

电子电路与系统基础I

习题课第十讲

第7次作业讲解（部分）

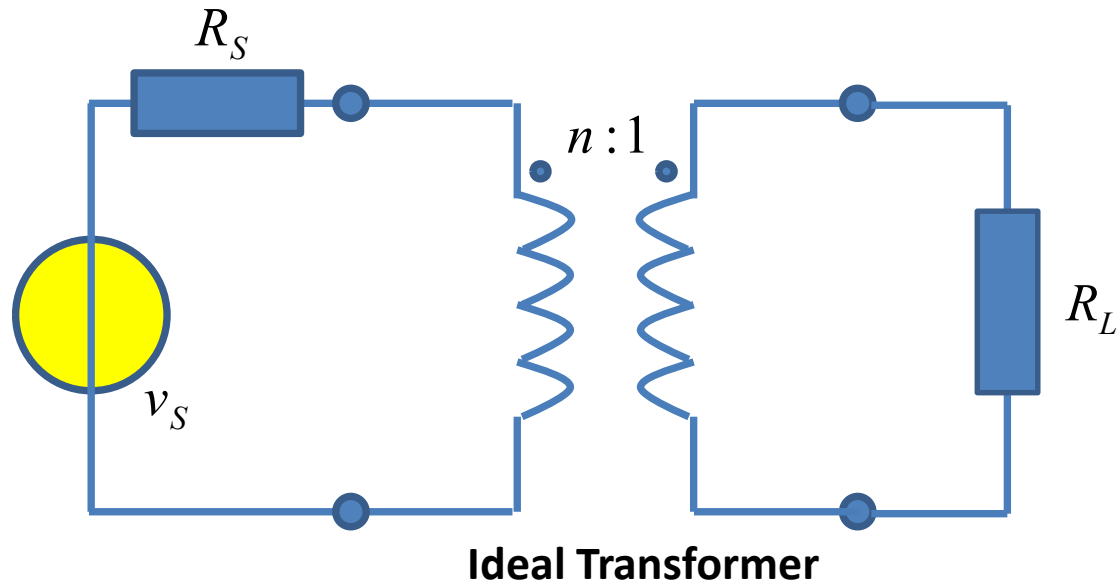
第8次作业讲解（部分）

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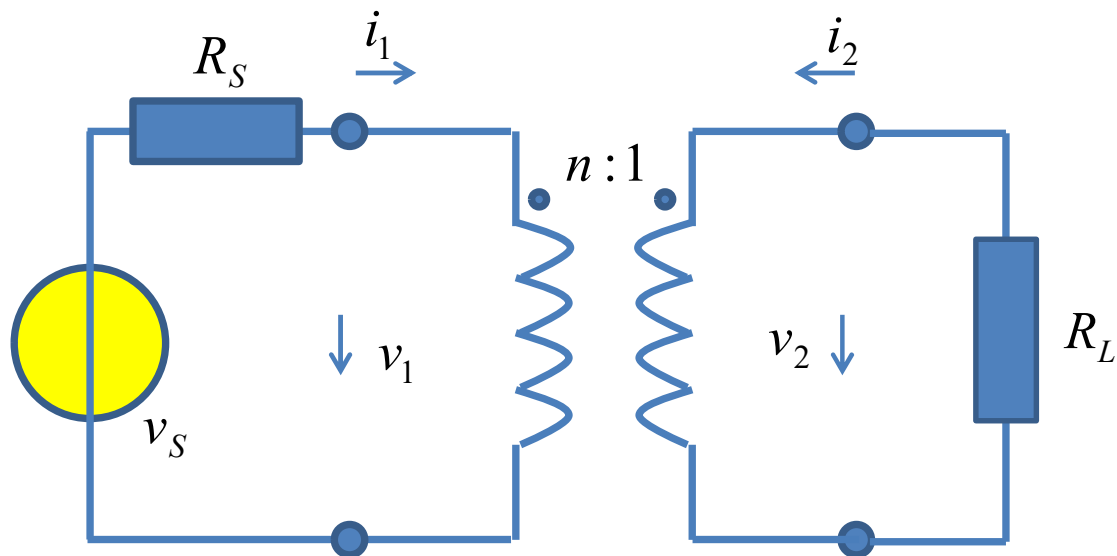
第7周作业

作业2 理想变压器实现阻抗匹配



负载电阻和信源内阻具有什么关系时，负载电阻可获得最大功率？此时信源输出多少功率？变压器消耗多少功率？负载消耗多少功率？

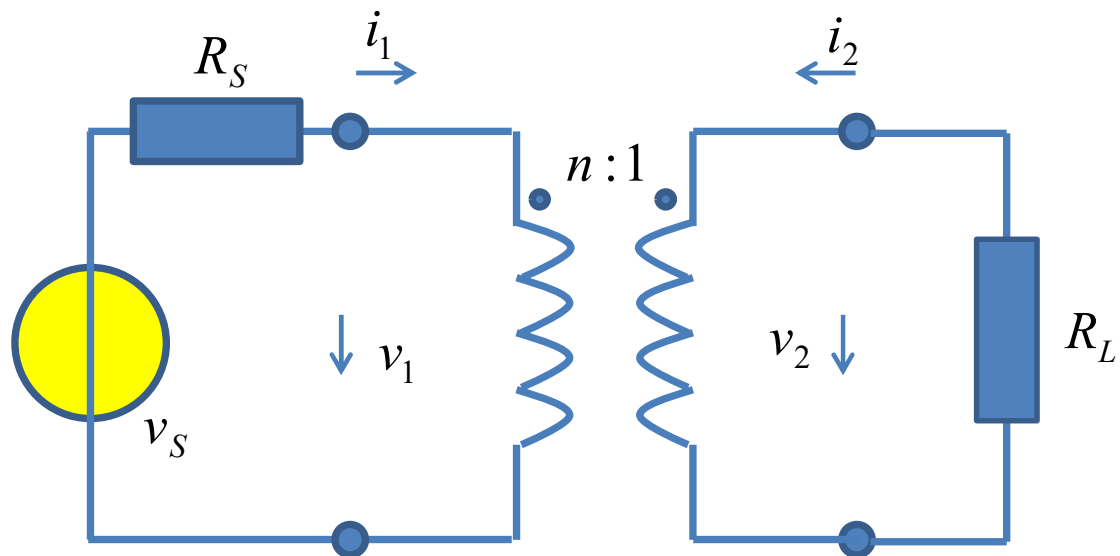
不考虑物理意义分析
 不从电路角度理解
 纯粹从数学方程求解角度分析
 对不熟悉的第一次碰到的电路



端口对接关系：定义一套端口电压电流，KVL、KCL自动满足，只需列写元件约束方程即可

$$\begin{array}{l}
 v_1 + i_1 R_S = v_S \quad \text{戴维南源约束} \quad \longrightarrow \quad v_2 = \frac{n^2 R_L}{n^2 R_L + R_S} \frac{v_S}{n} \\
 v_1 - n v_2 = 0 \quad \longrightarrow \quad v_1 = n v_2 \quad \longrightarrow \quad v_1 = \frac{n^2 R_L}{n^2 R_L + R_S} v_S \\
 i_1 + \frac{1}{n} i_2 = 0 \quad \text{理想变压器约束} \quad \longrightarrow \quad i_1 = -\frac{1}{n} i_2 = \frac{v_2}{n R_L} \quad \longrightarrow \quad i_1 = \frac{v_S}{n^2 R_L + R_S} \\
 v_2 + i_2 R_L = 0 \quad \text{负载约束} \quad \longrightarrow \quad i_2 = -\frac{v_2}{R_L} \quad \longrightarrow \quad i_2 = -\frac{n}{n^2 R_L + R_S} v_S
 \end{array}$$

对v2感兴趣，全部以v2为参变量表述其他中间变量



$$v_2 = \frac{n^2 R_L}{n^2 R_L + R_S} \frac{v_S}{n}$$

$$P_L = -\overline{v_2 i_2} = \frac{n^2 R_L}{(n^2 R_L + R_S)^2} V_{s,rms}^2 \leq \frac{V_{s,rms}^2}{4R_S} = P_{S,max}$$

