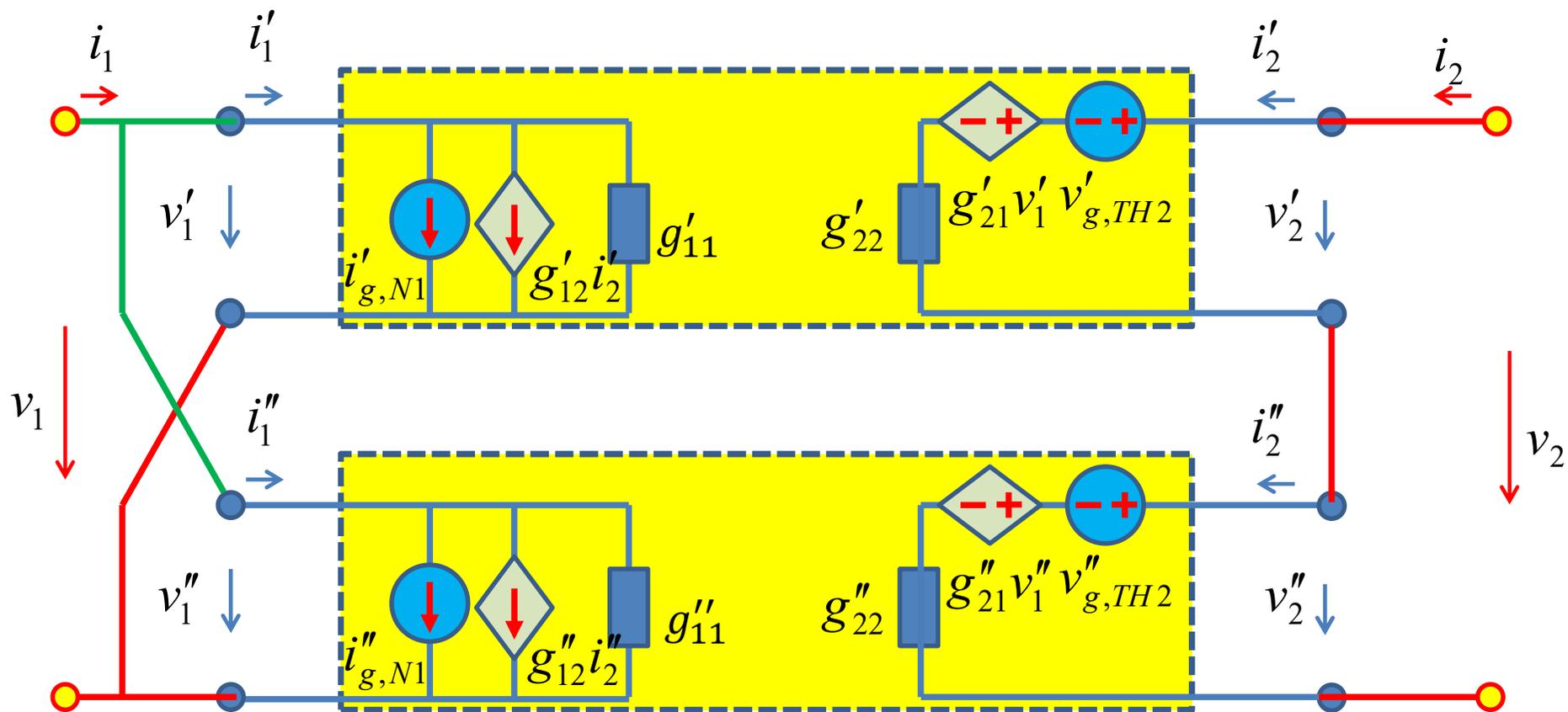
Series-parallel connection



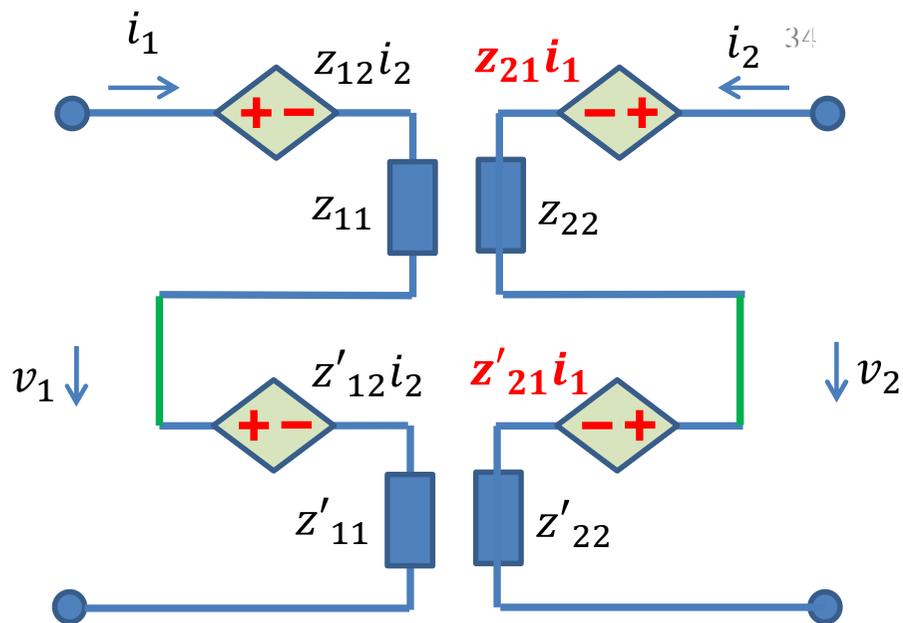
$$\mathbf{h} = \mathbf{h}' + \mathbf{h}''$$

# 并串连接

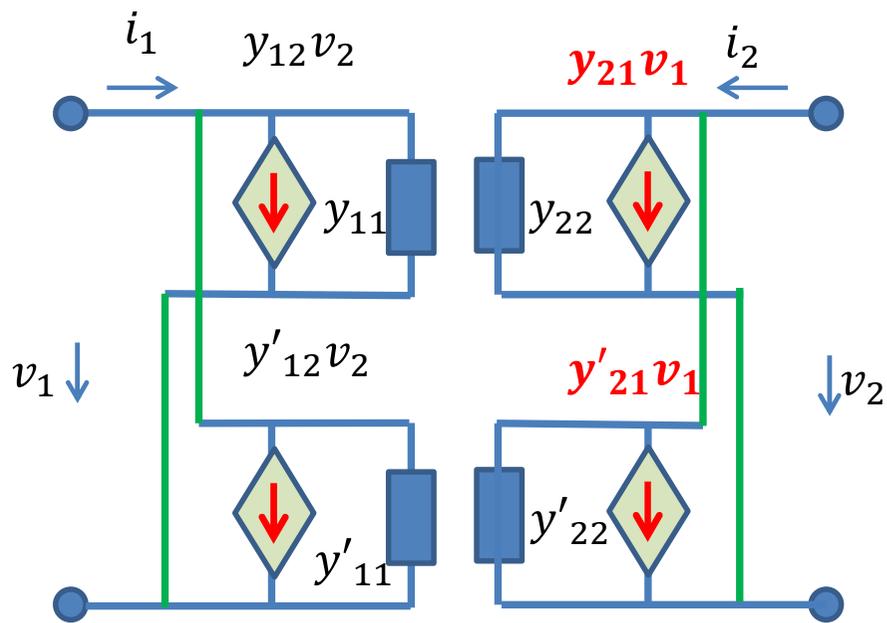
Parallel-series connection



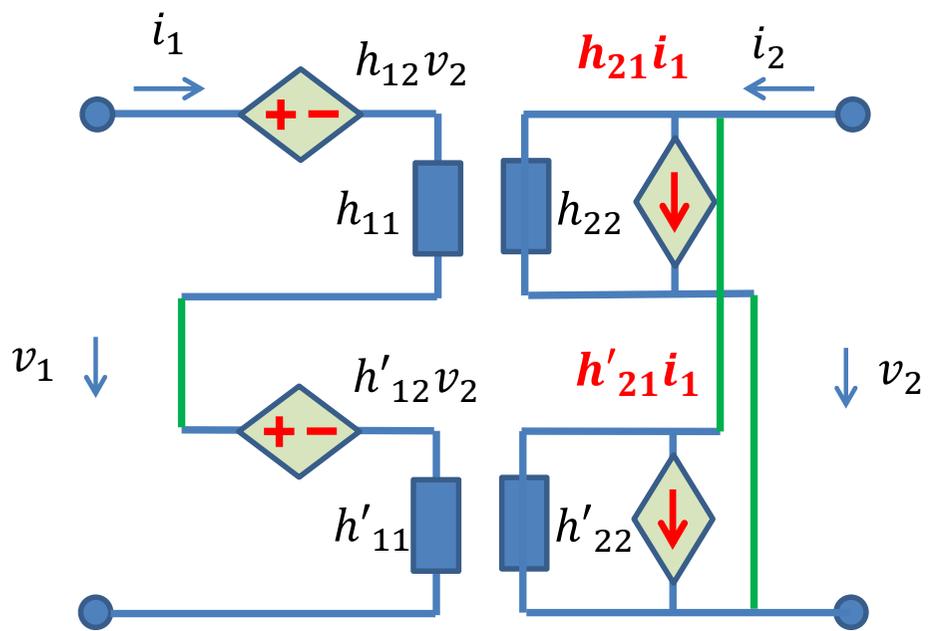
$$\mathbf{g} = \mathbf{g}' + \mathbf{g}''$$



