

电子电路与系统基础I

习题课第十三讲

第十一讲作业讲解
第十二讲作业讲解（部分）

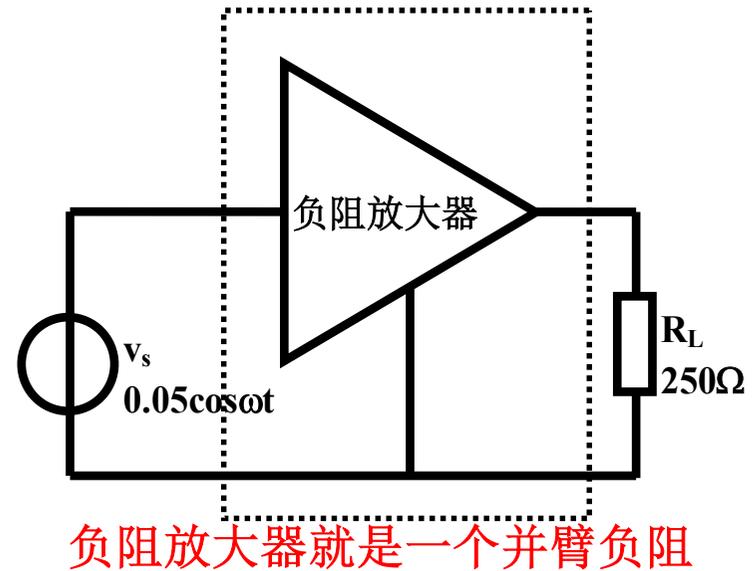
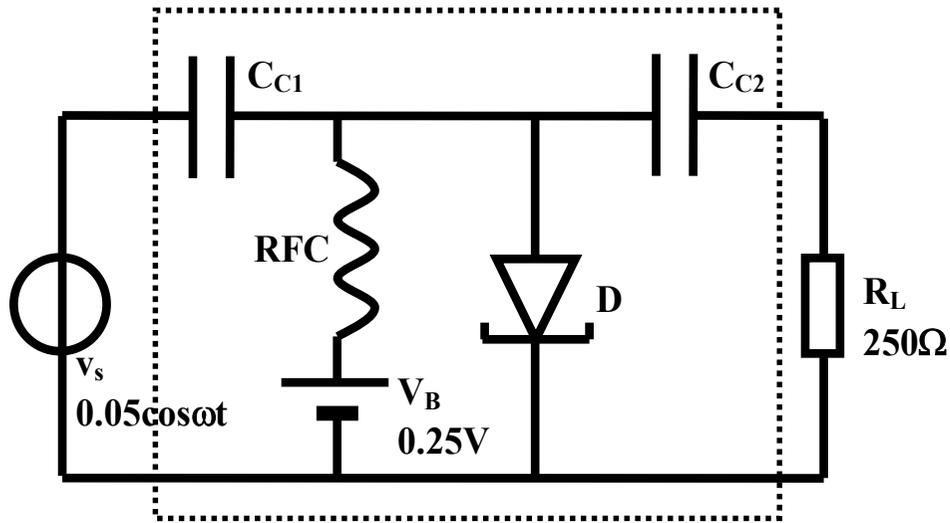
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第十一讲作业 作业1、2、3

交流小信号放大器网络参量及其对应等效电路

- (1) 给出图示二端口网络的网络参量（交流小信号参量，自选 z 、 y 、 h 和 S 参数）
 - 负阻放大器 p32图
 - 反射型负阻放大器 p33图
 - CE组态晶体管放大器 p48图
- (2) 给出对应参量的等效电路模型
- (3) 求放大器输入阻抗和输出阻抗
 - 考虑信源内阻、负载电阻的影响
- (4) 根据网络参量具体数值说明其有源性

负阻放大器抽象

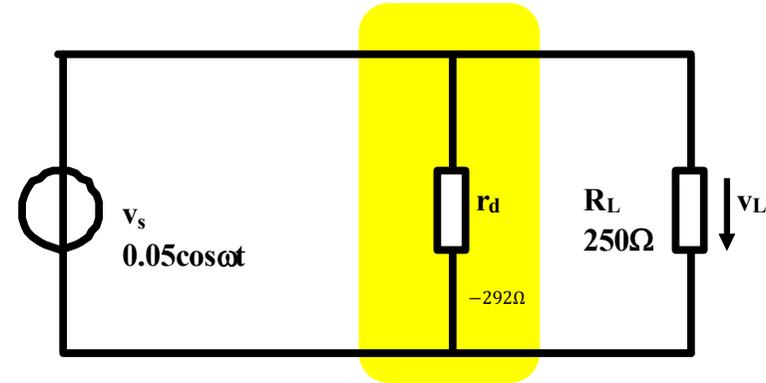
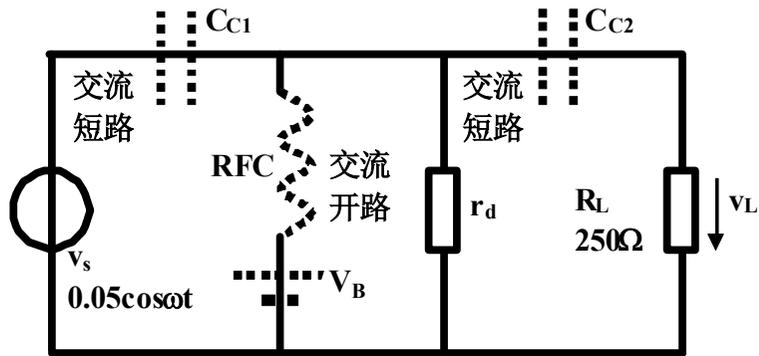
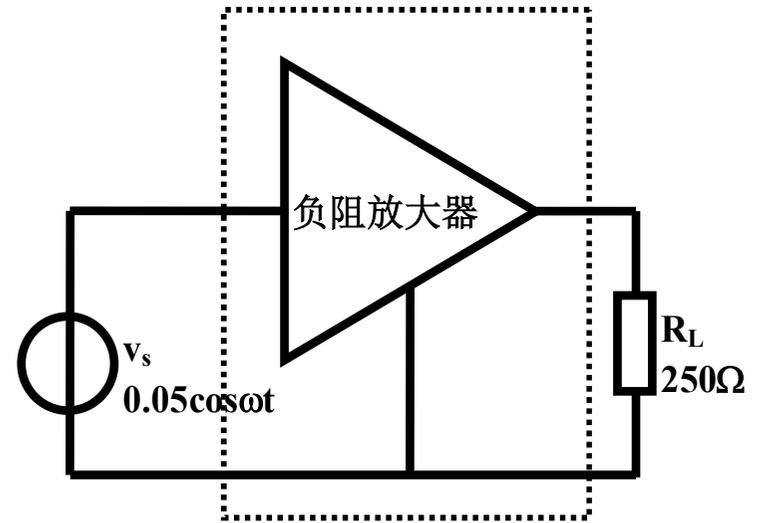
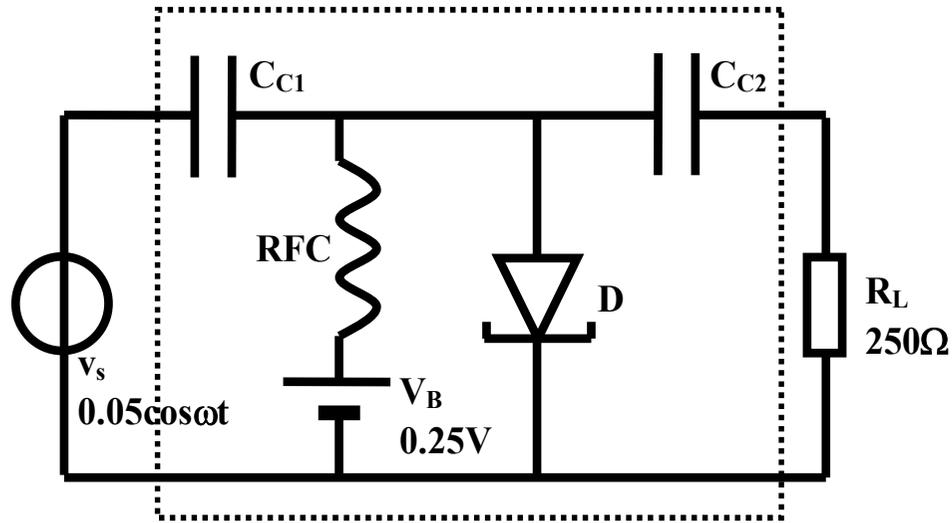


$$G_p = \frac{\overline{p_{out}}}{\overline{p_{in}}} = \frac{G_L}{G_L + g_d} > 1$$

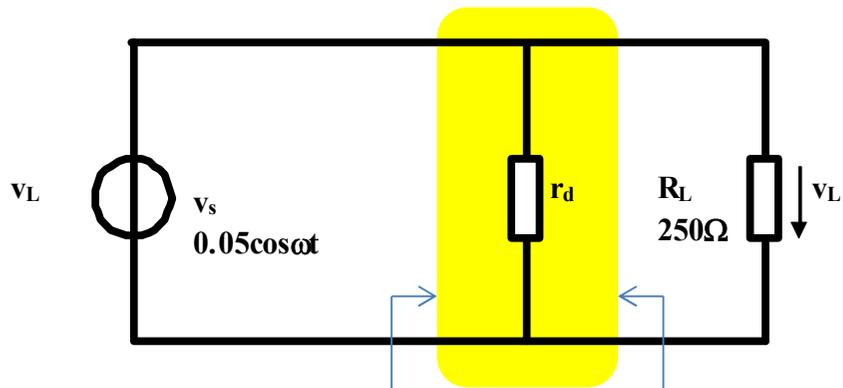
$$g_d < 0$$

作业1:

- (1) 给出图示虚框二端口网络的网络参量 (自选zyhg)
- (2) 给出对应参量的等效电路模型
- (3) 求放大器输入阻抗和输出阻抗



直流工作点位于负阻区，微分电阻为负阻



$$\mathbf{z} = \begin{bmatrix} r_d & r_d \\ r_d & r_d \end{bmatrix} = \begin{bmatrix} -292 & -292 \\ -292 & -292 \end{bmatrix} \Omega$$

并臂电阻, \mathbf{z} 参量

$$v_1 = (i_1 + i_2)r_d$$

$$v_2 = (i_1 + i_2)r_d$$

$$R_{in} = r_d || R_L$$

$$= \frac{r_d R_L}{r_d + R_L}$$

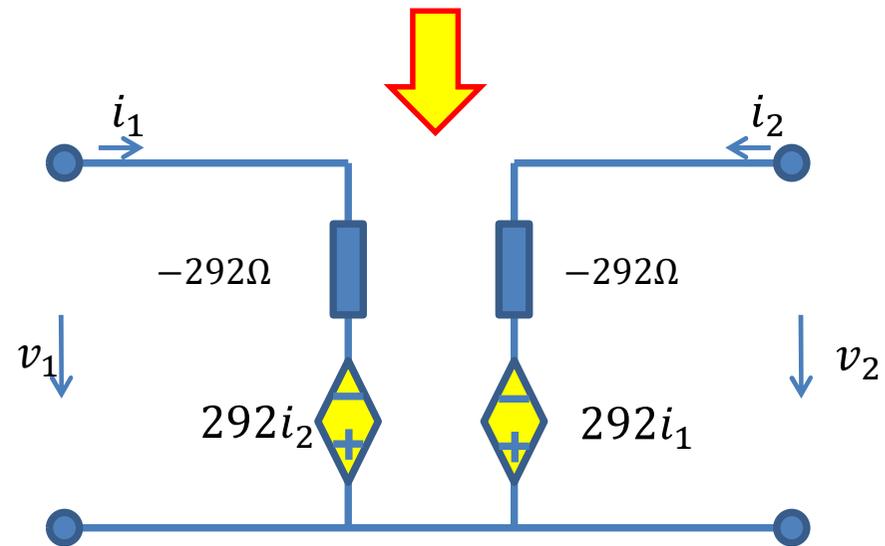
$$= \frac{-292 \times 250}{-292 + 250}$$

$$= 1.74 k\Omega$$

$$R_{out} = r_d || R_S = 0$$

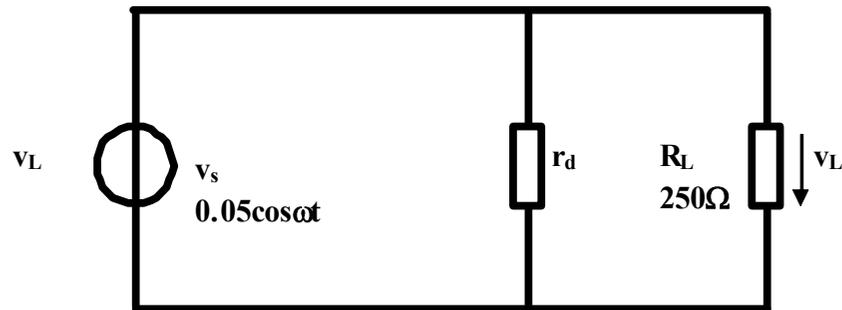
$$R_{in} = z_{11} - \frac{z_{12}z_{21}}{R_L + z_{22}}$$

$$R_{out} = z_{22} - \frac{z_{12}z_{21}}{R_S + z_{11}}$$



等效电路模型

有源性



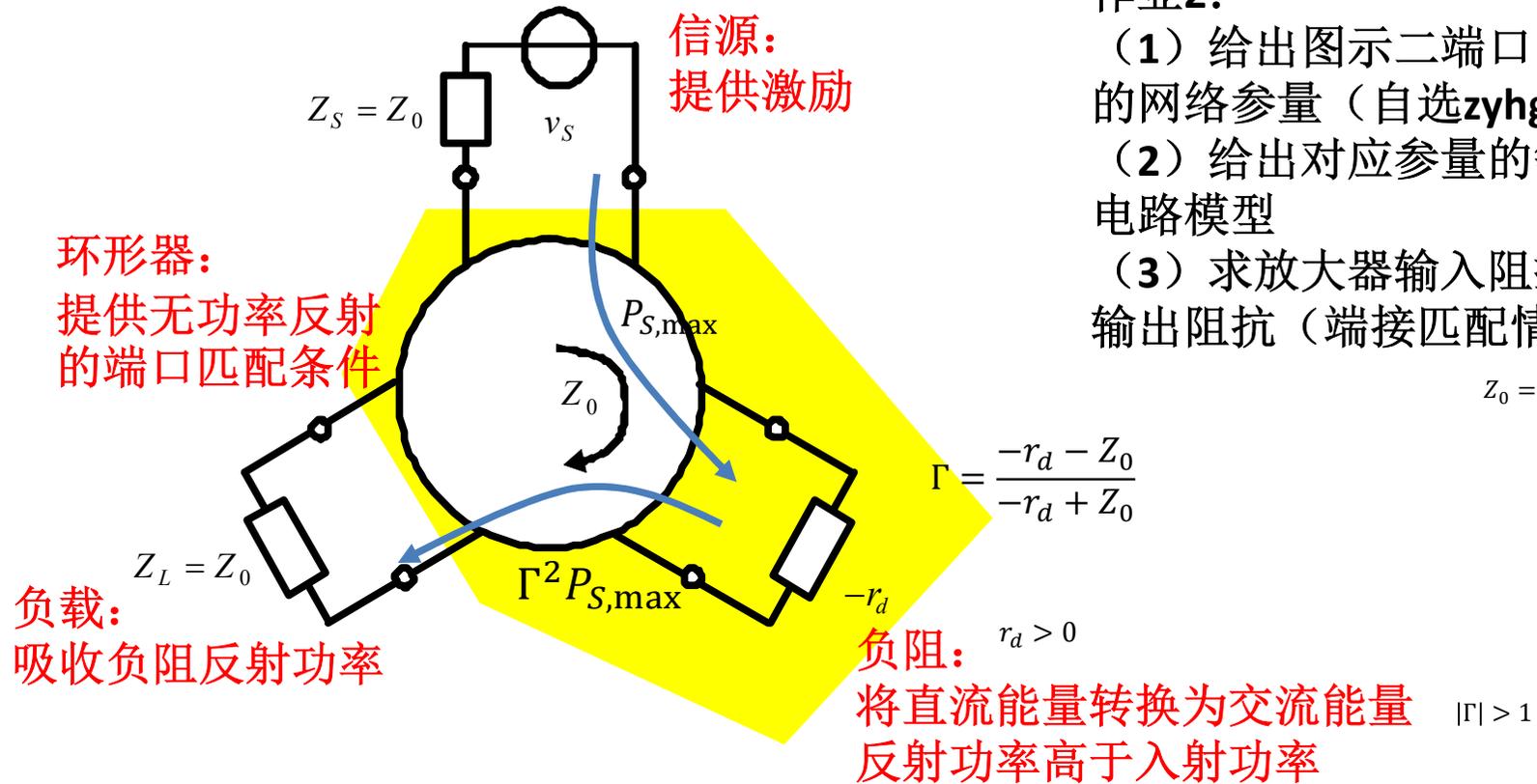
$$\mathbf{z} = \begin{bmatrix} r_d & r_d \\ r_d & r_d \end{bmatrix} = \begin{bmatrix} -292 & -292 \\ -292 & -292 \end{bmatrix} \Omega$$

只要端口电流之和不为0，
只要有电流流过负阻，
负阻即向外输出功率，
故而有源：具有向外输出功率的能力则称之为有源

$$\begin{aligned} p &= v_1 i_1 + v_2 i_2 \\ &= (r_d i_1 + r_d i_2) i_1 + (r_d i_1 + r_d i_2) i_2 \\ &= r_d (i_1^2 + 2i_1 i_2 + i_2^2) \\ &= r_d (i_1 + i_2)^2 \\ &= -292 \cdot (i_1 + i_2)^2 < 0 \end{aligned}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

反射型负阻放大器

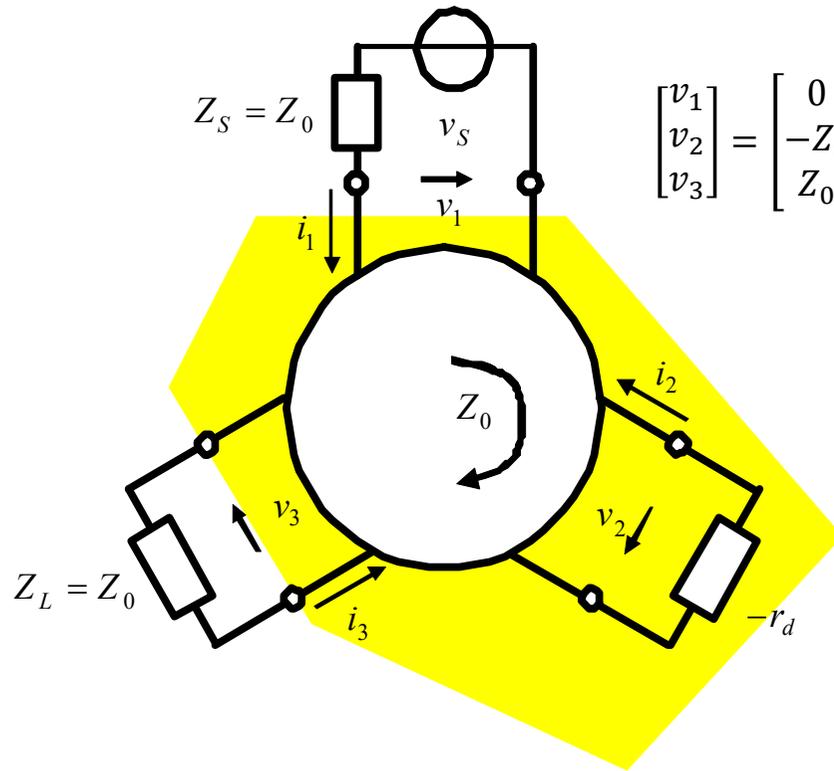


作业2:

- (1) 给出图示二端口网络的网络参量 (自选zyhg)
- (2) 给出对应参量的等效电路模型
- (3) 求放大器输入阻抗和输出阻抗 (端接匹配情况)

$$P_L = \Gamma^2 P_{Smax} = \left(\frac{Z_0 + r_d}{Z_0 - r_d} \right)^2 P_{Smax}$$

$$G_T = \frac{P_L}{P_{Smax}} = \Gamma^2 = \left(\frac{Z_0 + r_d}{Z_0 - r_d} \right)^2$$



$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

$$\begin{aligned} v_1 &= Z_0 i_2 - Z_0 i_3 \\ v_2 &= Z_0 i_3 - Z_0 i_1 \\ v_3 &= Z_0 i_1 - Z_0 i_2 \end{aligned}$$

环行器元件约束

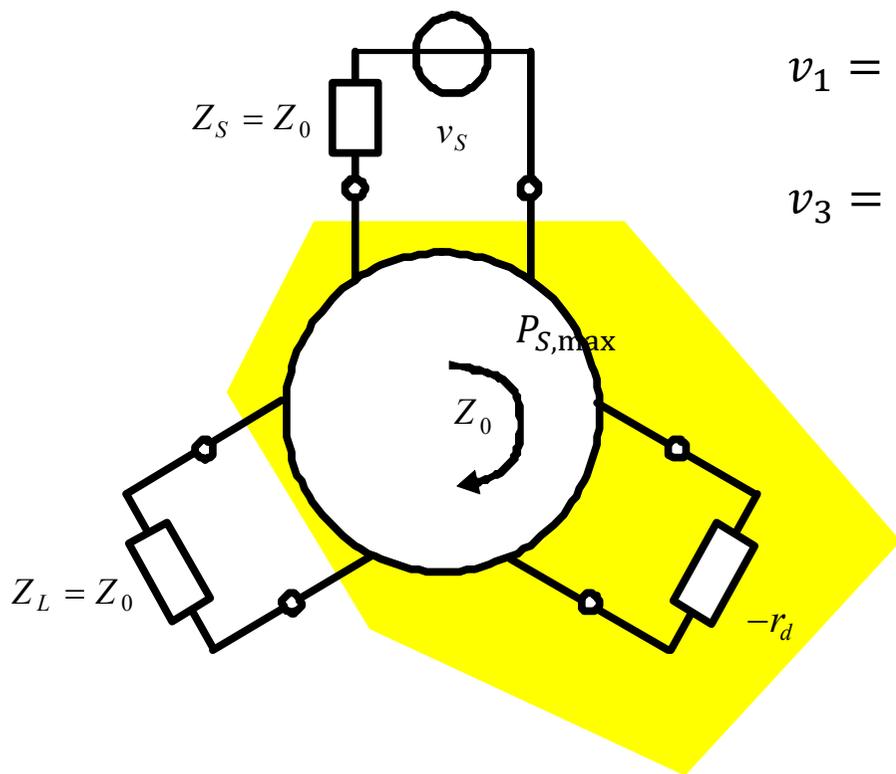
$$v_2 = r_d i_2 \quad \text{端口2接负阻: 负阻约束}$$

$$v_2 = Z_0 i_3 - Z_0 i_1 = r_d i_2$$

$$i_2 = \frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1$$

$$v_1 = Z_0 i_2 - Z_0 i_3 = Z_0 \left(\frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1 \right) - Z_0 i_3 = -\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0 \right) i_3$$

$$v_3 = Z_0 i_1 - Z_0 i_2 = Z_0 i_1 - Z_0 \left(\frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1 \right) = \left(\frac{Z_0^2}{r_d} + Z_0 \right) i_1 - \frac{Z_0^2}{r_d} i_3$$



$$v_1 = -\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0\right) i_3$$

$$v_3 = +\left(\frac{Z_0^2}{r_d} + Z_0\right) i_1 - \frac{Z_0^2}{r_d} i_3$$

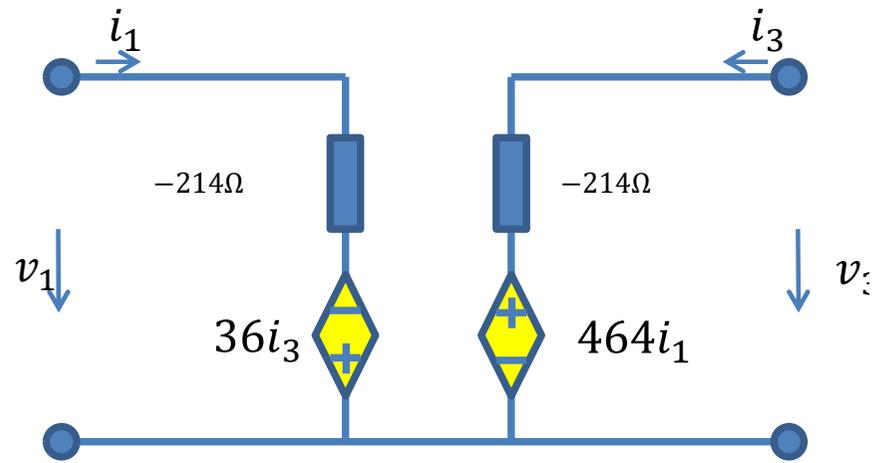
$$Z_0 = 250\Omega, r_d = 292\Omega$$

$$\mathbf{z} = \begin{bmatrix} -\frac{Z_0^2}{r_d} & \frac{Z_0^2}{r_d} - Z_0 \\ \frac{Z_0^2}{r_d} + Z_0 & -\frac{Z_0^2}{r_d} \end{bmatrix} = \begin{bmatrix} -214 & -36 \\ 464 & -214 \end{bmatrix} \Omega$$