$$v_1 = \frac{n^2 R_L}{n^2 R_L + R_S} v_S$$

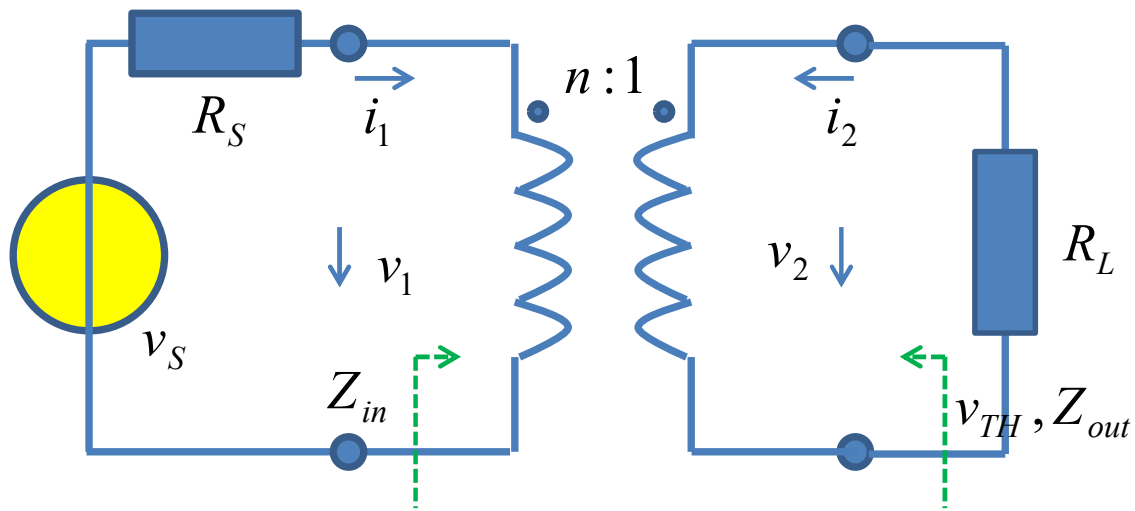
仅当 $R_S = n^2 R_L$ 等号成立

$$i_1 = \frac{v_S}{n^2 R_L + R_S}$$

$$i_2 = -\frac{n}{n^2 R_L + R_S} v_S$$

故而 $R_S = n^2 R_L$ 时，负载可获得信源额定功率

用等效电路解析表达式



$$v_1 = \frac{n^2 R_L}{n^2 R_L + R_S} v_S$$

$$i_1 = \frac{v_S}{n^2 R_L + R_S}$$

$$v_2 = \frac{n^2 R_L}{n^2 R_L + R_S} \frac{v_S}{n}$$

$$i_2 = -\frac{n}{n^2 R_L + R_S} v_S$$

$$Z_{in} = n^2 R_L$$

$$Z_{out} = \frac{R_S}{n^2}$$

$$v_{TH} = \frac{1}{n} v_S$$

对电路分析结果给出合理的解释（等效电路）：用等效电路理解则无需列大方程求解：足够积累后，应能够直接给结果

$$v_1 = \frac{Z_{in}}{R_S + Z_{in}} v_S$$

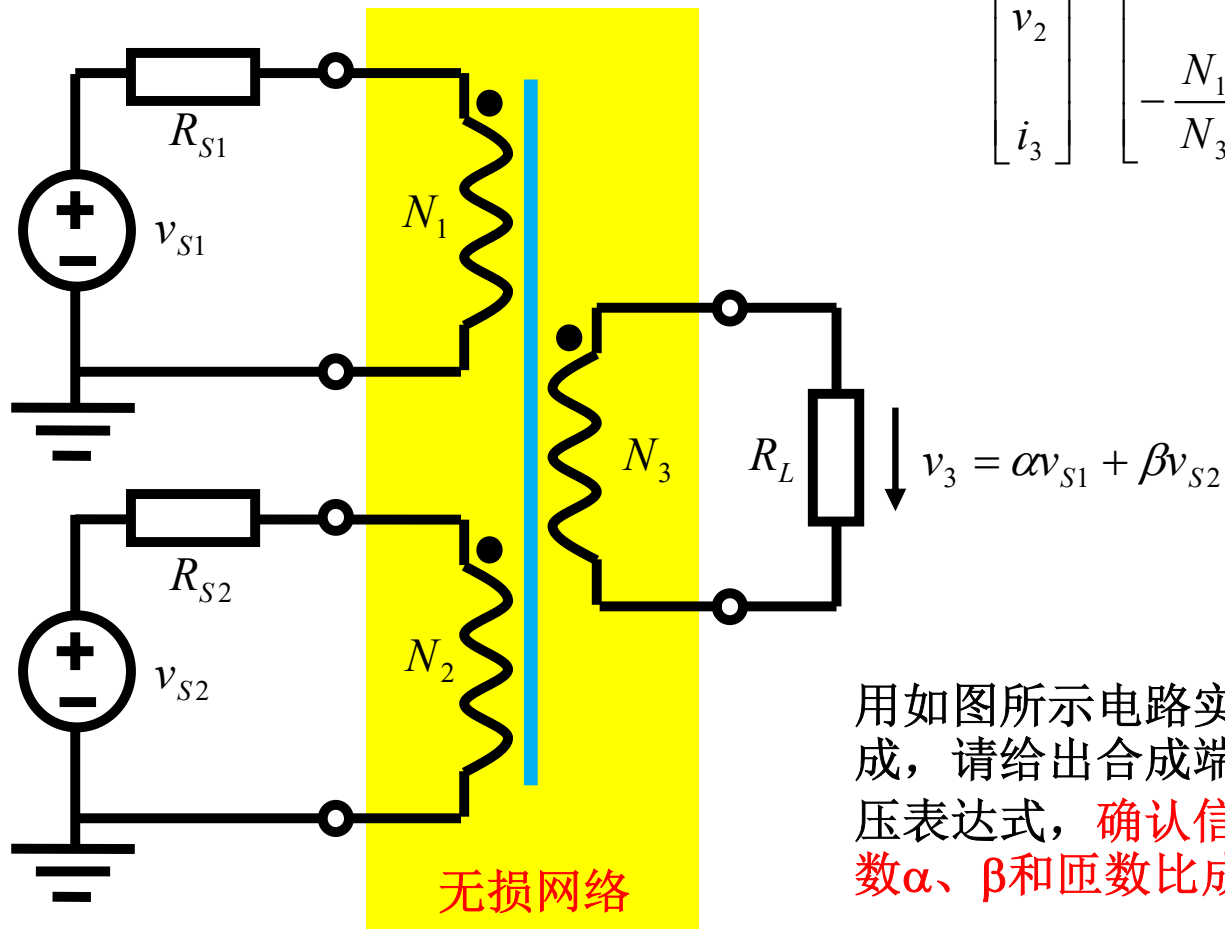
$$i_1 = \frac{v_S}{Z_{in} + R_S}$$

$$v_2 = \frac{R_L}{R_L + Z_{out}} v_{TH}$$

$$i_2 = -\frac{v_{TH}}{Z_{out} + R_L}$$

第7周作业

作业3 信号合成

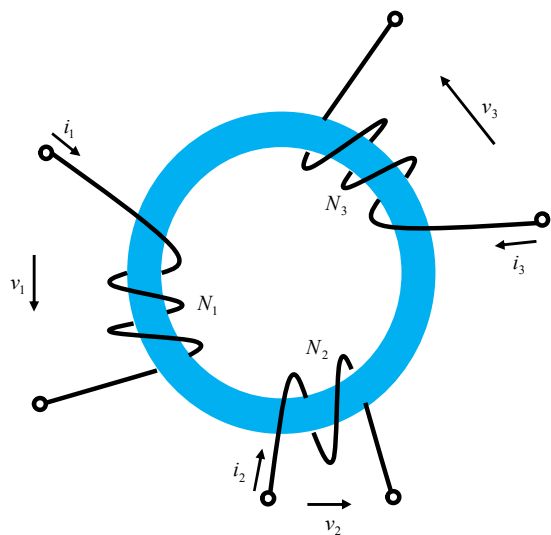


Ideal Transformer

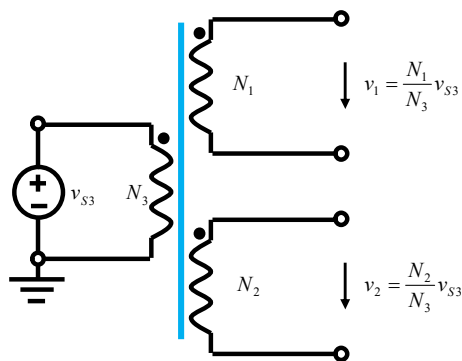
$$\begin{bmatrix} v_1 \\ v_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{N_1}{N_3} \\ 0 & 0 & \frac{N_2}{N_3} \\ -\frac{N_1}{N_3} & -\frac{N_2}{N_3} & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_3 \end{bmatrix}$$

用如图所示电路实现信号合成，请给出合成端口 v_3 的电压表达式，确认信号合成系数 α 、 β 和匝数比成正比关系

三个端口 没有本质区别



(a) 三端口电感绕制方式



(b) 三端口理想变压器信号分解

$$\begin{bmatrix} v_1 \\ v_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{N_1}{N_3} \\ 0 & 0 & \frac{N_2}{N_3} \\ -\frac{N_1}{N_3} & -\frac{N_2}{N_3} & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_3 \end{bmatrix}$$

$$v_1 - \frac{N_1}{N_3} v_3 = 0$$

$$v_2 - \frac{N_2}{N_3} v_3 = 0$$

$$i_3 + \frac{N_1}{N_3} i_1 + \frac{N_2}{N_3} i_2 = 0$$

$$\frac{v_1}{N_1} = \frac{v_2}{N_2} = \frac{v_3}{N_3} = \mathfrak{F}_0$$

$$N_1 i_1 + N_2 i_2 + N_3 i_3 = 0$$

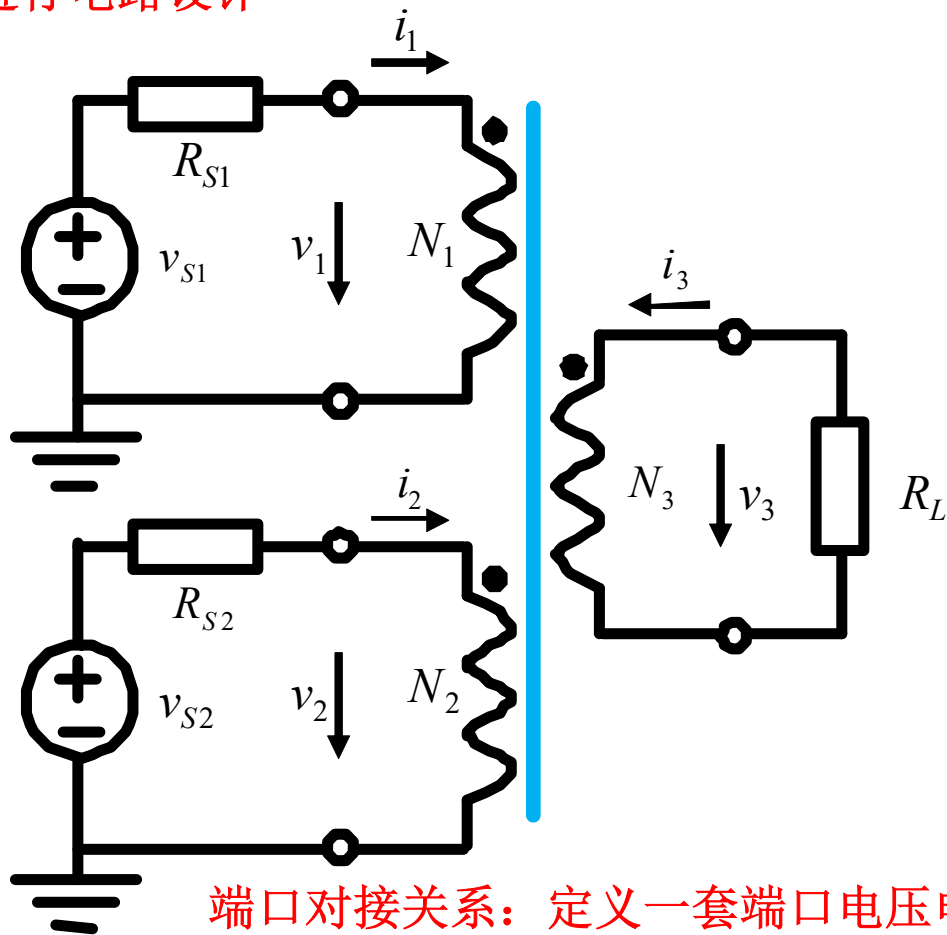
$$P_\Sigma = v_1 i_1 + v_2 i_2 + v_3 i_3 \equiv 0$$