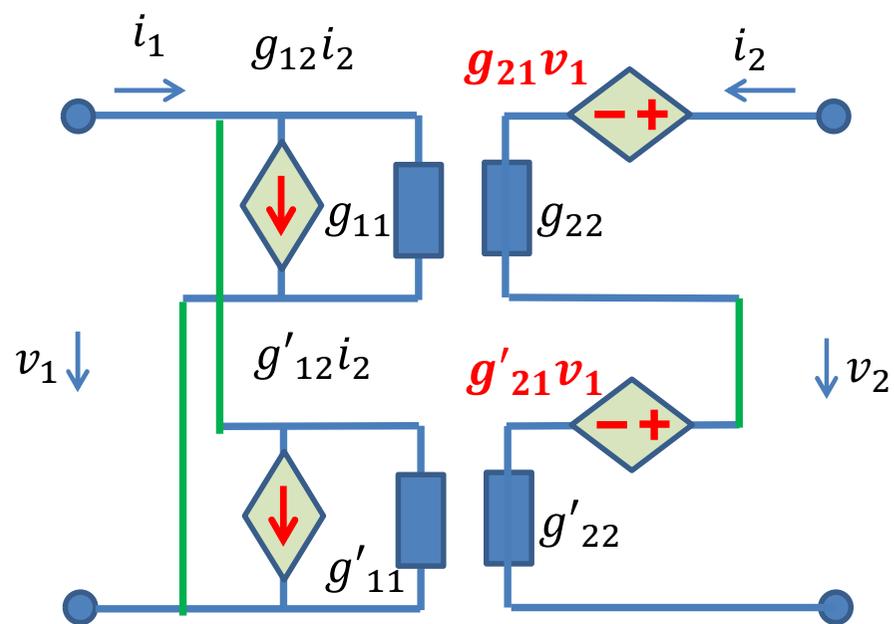
串串连接z相加



并并连接y相加

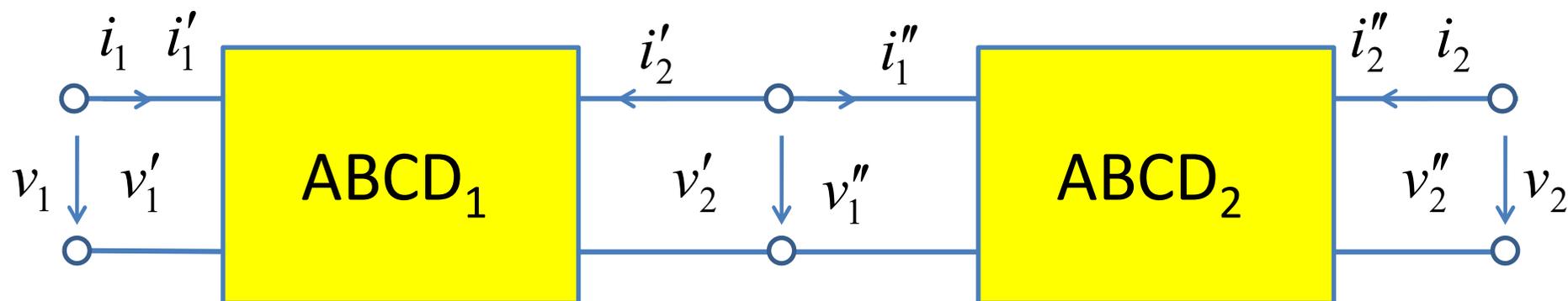


串并连接h相加



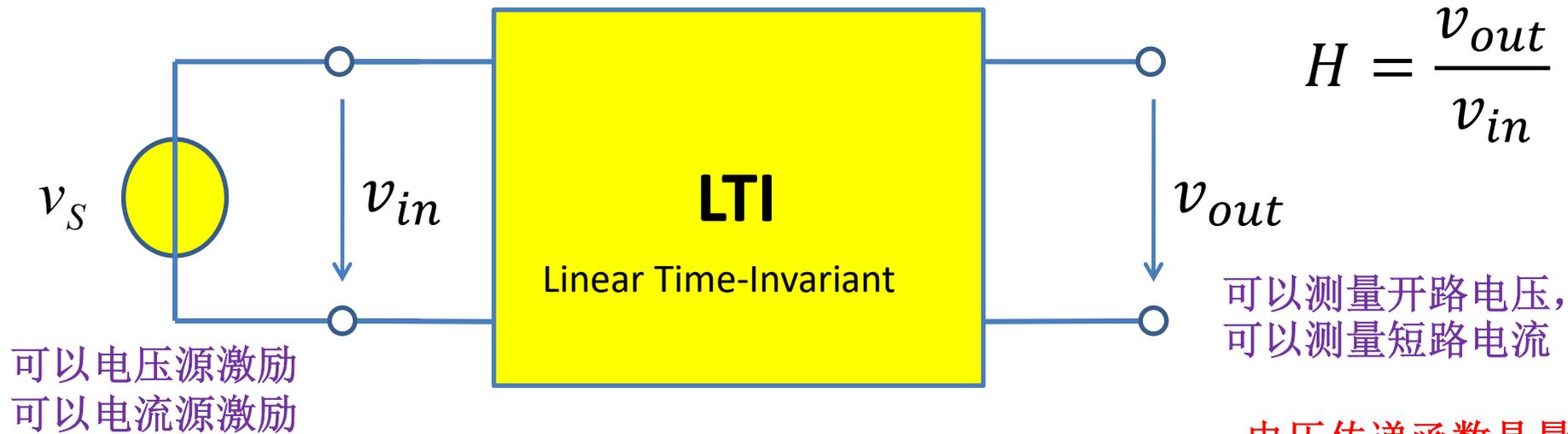
并串连接g相加

# 网络级联: cascade



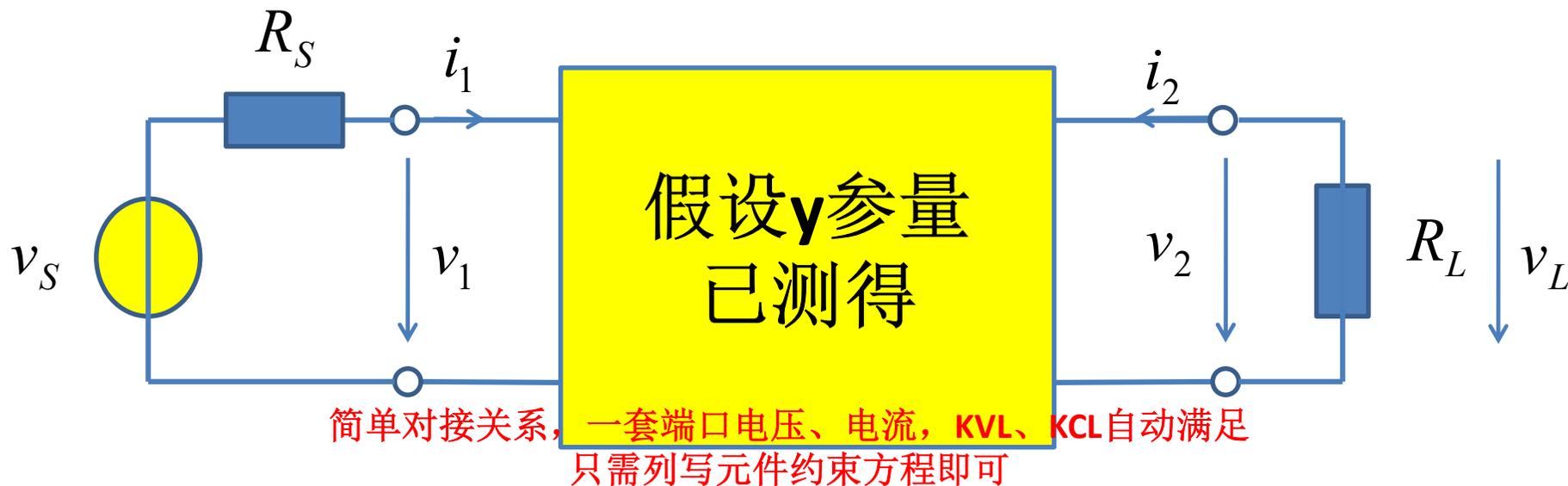
$$\begin{aligned} \begin{bmatrix} v_1 \\ i_1 \end{bmatrix} &= \begin{bmatrix} v'_1 \\ i'_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}_1 \begin{bmatrix} v'_2 \\ -i'_2 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}_1 \begin{bmatrix} v''_1 \\ i''_1 \end{bmatrix} \\ &= \begin{bmatrix} A & B \\ C & D \end{bmatrix}_1 \begin{bmatrix} A & B \\ C & D \end{bmatrix}_2 \begin{bmatrix} v''_2 \\ -i''_2 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}_1 \begin{bmatrix} A & B \\ C & D \end{bmatrix}_2 \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix} \\ &\quad \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}_1 \begin{bmatrix} A & B \\ C & D \end{bmatrix}_2 \end{aligned}$$