非互易网络

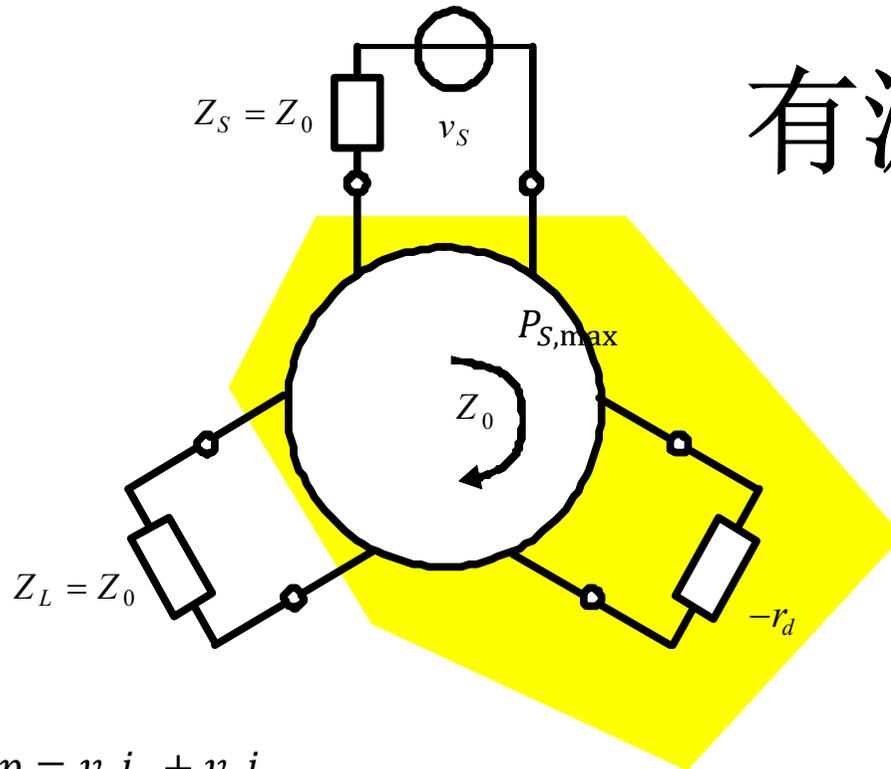
$$R_{in} = z_{11} - \frac{z_{12}z_{21}}{z_{22} + R_L} = -\frac{Z_0^2}{r_d} - \frac{\left(\frac{Z_0^2}{r_d} - Z_0\right)\left(\frac{Z_0^2}{r_d} + Z_0\right)}{-\frac{Z_0^2}{r_d} + Z_0} = Z_0$$

$$R_{out} = z_{22} - \frac{z_{12}z_{21}}{z_{11} + R_S} = -\frac{Z_0^2}{r_d} - \frac{\left(\frac{Z_0^2}{r_d} - Z_0\right)\left(\frac{Z_0^2}{r_d} + Z_0\right)}{-\frac{Z_0^2}{r_d} + Z_0} = Z_0$$



通过环行器，可以实现双端同时匹配

有源性



$$\mathbf{z} = \begin{bmatrix} -\frac{Z_0^2}{r_d} & \frac{Z_0^2}{r_d} - Z_0 \\ \frac{Z_0^2}{r_d} + Z_0 & -\frac{Z_0^2}{r_d} \end{bmatrix}$$

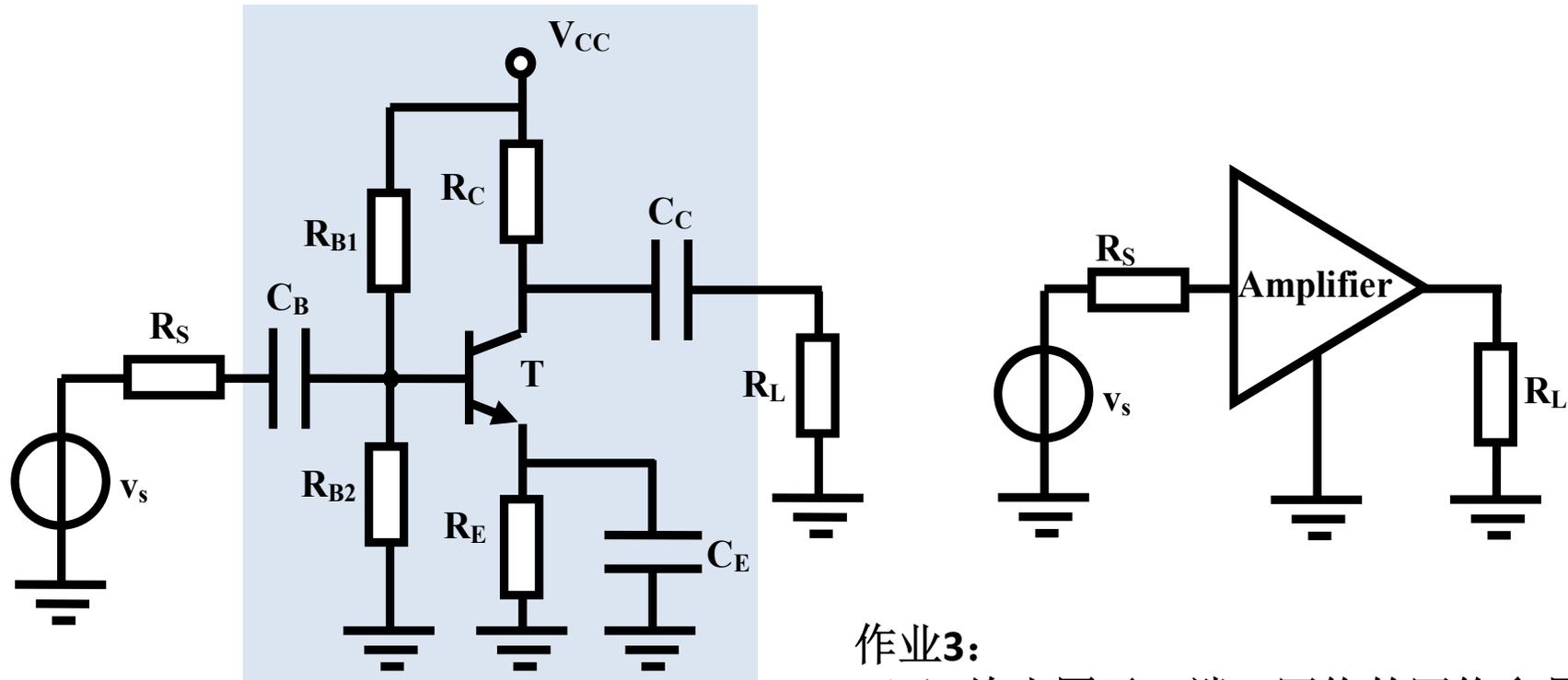
$$\begin{aligned} p &= v_1 i_1 + v_3 i_3 \\ &= \left(-\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0 \right) i_3 \right) i_1 + \left(\left(\frac{Z_0^2}{r_d} + Z_0 \right) i_1 - \frac{Z_0^2}{r_d} i_3 \right) i_3 \\ &= -\frac{Z_0^2}{r_d} i_1^2 - \frac{Z_0^2}{r_d} i_3^2 + 2 \frac{Z_0^2}{r_d} i_1 i_3 \\ &= -\frac{Z_0^2}{r_d} (i_1 - i_3)^2 < 0 \\ &= -\frac{v_2^2}{r_d} < 0 \end{aligned}$$

环形器+负阻：向外释放的纯功率全部是负阻释放的

只要端口电流之差不为0，只要有电压加载到负阻两端，负阻即向外输出功率，故有源

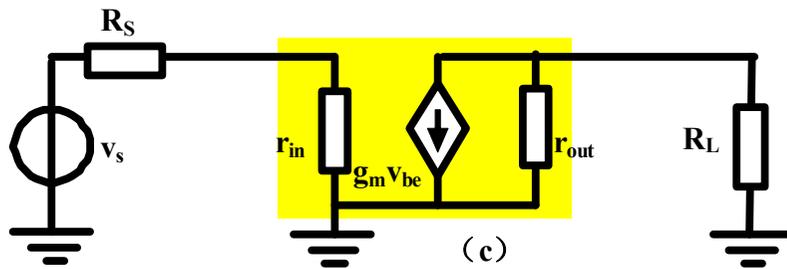
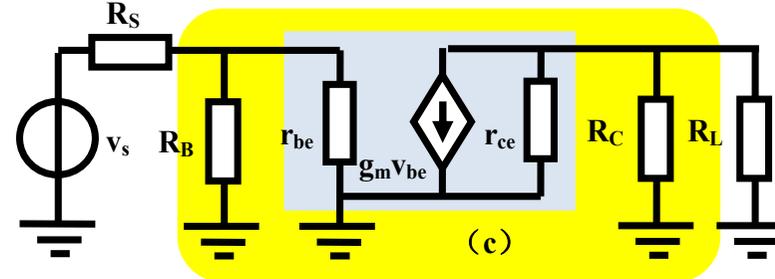
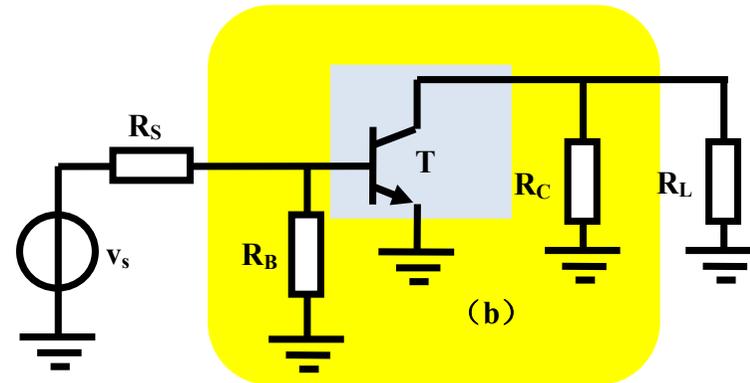
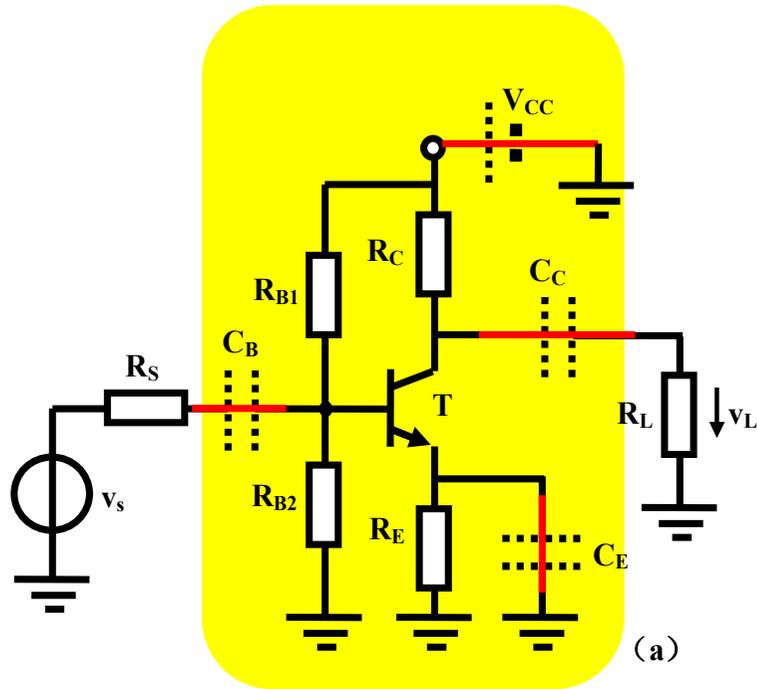
$$v_2 = Z_0 i_3 - Z_0 i_1$$

晶体管放大器抽象



作业3:

- (1) 给出图示二端口网络的网络参量 (自选zyhg)
- (2) 给出对应参量的等效电路模型
- (3) 求放大器输入阻抗和输出阻抗

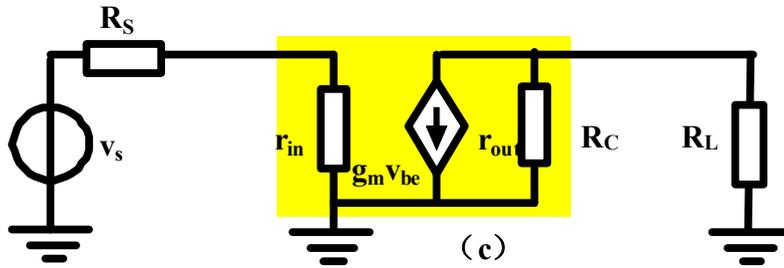


$$\begin{aligned}
 \mathbf{y} &= \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \\
 &= \begin{bmatrix} g_{be} + G_B & 0 \\ g_m & g_{ce} + G_C \end{bmatrix} \\
 &= \begin{bmatrix} 0.256 & 0 \\ 41.5 & 0.189 \end{bmatrix} mS
 \end{aligned}$$

$$r_{in} = \frac{1}{g_{be} + G_B} = r_{be} || R_B = 7.22k\Omega || 8.48k\Omega = 3.90k\Omega$$

$$r_{out} = \frac{1}{g_{ce} + G_C} = r_{ce} || R_C = 92.6k\Omega || 5.6k\Omega = 5.28k\Omega$$

有源性

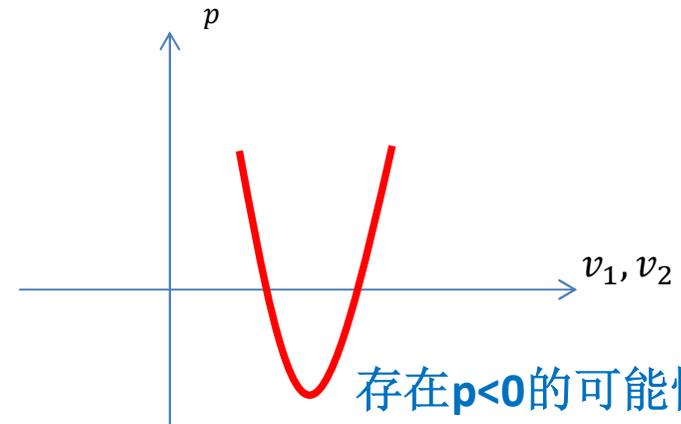


$$\begin{aligned}
 \mathbf{y} &= \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \\
 &= \begin{bmatrix} g_{be} + G_B & 0 \\ g_m & g_{ce} + G_C \end{bmatrix} \\
 &= \begin{bmatrix} 0.256 & 0 \\ 41.5 & 0.189 \end{bmatrix} \text{mS}
 \end{aligned}$$

$$\begin{aligned}
 p &= v_1 i_1 + v_2 i_2 \\
 &= v_1 ((g_{be} + G_B) v_1) + v_2 (g_m v_1 + (g_{ce} + G_C) v_2) \\
 &= (g_{be} + G_B) v_1^2 + g_m v_1 v_2 + (g_{ce} + G_C) v_2^2
 \end{aligned}$$

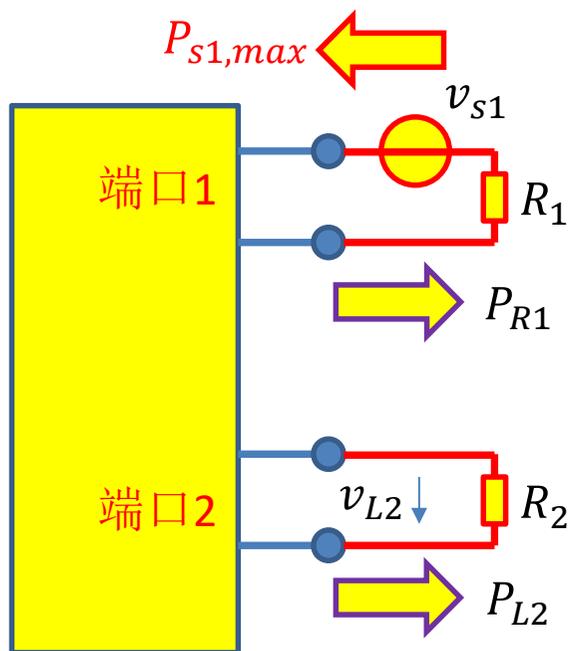
$$p < 0: \Delta = g_m^2 - 4(g_{be} + G_B)(g_{ce} + G_C) > 0$$

$$\begin{aligned}
 \Delta &= g_m^2 - 4(g_{be} + G_B)(g_{ce} + G_C) \\
 &= 41.5^2 - 4 \times 0.256 \times 0.189 = 1722 > 0
 \end{aligned}$$



存在 $p < 0$ 的可能性，
则可向外释放功率，
故而有源

S参量

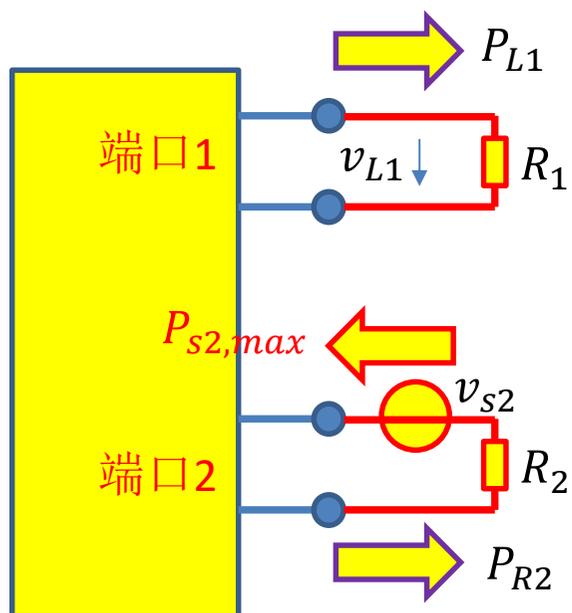


$$|S_{11}|^2 = \frac{P_{R1}}{P_{s1,max}}$$

$$|S_{21}|^2 = \frac{P_{L2}}{P_{s1,max}}$$

$$\mathbf{S}_{R1,R2} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} = \begin{bmatrix} \frac{z_{in}-R_1}{z_{in}+R_1} & 2\sqrt{\frac{R_2}{R_1}} \frac{v_{L1}}{v_{S2}} \\ 2\sqrt{\frac{R_1}{R_2}} \frac{v_{L2}}{v_{S1}} & \frac{z_{out}-R_2}{z_{out}+R_2} \end{bmatrix}$$

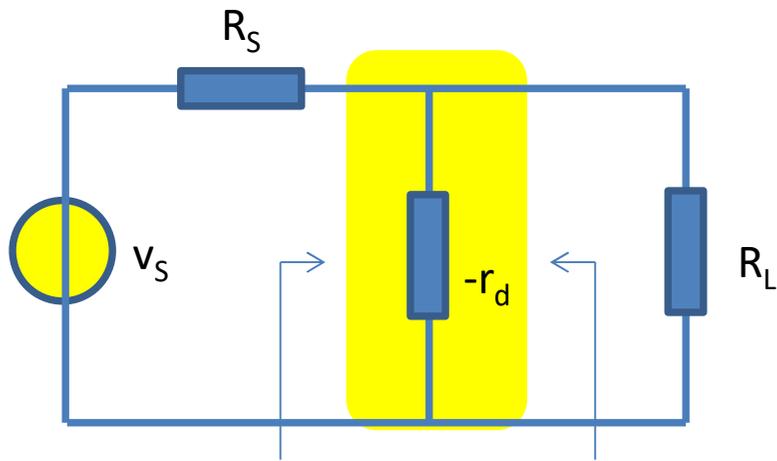
要求掌握S参量
定义下的S参量
计算，明确其物
理意义



$$|S_{12}|^2 = \frac{P_{L1}}{P_{s2,max}}$$

$$|S_{22}|^2 = \frac{P_{R2}}{P_{s2,max}}$$

负阻放大器：直接型



$$\begin{aligned}
 s_{11} &= \frac{z_{in} - R_S}{z_{in} + R_S} = \frac{R_L \parallel (-r_d) - R_S}{R_L \parallel (-r_d) + R_S} = \frac{\frac{-R_L r_d}{R_L - r_d} - R_S}{\frac{-R_L r_d}{R_L - r_d} + R_S} \\
 &= \frac{-R_L r_d - R_S R_L + R_S r_d}{-R_L r_d + R_S R_L - R_S r_d} \stackrel{R_S=R_L}{=} \frac{-r_d(R_S + R_L) + R_S R_L}{-r_d(R_S + R_L) + R_S R_L} \\
 &= \frac{1}{\frac{r_d}{R_S \parallel R_L} - 1} = \frac{1}{\frac{292}{25} - 1} = 0.0936
 \end{aligned}$$

二端口网络式对称，故而

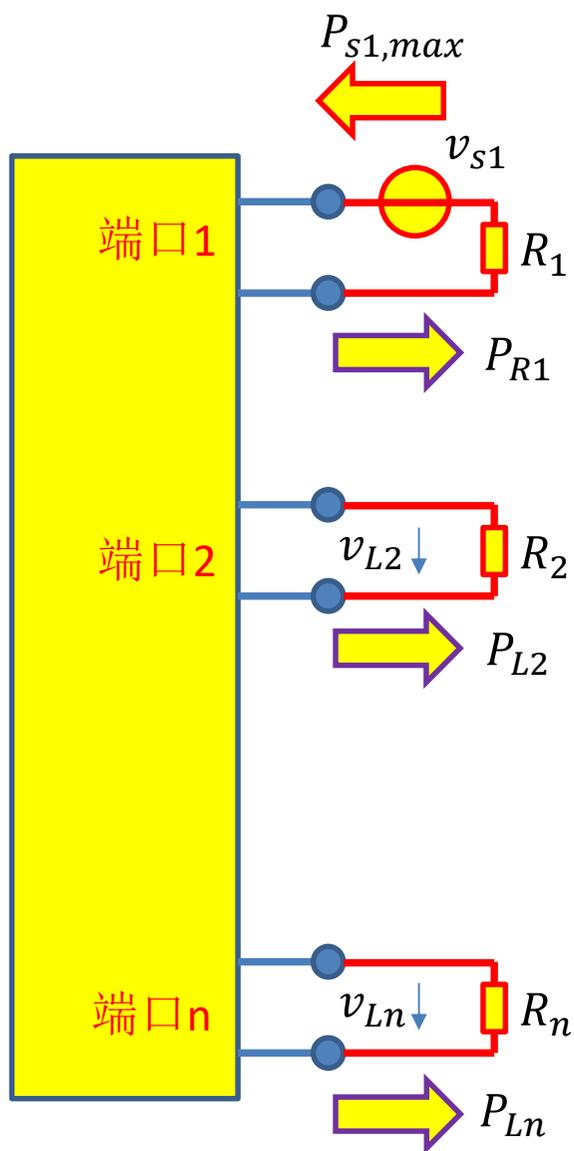
$$s_{22} = s_{11}$$

$$s_{12} = s_{21}$$

$$s_{R_S=50\Omega, R_L=50\Omega} = \begin{bmatrix} 0.0936 & 1.0936 \\ 1.0936 & 0.0936 \end{bmatrix}$$

$$\begin{aligned}
 s_{21} &= 2 \sqrt{\frac{R_S}{R_L} \frac{v_{L2}}{v_{S1}}} = 2 \sqrt{\frac{R_S}{R_L} \frac{R_L \parallel (-r_d)}{R_L \parallel (-r_d) + R_S}} \\
 &= 2 \sqrt{\frac{R_S}{R_L} \frac{\frac{-R_L r_d}{R_L - r_d}}{\frac{-R_L r_d}{R_L - r_d} + R_S}} = 2 \sqrt{\frac{R_S}{R_L} \frac{-R_L r_d}{-r_d(R_S + R_L) + R_S R_L}} \\
 &= 2 \frac{-50 \times 292}{-292 \times 100 + 50 \times 50} = 1.0936
 \end{aligned}$$