无损网络

第一次碰到的电路，先列数学方程求解

之后对解进行解析，赋予明确的物理意义或等效电路，方便记忆

再后则可根据对电路的理解、物理解释（等效电路）进行电路设计



端口对接关系：定义一套端口电压电流，KVL、KCL自动满足，只需列写元件约束方程即可

$$v_1 + i_1 R_{S1} = v_{S1}$$

$$v_2 + i_2 R_{S2} = v_{S2}$$

$$v_3 + i_3 R_L = 0$$

$$v_1 - \frac{N_1}{N_3} v_3 = 0$$

$$v_2 - \frac{N_2}{N_3} v_3 = 0$$

$$i_3 + \frac{N_1}{N_3} i_1 + \frac{N_2}{N_3} i_2 = 0$$

$$\begin{bmatrix} v_1 \\ v_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{N_1}{N_3} \\ 0 & 0 & \frac{N_2}{N_3} \\ -\frac{N_1}{N_3} & -\frac{N_2}{N_3} & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_3 \end{bmatrix}$$

MATLAB辅助符号运算：可用手工推，可用借助计算机

```
>> syms RS1 RS2 RL vS1 vS2 N1 N2 N3
>> A=[1 0 0 RS1 0 0;0 1 0 0 RS2 0;0 0 1 0 0 RL;1 0 -N1/N3 0 0 0;0 1 -N2/N3 0 0 0;0 0 0 N1/N3 N2/N3 1]
```

A =

$$\begin{bmatrix} 1 & 0 & 0 & RS1 & 0 & 0 \\ 0 & 1 & 0 & 0 & RS2 & 0 \\ 0 & 0 & 1 & 0 & 0 & RL \\ 1 & 0 & -N1/N3 & 0 & 0 & 0 \\ 0 & 1 & -N2/N3 & 0 & 0 & 0 \\ 0 & 0 & 0 & N1/N3 & N2/N3 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} v_{S1} \\ v_{S2} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

对 v_3 感兴趣，
以 v_3 为参变量
表述其他中间
变量，即可最
终只剩下关于
 v_3 的方程

```
>> inv(A)
```

ans =

```
[ N1^2*RS2*RL/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), N1*RS1*RL*N2/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2),
 [ N2*N1*RS2*RL/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), N2^2*RS1*RL/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2),
 [ N1*N3*RS2*RL/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), RS1*RL*N2*N3/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2),
 [ (N2^2*RL+RS2*N3^2)/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), -N2*RL*N1/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2),
 [ -N2*RL*N1/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), (N1^2*RL+RS1*N3^2)/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2),
 [ -RS2*N1*N3/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), -RS1*N2*N3/(N1^2*RS2*RL+N2^2*RS1*RL+RS2*RS1*N3^2), (N1^2*
```

$$v_3 = \frac{N_1 N_3 R_L R_{S2}}{N_1^2 R_{S2} R_L + N_2^2 R_{S1} R_L + N_3^2 R_{S1} R_{S2}} v_{S1} + \frac{N_2 N_3 R_L R_{S1}}{N_1^2 R_{S2} R_L + N_2^2 R_{S1} R_L + N_3^2 R_{S1} R_{S2}} v_{S2}$$

$$v_1 + i_1 R_{S1} = v_{S1}$$

$$v_2 + i_2 R_{S2} = v_{S2}$$

$$v_3 + i_3 R_L = 0$$

$$v_1 - \frac{N_1}{N_3} v_3 = 0$$

$$v_2 - \frac{N_2}{N_3} v_3 = 0$$

$$i_3 + \frac{N_1}{N_3} i_1 + \frac{N_2}{N_3} i_2 = 0$$

计算机求解的最大问题：很难看出物理意义

$$v_1 + i_1 R_{S1} = v_{S1} \quad \xrightarrow{\textcircled{3}} \quad i_1 = \frac{v_{S1}}{R_{S1}} - \frac{v_1}{R_{S1}} = \frac{v_{S1}}{R_{S1}} - \frac{N_1}{N_3} \frac{v_3}{R_{S1}}$$

$$v_2 + i_2 R_{S2} = v_{S2} \quad \xrightarrow{\textcircled{4}} \quad i_2 = \frac{v_{S2}}{R_{S2}} - \frac{v_2}{R_{S2}} = \frac{v_{S2}}{R_{S2}} - \frac{N_2}{N_3} \frac{v_3}{R_{S2}}$$

$$v_3 + i_3 R_L = 0 \quad \xrightarrow{\textcircled{5}} \quad i_3 = -\frac{v_3}{R_L}$$

$$v_1 - \frac{N_1}{N_3} v_3 = 0 \quad \xrightarrow{\textcircled{1}} \quad v_1 = \frac{N_1}{N_3} v_3$$

$$v_2 - \frac{N_2}{N_3} v_3 = 0 \quad \xrightarrow{\textcircled{2}} \quad v_2 = \frac{N_2}{N_3} v_3$$

$$i_3 + \frac{N_1}{N_3} i_1 + \frac{N_2}{N_3} i_2 = 0 \quad \xrightarrow{\textcircled{7}} \quad -\frac{v_3}{R_L} + \frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} - \left(\frac{N_1}{N_3}\right)^2 \frac{v_3}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}} - \left(\frac{N_2}{N_3}\right)^2 \frac{v_3}{R_{S2}} = 0$$

$$\frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}} = \frac{v_3}{R_L} + \left(\frac{N_1}{N_3}\right)^2 \frac{v_3}{R_{S1}} + \left(\frac{N_2}{N_3}\right)^2 \frac{v_3}{R_{S2}}$$

$$v_3 = \frac{\frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}}}{\frac{1}{R_L} + \left(\frac{N_1}{N_3}\right)^2 \frac{1}{R_{S1}} + \left(\frac{N_2}{N_3}\right)^2 \frac{1}{R_{S2}}}$$

从表达式给出等效电路解释

② 被 N_1/N_3 的变流比变换到端口3，形成端口3的源电流

① 端口1所接电源的诺顿源电流

⑤ 端口3的两个源电流相加，形成总源电流（并联）

④ 被 N_2/N_3 的变流比变换到端口3，形成端口3的源电流

③ 端口2所接电源的诺顿源电流

$$v_3 = \frac{\frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}}}{\frac{1}{R_L} + \left(\frac{N_1}{N_3}\right)^2 \frac{1}{R_{S1}} + \left(\frac{N_2}{N_3}\right)^2 \frac{1}{R_{S2}}}$$

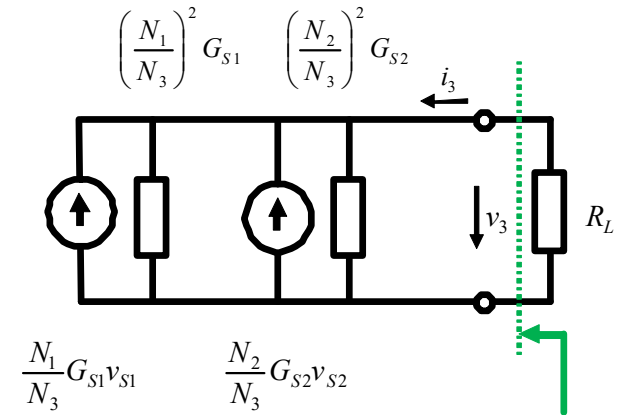
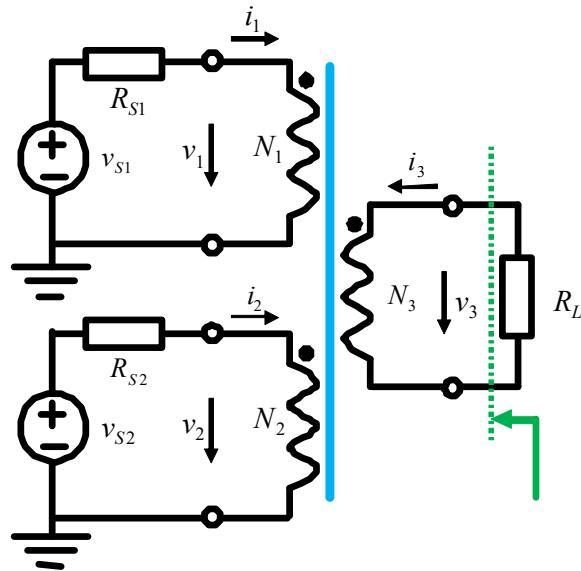
⑨ 端口3电压为源电流和总阻抗之积