# 四、 传递函数 Transfer Function



# 传递函数的获得

- 列写电路方程，其中， $v_S$ 为激励源视为已知量、 $v_L$ 为响应视为未知量，求解电路方程即可获得电压传递函数
  - 基本方法：结点电压法、回路电流法
    - 上节课最后求放大器放大倍数例：放大倍数就是传递函数
  - 简单电路结构：利用简单串并联的分压分流
    - 上节课的电阻衰减器衰减系数例：衰减系数为放大倍数的倒数，也是传递函数例
    - 可以用结点电压法，回路电流法，串并联，戴维南等效等
  - 网络参量已测得或容易获得，则可利用网络参量获取传递函数



$$v_1 + R_S i_1 = v_S$$

激励源元件约束方程

$$y_{11} v_1 + y_{12} v_2 - i_1 = 0$$

二端口网络元件约束方程

$$y_{21} v_1 + y_{22} v_2 - i_2 = 0$$

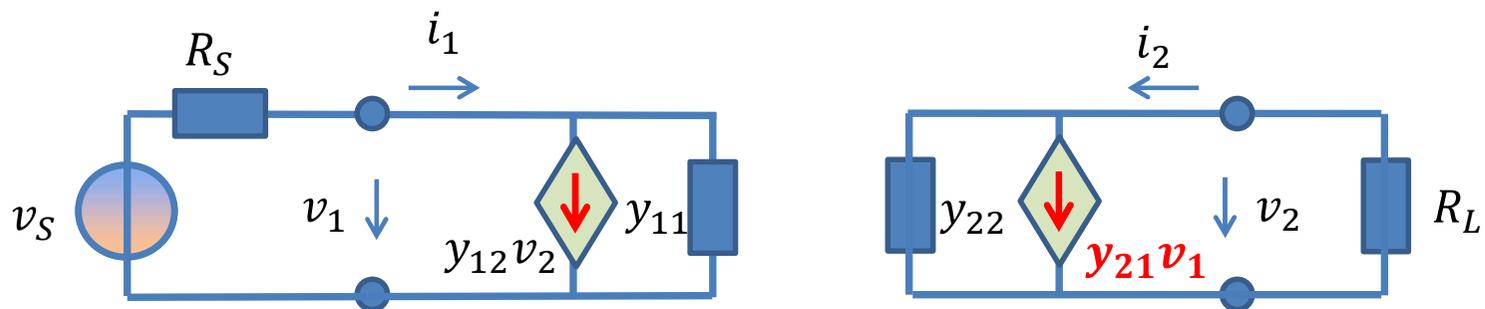
4个未知数  
 $v_1, i_1, v_2, i_2$

4个方程

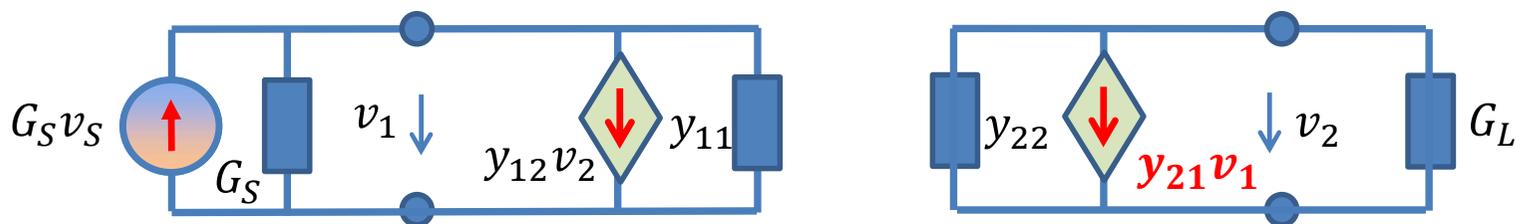
$$v_2 + R_L i_2 = 0$$

负载电阻元件约束方程

不仅仅  
数学语言可求解，用  
电路语言进行分析更是本课程基本功要求



$y$ 参量为导纳参量，将戴维南电压源转换为诺顿电流源处理是适当的



$$v_1 = \frac{G_S v_S - y_{12} v_2}{G_S + y_{11}} \quad v_2 = -\frac{y_{21} v_1}{G_L + y_{22}} = -\frac{y_{21}}{G_L + y_{22}} \frac{G_S v_S - y_{12} v_2}{G_S + y_{11}}$$

$$(G_S + y_{11})(G_L + y_{22})v_2 = -y_{21}G_S v_S + y_{21}y_{12}v_2$$

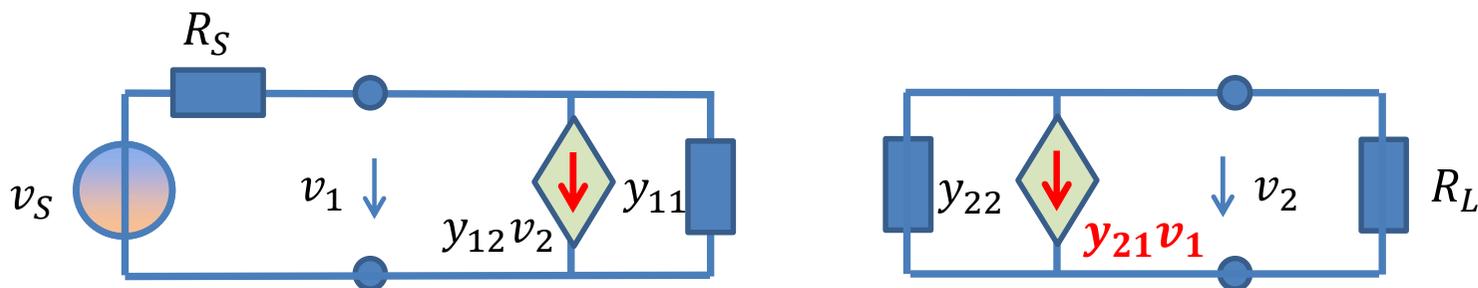
$$y_{21}G_S v_S = (y_{21}y_{12} - (G_S + y_{11})(G_L + y_{22}))v_2$$

$$H = \frac{v_L}{v_S} = \frac{v_2}{v_S} = \frac{y_{21}G_S}{y_{21}y_{12} - (G_S + y_{11})(G_L + y_{22})}$$

电路和数学  
是一体的

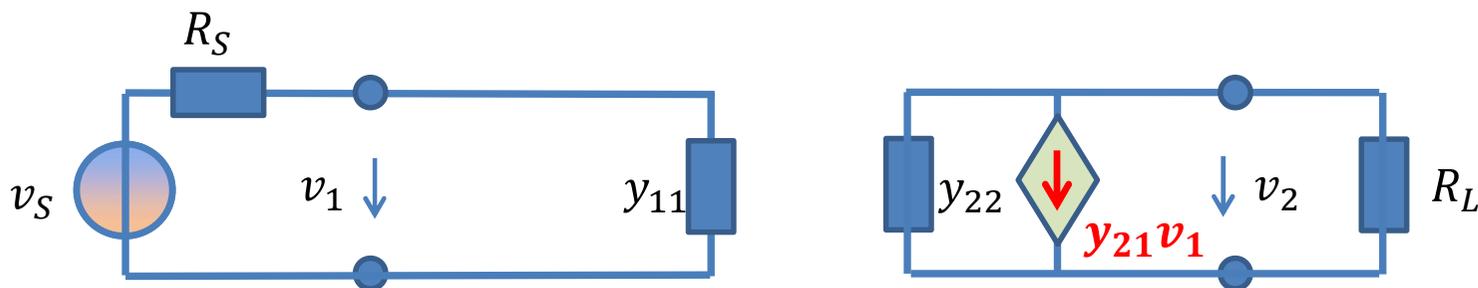
凡是复杂一点的公式，都应做量纲检查，极端检查，确保基本无误<sup>89</sup>

极端检查通过：  
假设是单向网络



$$H = \frac{v_L}{v_S} = \frac{v_2}{v_S} = \frac{y_{21} G_S}{y_{21} y_{12} - (G_S + y_{11})(G_L + y_{22})} \stackrel{y_{12}=0}{=} \frac{-y_{21} G_S}{(G_S + y_{11})(G_L + y_{22})}$$