散射参量和阻抗导纳参量之间 可相互转换：n端口网络



归一化阻抗参量

$$\hat{z} = \begin{bmatrix} \frac{1}{\sqrt{R_1}} & & \\ & \ddots & \\ & & \frac{1}{\sqrt{R_n}} \end{bmatrix} z \begin{bmatrix} \frac{1}{\sqrt{R_1}} & & \\ & \ddots & \\ & & \frac{1}{\sqrt{R_n}} \end{bmatrix}$$

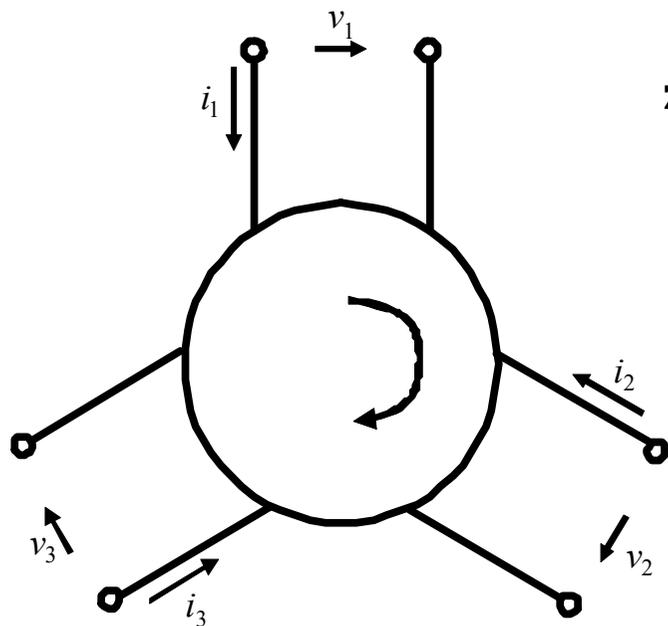
$$s = (\hat{z} + I)^{-1}(\hat{z} - I)$$

$$s = (I - \hat{y})(I + \hat{y})^{-1}$$

$$\hat{z} = (I + s)(I - s)^{-1}$$

$$\hat{y} = (I - s)(I + s)^{-1}$$

$$z = \begin{bmatrix} \sqrt{R_1} & & \\ & \ddots & \\ & & \sqrt{R_n} \end{bmatrix} \hat{z} \begin{bmatrix} \sqrt{R_1} & & \\ & \ddots & \\ & & \sqrt{R_n} \end{bmatrix}$$



$$\mathbf{z} = \begin{bmatrix} 0 & R & -R \\ -R & 0 & R \\ R & -R & 0 \end{bmatrix}$$

环行器例

在 $R_1 = R_2 = R_3 = Z_0 = R$ 条件下

$$\hat{\mathbf{z}} = \begin{bmatrix} \frac{1}{\sqrt{R}} & & \\ & \frac{1}{\sqrt{R}} & \\ & & \frac{1}{\sqrt{R}} \end{bmatrix} \begin{bmatrix} 0 & R & -R \\ -R & 0 & R \\ R & -R & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{R}} & & \\ & \frac{1}{\sqrt{R}} & \\ & & \frac{1}{\sqrt{R}} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix}$$

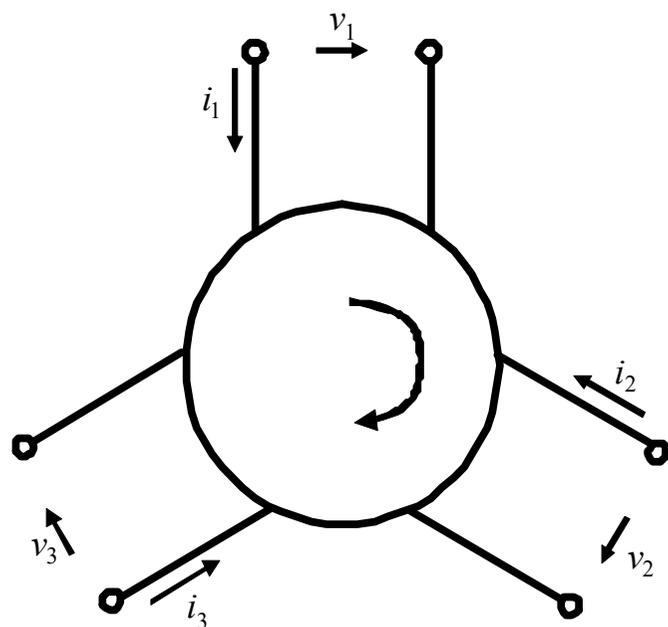
$$\mathbf{s} = (\hat{\mathbf{z}} + \mathbf{I})^{-1}(\hat{\mathbf{z}} - \mathbf{I})$$

$$= \begin{bmatrix} 1 & 1 & -1 \\ -1 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -1 & 1 & -1 \\ -1 & -1 & 1 \\ 1 & -1 & -1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

在三个端口均端接匹配时，端口1信号只能反相无损传输到端口2，端口2信号只能反相无损传输到端口3，端口3信号只能反相无损传输到端口1：环行

思考题



$$S_{R_1=R_2=R_3=Z_0} = \begin{bmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

$$z = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix}$$

$$S_{R_1=R_2=R_3=Z_0} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

请给出该理想环行器的zy参量矩阵？

n端口线性网络的S参量一定存在，但zy参量可能不存在

二端口网络的散射参量和阻抗导纳参量之间的转换关系式

$$s = (\hat{z} + I)^{-1}(\hat{z} - I)$$

$$s = (I - \hat{y})(I + \hat{y})^{-1}$$

$$S_{11} = \frac{\Delta \hat{z} + \hat{z}_{11} - \hat{z}_{22} - 1}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1}$$

$$S_{11} = -\frac{\Delta \hat{y} + \hat{y}_{11} - \hat{y}_{22} - 1}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1}$$

$$S_{12} = \frac{2\hat{z}_{12}}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1}$$

$$S_{12} = -\frac{2\hat{y}_{12}}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1}$$

$$S_{21} = \frac{2\hat{z}_{21}}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1}$$

$$S_{21} = -\frac{2\hat{y}_{21}}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1}$$

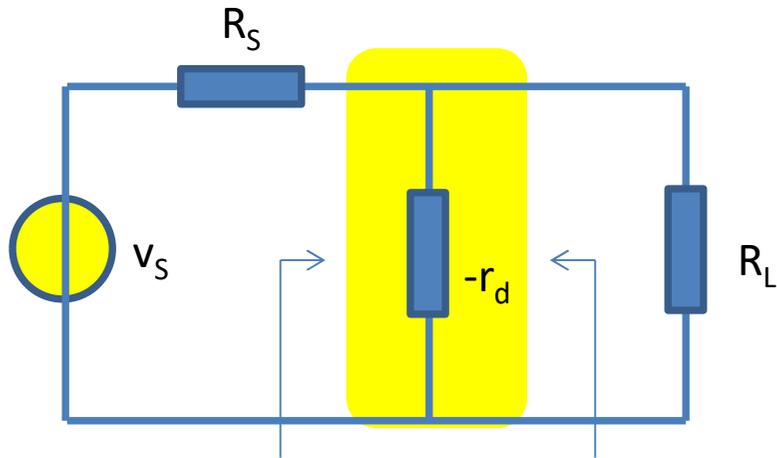
$$S_{22} = \frac{\Delta \hat{z} + \hat{z}_{22} - \hat{z}_{11} - 1}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1}$$

$$S_{22} = -\frac{\Delta \hat{y} + \hat{y}_{22} - \hat{y}_{11} - 1}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1}$$

$$\hat{z} = (I + s)(I - s)^{-1}$$

$$\hat{y} = (I - s)(I + s)^{-1}$$

套公式计算



$$z = \begin{bmatrix} -r_d & -r_d \\ -r_d & -r_d \end{bmatrix}$$

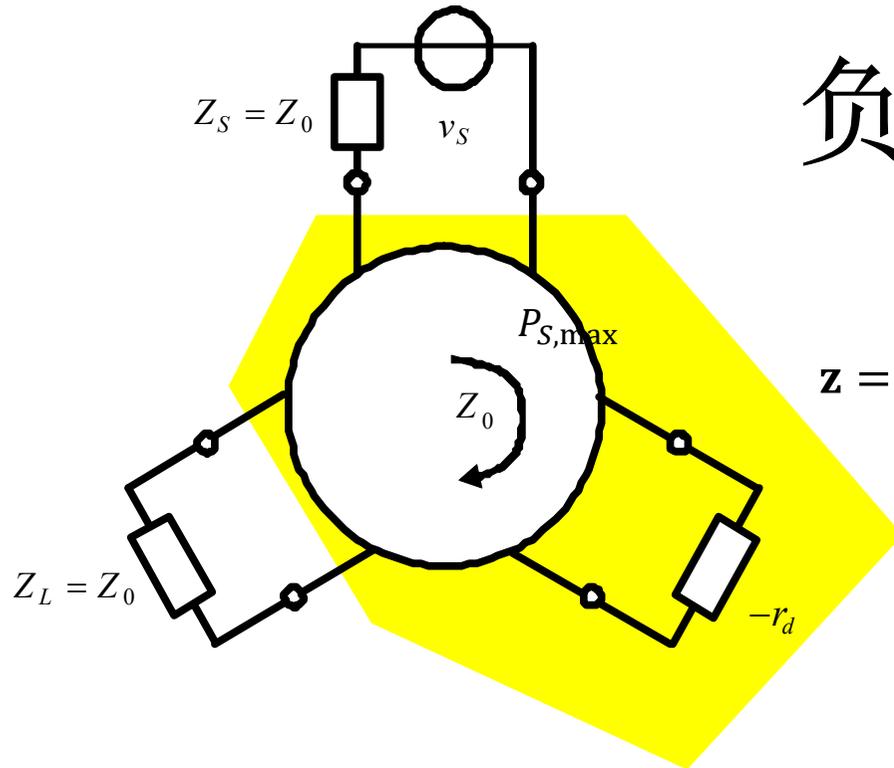
$$\hat{z} = \begin{bmatrix} \frac{1}{\sqrt{R_S}} & \\ & \frac{1}{\sqrt{R_L}} \end{bmatrix} \begin{bmatrix} -r_d & -r_d \\ -r_d & -r_d \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{R_S}} & \\ & \frac{1}{\sqrt{R_L}} \end{bmatrix} = \begin{bmatrix} -\frac{r_d}{R_S} & -\frac{r_d}{\sqrt{R_S R_L}} \\ -\frac{r_d}{\sqrt{R_S R_L}} & -\frac{r_d}{R_L} \end{bmatrix}$$

$$s_{11} = \frac{\Delta \hat{z} + \hat{z}_{11} - \hat{z}_{22} - 1}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1} = \frac{-1}{-\frac{r_d}{R_S} - \frac{r_d}{R_L} + 1} = \frac{1}{\frac{r_d}{R_S || R_L} - 1} = 0.0936$$

$$S_{R_S=50\Omega, R_L=50\Omega} = \begin{bmatrix} 0.0936 & 1.0936 \\ 1.0936 & 0.0936 \end{bmatrix}$$

$$s_{21} = \frac{2\hat{z}_{21}}{\Delta \hat{z} + \hat{z}_{11} + \hat{z}_{22} + 1} = \frac{2\frac{-r_d}{\sqrt{R_S R_L}}}{-\frac{r_d}{R_S} - \frac{r_d}{R_L} + 1} = \frac{2\frac{r_d}{\sqrt{R_S R_L}}}{\frac{r_d}{R_S || R_L} - 1} = 1.0936$$

负阻放大器：反射型



$$\mathbf{z} = \begin{bmatrix} -\frac{Z_0^2}{r_d} & \frac{Z_0^2}{r_d} - Z_0 \\ \frac{Z_0^2}{r_d} + Z_0 & -\frac{Z_0^2}{r_d} \end{bmatrix}$$

$$\hat{\mathbf{z}}_{R_1=Z_0, R_3=Z_0} = \begin{bmatrix} -\frac{Z_0}{r_d} & \frac{Z_0}{r_d} - 1 \\ \frac{Z_0}{r_d} + 1 & -\frac{Z_0}{r_d} \end{bmatrix}$$

$$S_{11} = \frac{\Delta \hat{\mathbf{z}} + \hat{z}_{11} - \hat{z}_{22} - 1}{\Delta \hat{\mathbf{z}} + \hat{z}_{11} + \hat{z}_{22} + 1} = \frac{1 - 1}{1 - \frac{Z_0}{r_d} - \frac{Z_0}{r_d} + 1} = 0$$

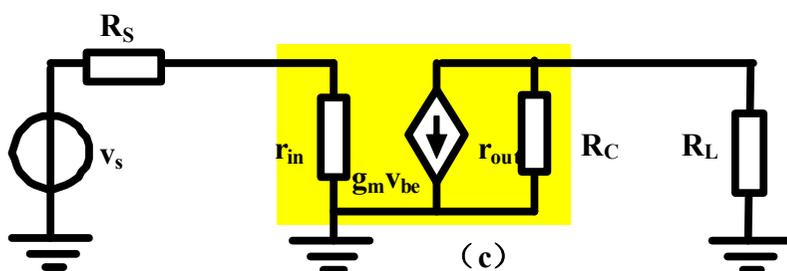
$$S_{12} = \frac{2\hat{z}_{12}}{\Delta \hat{\mathbf{z}} + \hat{z}_{11} + \hat{z}_{22} + 1} = \frac{2\left(\frac{Z_0}{r_d} - 1\right)}{1 - \frac{Z_0}{r_d} - \frac{Z_0}{r_d} + 1} = -1$$

$$S_{21} = \frac{2\hat{z}_{21}}{\Delta \hat{\mathbf{z}} + \hat{z}_{11} + \hat{z}_{22} + 1} = \frac{2\left(\frac{Z_0}{r_d} + 1\right)}{1 - \frac{Z_0}{r_d} - \frac{Z_0}{r_d} + 1} = \frac{Z_0 + r_d}{r_d - Z_0} = \Gamma_d$$

$$\mathbf{S}_{R_1=Z_0, R_2=Z_0} = \begin{bmatrix} 0 & -1 \\ \Gamma_d & 0 \end{bmatrix}$$

双向非互易网络
 端口1到端口3功率增益>1
 端口3到端口1功率增益为1

CE组态晶体管放大器



$$\begin{aligned}
 \mathbf{y} &= \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \\
 &= \begin{bmatrix} g_{be} + G_B & 0 \\ g_m & g_{ce} + G_C \end{bmatrix} \\
 &= \begin{bmatrix} 0.256 & 0 \\ 41.5 & 0.189 \end{bmatrix} mS
 \end{aligned}$$

$$\begin{aligned}
 \hat{\mathbf{y}} &= \begin{bmatrix} \frac{1}{\sqrt{G_S}} & \\ & \frac{1}{\sqrt{G_L}} \end{bmatrix} \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{G_S}} & \\ & \frac{1}{\sqrt{G_L}} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{g_{in}}{G_S} & 0 \\ \frac{g_m}{\sqrt{G_S G_L}} & \frac{g_{out}}{G_L} \end{bmatrix} \stackrel{G_S=g_{in}, G_L=g_{out}}{\cong} \begin{bmatrix} 1 & 0 \\ \frac{g_m}{\sqrt{g_{in} g_{out}}} & 1 \end{bmatrix}
 \end{aligned}$$

$$s_{11} = -\frac{\Delta \hat{y} + \hat{y}_{11} - \hat{y}_{22} - 1}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1} = 0$$

$$s_{21} = -\frac{2\hat{y}_{21}}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1}$$

$$= -\frac{2 \frac{g_m}{\sqrt{g_{in} g_{out}}}}{1 + 1 + 1 + 1} = -\frac{1}{2} \frac{g_m}{\sqrt{g_{in} g_{out}}}$$

$$S_{G_1=g_{in}, G_2=g_{out}} = \begin{bmatrix} 0 & 0 \\ -\frac{1}{2} \frac{g_m}{\sqrt{g_{in} g_{out}}} & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ -94.33 & 0 \end{bmatrix}$$

CE组态晶体管放大器

$$\begin{aligned}
 \mathbf{y} &= \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \\
 &= \begin{bmatrix} g_{be} + G_B & 0 \\ g_m & g_{ce} + G_C \end{bmatrix} \\
 &= \begin{bmatrix} 0.256 & 0 \\ 41.5 & 0.189 \end{bmatrix} mS
 \end{aligned}$$

$$\begin{aligned}
 s_{11} &= -\frac{\Delta \hat{y} + \hat{y}_{11} - \hat{y}_{22} - 1}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1} = -\frac{\frac{Z_0^2}{r_{in}r_{out}} + \frac{Z_0}{r_{in}} - \frac{Z_0}{r_{out}} - 1}{\frac{Z_0^2}{r_{in}r_{out}} + \frac{Z_0}{r_{in}} + \frac{Z_0}{r_{out}} + 1} \\
 &= -\frac{\left(\frac{Z_0}{r_{in}} - 1\right)\left(\frac{Z_0}{r_{out}} + 1\right)}{\left(\frac{Z_0}{r_{in}} + 1\right)\left(\frac{Z_0}{r_{out}} + 1\right)} = \frac{r_{in} - Z_0}{r_{in} + Z_0} = \Gamma_{in}
 \end{aligned}$$

$$\begin{aligned}
 \hat{\mathbf{y}} &= \begin{bmatrix} \frac{1}{\sqrt{G_S}} & \\ & \frac{1}{\sqrt{G_L}} \end{bmatrix} \begin{bmatrix} g_{in} & 0 \\ g_m & g_{out} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{G_S}} & \\ & \frac{1}{\sqrt{G_L}} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{g_{in}}{G_S} & 0 \\ \frac{g_m}{\sqrt{G_S G_L}} & \frac{g_{out}}{G_L} \end{bmatrix} \stackrel{R_S=R_L=Z_0=50\Omega}{\cong} \begin{bmatrix} g_{in}Z_0 & 0 \\ g_mZ_0 & g_{out}Z_0 \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 s_{21} &= -\frac{2\hat{y}_{21}}{\Delta \hat{y} + \hat{y}_{11} + \hat{y}_{22} + 1} = -\frac{2g_mZ_0}{\left(\frac{Z_0}{r_{in}} + 1\right)\left(\frac{Z_0}{r_{out}} + 1\right)} \\
 &= -\frac{2g_mZ_0r_{in}r_{out}}{(Z_0 + r_{in})(Z_0 + r_{out})} = 2\sqrt{\frac{Z_0}{Z_0 + r_{in}} \frac{r_{out}Z_0}{Z_0 + r_{out}}} (-g_m) \frac{r_{in}}{Z_0 + r_{in}}
 \end{aligned}$$

单向网络电压增益

阻抗严重不匹配

$$\mathbf{s}_{R_S=R_L=Z_0=50\Omega} = \begin{bmatrix} \Gamma_{in} & 0 \\ -2\sqrt{\frac{R_S}{R_L}} \frac{v_L}{v_S} & \Gamma_{out} \end{bmatrix} = \begin{bmatrix} 0.9747 & 0 \\ -4.0592 & 0.9813 \end{bmatrix}$$

12.2dB反相增益

对S参量的要求

- 记住定义

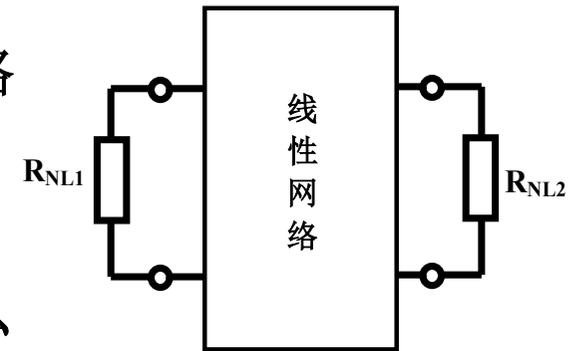
$$\mathbf{S}_{R_1, R_2} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} = \begin{bmatrix} \frac{z_{in} - R_1}{z_{in} + R_1} & 2 \sqrt{\frac{R_2}{R_1}} \frac{v_{L1}}{v_{S2}} \\ 2 \sqrt{\frac{R_1}{R_2}} \frac{v_{L2}}{v_{S1}} & \frac{z_{out} - R_2}{z_{out} + R_2} \end{bmatrix}$$

- 知道S参量物理含义
- 会根据定义计算S参量
- S参量和Z参量Y参量转换关系
 - 知道可以相互转换，需要时会查公式运用即可

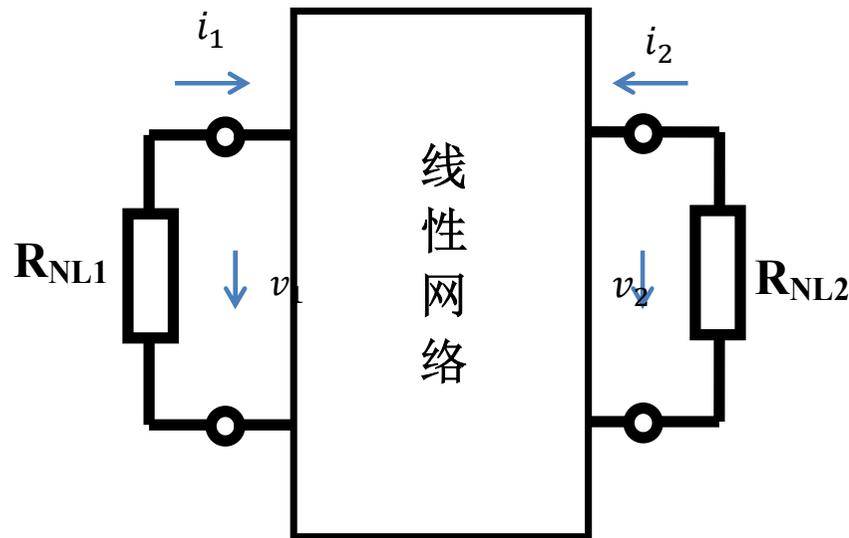
作业 4

非线性局部线性化

- **练习4.30:** 如图所示, 假设某非线性电路中包含两个单端口的非线性电阻器件, 剩余的电路则是线性电阻电路和理想电源构成的线性网络。
 - (1) 假设两个非线性电阻器件都是压控器件, 则二端口的线性网络应该采用什么参量描述比较适当?
 - (2) 假设两个非线性电阻器件都是流控器件, 则二端口的线性网络应该采用什么参量描述比较适当?
 - (3) 假设两个非线性电阻器件一个是压控器件, 一个是流控器件, 则二端口的线性网络应该采用什么参量描述比较适当?
 - (4) 不妨假设两个非线性电阻器件都是流控器件, 并且假设线性网络中的源等效中包含直流分量和交流小信号分量, 请描述该网络的交直流分析全过程。