⑦ 端口2的源内导被变换到端口3

⑥ 端口1的源内导被变换到端口3

⑧ 端口3的总电导是两个等效源内导和负载电导之和（并联结构）

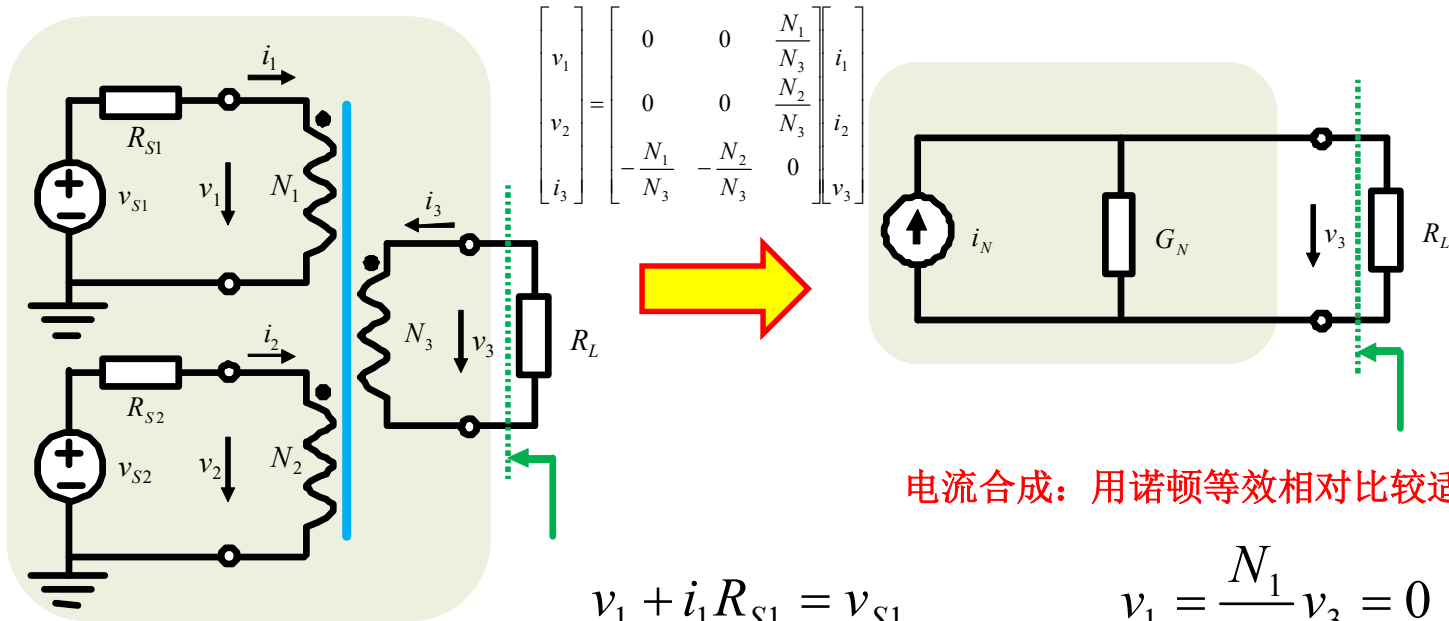
等效电路



$$v_3 = \frac{\frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}}}{\frac{1}{R_L} + \left(\frac{N_1}{N_3}\right)^2 \frac{1}{R_{S1}} + \left(\frac{N_2}{N_3}\right)^2 \frac{1}{R_{S2}}} = \alpha i_{S1} + \beta i_{S2}$$

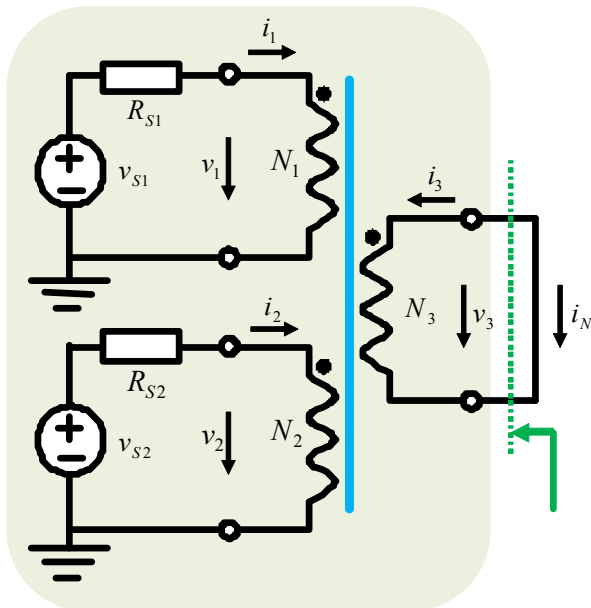
$$\alpha : \beta \sim N_1 : N_2$$

用诺顿定理求等效源电流



电流合成：用诺顿等效相对比较适当

诺顿源电流：输出端口短路电流



$$v_1 + i_1 R_{S1} = v_{S1}$$

$$v_1 = \frac{N_1}{N_3} v_3 = 0$$

$$v_2 + i_2 R_{S2} = v_{S2}$$

$$v_2 = \frac{N_2}{N_3} v_3 = 0$$

$$v_3 = 0$$

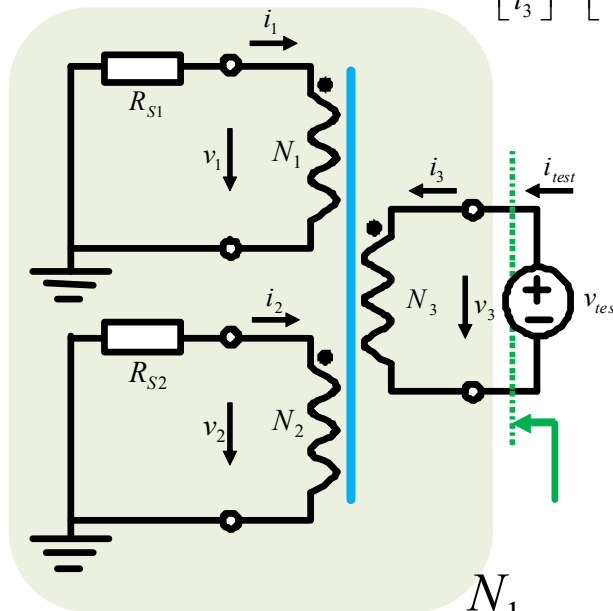
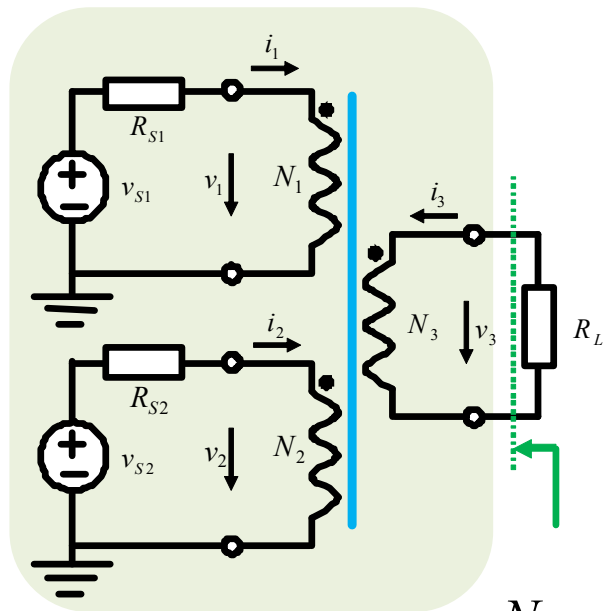
$$i_N = -i_3 = \frac{N_1}{N_3} i_1 + \frac{N_2}{N_3} i_2$$

$$= \frac{N_1}{N_3} \frac{v_{S1}}{R_{S1}} + \frac{N_2}{N_3} \frac{v_{S2}}{R_{S2}}$$

$$= \frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}$$

用诺顿定理求源内导

$$\begin{bmatrix} v_1 \\ v_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{N_1}{N_3} \\ 0 & 0 & \frac{N_2}{N_3} \\ -\frac{N_1}{N_3} & -\frac{N_2}{N_3} & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_3 \end{bmatrix}$$



$$v_1 + i_1 R_{S1} = 0$$

$$v_2 + i_2 R_{S2} = 0$$

$$v_3 = v_{test}$$

$$v_1 = \frac{N_1}{N_3} v_3 = \frac{N_1}{N_3} v_{test}$$

$$v_2 = \frac{N_2}{N_3} v_3 = \frac{N_2}{N_3} v_{test}$$

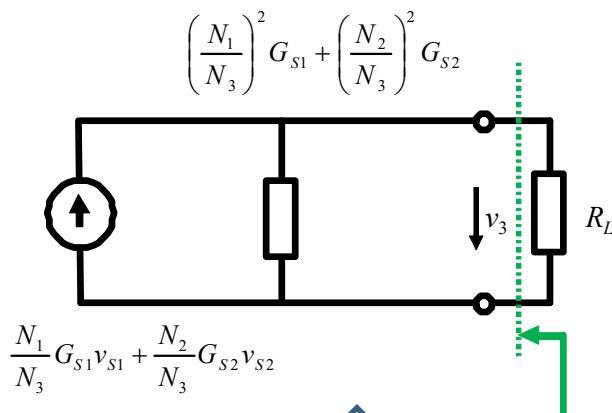
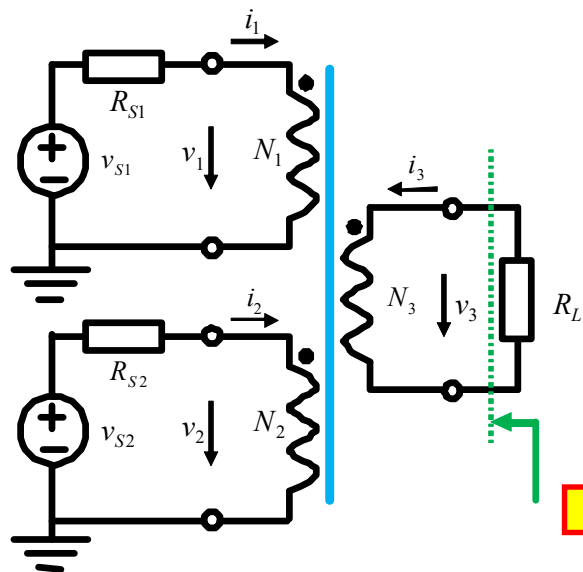
$$G_N = \frac{i_{test}}{v_{test}} = \left(\frac{N_1}{N_3} \right)^2 G_{S1} + \left(\frac{N_2}{N_3} \right)^2 G_{S2}$$

$$i_{test} = i_3 = -\frac{N_1}{N_3} i_1 - \frac{N_2}{N_3} i_2$$

$$= \frac{N_1}{N_3} \frac{v_1}{R_{S1}} + \frac{N_2}{N_3} \frac{v_2}{R_{S2}}$$

$$= \left(\frac{N_1}{N_3} \right)^2 \frac{v_{test}}{R_{S1}} + \left(\frac{N_2}{N_3} \right)^2 \frac{v_{test}}{R_{S2}}$$