单向网络比较简单

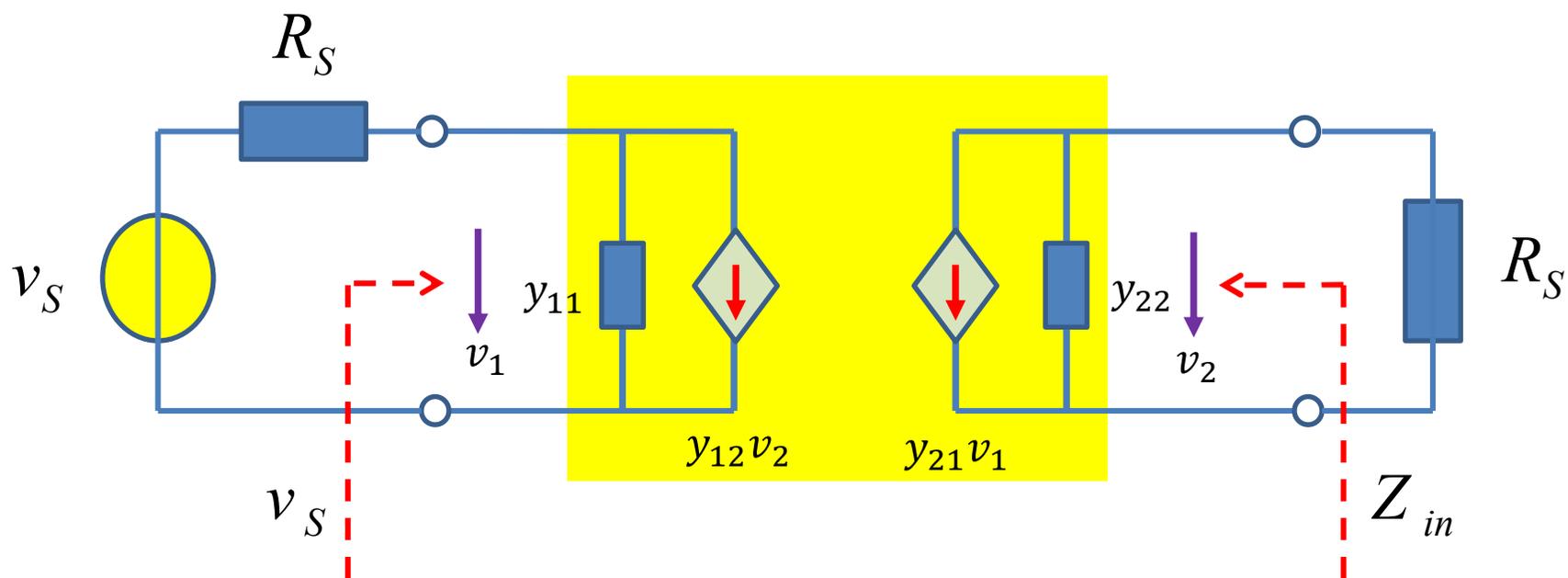
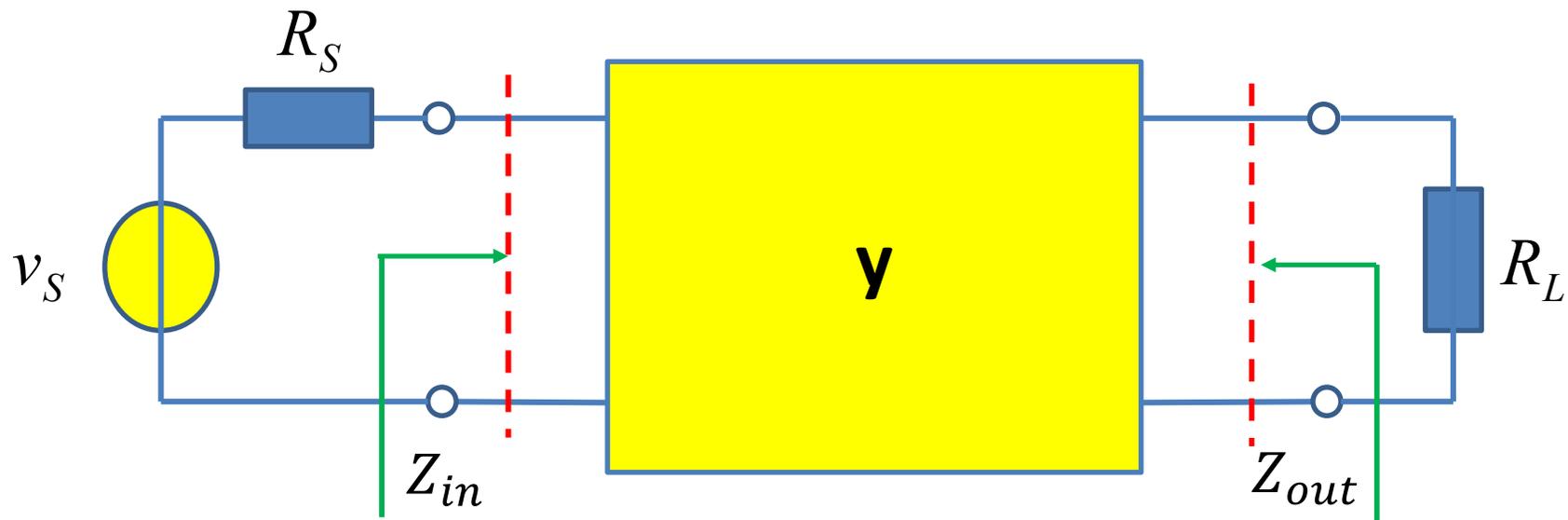


$$v_1 = \frac{\frac{1}{y_{11}}}{R_S + \frac{1}{y_{11}}} v_S = \frac{G_S}{G_S + y_{11}} v_S \quad v_2 = -\frac{y_{21} v_1}{y_{22} + G_L} = \frac{1}{y_{22} + G_L} (-y_{21}) \frac{G_S}{G_S + y_{11}} v_S$$

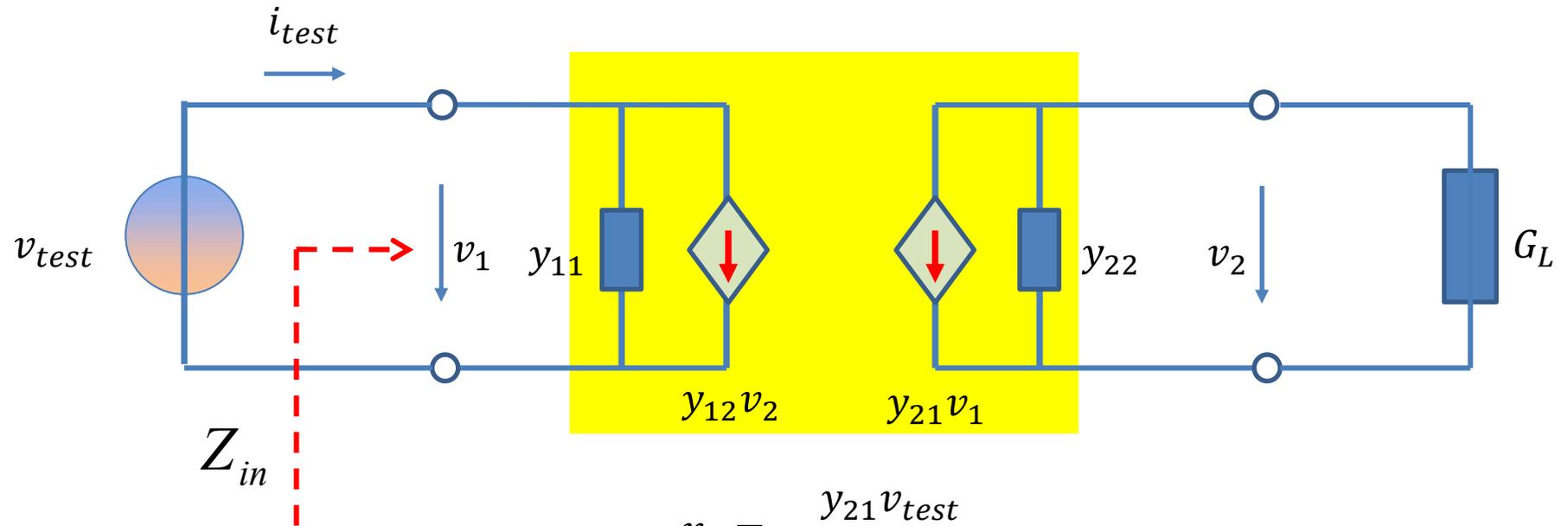
单向网络的传递函数为分传递函数之积，这是我们喜好单向网络的重要原因：**随手写答案**

输出电流流过输出回路总电阻形成输出电压  
被本征跨导增益转换为输出电流  
输入回路分压

# 输入阻抗，输出阻抗



# 输入阻抗，输入导纳



$$v_2 = -\frac{y_{21}v_{test}}{y_{22} + G_L}$$

$$i_{test} = y_{11}v_1 + y_{12}v_2 = y_{11}v_{test} - \frac{y_{12}y_{21}v_{test}}{y_{22} + G_L}$$

$$Y_{in} = \frac{i_{test}}{v_{test}} = y_{11} - \frac{y_{12}y_{21}}{y_{22} + G_L}$$

# 输入/输出阻抗/导纳

$$Y_{in} = y_{11} - \frac{y_{12}y_{21}}{y_{22} + G_L}$$

$$Y_{out} = y_{22} - \frac{y_{21}y_{12}}{y_{11} + G_S}$$

$$Z_{in} = z_{11} - \frac{z_{12}z_{21}}{z_{22} + R_L}$$

$$Z_{out} = z_{22} - \frac{z_{21}z_{12}}{z_{11} + Z_S}$$

$$Z_{in} = h_{11} - \frac{h_{12}h_{21}}{h_{22} + G_L}$$

$$Y_{out} = h_{22} - \frac{h_{21}h_{12}}{h_{11} + R_S}$$

$$Y_{in} = g_{11} - \frac{g_{12}g_{21}}{g_{22} + R_L}$$

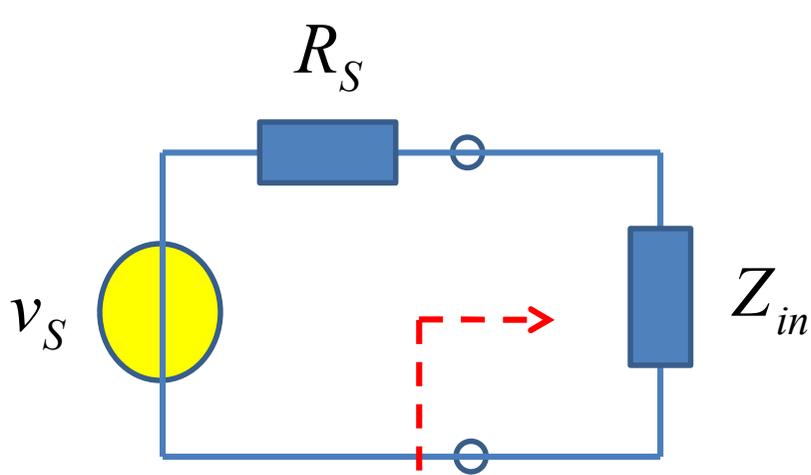
$$Z_{out} = g_{22} - \frac{g_{21}g_{12}}{g_{11} + G_S}$$