两个非线性电阻都是压控器件



简单对接关系，每个端口只需定义一套端口电压、端口电流即可

压控器件

$$-i_1 = i_{NL1} = f_{iv,1}(v_{NL1}) = f_{iv,1}(v_1) \quad R_{NL1}$$

$$-i_2 = i_{NL2} = f_{iv,2}(v_{NL2}) = f_{iv,2}(v_2) \quad R_{NL2}$$

所谓压控，就是以电压作为自变量描述其他因变量，如电流：故而应首先获得电压，其次由电压获得电流

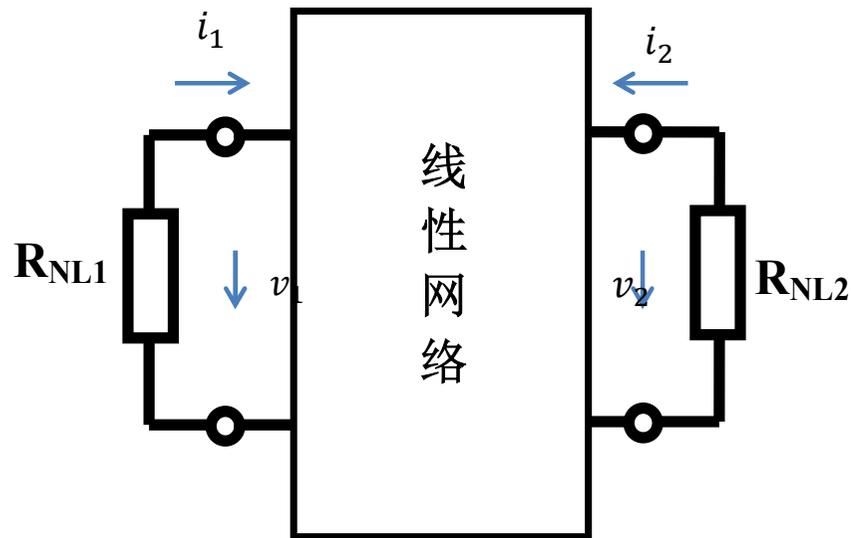
$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \mathbf{y} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} i_{N1} \\ i_{N2} \end{bmatrix} \quad \text{线性网络}$$

全部采用压控形式，则最终电路方程中只有电压为未知量

$$\begin{bmatrix} f_{iv,1}(v_1) \\ f_{iv,2}(v_2) \end{bmatrix} + \mathbf{y} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} i_{N1} \\ i_{N2} \end{bmatrix} = 0 \quad \text{最适电路方程}$$

由此方程求出 v_1, v_2 ，再代回求 i_1, i_2

两个非线性电阻都是流控器件



简单对接关系，每个端口只需定义一套端口电压、端口电流即可

流控器件

$$v_1 = v_{NL1} = f_{vi,1}(i_{NL1}) = f_{vi,1}(-i_1) \quad \mathbf{R_{NL1}}$$

$$v_2 = v_{NL2} = f_{vi,2}(i_{NL2}) = f_{vi,2}(-i_2) \quad \mathbf{R_{NL2}}$$

所谓流控，就是以电流作为自变量描述其他因变量，如电压：故而应首先获得电流，其次由电流求取电压

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \mathbf{z} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

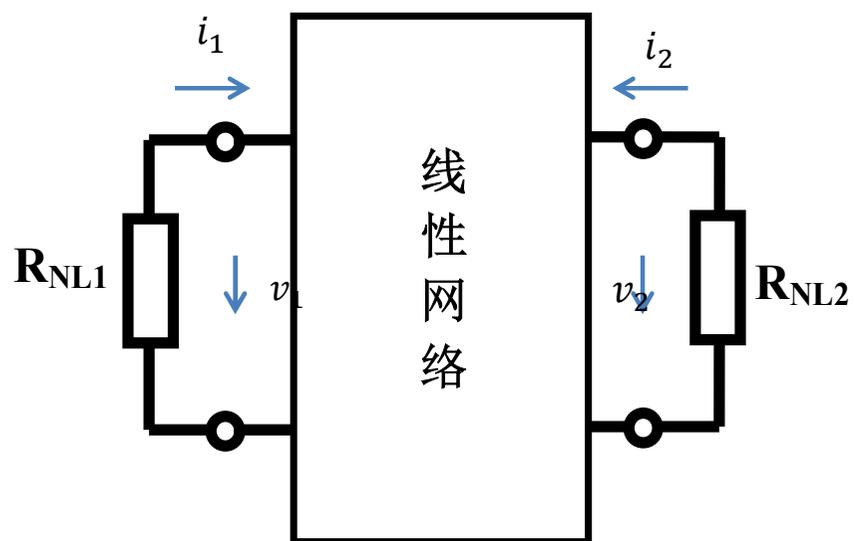
线性网络

$$\begin{bmatrix} f_{vi,1}(-i_1) \\ f_{vi,2}(-i_2) \end{bmatrix} = \mathbf{z} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

最适
电路
方程

由此方程求出 i_1, i_2 ，再代回求 v_1, v_2

两个非线性电阻一压控一流控



R_{NL1} 压控 R_{NL2} 流控, g 参量描述线性网络最适当: 获得最适电路方程

R_{NL1} 流控 R_{NL2} 压控, h 参量描述线性网络最适当: 获得最适电路方程

压控器件

$$-i_1 = i_{NL1} = f_{iv,1}(v_{NL1}) = f_{iv,1}(v_1) \quad R_{NL1}$$

流控器件

$$v_2 = v_{NL2} = f_{vi,2}(i_{NL2}) = f_{vi,2}(-i_2) \quad R_{NL2}$$

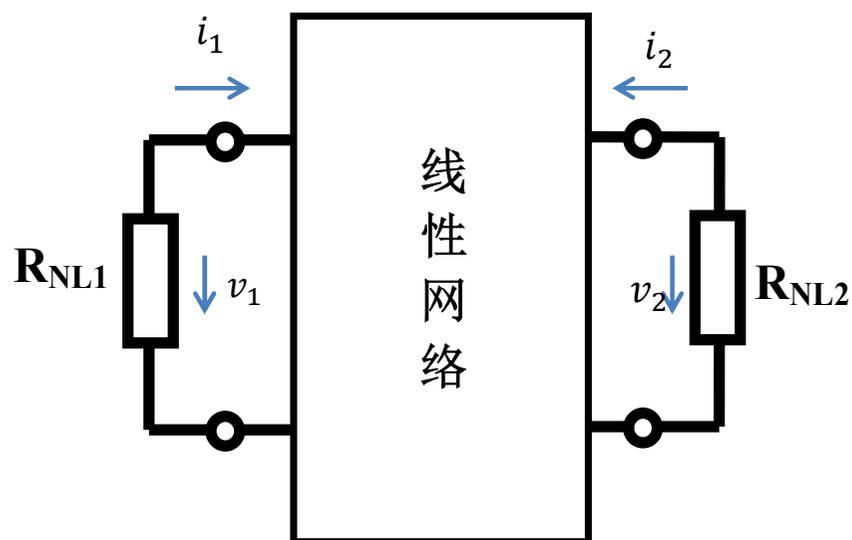
流控器件需要先确认其电流, 压控器件需要先确认其电压

$$\begin{bmatrix} i_1 \\ v_2 \end{bmatrix} = \mathbf{g} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} i_{N1} \\ v_{TH2} \end{bmatrix} \quad \text{线性网络}$$

$$\begin{bmatrix} -f_{iv,1}(v_1) \\ f_{vi,2}(-i_2) \end{bmatrix} = \mathbf{g} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} i_{N1} \\ v_{TH2} \end{bmatrix} \quad \text{最适电路方程}$$

由此方程求出 v_1, i_2 , 再代回求 i_1, v_2

两个非线性电阻都是流控器件



$$\begin{bmatrix} f_{vi,1}(-i_1) \\ f_{vi,2}(-i_2) \end{bmatrix} = \mathbf{z} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

$$\begin{bmatrix} f_1(-i_1) \\ f_2(-i_2) \end{bmatrix} = \mathbf{z} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} I_{10} \\ I_{20} \end{bmatrix} + \begin{bmatrix} \Delta i_1 \\ \Delta i_2 \end{bmatrix}$$

$$\begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix} = \begin{bmatrix} V_{TH10} + \Delta v_{TH1} \\ V_{TH20} + \Delta v_{TH2} \end{bmatrix}$$

$$\begin{aligned} \begin{bmatrix} f_1(-i_1) \\ f_2(-i_2) \end{bmatrix} &= \begin{bmatrix} f_1(-I_{10} - \Delta i_1) \\ f_2(-I_{20} - \Delta i_2) \end{bmatrix} \\ &= \begin{bmatrix} f_1(-I_{10}) - \frac{\partial f_1}{\partial i_{NL1}} \Delta i_1 + \dots \\ f_2(-I_{20}) - \frac{\partial f_2}{\partial i_{NL2}} \Delta i_2 + \dots \end{bmatrix} \approx \begin{bmatrix} f_1(-I_{10}) \\ f_2(-I_{20}) \end{bmatrix} - \begin{bmatrix} \frac{\partial f_1}{\partial i_{NL}} \Delta i_1 \\ \frac{\partial f_2}{\partial i_{NL}} \Delta i_2 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} f_1(-i_1) \\ f_2(-i_2) \end{bmatrix} = \mathbf{z} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} v_{TH1} \\ v_{TH2} \end{bmatrix}$$

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} I_{10} \\ I_{20} \end{bmatrix} + \begin{bmatrix} \Delta i_1 \\ \Delta i_2 \end{bmatrix}$$

$$\mathbf{z} \begin{bmatrix} I_{10} + \Delta i_1 \\ I_{20} + \Delta i_2 \end{bmatrix} + \begin{bmatrix} V_{TH10} + \Delta v_{TH1} \\ V_{TH20} + \Delta v_{TH2} \end{bmatrix} = \begin{bmatrix} f_1(-I_{10} - \Delta i_1) \\ f_2(-I_{20} - \Delta i_2) \end{bmatrix} \approx \begin{bmatrix} f_1(-I_{10}) \\ f_2(-I_{20}) \end{bmatrix} - \begin{bmatrix} \frac{\partial f_1}{\partial i_{NL1}} \Delta i_1 \\ \frac{\partial f_2}{\partial i_{NL2}} \Delta i_2 \end{bmatrix}$$

$$\mathbf{z} \begin{bmatrix} I_{10} \\ I_{20} \end{bmatrix} + \begin{bmatrix} V_{TH10} \\ V_{TH20} \end{bmatrix} = \begin{bmatrix} f_1(-I_{10}) \\ f_2(-I_{20}) \end{bmatrix}$$

直流非线性分析

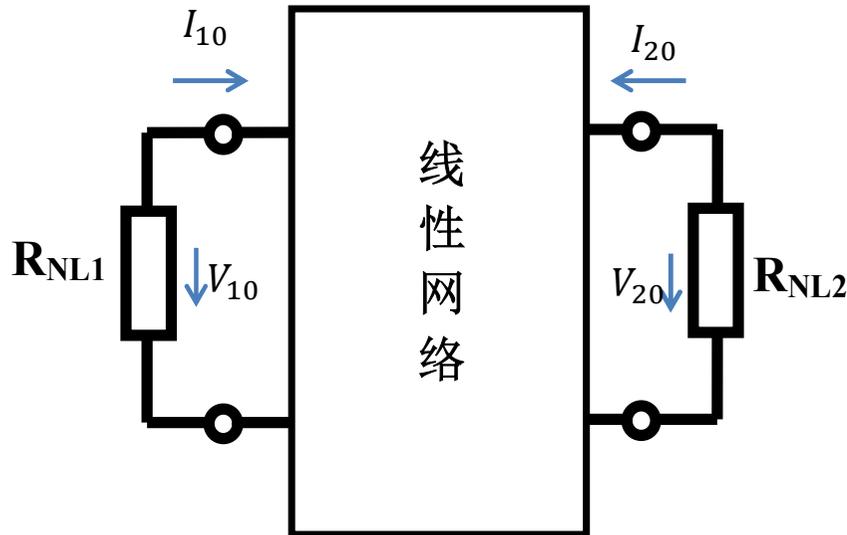
$$\mathbf{z} \begin{bmatrix} \Delta i_1 \\ \Delta i_2 \end{bmatrix} + \begin{bmatrix} \Delta v_{TH1} \\ \Delta v_{TH2} \end{bmatrix} = - \begin{bmatrix} \frac{\partial f_1}{\partial i_{NL1}} \Delta i_1 \\ \frac{\partial f_2}{\partial i_{NL2}} \Delta i_2 \end{bmatrix} = - \begin{bmatrix} r_{d1} \Delta i_1 \\ r_{d2} \Delta i_2 \end{bmatrix}$$

交流线性分析

如果线性网络中存在耦合电容、高频扼流圈，
直流分析和交流分析不同，体现在 \mathbf{z} 参量不同

直流分析和交流小信号分析

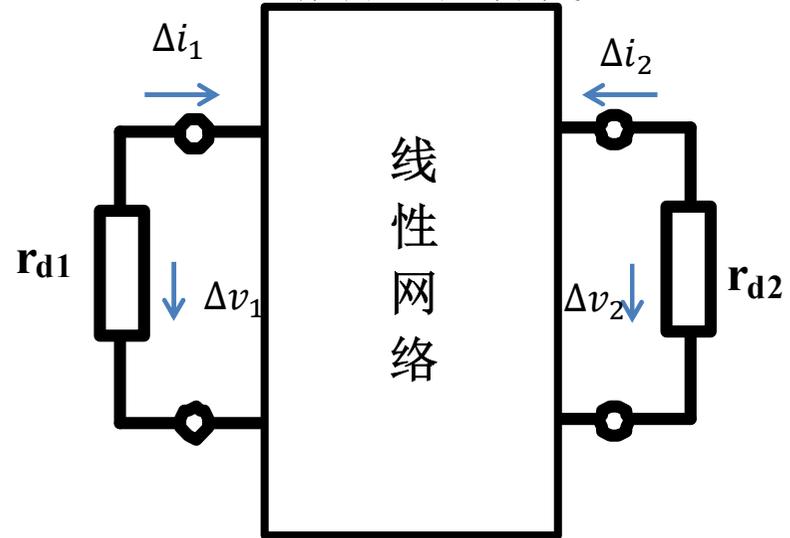
直流分析时，两个单端口
非线性电阻无变动



线性网络中只有直流电源起作用，交流电源不起作用
(交流电压源短路，交流电流源开路)，耦合电容开路，
高频扼流圈短路

$$\mathbf{z}_{DC} \begin{bmatrix} I_{10} \\ I_{20} \end{bmatrix} + \begin{bmatrix} V_{TH10} \\ V_{TH20} \end{bmatrix} = \begin{bmatrix} V_{10} \\ V_{20} \end{bmatrix} = \begin{bmatrix} f_1(-I_{10}) \\ f_2(-I_{20}) \end{bmatrix}$$

交流分析时，两个单端口
非线性电阻用其直流工作点上的微分电阻替代



线性网络中只有交流电源起作用，直流电源不起作用
(直流电压源短路，直流电流源开路)，耦合电容短路，
高频扼流圈开路

$$\mathbf{z}_{AC} \begin{bmatrix} \Delta i_1 \\ \Delta i_2 \end{bmatrix} + \begin{bmatrix} \Delta v_{TH1} \\ \Delta v_{TH2} \end{bmatrix} = \begin{bmatrix} \Delta v_1 \\ \Delta v_2 \end{bmatrix} = - \begin{bmatrix} r_{d1} \Delta i_1 \\ r_{d2} \Delta i_2 \end{bmatrix}$$

作业5 线性范围

- 已知某非线性电阻器件的伏安特性曲线具有如下特性，

(1)
$$i = I_0 \tanh \frac{v}{2v_T}$$
 v为输入，i为输出

(2)
$$y = K_d \sin x$$
 x为输入，y为输出

请给出线性范围最大的直流工作点位置，以及**1dB**线性范围大小。

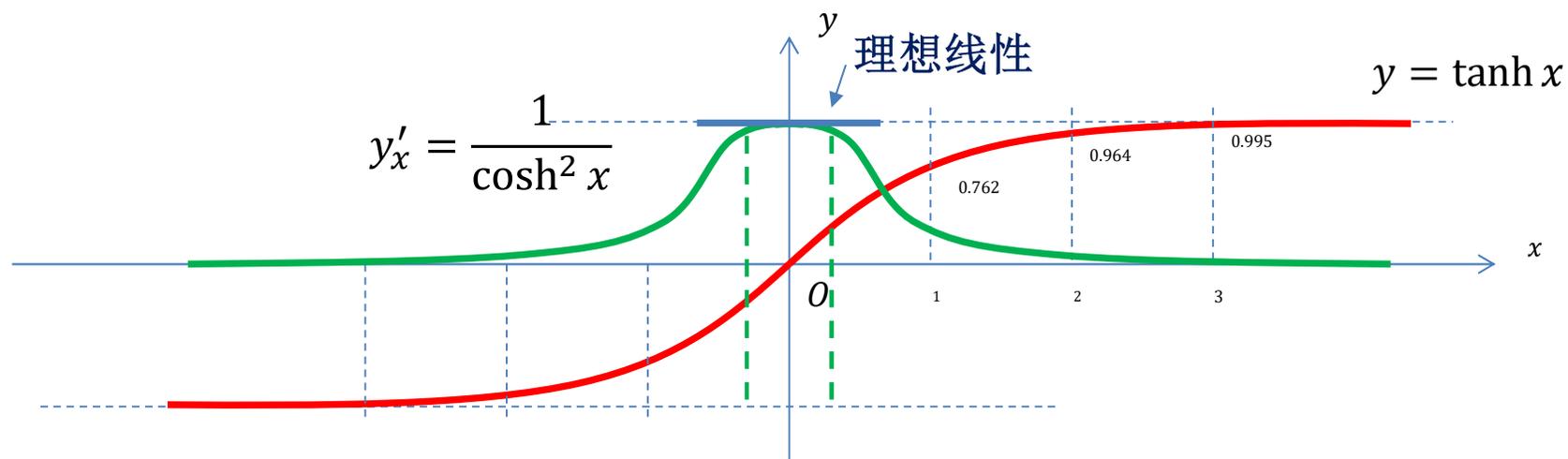
双曲正切函数

$$i = I_0 \tanh \frac{v}{2v_T}$$

$$y = \tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

BJT差分对管非线性跨导转移特性

$$y'_x = \frac{1}{\cosh^2 x}$$



最大的线性区在 $x=0$ 位置

$$i_o = I_0 \tanh \frac{v_{id}}{2v_T}$$

$$20 \log_{10} \left(\cosh^2 \frac{v_{id,1dB}}{2v_T} \right) = 1dB$$

$$g_m = \frac{di_o}{dv_{id}} = \frac{I_0}{2v_T} \frac{1}{\cosh^2 \frac{v_{id}}{2v_T}}$$

$$\cosh^2 \frac{v_{id,1dB}}{2v_T} = 10^{\frac{1}{20}}$$

$$g_{m0} = g_m(v_{id} = 0) = \frac{I_0}{2v_T} = \frac{0.5I_{EE}}{v_T} = \frac{I_{C0}}{v_T}$$

$$\cosh \frac{v_{id,1dB}}{2v_T} = 10^{\frac{1}{40}} = 1.059$$

I_{EE} , 差分对尾电流

I_{C0} , 差分对管直流电流

$$\frac{g_{m0}}{g_m} = \frac{\frac{I_0}{2v_T}}{\frac{I_0}{2v_T} \frac{1}{\cosh^2 \frac{v_{id}}{2v_T}}} = \cosh^2 \frac{v_{id}}{2v_T}$$

$$\begin{aligned} v_{id,1dB} &= 2v_T \cdot \cosh^{-1} 1.059 \\ &= \pm 0.685v_T = \pm 17.8mV \\ &\approx \pm 18mV \end{aligned}$$

±18mV作为BJT差分对的线性范围

1dB线性范围内: $i_o = I_0 \tanh \frac{v_{id}}{2v_T} \approx I_0 \frac{v_{id}}{2v_T} = \frac{I_0}{2v_T} v_{id} = g_{m0} v_{id}$

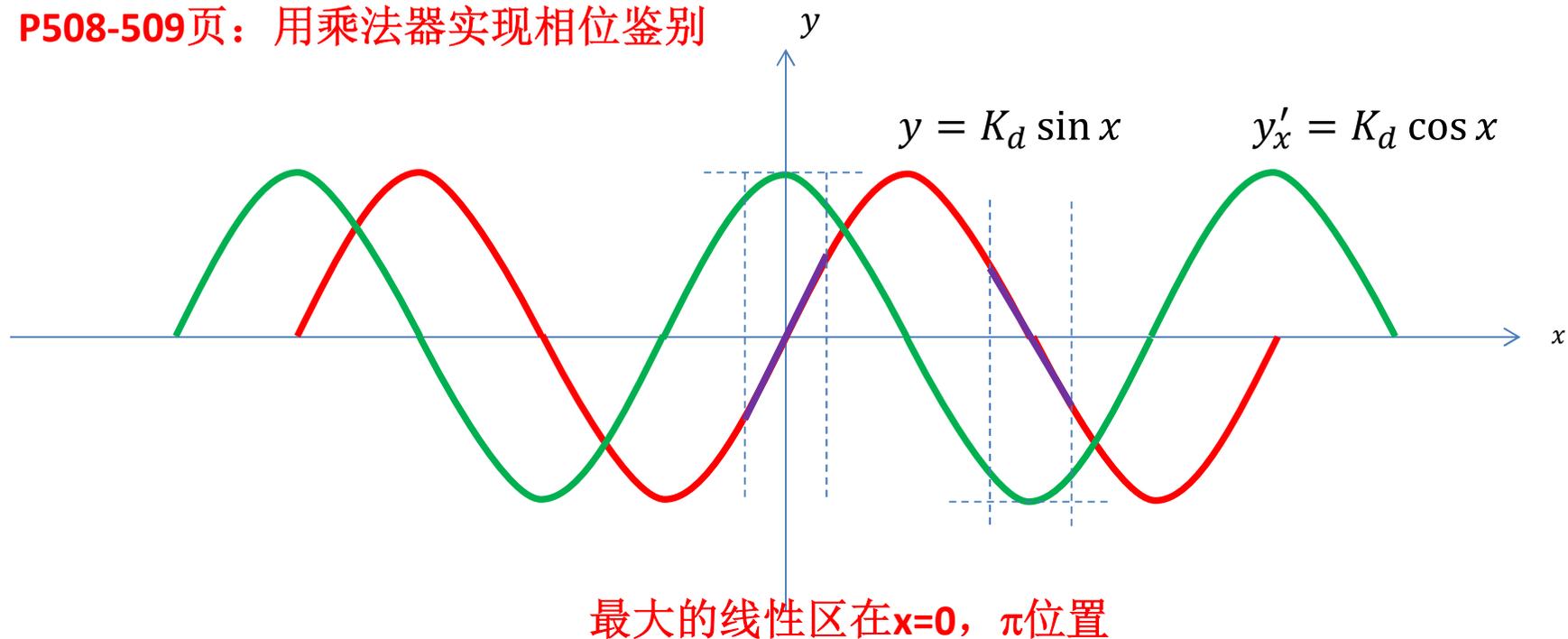
正弦函数

$$y = K_d \sin x$$

$$y'_x = K_d \cos x$$

来源：正弦鉴相特性

P508-509页：用乘法器实现相位鉴别



$$y = K_d \sin x$$

$$20 \log_{10} \frac{1}{\cos x_{1dB}} = 1dB$$

$$y'_x = K_d \cos x$$

$$\frac{1}{\cos x_{1dB}} = 10^{\frac{1}{20}}$$

$$(y'_x)_{max} = K_d \cos 0 = K_d$$

$$\frac{(y'_x)_{max}}{y'_x} = \frac{K_d}{K_d \cos x} = \frac{1}{\cos x}$$

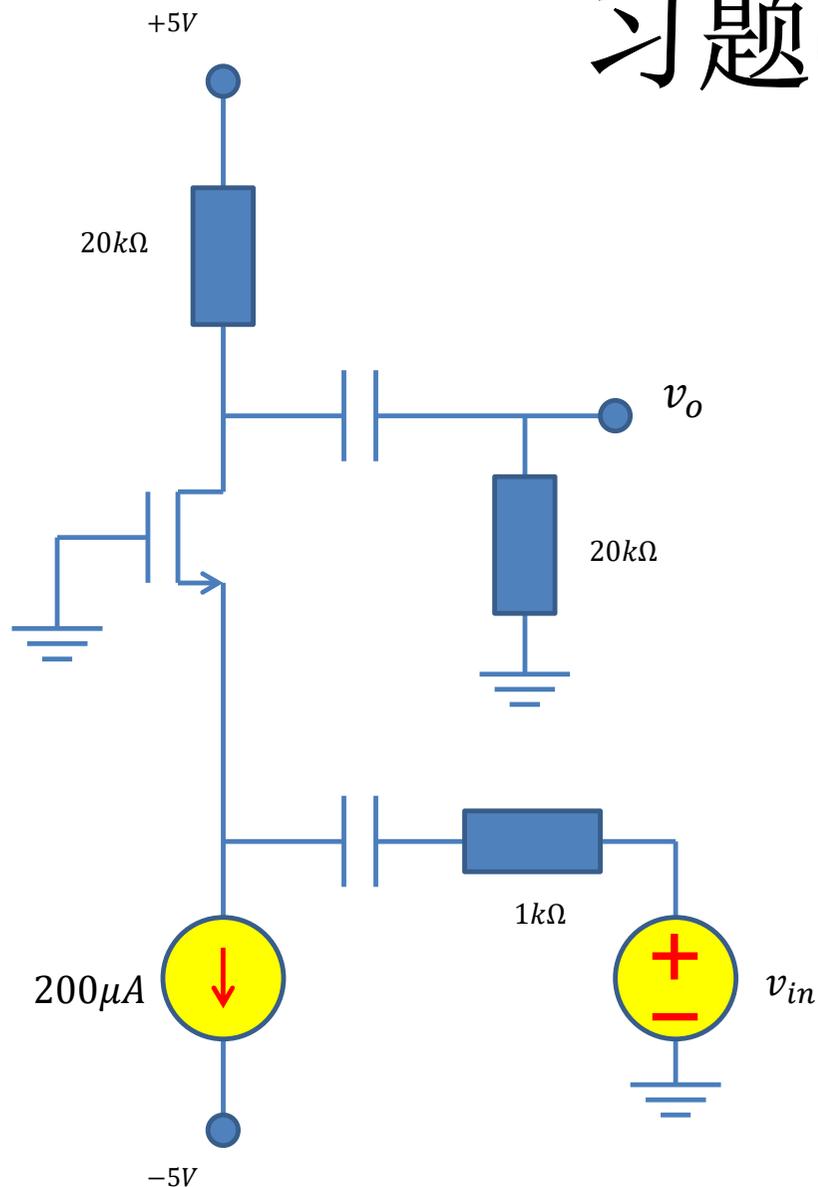
$$\begin{aligned} x_{1dB} &= \arccos 10^{-\frac{1}{20}} \\ &= \pm 0.471 = \pm 27^\circ \end{aligned}$$