等效电路理解更直观易记



$$v_3 = \frac{\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}}{G_L + \left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2}}$$

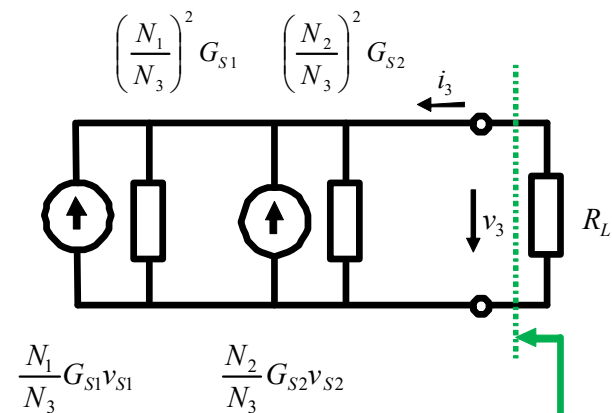
$$= \left(\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}\right) \frac{G_L}{G_L + \frac{N_1^2}{N_3^2} G_{S1} + \frac{N_2^2}{N_3^2} G_{S2}} R_L$$

↑
总电流

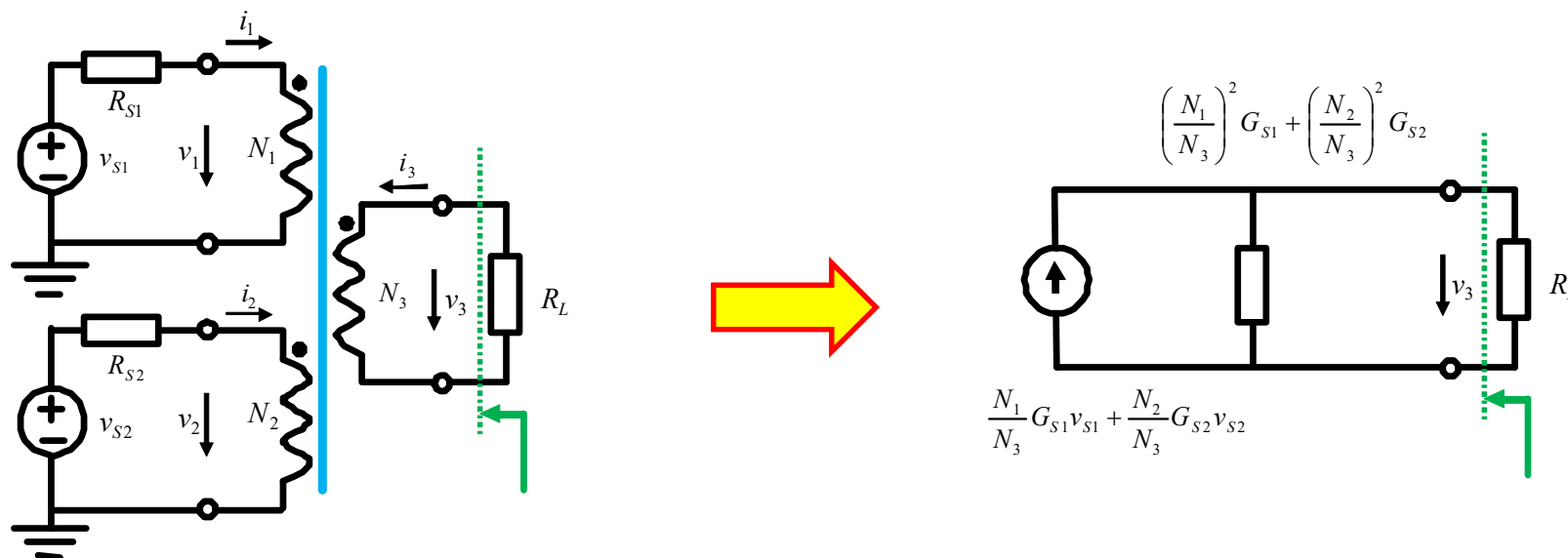
↑
在 G_L 上的分流

↑
流过 R_L 产生的电压

$$= \left(\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}\right) \lambda R_L$$



匹配？最大功率传输？

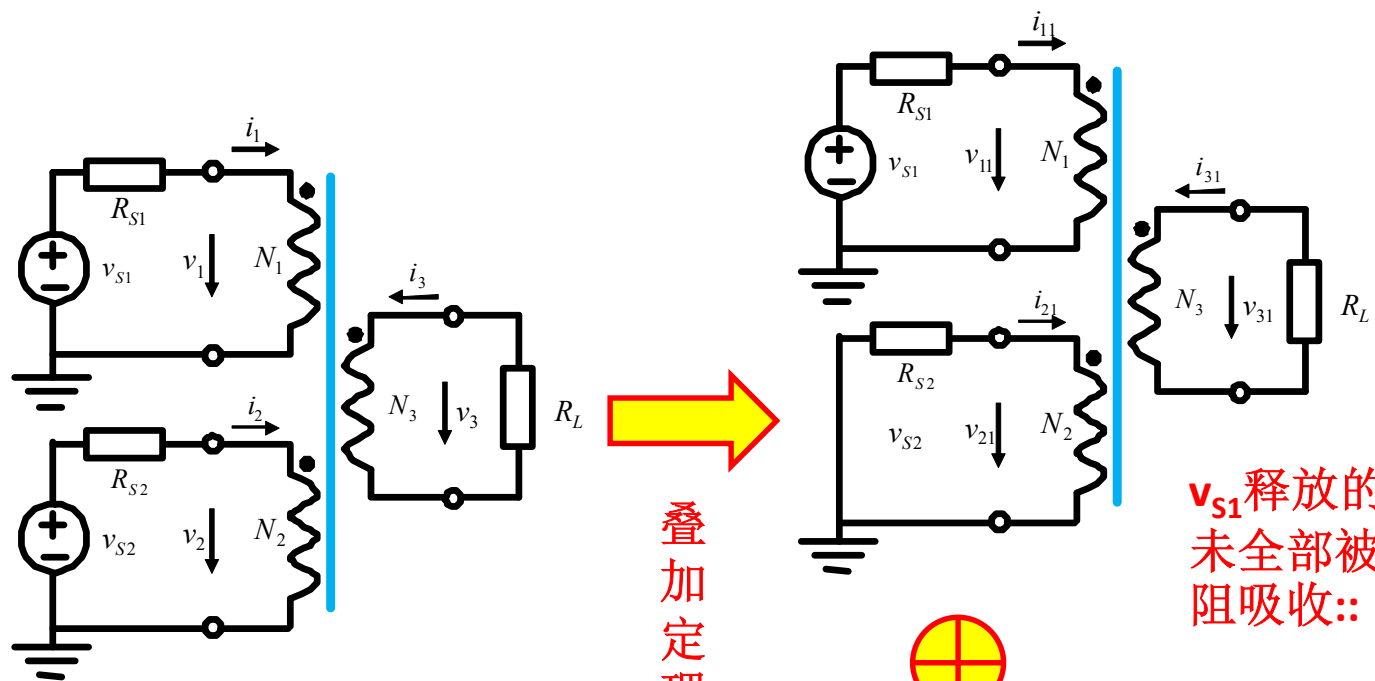


$$R_L = \frac{1}{\left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2}}$$

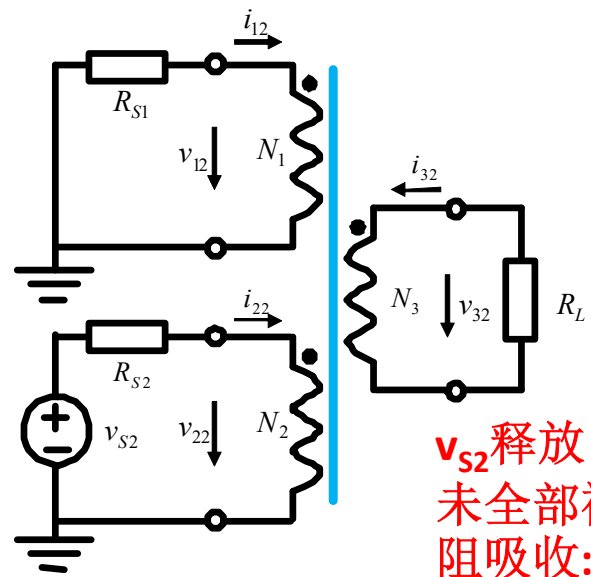
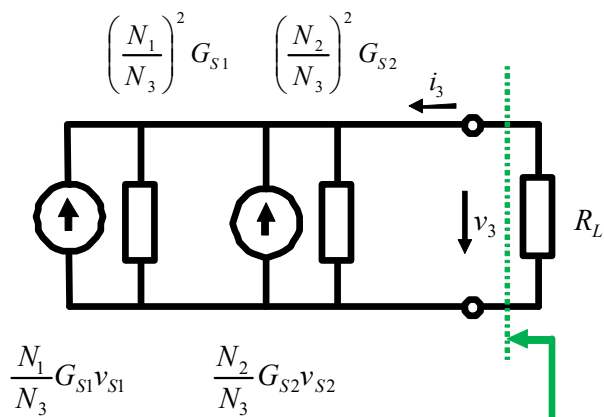
负载能够获得等效源的额定功率！！