$$Y_{in} = \frac{1}{Z_{in}}$$

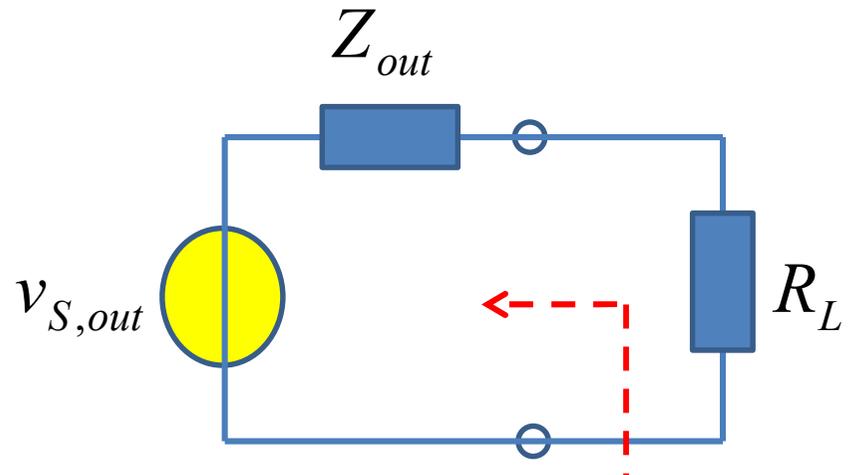
$$Y_{out} = \frac{1}{Z_{out}}$$

格式规范一致，记忆十分方便简单

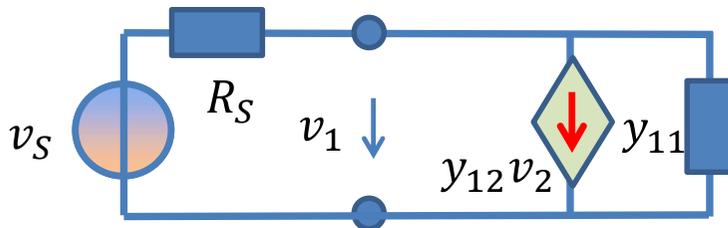
# 输入等效和输出等效



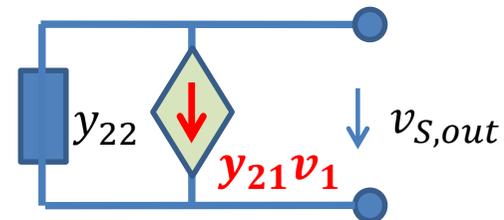
二端口网络和负载电阻在端口1的单端口等效电路



二端口网络和激励信源在端口2的单端口等效电路



$$v_1 = \frac{G_S v_S - y_{12} v_2}{G_S + y_{11}}$$



$$v_2 = -\frac{y_{21} v_1}{y_{22}} = -\frac{y_{21} G_S v_S - y_{12} v_2}{y_{22} (G_S + y_{11})}$$

$$-y_{22} (G_S + y_{11}) v_2 = y_{21} G_S v_S - y_{21} y_{12} v_2$$

$$v_{S,out} = v_2 = \frac{y_{21} G_S}{y_{21} y_{12} - y_{22} (G_S + y_{11})} v_S$$

# ABCD参量在传递函数中的应用例



简单对接关系，一套端口电压、电流，KVL、KCL自动满足  
只需列写元件约束方程即可

$$v_1 + R_S i_1 = v_S$$

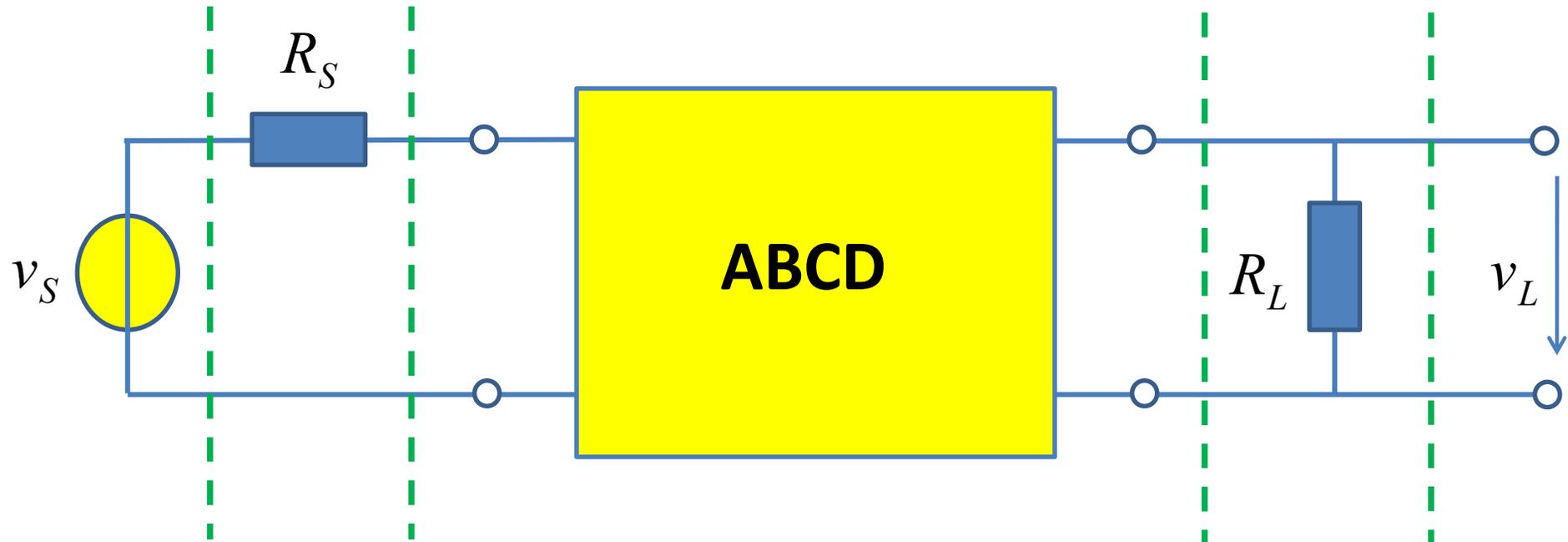
$$v_1 - A v_2 + B i_2 = 0$$

$$i_1 - C v_2 + D i_2 = 0$$

$$v_2 + R_L i_2 = 0$$

直接求解电路方程是数学基本功，  
但没有掌握电路语言分析的基本功

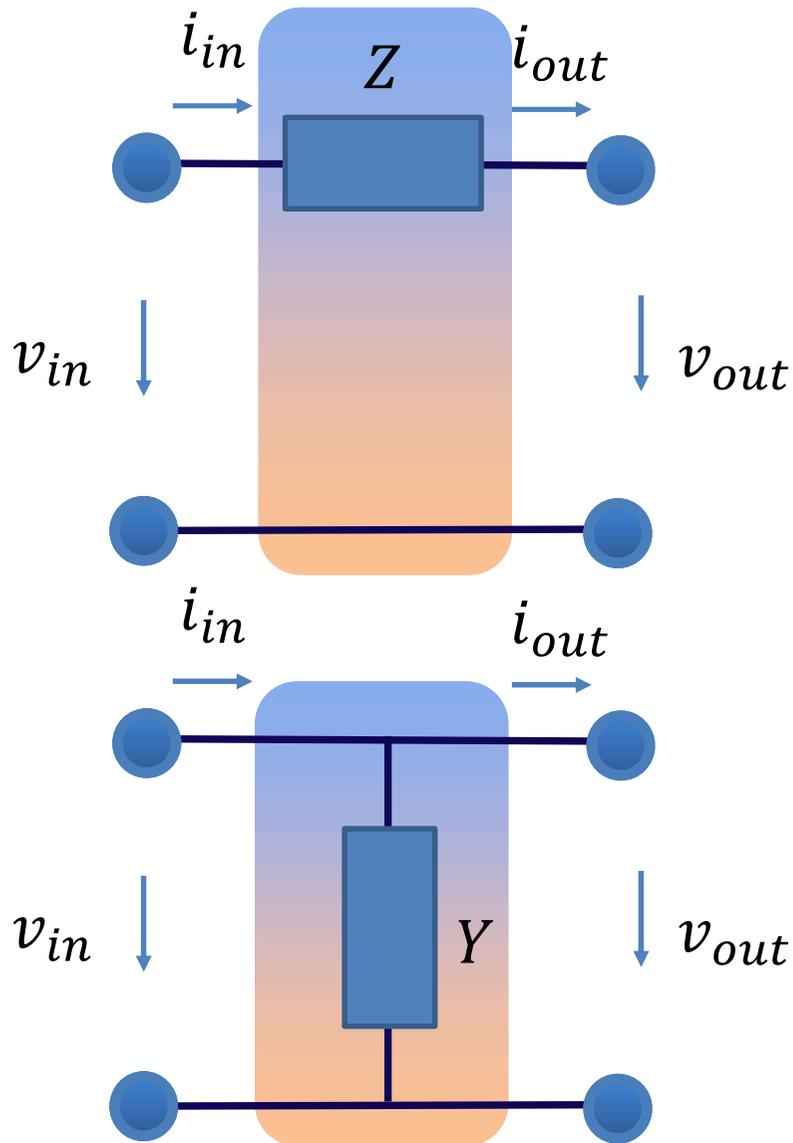
# 电路语言基本功



$$\begin{bmatrix} A_c & B_c \\ C_c & D_c \end{bmatrix} = \begin{bmatrix} A_S & B_S \\ C_S & D_S \end{bmatrix} \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} A_L & B_L \\ C_L & D_L \end{bmatrix}$$