方便记忆: $\pm 30^\circ$ 作为 $\sin x$ 的线性范围

1dB线性范围内: $y = K_d \sin x \approx K_d x$

输入信号幅度**1dB**线性范围内, 非线性用线性替代, 线性分析产生的误差一定程度上可以接受

习题6: CG组态放大器



$$i_D = \beta(v_{GS} - V_{TH})^2 \left(1 + \frac{v_{DS}}{V_E}\right)$$

$$\beta = 1\text{mA/V}^2$$

$$V_{TH} = 1\text{V}$$

$$V_E = 20\text{V}$$

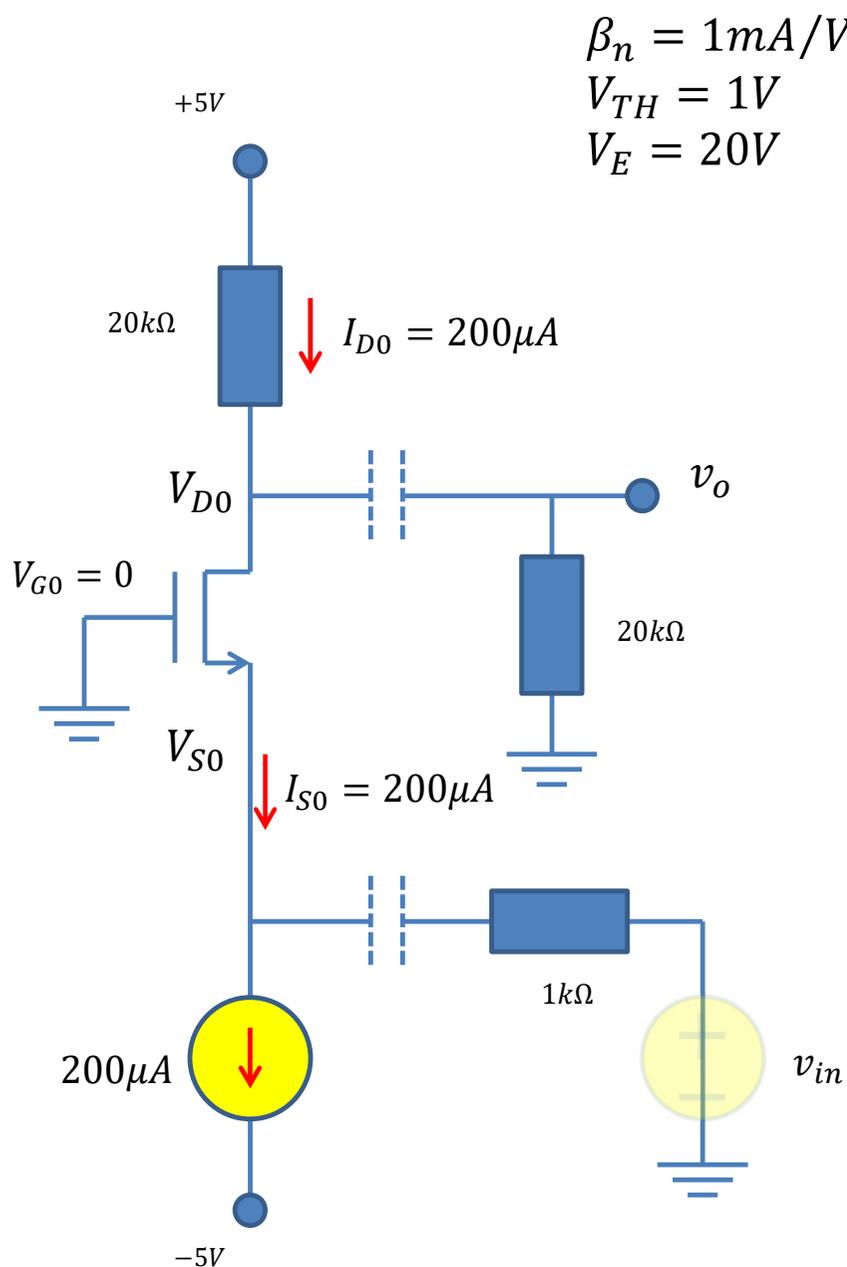
- 确认直流工作点在恒流区
- 求电压放大倍数和功率放大倍数

$$A_v = \frac{v_o}{v_s}$$

$$G_p = \frac{P_L}{P_{S,\max}}$$

- 选作: 分析说明MOSFET将直流电能转换为交流电能
 - (1) 将电容抽象为直流电压源, 分析每个部件上的电压电流, 说明无交流小信号激励时晶体管消耗的能量多, 有交流小信号激励时, 晶体管消耗的能量降低。可以理解为晶体管将吸收的直流能量转换为交流能量送出去, 被负载电阻吸收
 - (2) 说明晶体管微分元件y参量电路为有源电路

直流分析



$$V_{D0} = V_{DD} - I_{D0}R_D = 5 - 4 = 1\text{V}$$

$$V_{GD} = -1\text{V} < V_{TH}$$

$$\begin{aligned}
 I_{D0} &= \beta_n (V_{GS0} - V_{TH})^2 \left(1 + \frac{V_{DS0}}{V_E} \right) \\
 &= \beta_n (V_{G0} - V_{S0} - V_{TH})^2 \left(1 + \frac{V_{D0} - V_{S0}}{V_E} \right) \\
 &= \beta_n (V_{S0} + V_{TH})^2 \left(1 + \frac{1 - V_{S0}}{V_E} \right)
 \end{aligned}$$

$$0.2 = (V_{S0} + 1)^2 \left(1 + \frac{1 - V_{S0}}{20} \right)$$

方程化简后，只有一个未知量 V_{S0} 待求

直流非线性分析：非线性方程求解

简单迭代法

$$0.2 = (V_{S0} + 1)^2 \left(1 + \frac{1 - V_{S0}}{20} \right)$$

$$V_{S0} = -1 - \sqrt{\frac{0.2}{1 + \frac{1 - V_{S0}}{20}}}$$

有意义解
无意义解？自己分析

$$V_{S0}^{(0)} = -1 - \sqrt{\frac{0.2}{1}} = -1.447$$

不考虑厄利效应的解作为初始值

$$V_{S0}^{(1)} = -1 - \sqrt{\frac{0.2}{1 + \frac{1 - V_{S0}^{(0)}}{20}}} = -1 - \sqrt{\frac{0.2}{1 + \frac{1 + 1.447}{20}}} = -1.422$$

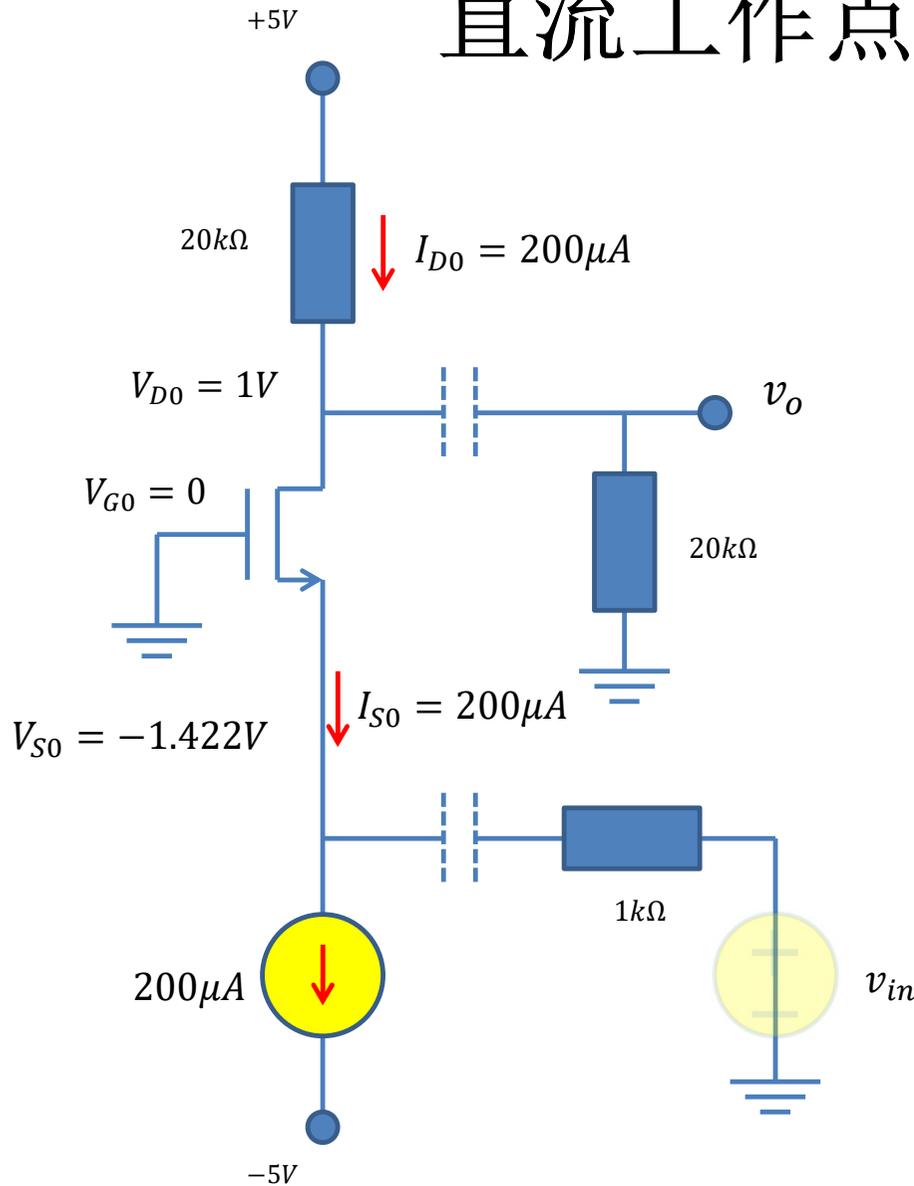
考虑厄利效应和 不
考虑厄利效应微有
差别，差别不大

$$V_{S0}^{(2)} = -1 - \sqrt{\frac{0.2}{1 + \frac{1 - V_{S0}^{(1)}}{20}}} = -1 - \sqrt{\frac{0.2}{1 + \frac{1 + 1.422}{20}}} = -1.422$$

迭代结果在有效
位数内看已无差
别，迭代结束

直流工作点决定微分元件

$$\begin{aligned}\beta_n &= 1\text{mA}/\text{V}^2 \\ V_{TH} &= 1\text{V} \\ V_E &= 20\text{V}\end{aligned}$$



$$i_D = \beta_n (v_{GS} - V_{TH})^2 \left(1 + \frac{v_{DS}}{V_E} \right)$$

$$g_m = \frac{\partial i_D}{\partial v_{GS}} \Big|_Q$$

$$\begin{aligned}&= 2\beta_n (V_{GS0} - V_{TH}) \left(1 + \frac{V_{DS0}}{V_E} \right) \\ &= \frac{2I_{D0}}{V_{GS0} - V_{TH}} = \frac{2 \times 200\mu}{1.422 - 1} = 0.947\text{mS}\end{aligned}$$

$$g_{ds} = \frac{\partial i_D}{\partial v_{DS}} \Big|_Q = \beta_n (V_{GS0} - V_{TH})^2 \frac{1}{V_E}$$

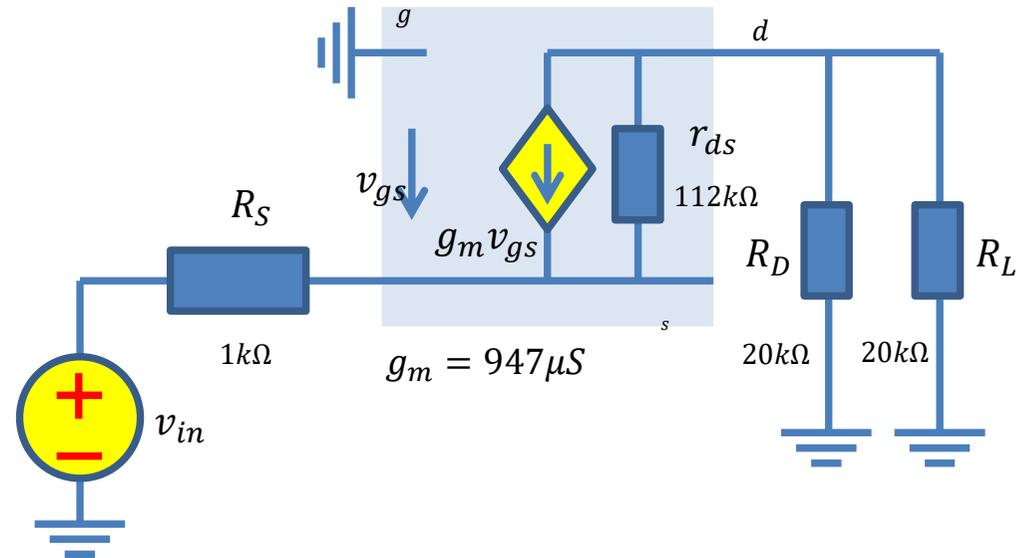
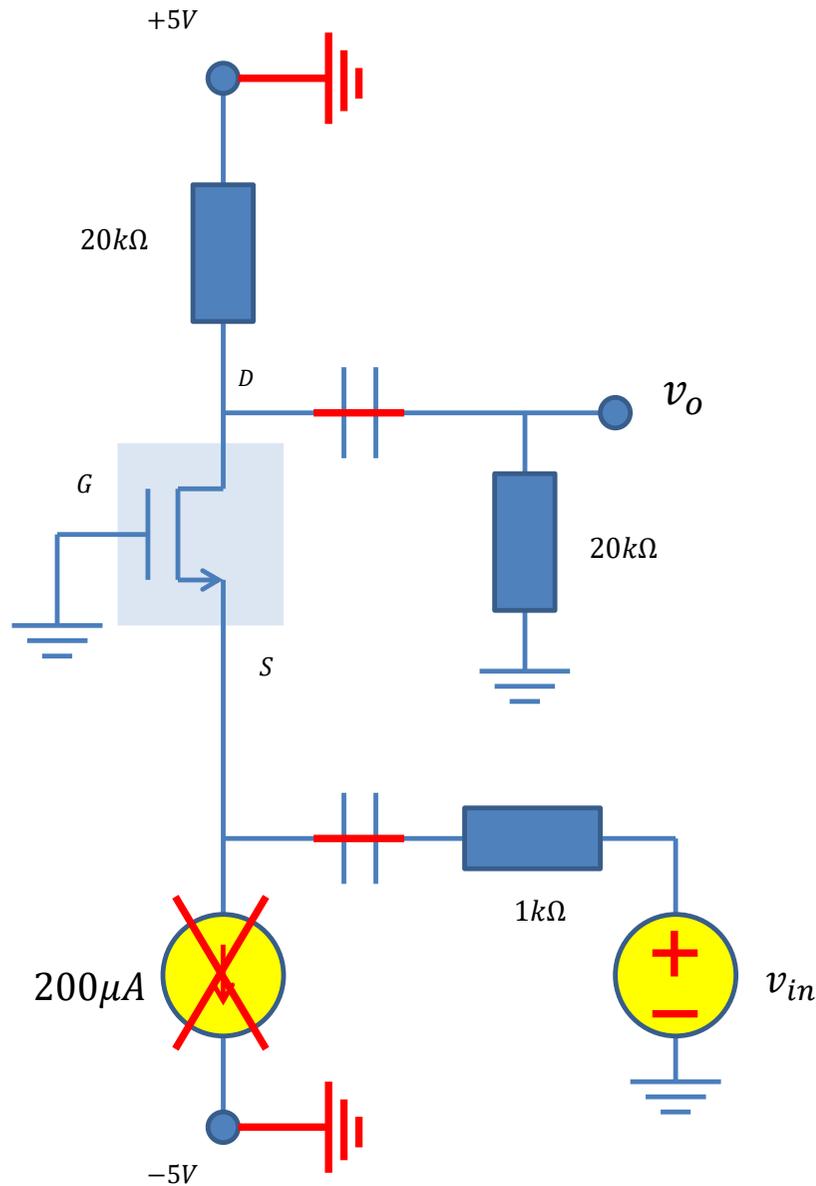
$$= 1 \times (0.422)^2 \times \frac{1}{20} = 8.92\mu\text{S}$$

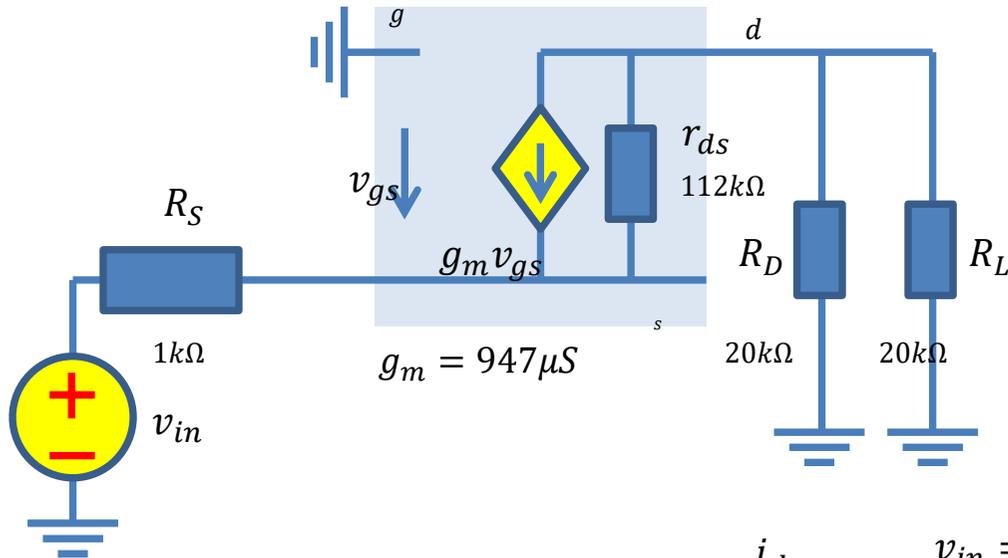
$$r_{ds} = 112\text{k}\Omega$$

$$g_{ds} \approx \frac{I_{D0}}{V_E} = 10\mu\text{S}$$

$$r_{ds} \approx 100\text{k}\Omega$$

交流小信号分析

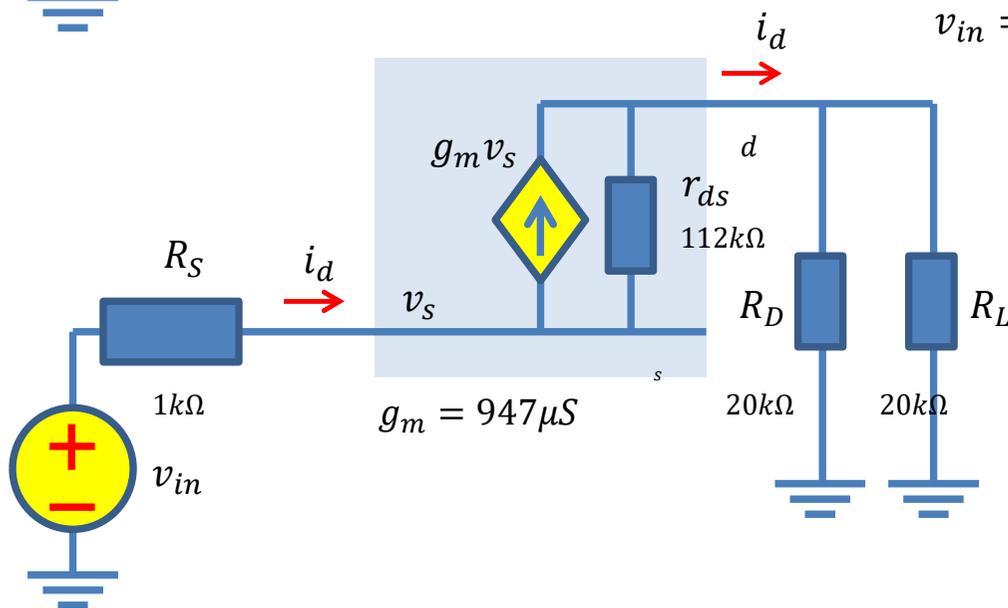




$$v_{in} = i_d R_S + (i_d - g_m v_s) r_{ds} + i_d (R_D || R_L)$$

$$v_{in} = i_d R_S + v_s$$

$$v_s = v_{in} - i_d R_S$$



$$v_{in} = i_d R_S + (i_d - g_m (v_{in} - i_d R_S)) r_{ds} + i_d (R_D || R_L)$$

$$i_d = \frac{1 + g_m r_{ds}}{R_S + r_{ds} + g_m r_{ds} R_S + (R_D || R_L)} v_{in}$$

$$G_p = \frac{V_{L,rms}^2 / R_L}{V_{S,rms}^2 / 4R_S} = 4 \frac{R_S}{R_L} \left(\frac{V_{L,rms}}{V_{S,rms}} \right)^2$$