负载吸收的功率是否就是实际信源所释放的功率？

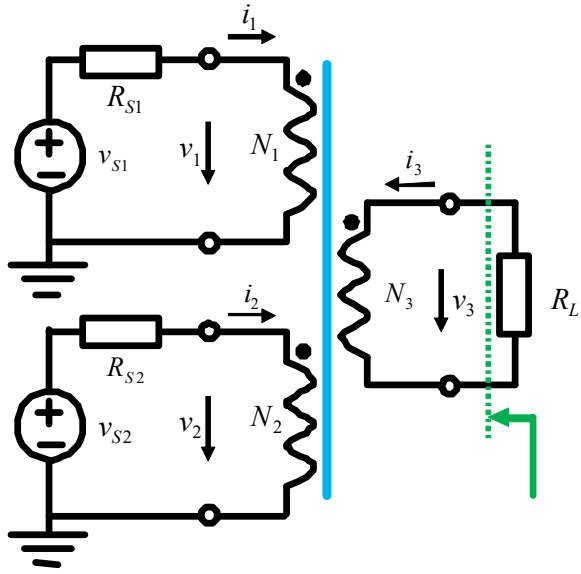
信源内阻也吸收功率？



v_{S1} 释放的功率并未全部被负载电阻吸收::



v_{S2} 释放的功率并未全部被负载电阻吸收::



$$R_L = \frac{1}{\left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2}}$$

$$N_3^2 G_L = N_1^2 G_{S1} + N_2^2 G_{S2}$$

$$v_3 = \left(\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}\right) \frac{N_3^2 G_L}{N_3^2 G_L + N_1^2 G_{S1} + N_2^2 G_{S2}} R_L$$

$$= \left(\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}\right) \frac{N_3^2}{2(N_1^2 G_{S1} + N_2^2 G_{S2})}$$

$$P_L = \frac{v_{3,rms}^2}{R_L} = \frac{\left(\frac{N_1}{N_3} i_{S1} + \frac{N_2}{N_3} i_{S2}\right)^2}{4} \frac{N_3^2}{N_1^2 G_{S1} + N_2^2 G_{S2}}$$

$$= \frac{1}{4} \frac{1}{N_1^2 G_{S1} + N_2^2 G_{S2}} \left(\overline{N_1^2 i_{S1}^2} + 2\overline{N_1 N_2 i_{S1} i_{S2}} + \overline{N_2^2 i_{S2}^2}\right)$$

$$= \frac{1}{4} \frac{1}{N_1^2 G_{S1} + N_2^2 G_{S2}} \left(N_1^2 \overline{i_{S1,rms}^2} + 2N_1 N_2 \overline{i_{S1} i_{S2}} + N_2^2 \overline{i_{S2,rms}^2}\right)$$

$$P_{S1,max} = \frac{1}{4} \frac{v_{S1,rms}^2}{R_{S1}} = \frac{1}{4} \frac{i_{S1,rms}^2}{G_{S1}}$$

$$P_{S2,max} = \frac{1}{4} \frac{v_{S2,rms}^2}{R_{S2}} = \frac{1}{4} \frac{i_{S2,rms}^2}{G_{S2}}$$

$$P_{S,max} = P_{S1,max} + P_{S2,max} = \frac{1}{4} \frac{i_{S1,rms}^2}{G_{S1}} + \frac{1}{4} \frac{i_{S2,rms}^2}{G_{S2}}$$

$$P_L = \frac{1}{4} \frac{1}{N_1^2 G_{S1} + N_2^2 G_{S2}} \left(N_1^2 \overline{i_{S1,rms}^2} + 2N_1 N_2 \overline{i_{S1} i_{S2}} + N_2^2 \overline{i_{S2,rms}^2}\right) \sim\sim P_{S,max} = \frac{1}{4} \frac{i_{S1,rms}^2}{G_{S1}} + \frac{1}{4} \frac{i_{S2,rms}^2}{G_{S2}}$$

$$N_1^2 \overline{i_{S1,rms}^2} + 2N_1 N_2 \overline{i_{S1} i_{S2}} + N_2^2 \overline{i_{S2,rms}^2} \sim\sim N_1^2 \overline{i_{S1,rms}^2} + N_2^2 \frac{G_{S2}}{G_{S1}} \overline{i_{S1,rms}^2} + N_1^2 \frac{G_{S1}}{G_{S2}} \overline{i_{S2,rms}^2} + N_2^2 \overline{i_{S2,rms}^2}$$

$$2N_1 N_2 \overline{i_{S1} i_{S2}} \sim\sim N_2^2 \frac{G_{S2}}{G_{S1}} \overline{i_{S1,rms}^2} + N_1^2 \frac{G_{S1}}{G_{S2}} \overline{i_{S2,rms}^2}$$

$$2N_1 N_2 \overline{i_{S1} i_{S2}} \leq N_2^2 \frac{G_{S2}}{G_{S1}} \overline{i_{S1,rms}^2} + N_1^2 \frac{G_{S1}}{G_{S2}} \overline{i_{S2,rms}^2}$$

最大功率传输的条件

$$P_L = \frac{1}{4} \frac{1}{N_1^2 G_{S1} + N_2^2 G_{S2}} \left(N_1^2 i_{S1,rms}^2 + 2N_1 N_2 \overline{i_{S1} i_{S2}} + N_2^2 i_{S2,rms}^2 \right) \leq P_{S,max} = \frac{1}{4} \frac{i_{S1,rms}^2}{G_{S1}} + \frac{1}{4} \frac{i_{S2,rms}^2}{G_{S2}}$$

$$2N_1 N_2 \overline{i_{S1} i_{S2}} \leq N_2^2 \frac{G_{S2}}{G_{S1}} i_{S1,rms}^2 + N_1^2 \frac{G_{S1}}{G_{S2}} i_{S2,rms}^2$$

$$2N_1 N_2 G_{S1} G_{S2} \overline{i_{S1} i_{S2}} \leq N_2^2 G_{S2}^2 \overline{i_{S1}^2} + N_1^2 G_{S1}^2 \overline{i_{S2}^2}$$