$$H = \frac{v_L}{v_S} = \frac{1}{A_c}$$

# 串臂阻抗和并臂导纳的传输参量矩阵



$$i_{in} = i_{out}$$

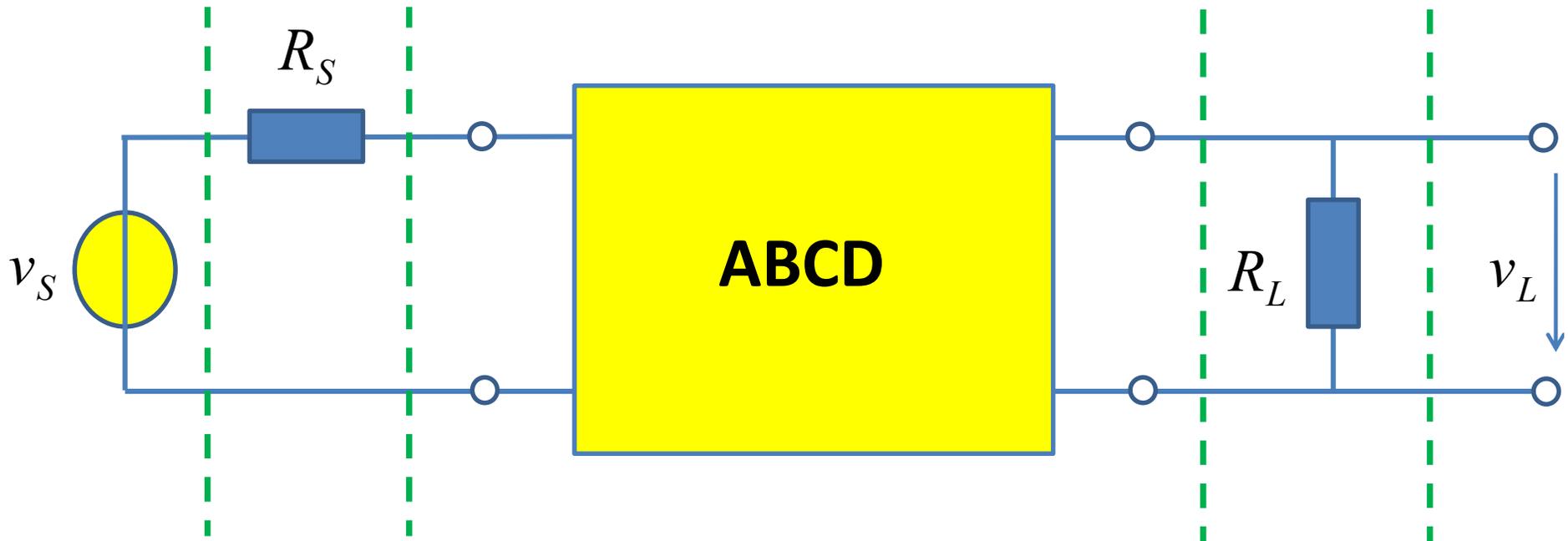
$$v_{in} = Z i_{in} + v_{out}$$

$$\begin{bmatrix} v_{in} \\ i_{in} \end{bmatrix} = \begin{bmatrix} 1 & Z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v_{out} \\ i_{out} \end{bmatrix}$$

$$v_{in} = v_{out}$$

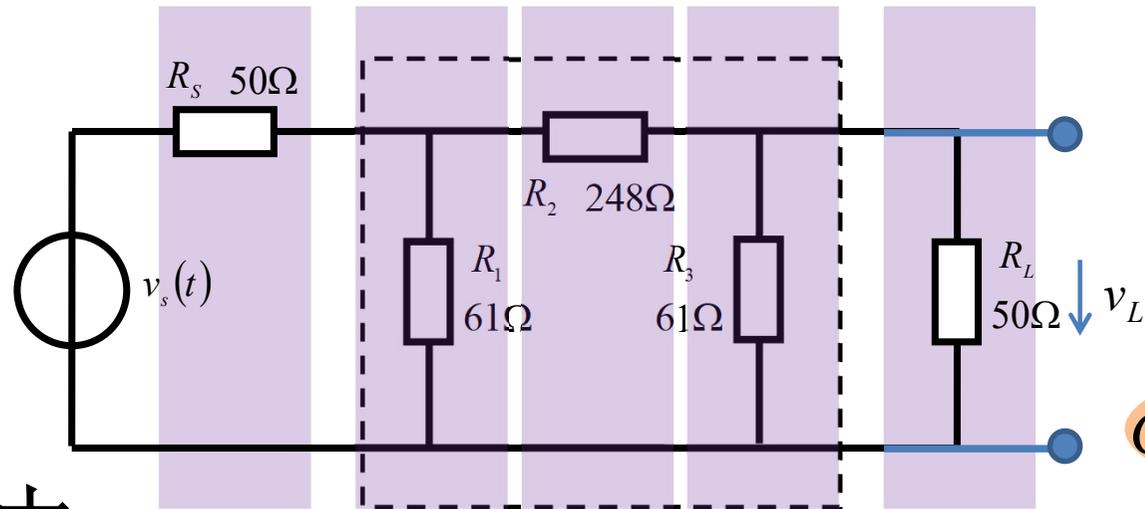
$$i_{in} = Y v_{in} + i_{out}$$

$$\begin{bmatrix} v_{in} \\ i_{in} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ Y & 1 \end{bmatrix} \begin{bmatrix} v_{out} \\ i_{out} \end{bmatrix}$$



$$\begin{aligned}
 \begin{bmatrix} A_c & B_c \\ C_c & D_c \end{bmatrix} &= \begin{bmatrix} A_S & B_S \\ C_S & D_S \end{bmatrix} \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} A_L & B_L \\ C_L & D_L \end{bmatrix} = \begin{bmatrix} 1 & R_S \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{1}{R_L} & 1 \end{bmatrix} \\
 &= \begin{bmatrix} A + CR_S & B + DR_S \\ C & D \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{1}{R_L} & 1 \end{bmatrix} = \begin{bmatrix} A + CR_S + \frac{B + DR_S}{R_L} & \dots \\ \dots & \dots \end{bmatrix}
 \end{aligned}$$

$$H = \frac{v_L}{v_S} = \frac{1}{A_c} = \frac{1}{A + CR_S + \frac{B + DR_S}{R_L}} = \frac{R_L}{AR_L + B + CR_S R_L + DR_S}$$



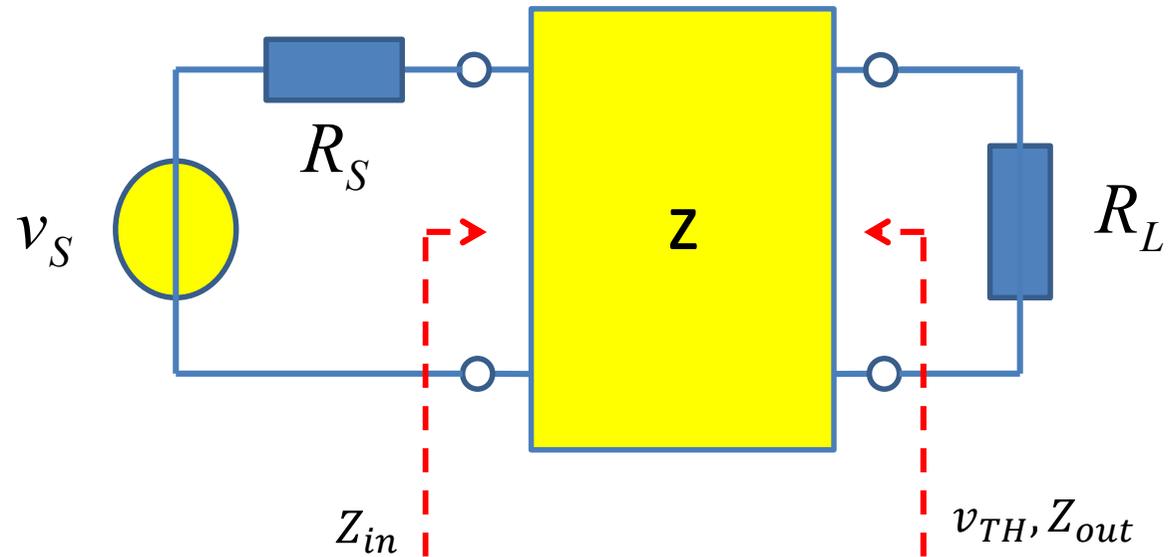
$$A_{v0} = \frac{v_L}{v_S} = \frac{1}{A} = 0.0498$$

$$G_T = 20 \log(2 A_{v0}) = -20 \text{ dB}$$

# 电阻衰减器分析

$$\begin{aligned}
 \mathbf{ABCD} &= \begin{bmatrix} 1 & R_S \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ G_1 & 1 \end{bmatrix} \begin{bmatrix} 1 & R_2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ G_3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ G_L & 1 \end{bmatrix} \\
 &= \begin{bmatrix} 1 & 50 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0.0164 & 1 \end{bmatrix} \begin{bmatrix} 1 & 248 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0.0164 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0.020 & 1 \end{bmatrix} \\
 &= \begin{bmatrix} 20.063 & 501.28 \\ 0.2007 & 5.0656 \end{bmatrix} = \begin{bmatrix} \frac{1}{0.0498} & \frac{1}{0.0020} \\ \frac{1}{4.9814} & \frac{1}{0.1974} \end{bmatrix} = \begin{bmatrix} \frac{1}{A_{v0}} & \frac{1}{G_{m0}} \\ \frac{1}{R_{m0}} & \frac{1}{A_{i0}} \end{bmatrix}
 \end{aligned}$$