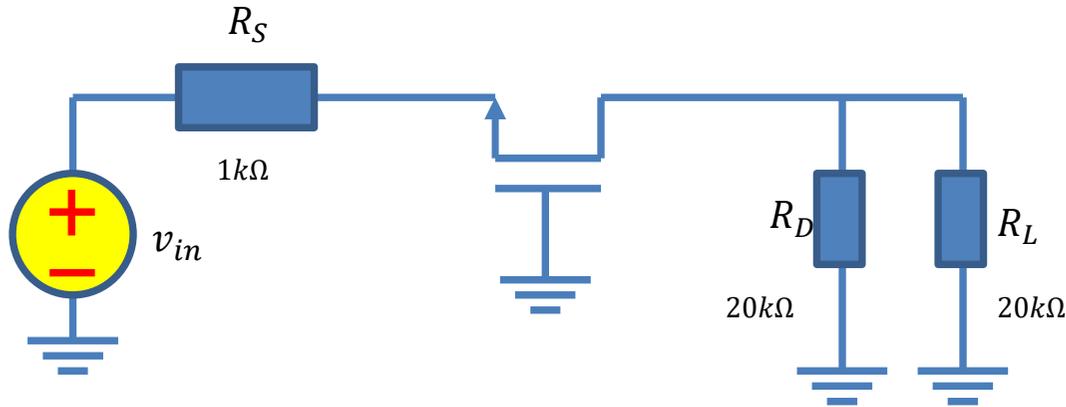
$$= 4 \times \frac{1k}{20k} \times (4.674)^2 = 4.369 = 6.4dB$$

$$A_v = \frac{v_L}{v_{in}} = \frac{i_d (R_D || R_L)}{v_{in}} = \frac{(1 + g_m r_{ds})(R_D || R_L)}{R_S + r_{ds} + g_m r_{ds} R_S + (R_D || R_L)}$$

$$= \frac{(1 + 0.947m \times 112k) \cdot 10k}{1k + 112k + 0.947m \times 112k \times 1k + 10k} = \frac{1070.64k}{229.064k} = 4.674 = 13.4dB$$

功率增益和电压增益不同

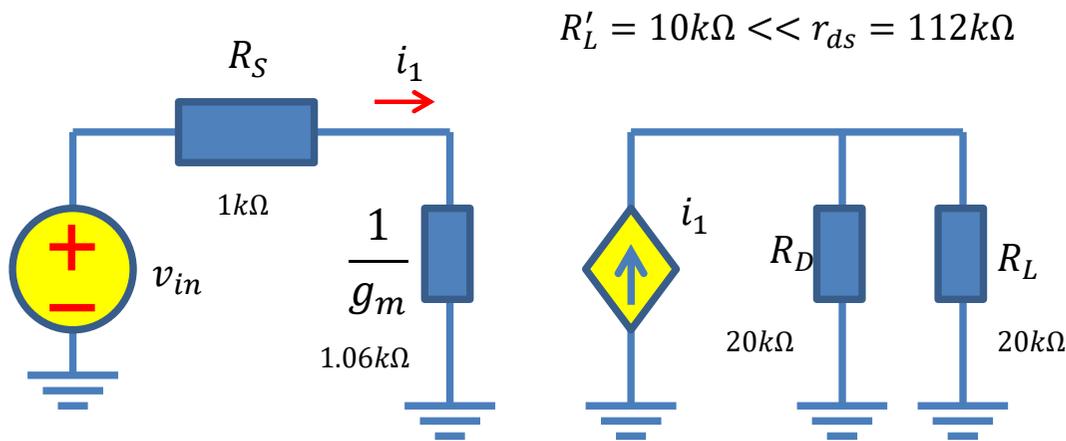
电流缓冲器模型



$$i_1 = \frac{1}{R_S + \frac{1}{g_m}} v_{in}$$

$$= \frac{g_m}{1 + g_m R_S} v_{in} = g_{mf} v_{in}$$

$$v_L = i_1 R'_L = g_{mf} R'_L v_{in}$$



$$\frac{v_L}{v_{in}} = g_{mf} R'_L$$

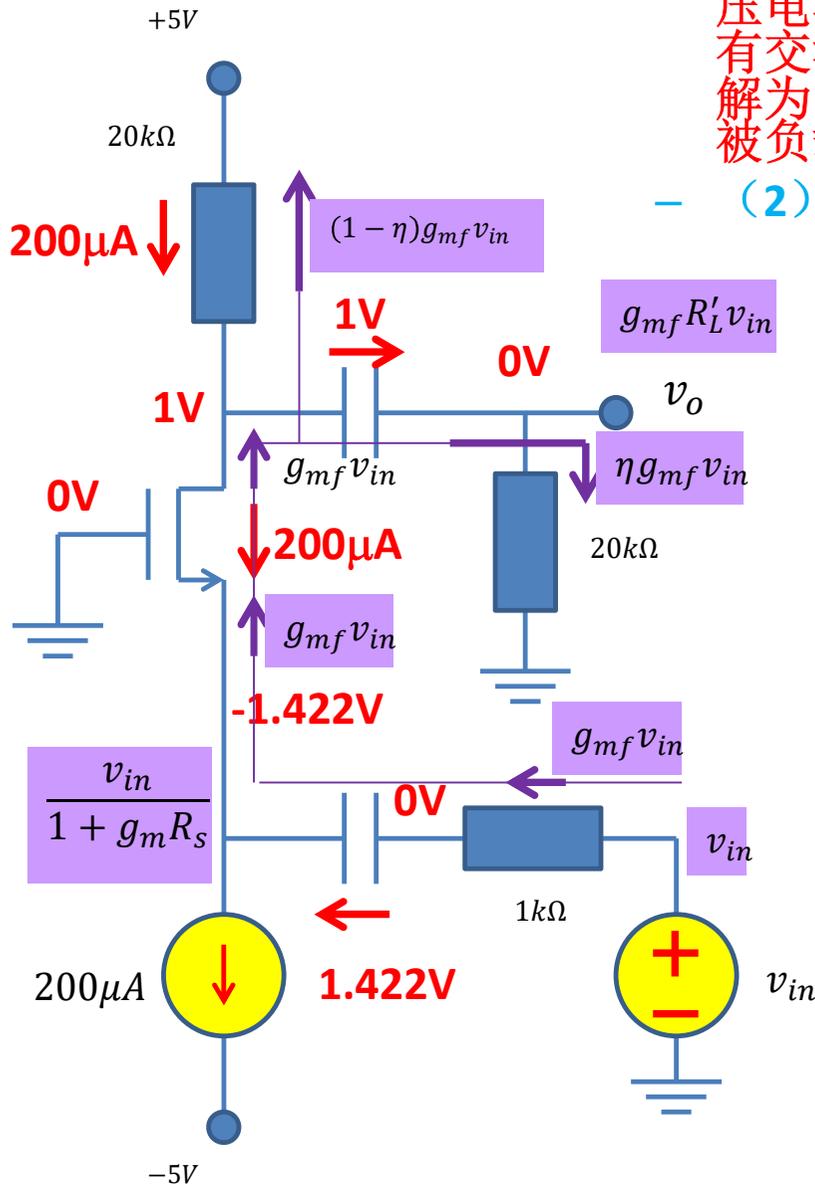
$$= \frac{0.947m}{1 + 0.947m \times 1k} \times 10k$$

$$= 0.4864m \times 10k = 4.864$$

$$= 13.7dB$$

差0.3dB: 误差可以容忍

- 选作：分析说明MOSFET将直流电能转换为交流电能
 - (1) 将电容抽象为直流电压源，分析每个部件上的电压电流，说明无交流小信号激励时晶体管消耗的能量多，有交流小信号激励时，晶体管消耗的能量降低。可以理解为晶体管将吸收的直流能量转换为交流能量送出去，被负载电阻吸收
 - (2) 说明晶体管微分元件y参量电路为有源电路



如果没有激励信号 $v_{in} = 0$

直流功率

+5V电源提供

$$5V \times 200\mu A = 1mW$$

-5V电源提供

$$5V \times 200\mu A = 1mW$$

偏置电阻消耗

$$4V \times 200\mu A = 0.8mW$$

晶体管消耗

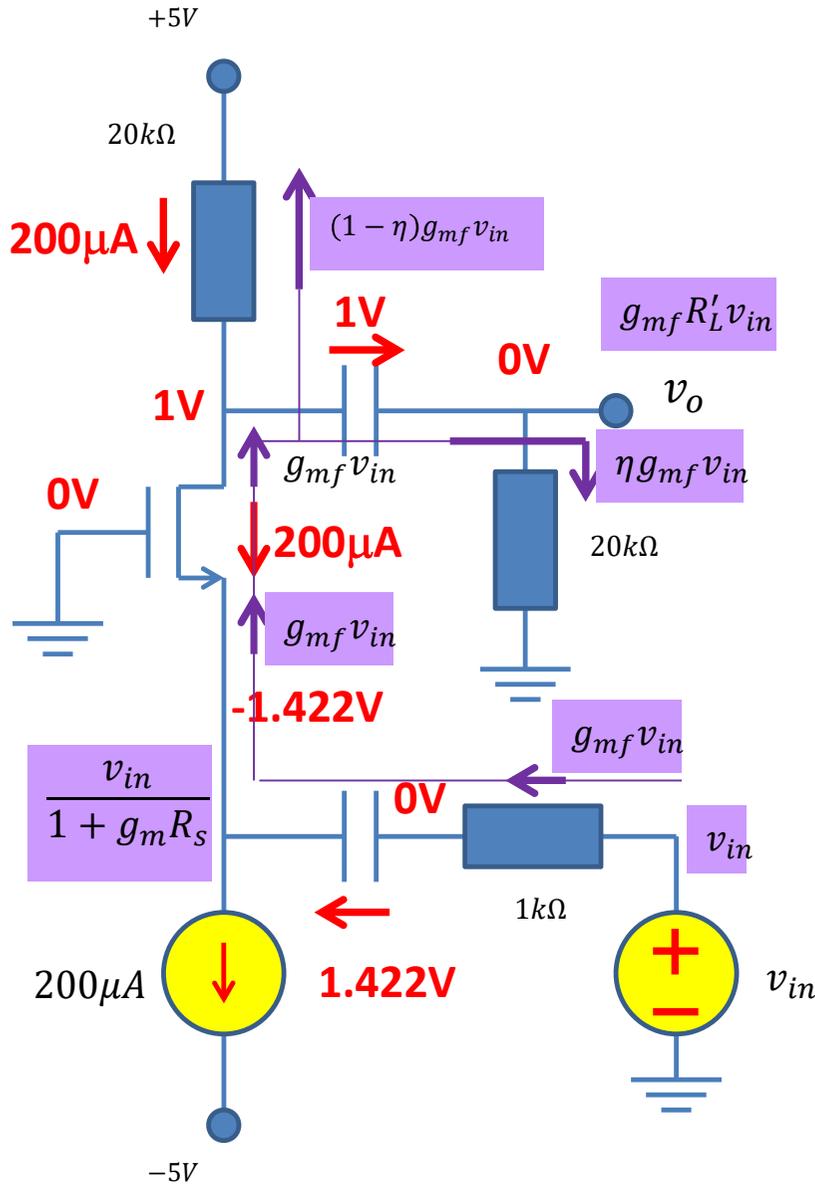
$$2.422V \times 200\mu A = 0.48mW$$

偏置电流源消耗

$$3.578V \times 200\mu A = 0.72mW$$

由工作在恒流区的晶体管等效
本质上仍然是电阻，仅提供恒流特性而已

供能



现加入激励信号 $v_{in} = V_m \cos \omega t$

直流功率

+5V电源提供

$$\frac{5V \times (0.2mA - (1 - \eta)g_m v_{in})}{= 1mW}$$

-5V电源提供

$$5V \times 200\mu A = 1mW$$

小信号激励功率

v_{in} 提供

$$\overline{v_{in} \cdot g_m v_{in}} = g_m \overline{v_{in}^2}$$

$$= 0.5g_m V_m^2 = 0.24V_m^2$$

小信号源内阻耗能

$$\overline{(g_m v_{in})^2 R_s} = g_m^2 R_s \overline{v_{in}^2}$$

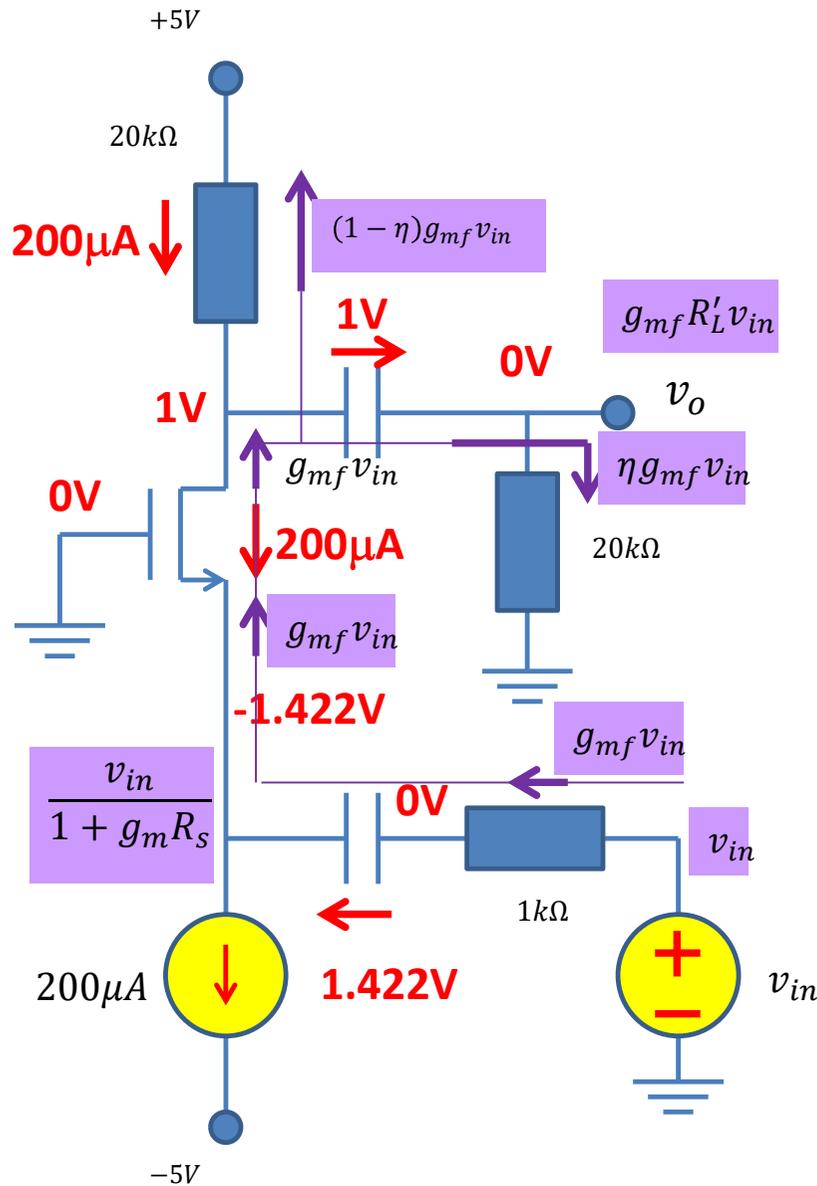
$$= 0.5g_m^2 R_s V_m^2 = 0.12V_m^2$$

偏置电流源消耗

$$\frac{\left(3.578V + \frac{v_{in}}{1 + g_m R_s}\right) \times 200\mu A}{= 0.72mW}$$

耗能

现加入激励信号 $v_{in} = V_m \cos \omega t$

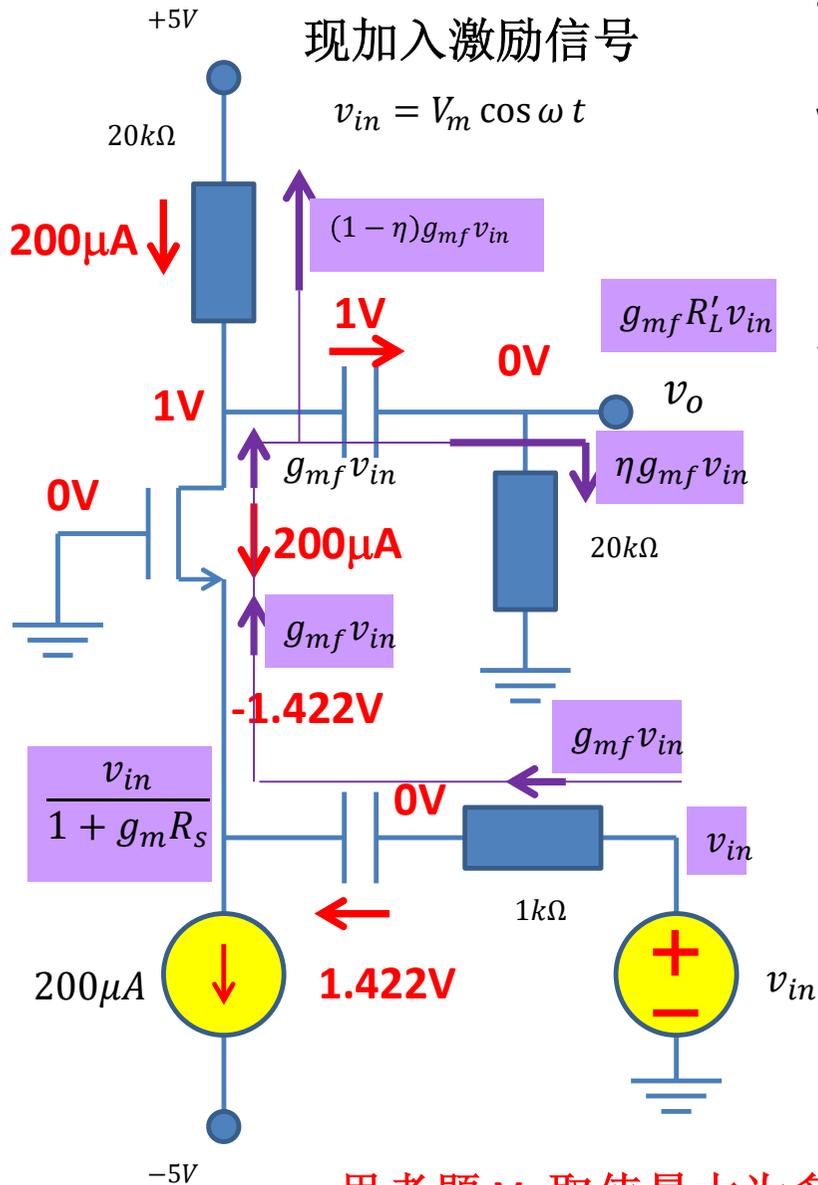


偏置电阻消耗 $\overline{(4 - g_{mf} R'_L v_{in}) \cdot (0.2 - (1 - \eta) g_{mf} v_{in})}$
 $= 0.8 + (1 - \eta) g_{mf}^2 R'_L \overline{v_{in}^2}$
 $= 0.8 + 0.5(1 - \eta) g_{mf}^2 R'_L V_m^2$
 $= (0.8 + 0.59 V_m^2) mW$

负载电阻消耗 $\overline{g_{mf} R'_L v_{in} \cdot \eta g_{mf} v_{in}} = \eta g_{mf}^2 R'_L \overline{v_{in}^2}$
 $= 0.5 \eta g_{mf}^2 R'_L V_m^2 = 0.59 V_m^2$

晶体管消耗 $\overline{(2.422 + g_{mf} (R'_L - r_e) v_{in}) \cdot (0.2 - g_{mf} v_{in})}$
 $= 0.48 - g_{mf}^2 (R'_L - r_e) \overline{v_{in}^2}$
 $= 0.48 - 0.5 g_{mf}^2 (R'_L - r_e) V_m^2$
 $= (0.48 - 1.06 V_m^2) mW$

供能与耗能



+5V电源供能

$$5V \times (0.2mA - (1 - \eta)g_{mf}v_{in}) = 1mW$$

-5V电源供能

$$5V \times 200\mu A = 1mW$$

v_{in} 供能

$$v_{in} \cdot g_{mf}v_{in} = 0.24V_m^2$$

小信号源内阻耗能

$$(g_{mf}v_{in})^2 R_s = 0.12V_m^2$$

偏置电流源耗能

$$(3.578V + v) \times 200\mu A = 0.72mW$$

偏置电阻消耗

$$(4 - g_{mf}R'_L v_{in}) \cdot (0.2 - (1 - \eta)g_{mf}v_{in}) = (0.8 + 0.59V_m^2)mW$$

负载电阻消耗

$$g_{mf}R'_L v_{in} \cdot \eta g_{mf}v_{in} = 0.59V_m^2$$

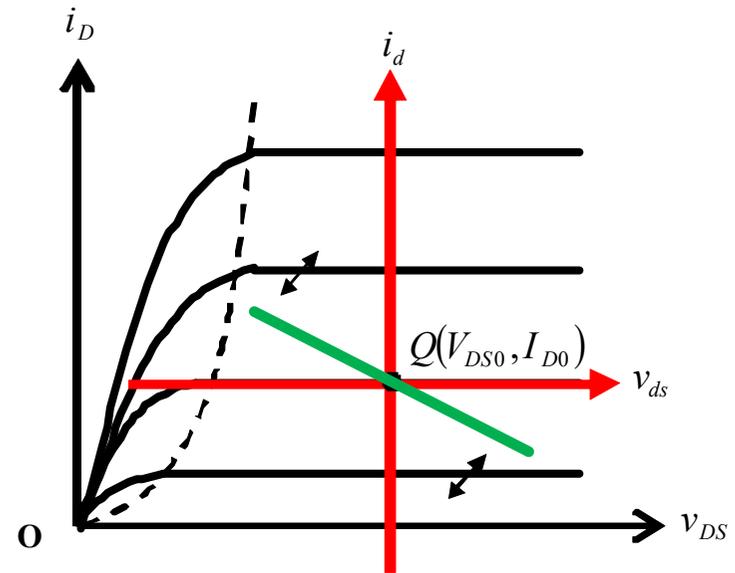
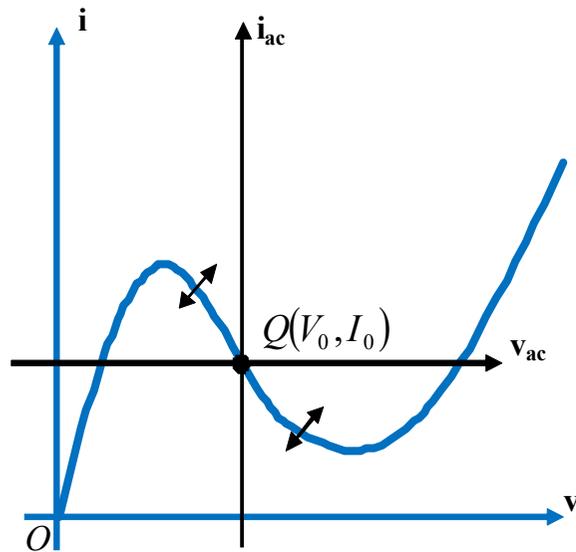
晶体管消耗

$$(2.422 + g_{mf}(R'_L - r_e)v_{in}) \cdot (0.2 - g_{mf}v_{in}) = (0.48 - 1.06V_m^2)mW$$

晶体管是换能器件

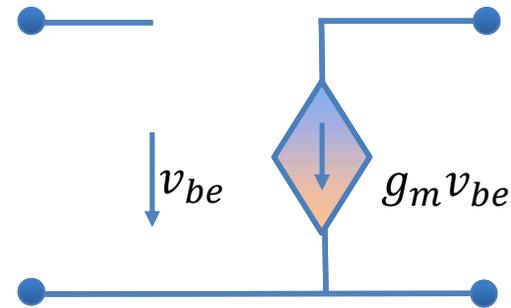
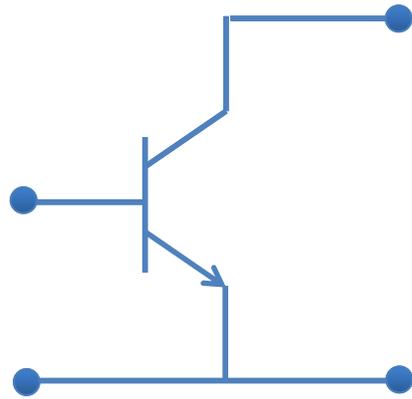
晶体管为换能器