$$N_2 G_{S2} i_{S1} = N_1 G_{S1} i_{S2}$$

$$\frac{i_{S1}}{N_1 G_{S1}} = \frac{i_{S2}}{N_2 G_{S2}}$$

阻抗匹配条件

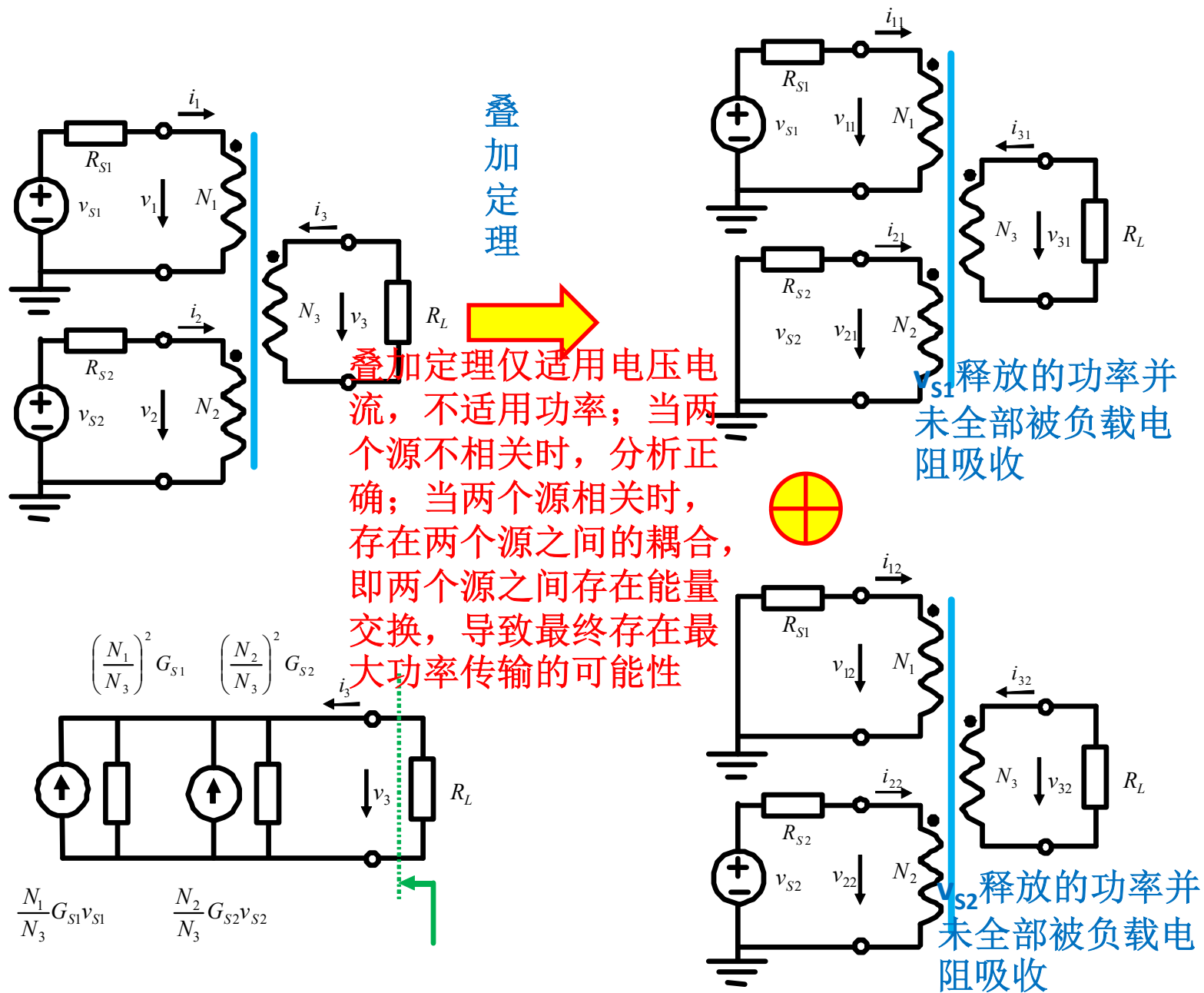
源相关条件

$$\frac{v_{S1}}{N_1} = \frac{v_{S2}}{N_2}$$

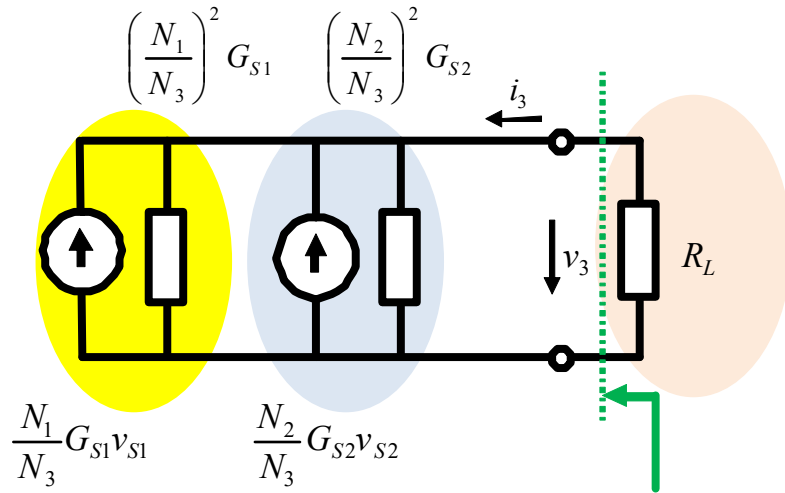
$$R_L = \frac{1}{\left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2}}$$

两个激励源不是任意的源
同步变化的源
任意时刻电压幅度比值是确定的值

物理解释错误出在哪里？



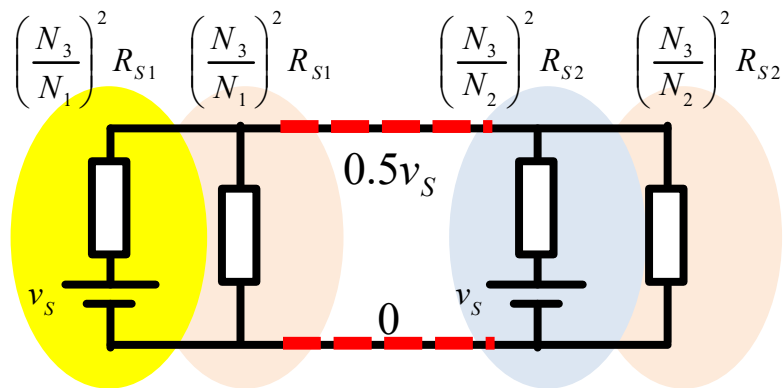
从等效电路看



$$G_L = \left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2} \quad \frac{v_{S1}}{N_1} = \frac{v_{S2}}{N_2} = \frac{v_S}{N_3}$$

$$i_{N1} = \frac{N_1}{N_3} G_{S1} v_{S1} = \left(\frac{N_1}{N_3}\right)^2 G_{S1} v_S$$

$$i_{N2} = \frac{N_2}{N_3} G_{S2} v_{S2} = \left(\frac{N_2}{N_3}\right)^2 G_{S2} v_S$$



在满足阻抗匹配条件和源相关条件下：
两个源阻回路之间电压相等，无电流，
相当于开路：可视为两个源分别各自
匹配，分别将最大功率传输给各自匹
配的电阻

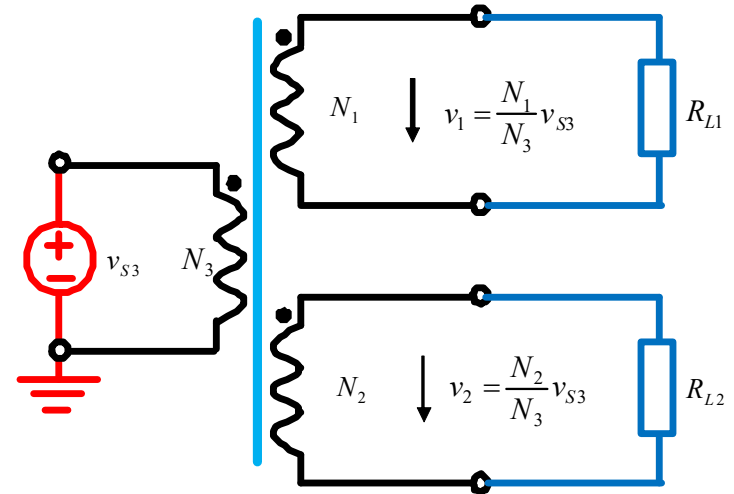
学会对计算结果进行物理解释

- 第一次还没有建立起物理概念时，可以通过各种方式获得解析表达式
 - 解析式可以是近似的，可以是精确的
 - 可用借助计算机辅助公式推导
- 对解析式进行物理解释，以后碰到类似问题可以直接给出结论，无需再经过列写方程、求解方程的过程
 - 建立起大量的这类直观的简单等效电路概念之后，可以帮助我们进行复杂电路的设计
- 分析过一个电路，则建立一个等效电路模型，其后直接从等效电路角度分析，从等效电路角度进行电路设计
 - 电路等效是数学方程计算过程的符号化表述，直观，易于理解
 - 给予物理解释后，直观，容易记忆，便于设计时直接利用

三端口理想变压器

端口约束方程中看到了什么？

$$\begin{bmatrix} v_1 \\ v_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{N_1}{N_3} \\ 0 & 0 & \frac{N_2}{N_3} \\ -\frac{N_1}{N_3} & -\frac{N_2}{N_3} & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_3 \end{bmatrix}$$



电压信号的分解

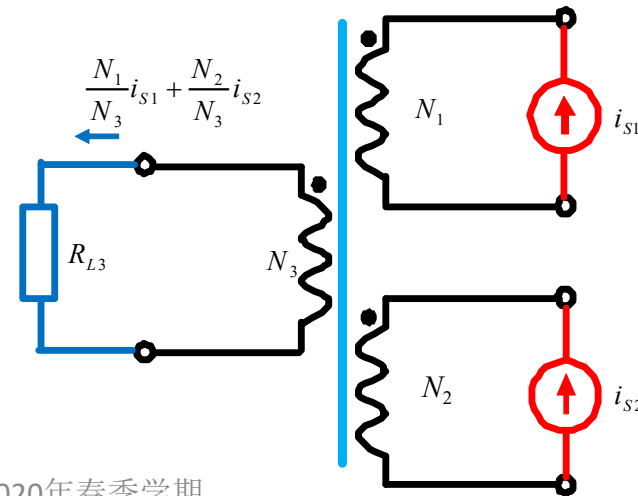
$$v_1 = \frac{N_1}{N_3} v_3$$

电压信号的分解

$$v_2 = \frac{N_2}{N_3} v_3$$

$$i_3 = -\frac{N_1}{N_3} i_1 - \frac{N_2}{N_3} i_2$$

电流信号的合成



电流信号的合成

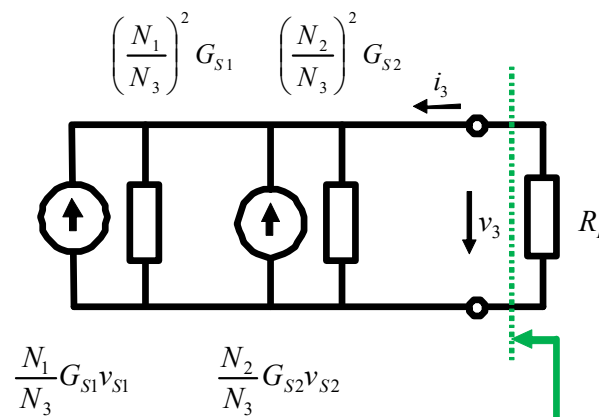
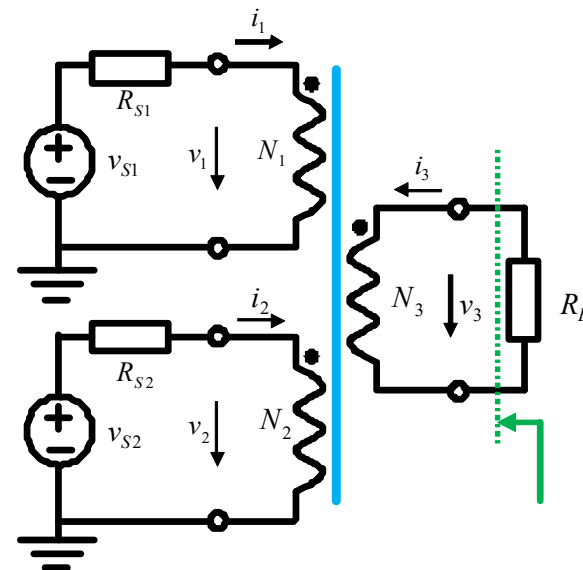
三端口理想变压器 功率合成器