# 作业1

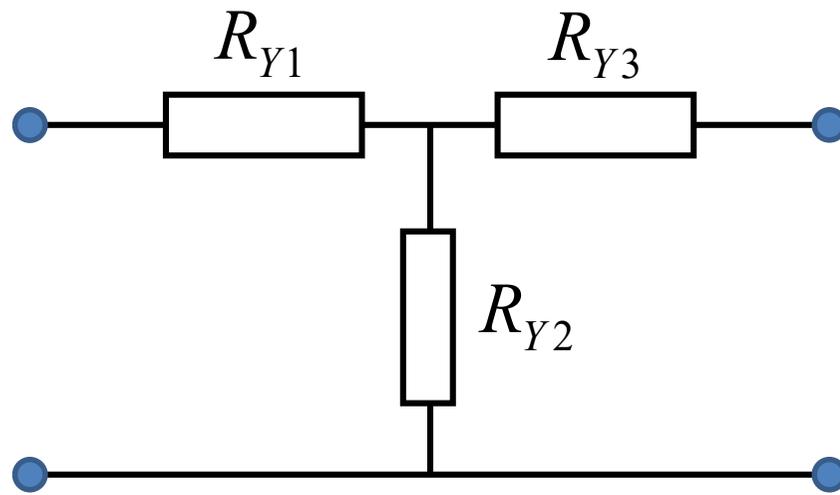


- 已知二端口网络的 $z$ 参量，1端口接信源 ( $v_s, R_s$ )，2端口接负载 $R_L$ 
  - 求输入阻抗 $Z_{in}$
  - 求输出端戴维南等效 $v_{TH}, Z_{out}$ 
    - 要求有详细的推导步骤：要求用电路语言分析
  - 在此基础上，考察单向网络的表达式与等效电路之间的关系
    - $z$ 参量单向网络：将 $z_{12}=0$ ， $z_{21}=R_m$ 代入表达式即可
    - 通过等效电路图分析，比对解表达式，理解对电路中的分压、分流关系

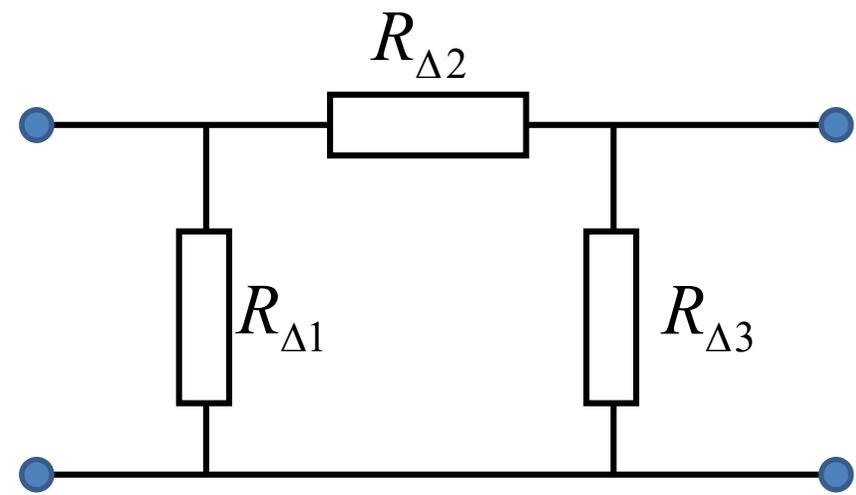
# 作业2: Y- $\Delta$ 转换关系的推导

- 如果两个二端口网络具有相同的网络参量矩阵, 这两个二端口网络则可认为是等效的
  - Y形网络和 $\Delta$ 形网络等价, 显然它们的电阻必须满足某种关系
    - 求Y形网络的z矩阵, 求逆获得其y矩阵
    - 求 $\Delta$ 形网络的y矩阵
    - 两者相等, 求出Y- $\Delta$ 转换关系:  $R_{\Delta}$ 如何用 $R_Y$ 表示?
    - 反之,  $R_Y$ 如何用 $R_{\Delta}$ 表示?

ABCD参量是否更简单?

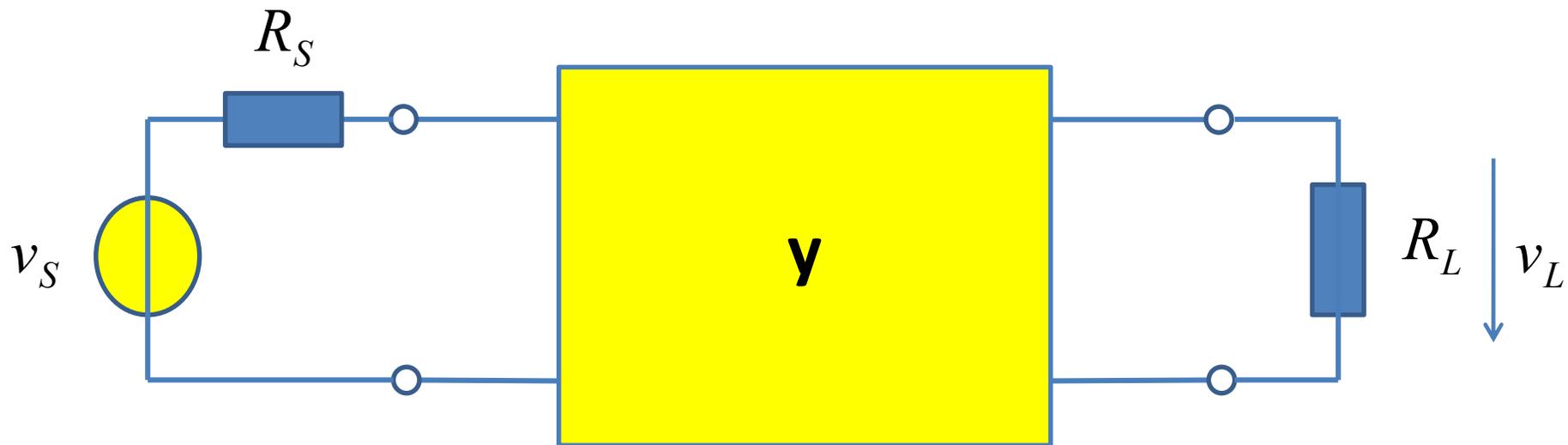


T形网络, Y形网络



$\pi$ 形网络,  $\Delta$ 形网络

# 作业3 单向化条件

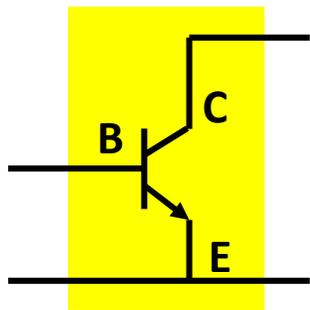


$$H_{\text{双向网络}} = \frac{v_L}{v_S} = \frac{v_2}{v_S} = \frac{y_{21}G_S}{y_{21}y_{12} - (y_{11} + G_S)(y_{22} + G_L)} \quad H_{\text{单向网络}}^{y_{12}=0} = \frac{y_{21}R_L}{-(1 + R_S y_{11})(1 + R_L y_{22})}$$

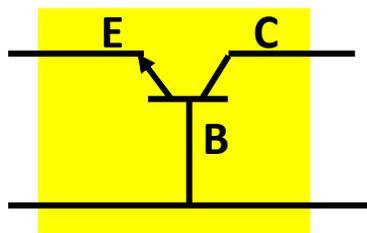
如果满足单向化条件:  $|y_{21}y_{12}| \ll |(y_{11} + G_S)(y_{22} + G_L)|$