- 工作在负阻区的负阻器件，工作在有源区的晶体管，具有将直流能量转换为交流能量的能力，它们都是换能器件，和直流偏置源组合后，可形成向外端口输出交流能量的有源器件



第十二讲作业

作业1 理想晶体管

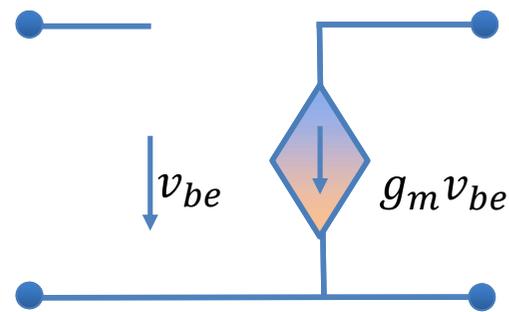
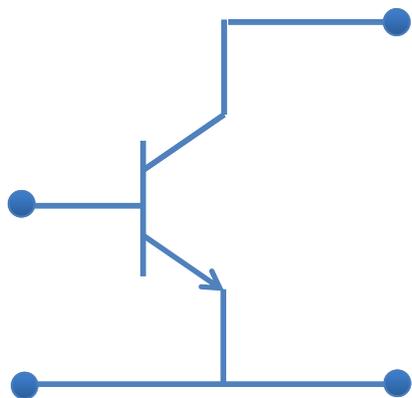


电流增益 $\beta \rightarrow \infty$ ，厄利电压 $V_A \rightarrow \infty$

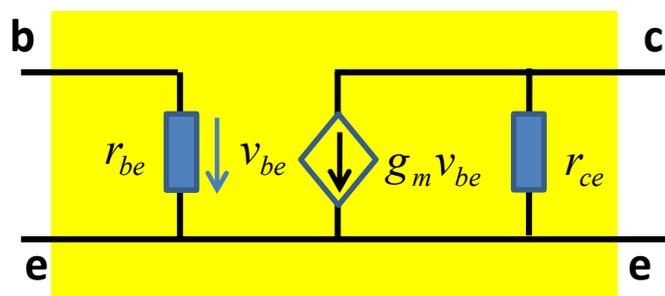
理想晶体管模型为理想压控流源。

- 1) 列写含有串反馈电阻的CE组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 2) 列写CB组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 3) 列写CC组态理想晶体管的端口约束方程，并将其转化为二端口等效电路
- 4) 前述三个二端口网络，端口1对接戴维南源 (v_s , R_s)，端口2对接负载电阻 R_L ，分析电压增益 $A_v = v_L / v_s$

晶体管是接近理想的压控流源



电流增益 $\beta \rightarrow \infty$, 厄利电压 $V_A \rightarrow \infty$



$$g_m = 40\text{mS}$$

$$r_{be} = 10\text{k}\Omega$$

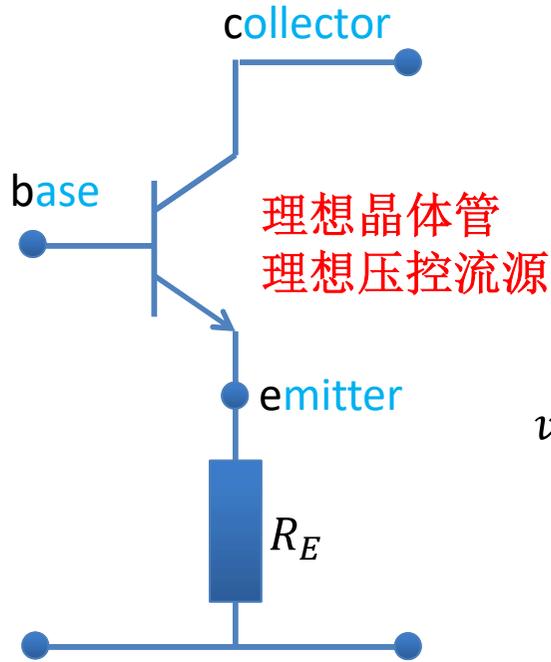
$$r_{ce} = 100\text{k}\Omega$$

$$g_m = \frac{I_C}{v_T}$$

$$r_{be} = \beta \frac{1}{g_m} \xrightarrow{\beta \rightarrow \infty} \infty$$

$$r_{ce} = \frac{V_A}{I_{C0}} \xrightarrow{V_A \rightarrow \infty} \infty$$

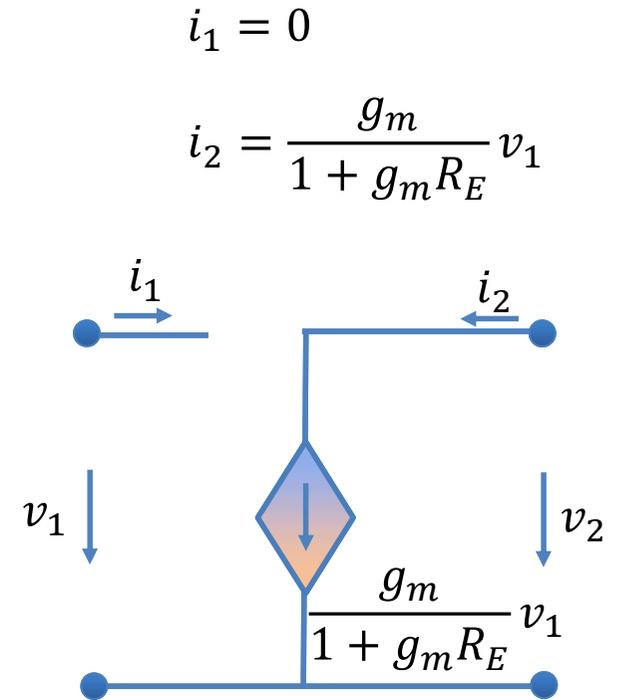
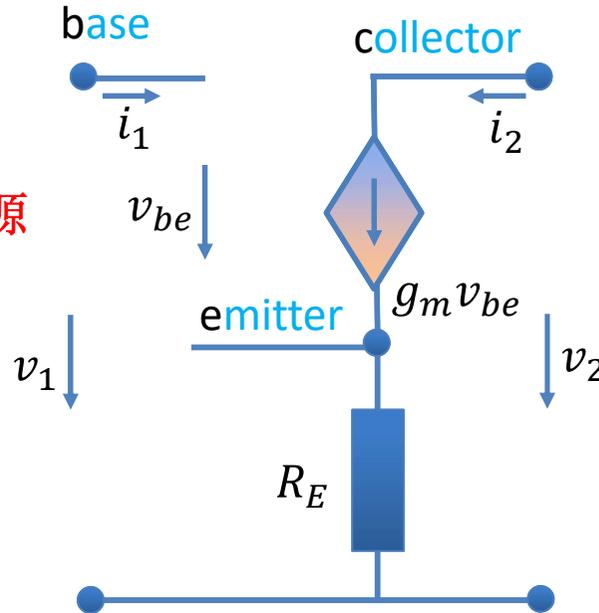
理想压控流源的串串负反馈仍然是理想压控流源



$$i_2 = g_m v_{be} = g_m (v_b - v_e)$$

$$= g_m (v_1 - i_2 R_E) = g_m v_1 - i_2 g_m R_E$$

$$i_2 = \frac{g_m}{1 + g_m R_E} v_1$$



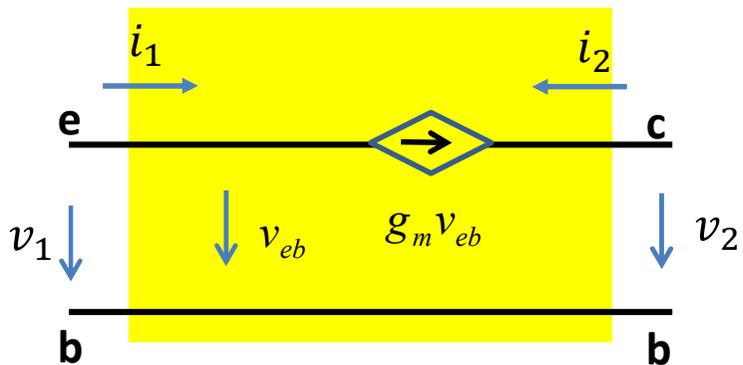
$$i_1 = 0$$

$$i_2 = \frac{g_m}{1 + g_m R_E} v_1$$

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ \frac{g_m}{1 + g_m R_E} & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

结论：理想晶体管加串联负反馈RE后仍然是理想晶体管，只不过跨导增益发生改变而已

CB组态电路模型



$$i_1 = g_m v_1$$

$$i_2 = -i_1 = -g_m v_1$$

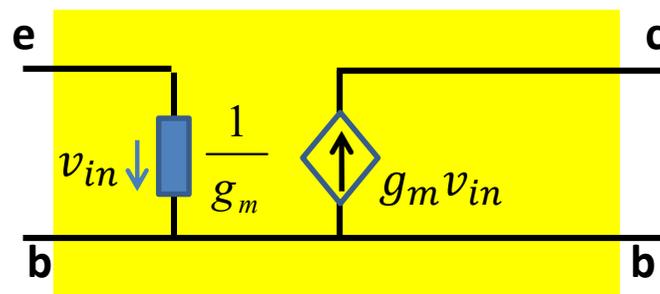
端口伏安特性方程： y 参量表述

$$v_1 = \frac{1}{g_m} i_1$$

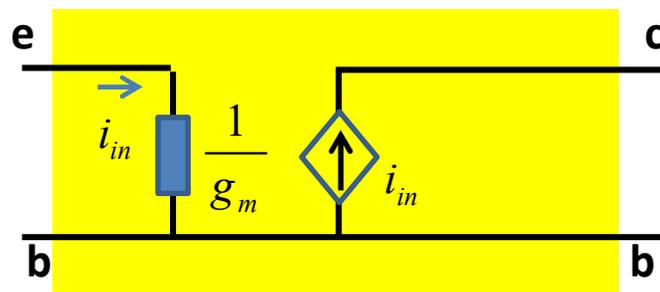
$$i_2 = -i_1$$

h 参量表述

$$R_L \ll r_{ce} \rightarrow \infty$$

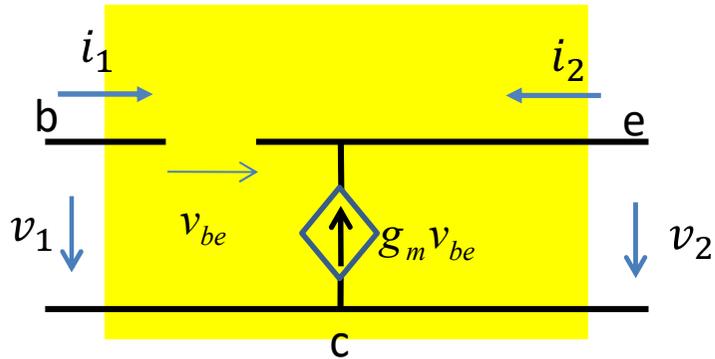


理想晶体管CB组态 y 参量电路模型



理想晶体管CB组态 h 参量电路模型
电流缓冲器模型

CC组态电路模型



$$i_1 = 0$$

$$i_2 = -g_m v_{be} = -g_m v_1 + g_m v_2$$

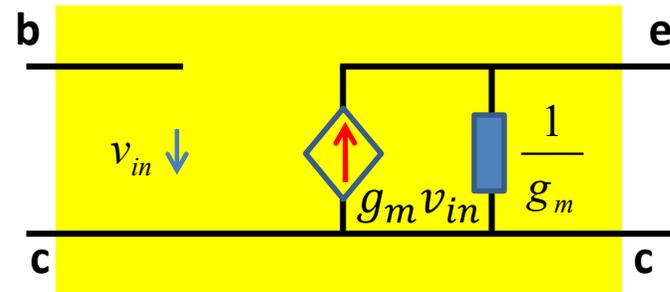
端口伏安特性方程： y 参量表述

$$i_1 = 0$$

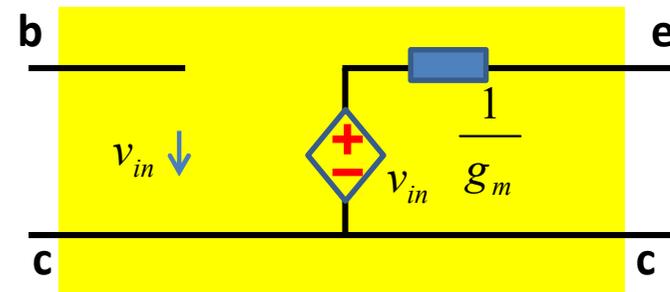
$$v_2 = v_1 + \frac{1}{g_m} i_2$$

g 参量表述

$$R_S \ll r_{be} \rightarrow \infty$$

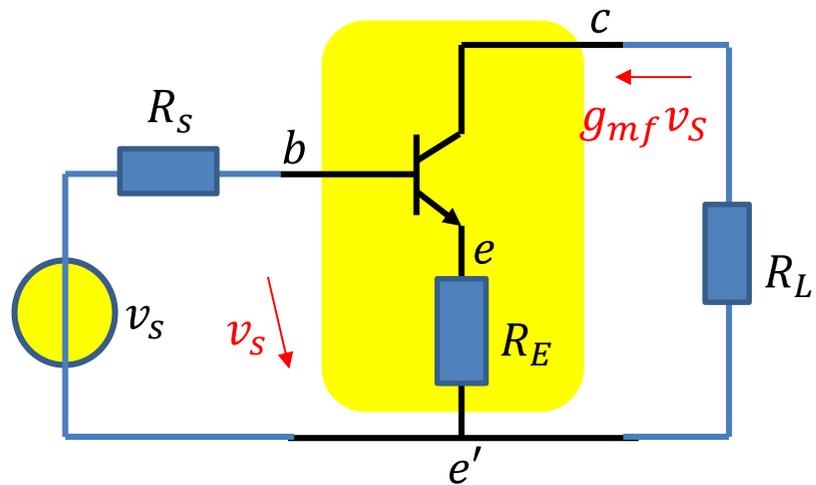


理想晶体管CC组态 y 参量电路模型



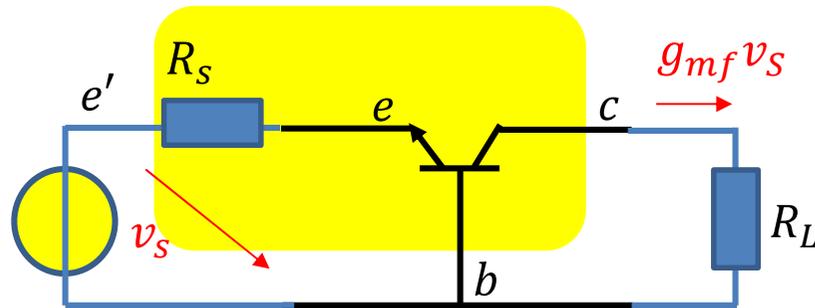
理想晶体管CC组态 g 参量电路模型
电压缓冲器模型：单向网络

三种组态放大器放大倍数



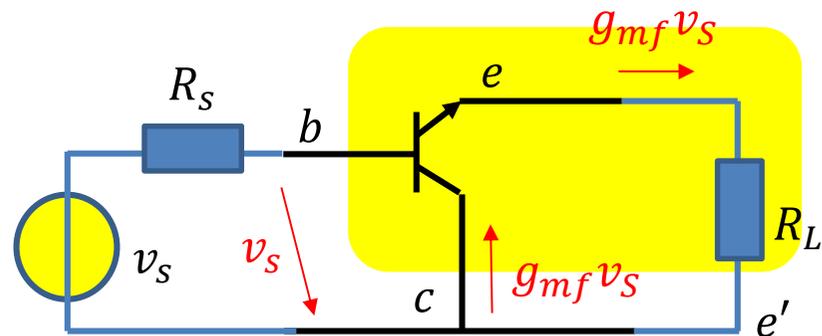
$$A_{v,CE} = -g_{mf}R_L = -\frac{g_m}{1 + g_m R_E} R_L$$

$$R_s \ll r_{be} \text{ 或 } R_L \ll r_{ce}$$



$$A_{v,CB} = +g_{mf}R_L = \frac{g_m}{1 + g_m R_s} R_L$$

$$R_L \ll r_{ce}$$

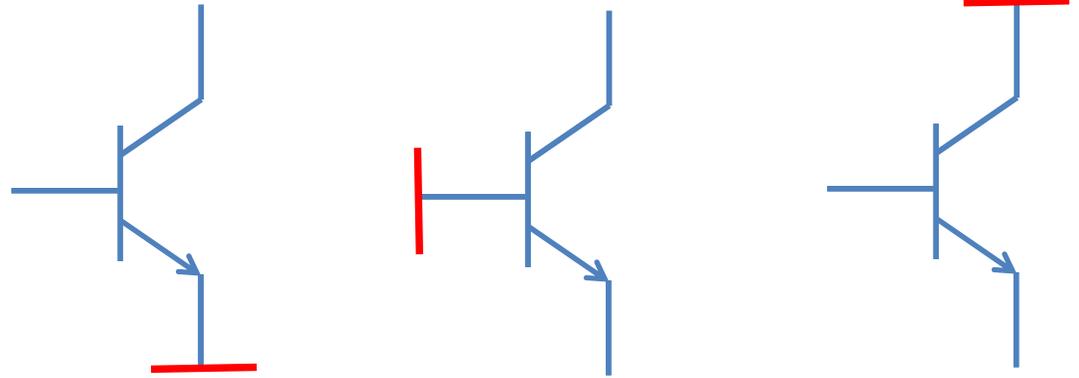


$$A_{v,CC} = +g_{mf}R_L = \frac{g_m}{1 + g_m R_L} R_L$$

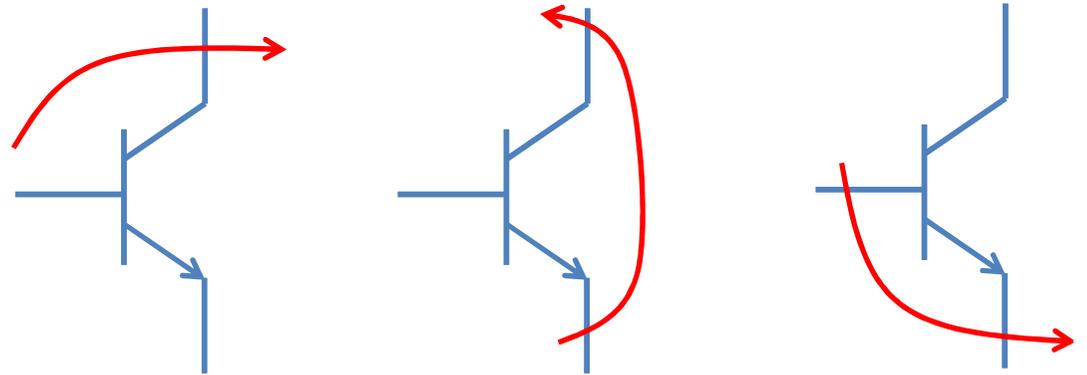
$$R_s \ll r_{be}$$

晶体管组态判定

- 看哪个端点交流接地
 - 谁接地，该端就是公共端



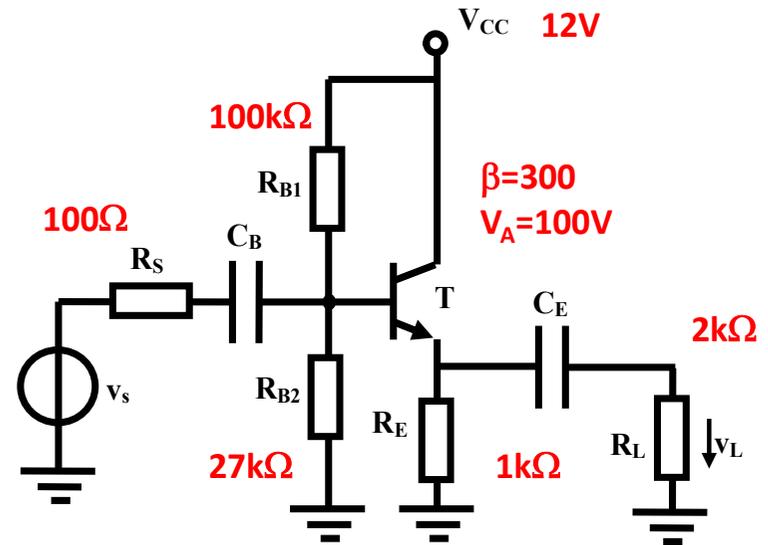
- 看信号放大路径，信号如何流动
 - 信号从B到C，就是共E
 - 信号从B到E，就是共C
 - 信号从E到C，就是共B



作业2 集电极交流地，故而CC组态

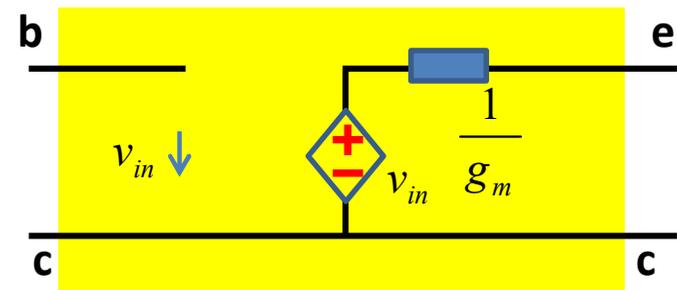
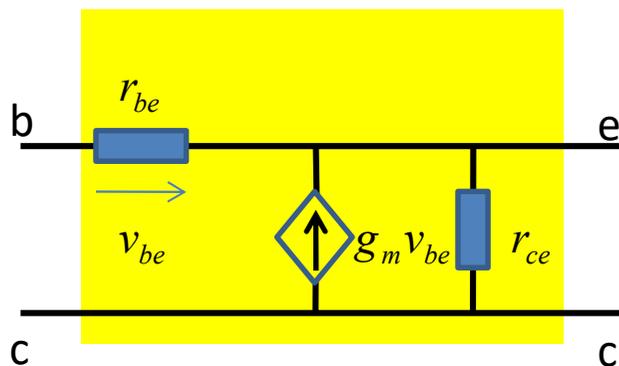
CC组态放大器