双向网络则可等视为单向网络  $H_{\text{双向网络}} \approx H_{\text{单向网络}}$  单向网络可以直接写传递函数

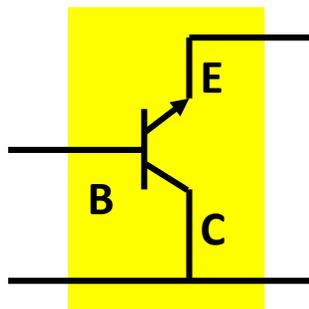
给出用z参量、h参量、g参量表述的线性二端口网络的单向化条件



Common Emitter

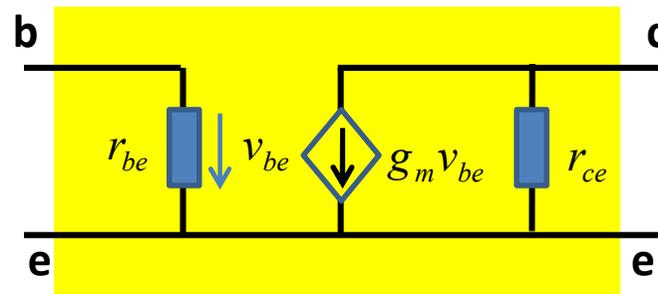


Common Base



Common Collector

# BJT 交流小信号电路模型

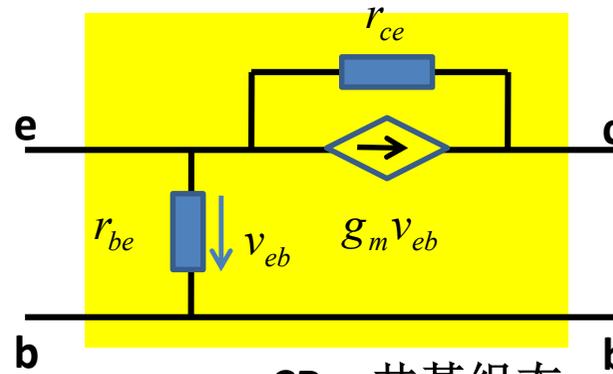


CE: 共射组态

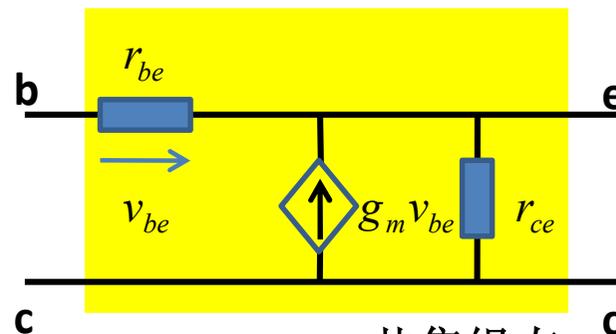
$$g_m = 40\text{mS}$$

$$r_{be} = 10\text{k}\Omega$$

$$r_{ce} = 100\text{k}\Omega$$

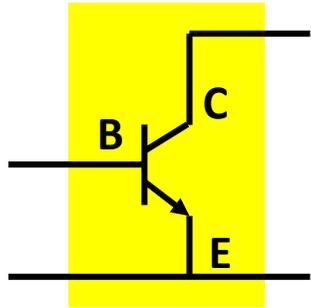


CB: 共基组态

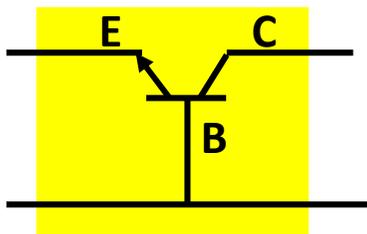


CC: 共集组态

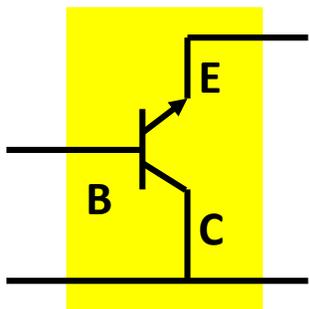
# 作业4 求电压放大倍数



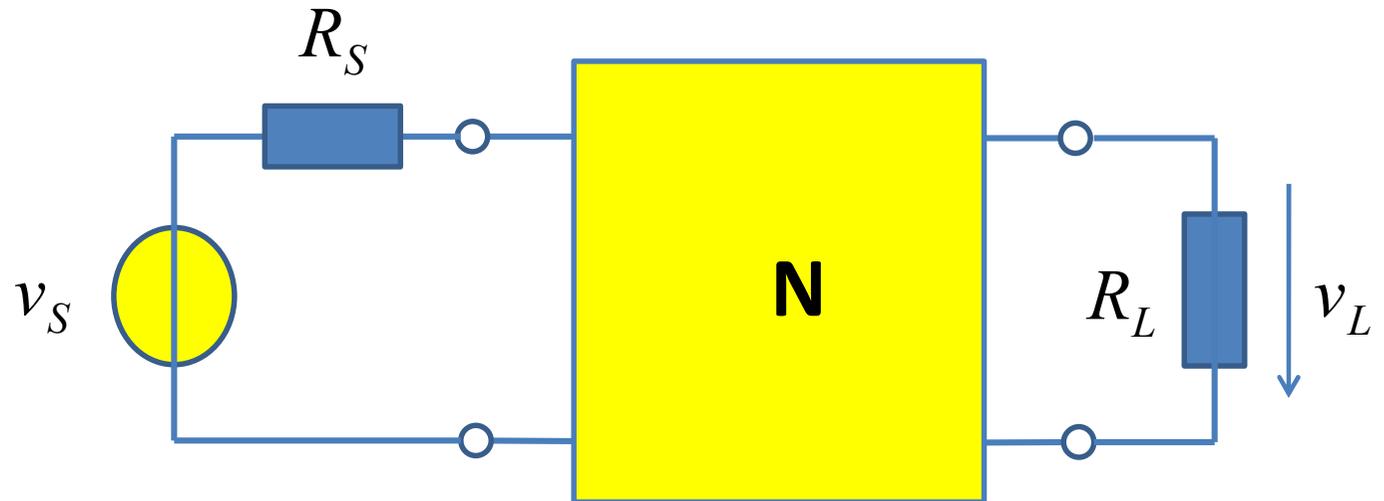
Common Emitter



Common Base



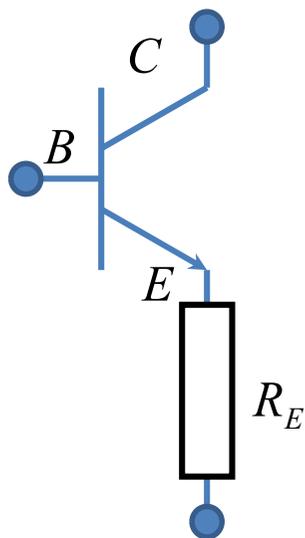
Common Collector



求三种组态晶体管放大器的输入电阻，输出电阻，电压传递函数表达式（符号表达式），代入具体数值求其电压放大倍数（ $R_S=50\Omega, R_L=1k\Omega$ ）

方法不限：可以用回路电流法，结点电压法，二端口网络参量法

# 作业5：串联负反馈



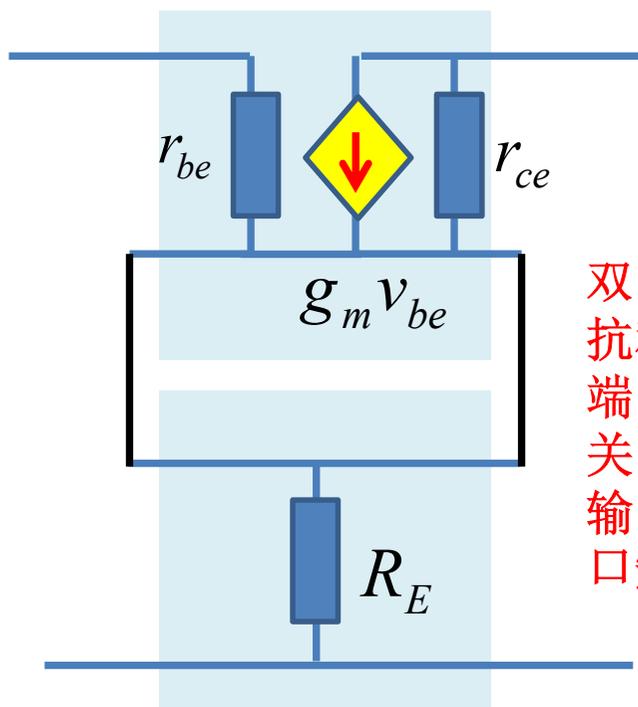
$$g_m = 40\text{mS}$$

$$r_{be} = 10\text{k}\Omega$$

$$r_{ce} = 100\text{k}\Omega$$

$$R_E = 100\Omega, 1\text{k}\Omega$$

- 负反馈电阻 $R_E$ 和BJT是串串连接关系，求
  - 总导纳参量 $y$ 
    - 先求总阻抗参量 $z$ ，再求逆
    - 先符号运算，再代入具体数值



双向网络输入阻抗和输出阻抗和端口外接负载有关，这里的输入、输出阻抗特指端口短路阻抗

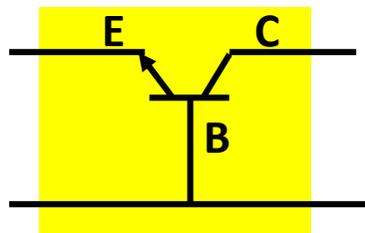
- 思考：如果负反馈电阻很大，串串负反馈形成的跨导放大器的输入电阻( $1/y_{11}$ )、输出电阻( $1/y_{22}$ )、跨导增益( $y_{21}$ )有无简单表达式？
- 加串串负反馈电阻后，形成的跨导放大器和原始晶体管的跨导放大器有何好处？

$$g_m r_{be} \gg 1; g_m r_{ce} \gg 1;$$

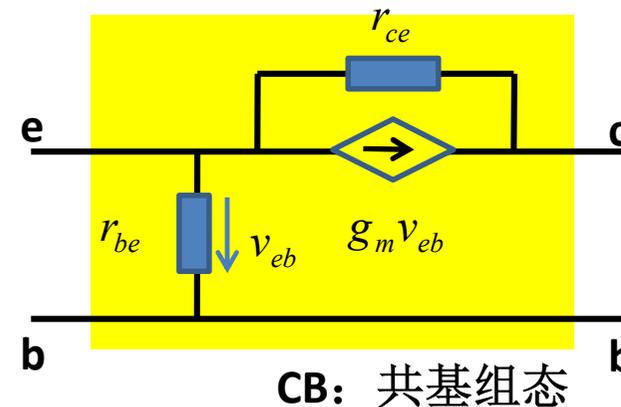
$$r_{be}, r_{ce} \gg R_E; g_m R_E \gg 1$$

# CAD

- 画出右侧**CB**组态等效电路，用**CAD**工具获得该二端口网络的 $\mathbf{y}$ 参量
- 画出 $\mathbf{y}$ 参量等效电路，确认确实是等效电路  
– 一样的输入，导致一样的输出



Common Base



CB: 共基组态