- (1) 直流分析
- (2) 交流分析
 - 采用y参量跨导器模型分析
 - 采用CC电压缓冲器模型分析

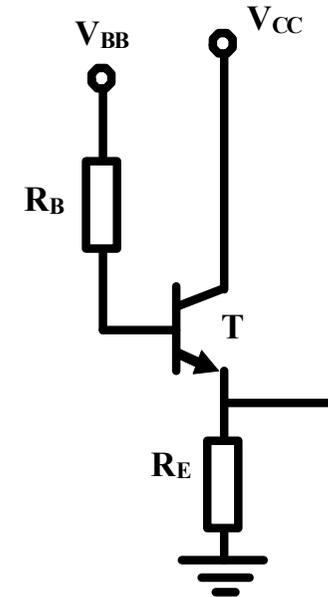
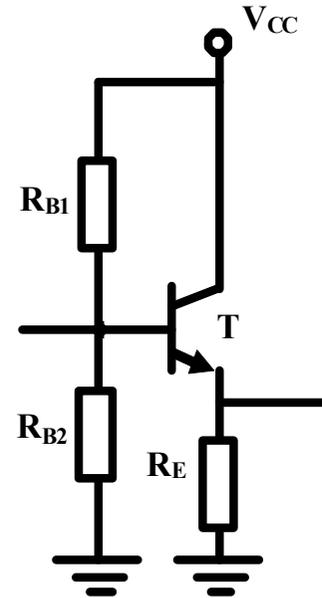
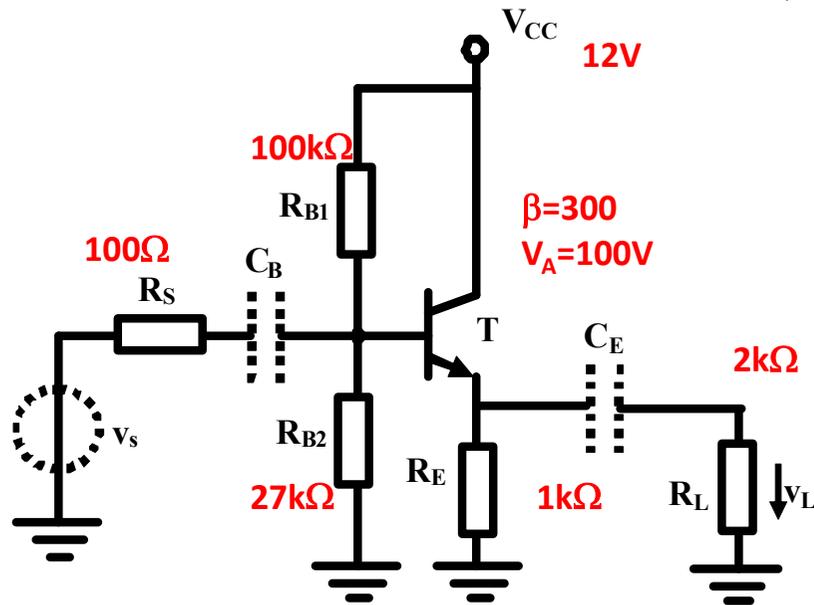


$$A_v = \frac{v_L}{v_S} = ?$$

$$A_i = \frac{i_L}{i_S} = \frac{i_L}{G_S v_S} = ?$$



直流分析

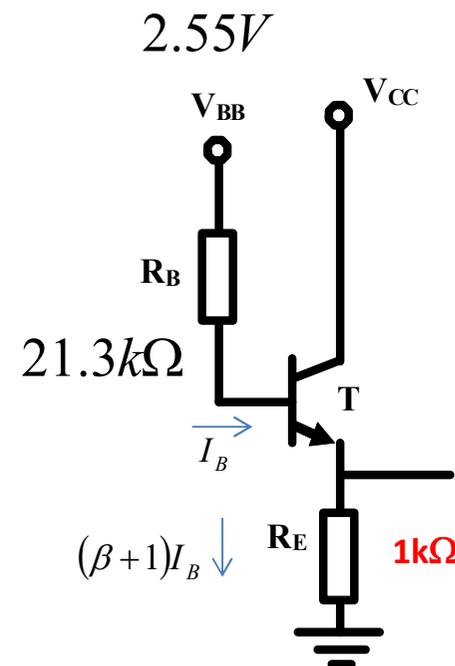
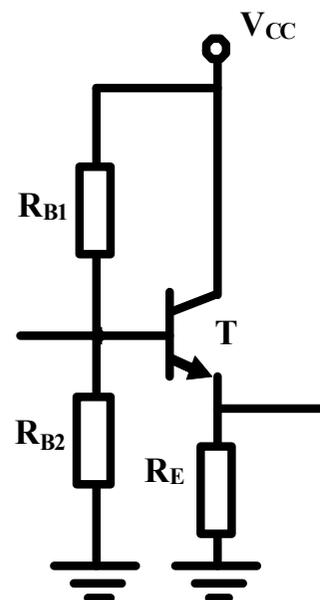
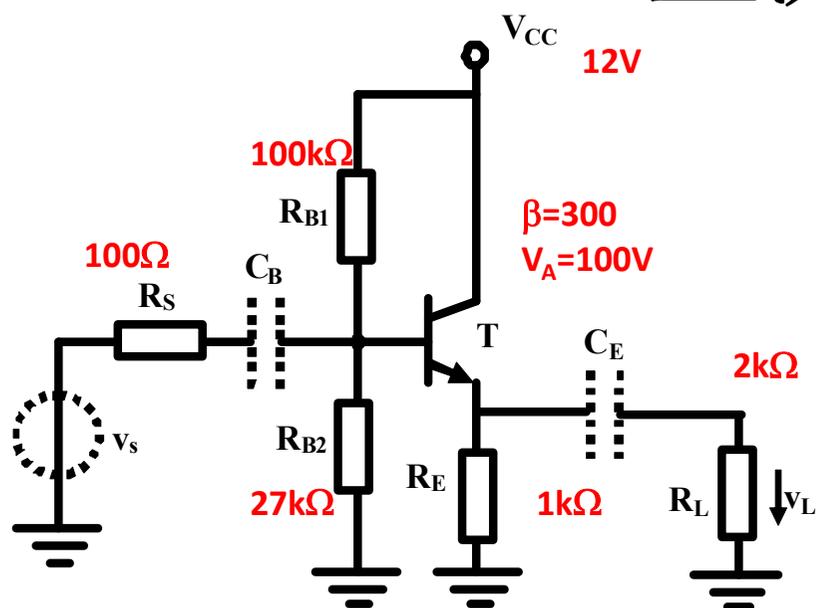


$$V_{BB} = \frac{R_{B2}}{R_{B1} + R_{B2}} V_{CC} = \frac{27k}{100k + 27k} \times 12 = 2.55V$$

$$R_B = R_{B1} \parallel R_{B2} = \frac{R_{B1} R_{B2}}{R_{B1} + R_{B2}} = \frac{100k \times 27k}{100k + 27k} = 21.3k\Omega$$

戴维南等效

直流分析



$$I_B R_B + V_{BE} + (\beta + 1)I_B R_E = V_{BB}$$

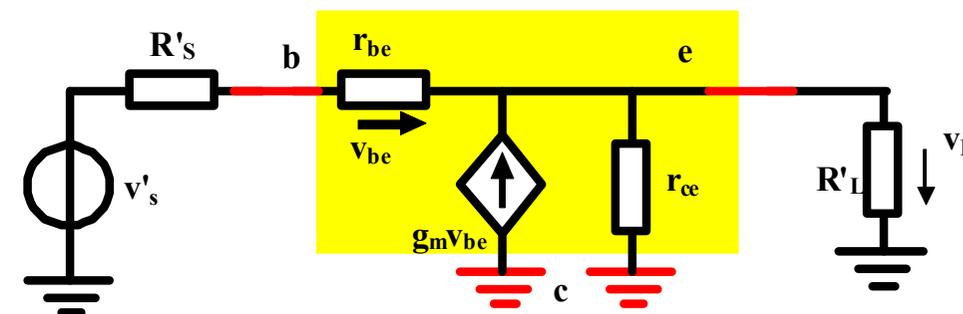
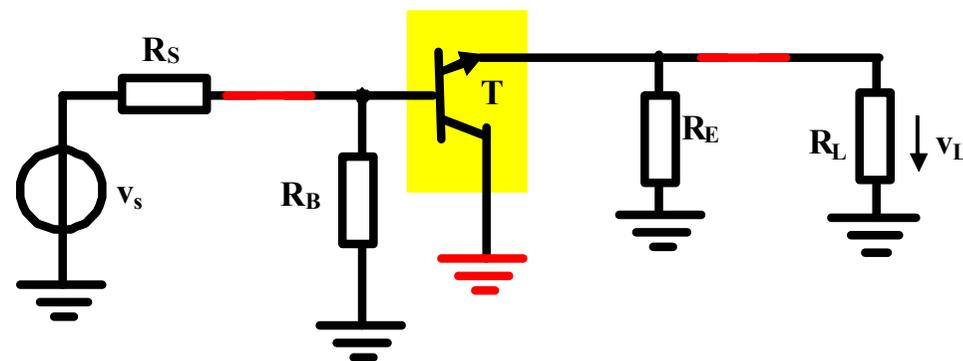
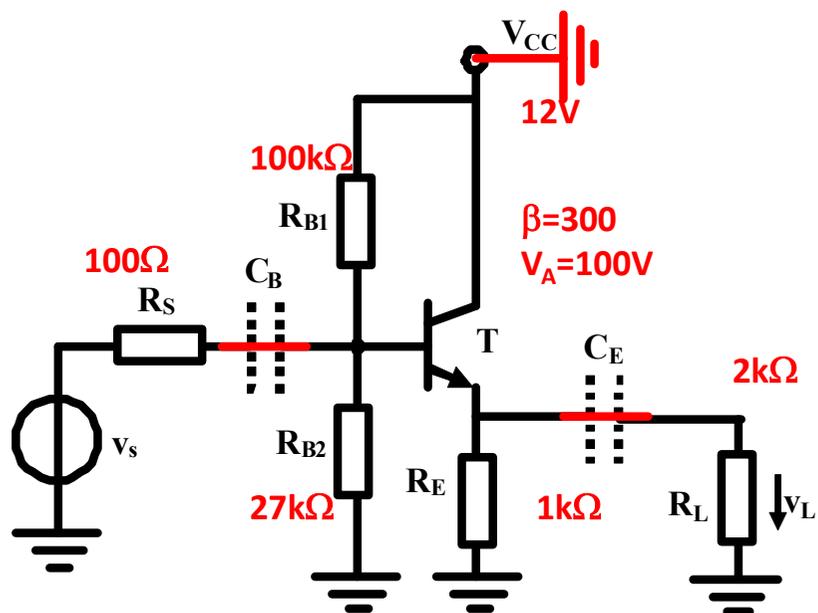
戴维南等效

$$I_B = \frac{V_{BB} - V_{BE}}{R_B + (\beta + 1)R_E} = \frac{2.55 - 0.7}{21.3k + 301 \times 1} = 5.74 \mu A$$

$$I_C = \beta I_B = 1.72 mA$$

$$V_{CE} = V_{CC} - R_E I_E = 12 - 301 \times 5.74 \mu \times 1k = 10.27V > 0.2 = V_{CE,sat}$$

交流小信号分析



$$v'_S = \frac{R_B}{R_S + R_B} v_S = \frac{21.3k}{0.1k + 21.3k} v_S = 0.995 v_S$$

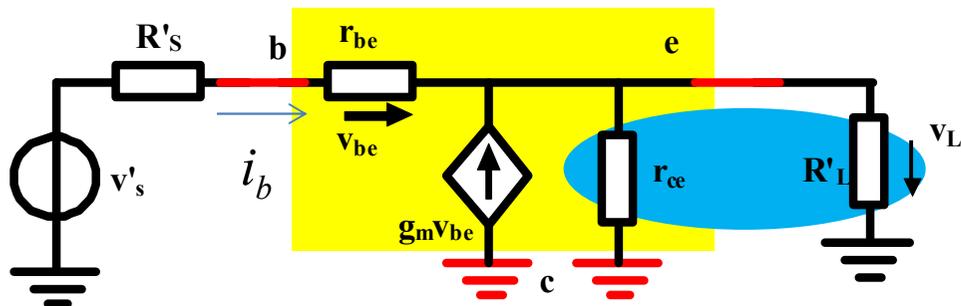
$$R'_S = R_S \parallel R_B = \frac{R_S R_B}{R_S + R_B} = 99.5 \Omega$$

$$R'_L = R_L \parallel R_E = 1k\Omega \parallel 2k\Omega = 667 \Omega$$

$$g_m = \frac{I_C}{v_T} = 66.2 mS$$

$$r_{be} = \beta \frac{1}{g_m} = 4.53 k\Omega$$

$$r_{ce} = \frac{V_A}{I_C} = 58.1 k\Omega$$



$$R_L'' = R_L' \parallel r_{ce} = 667 \parallel 58.1k = 659\Omega$$

$$A_i = \frac{i_L}{G_S v_S} = \frac{v_L / R_L}{G_S v_S}$$

$$= \frac{v_L}{v_S} \frac{R_S}{R_L}$$

$$= 0.972 \times \frac{100}{2000} = 0.0486$$

太小了：源内阻太小，源内阻分流过大，导致电流增益很小

换一种定义：输出端口电流比输入端口电流

$$A_i = \frac{i_{out}}{i_{in}}$$

$$v'_S = i_b (R'_S + r_{be}) + (i_b + g_m r_{be} i_b) R_L''$$

$$v_L = (i_b + g_m r_{be} i_b) R_L''$$

$$A_v = \frac{v_L}{v_S} = \frac{(i_b + g_m r_{be} i_b) R_L''}{i_b (R'_S + r_{be}) + (i_b + g_m r_{be} i_b) R_L''} \frac{v'_S}{v_S}$$

$$= \frac{(1 + g_m r_{be}) R_L''}{R'_S + r_{be} + R_L'' + g_m r_{be} R_L''} \frac{v'_S}{v_S}$$

$$= \frac{(1 + 66.2m \times 4.53k) \times 0.659}{0.0995 + 4.53 + (1 + 66.2m \times 4.53k) \times 0.659} \times 0.995$$

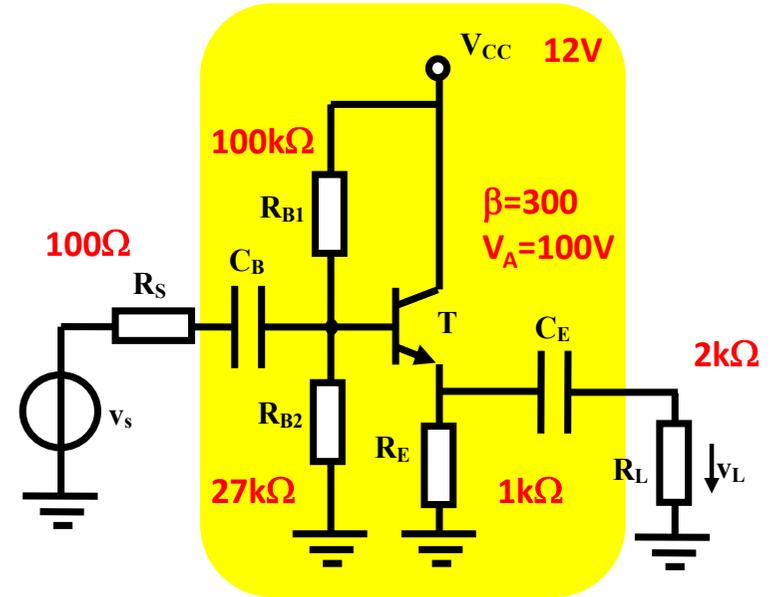
$$= 0.977 \times 0.995 = 0.972 \quad \text{预期之中的结果}$$

电流增益

$$A_i = \frac{i_{out}}{i_{in}} = \frac{i_{out}R_L}{i_{in}(R_S + R_B || r_{bc})} \frac{(R_S + R_B || r_{bc})}{R_L}$$

$$= \frac{v_L (R_S + R_B || r_{bc})}{v_S R_L}$$

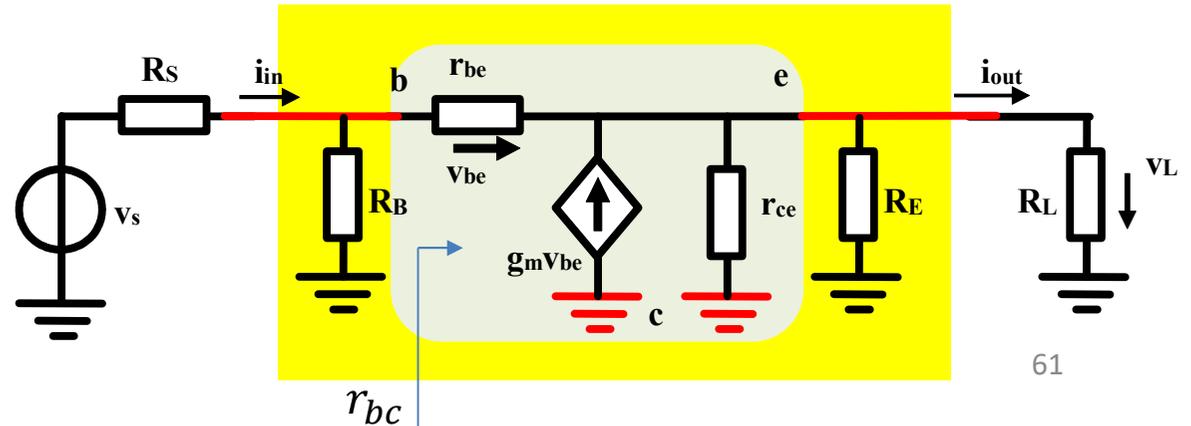
$$= A_v \frac{(R_S + R_B || (r_{be} + (r_{ce} || R_E || R_C) + g_m r_{be} (r_{ce} || R_E || R_C)))}{R_L}$$



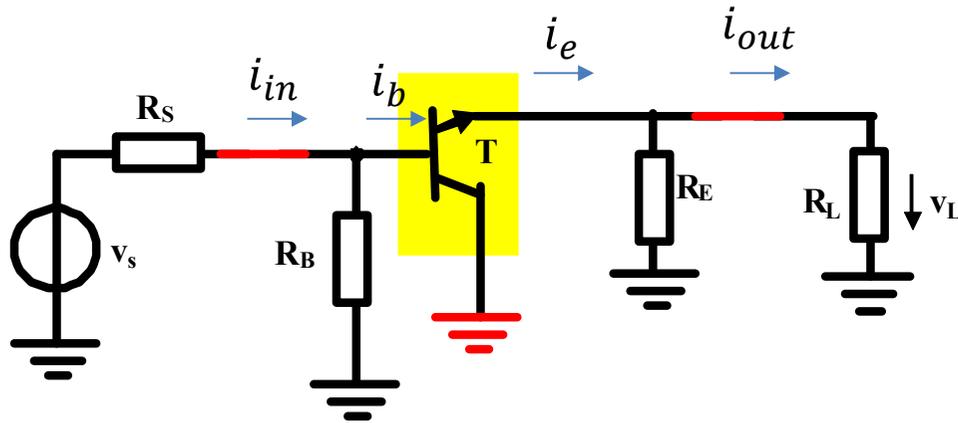
$$= 0.972 \times \frac{(100 + 21.3k || (4.53k + (58.1k || 1k || 2k) + 66.2m \times 4.53k \times 659))}{2k}$$

$$= 0.972 \times \frac{(100 + 21.3k || 203k)}{2k}$$

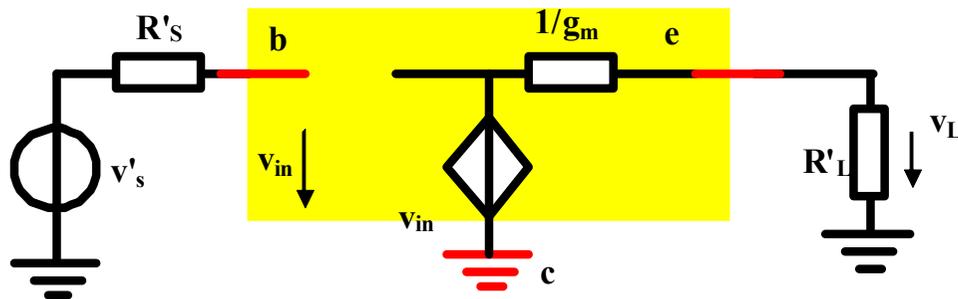
$$= 0.972 \times \frac{19.3k}{2k} = 9.4$$



电压缓冲器模型分析



$$99.5\Omega = R'_S \ll r_{be} = 4.53k$$



$$\begin{aligned} r_{bc} &= r_{be} + (r_{ce} \parallel R_E \parallel R_C) + g_m r_{be} (r_{ce} \parallel R_E \parallel R_C) \\ &= 4.53k + (58.1k \parallel 1k \parallel 2k) + 66.2m \times 4.53k \times 659 \\ &= 203k\Omega \end{aligned}$$

$$v_{in} = v'_S = 0.995v_S$$

$$v_L = \frac{R'_L}{R'_L + \frac{1}{g_m}} v'_S$$

$$= \frac{g_m}{1 + g_m R'_L} R'_L v'_S = g_{mf} R'_L v'_S$$

$$= \frac{66.2m \times 0.667k}{1 + 66.2m \times 0.667k} \times 0.995v_S$$

$$= \frac{44.1}{45.1} \times 0.995v_S = 0.973v_S$$

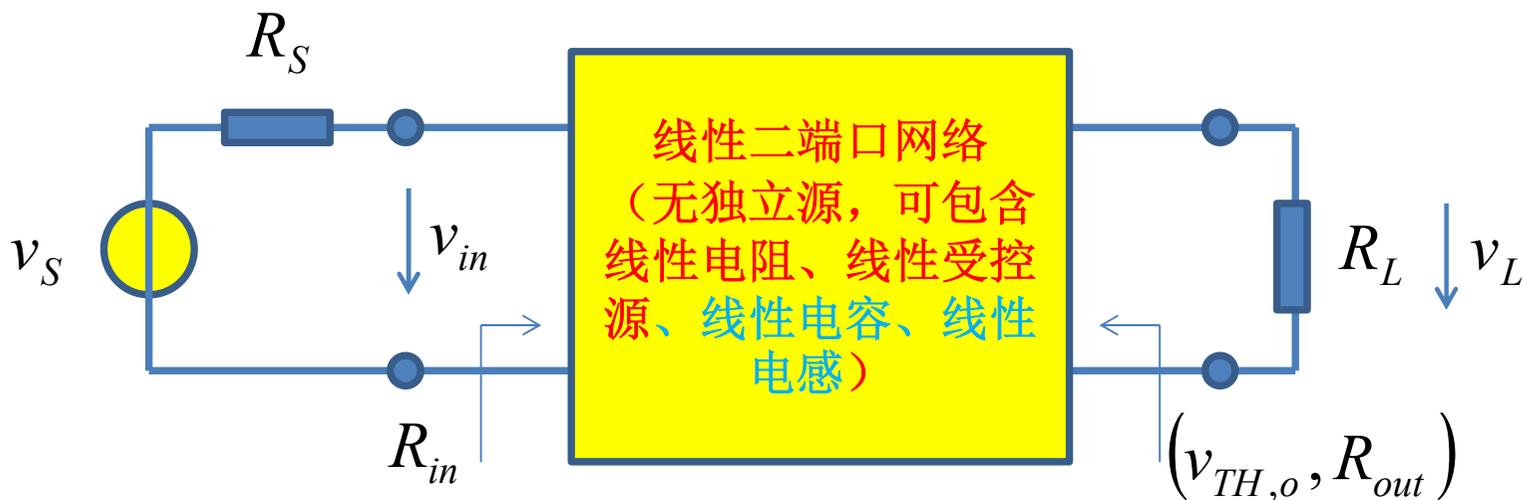
$$A_i = \frac{i_{out}}{i_{in}} = \frac{i_{out}}{i_e} \frac{i_e}{i_b} \frac{i_b}{i_{in}}$$

$$= \frac{G_L}{G_L + G_E} (\beta + 1) \frac{g_{bc}}{g_{bc} + G_B}$$

$$= \frac{R_E}{R_L + R_E} (\beta + 1) \frac{R_B}{r_{bc} + R_B}$$

$$\begin{aligned} &= \frac{1k}{1k + 2k} \times 301 \times \frac{21.3k}{203k + 21.3k} \\ &= 9.5 \end{aligned}$$

增益定义



$$G_T = \frac{P_L}{P_{si,max}} \quad A_v = 2 \sqrt{\frac{R_S}{R_L}} \frac{v_L}{v_S} \quad A_i = 2 \sqrt{\frac{G_S}{G_L}} \frac{i_L}{i_S}$$

射频电路常用定义

$$G_A = \frac{P_{so,max}}{P_{si,max}} \quad A_v = \frac{v_L}{v_S} \quad A_i = \frac{i_L}{i_S}$$

一般性定义, 不要求电阻负载

$$G_p = \frac{P_L}{P_{in}} \quad A_v = \frac{v_L}{v_{in}} \quad A_i = \frac{i_L}{i_{in}}$$

低频电路常用定义

$$P_L = \frac{V_{L,rms}^2}{R_L} \quad P_{si,max} = \frac{V_{S,rms}^2}{4R_S} \quad P_{so,max} = \frac{V_{TH,o,rms}^2}{4R_{out}} \quad P_{in} = \frac{V_{in,rms}^2}{R_{in}}$$