$$P_L = P_{S1,\max} + P_{S2,\max}$$

功率合成

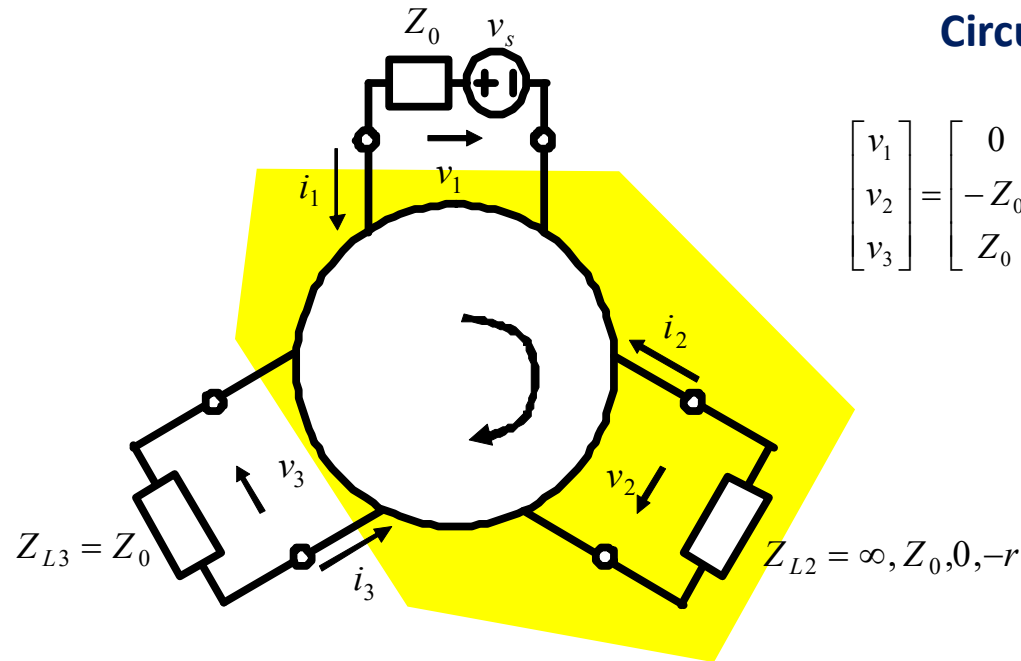
$$G_L = \left(\frac{N_1}{N_3}\right)^2 G_{S1} + \left(\frac{N_2}{N_3}\right)^2 G_{S2} \quad \text{阻抗匹配条件}$$

$$\frac{v_{S1}}{N_1} = \frac{v_{S2}}{N_2} \quad \text{源相关条件}$$



第7周作业

作业4 负阻放大器



Circulator

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

证明：（1）当端口2开路或短路时，环行器端口1吸收的功率全部从端口3送出，为端口3匹配负载吸收

（2）选作：当端口2为负阻时，环行器端口3获得功率高于端口1吸收功率，以端口2为内部端口，以端口1为输入端口，以端口3为输出端口，求该二端口网络的输入电阻、输出电阻和功率增益

端口2短路 功率全反射

$$i_1 = i_{test} \quad \textcircled{1}$$

$$v_2 = 0 \quad \textcircled{2}$$

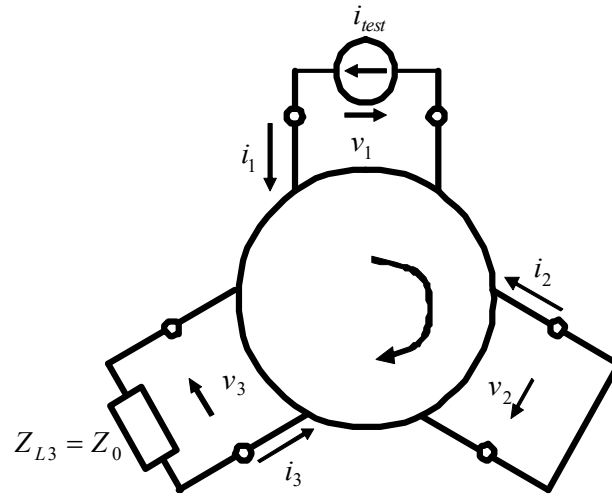
$$v_3 + i_3 Z_0 = 0 \quad \textcircled{4}$$

端口对接关系，只需列写元件约束即可

$$v_1 - Z_0 i_2 + Z_0 i_3 = 0 \quad \textcircled{6}$$

$$v_2 - Z_0 i_3 + Z_0 i_1 = 0 \quad \textcircled{3}$$

$$v_3 - Z_0 i_1 + Z_0 i_2 = 0 \quad \textcircled{5}$$



$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} Z_0 \\ 0 \\ -Z_0 \\ 1 \\ 2 \\ 1 \end{bmatrix} i_{test}$$

$$\begin{aligned} P_1 &= v_1 i_1 \\ &= Z_0 i_{test} i_{test} \\ &= Z_0 i_{test}^2 \end{aligned}$$

端口1吸收功率

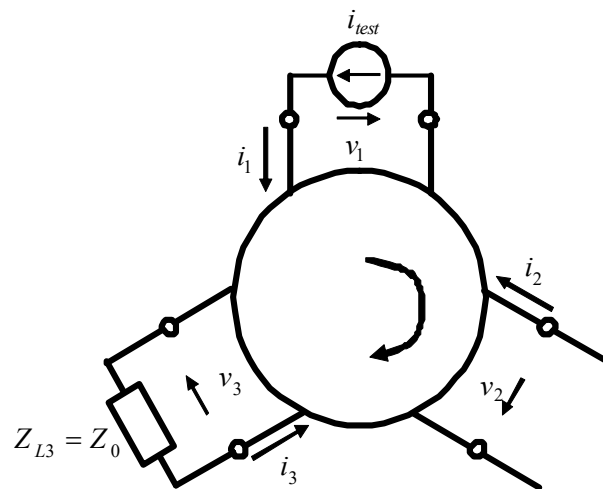
$$\begin{aligned} P_2 &= v_2 i_2 \\ &= 0 \cdot 2i_{test} = 0 \end{aligned}$$

端口2短路，
功率全反射

$$\begin{aligned} P_3 &= v_3 i_3 \\ &= -Z_0 i_{test} \cdot i_{test} \\ &= -Z_0 i_{test}^2 \end{aligned}$$

全部从端口3释放，
为匹配负载吸收

端口2开路 功率全反射



$$i_1 = i_{test} \quad \textcircled{1}$$

$$i_2 = 0 \quad \textcircled{2}$$

$$v_3 + i_3 Z_0 = 0 \quad \textcircled{4}$$

端口对接关系，只需列写元件约束即可

$$v_1 - Z_0 i_2 + Z_0 i_3 = 0 \quad \textcircled{6}$$

$$v_2 - Z_0 i_3 + Z_0 i_1 = 0 \quad \textcircled{5}$$

$$v_3 - Z_0 i_1 + Z_0 i_2 = 0 \quad \textcircled{3}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} Z_0 \\ -2Z_0 \\ Z_0 \\ 1 \\ 0 \\ -1 \end{bmatrix} i_{test}$$

$$\begin{aligned} P_1 &= v_1 i_1 \\ &= Z_0 i_{test} i_{test} \\ &= Z_0 i_{test}^2 \end{aligned}$$

端口1吸收功率

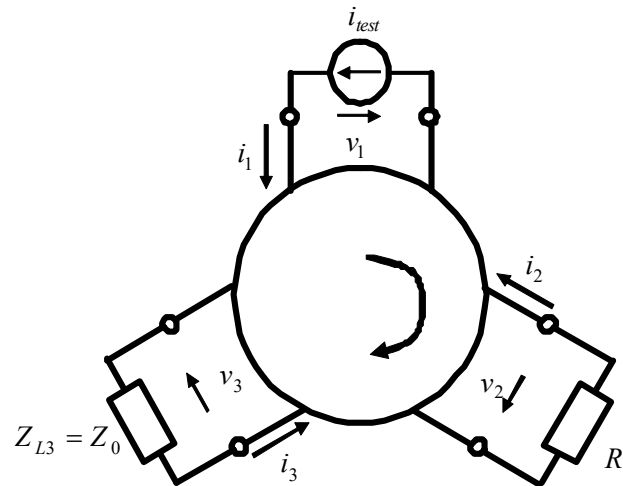
$$\begin{aligned} P_2 &= v_2 i_2 \\ &= -2Z_0 i_{test} \cdot 0 = 0 \end{aligned}$$

端口2开路，
功率全反射

$$\begin{aligned} P_3 &= v_3 i_3 \\ &= Z_0 i_{test} \cdot (-i_{test}) \\ &= -Z_0 i_{test}^2 \end{aligned}$$

全部从端口3释放，
为匹配负载吸收

端口2不匹配 功率反射



$$i_1 = i_{test} \quad \text{①}$$

$$v_2 + R_2 i_2 = 0 \quad \text{④}$$

$$v_3 + i_3 Z_0 = 0 \quad \text{⑤}$$

端口对接关系，只需列写元件约束即可

$$v_1 - Z_0 i_2 + Z_0 i_3 = 0 \quad \text{⑥}$$

$$v_2 - Z_0 i_3 + Z_0 i_1 = 0 \quad \text{②}$$

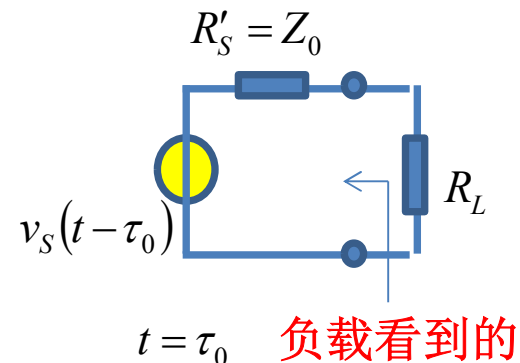
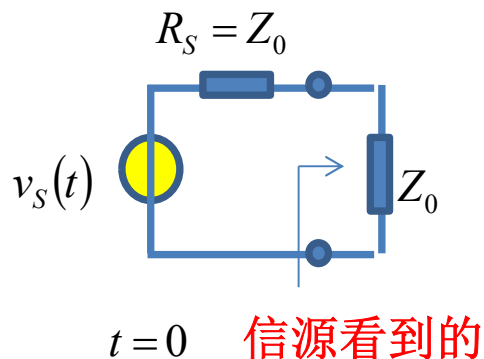
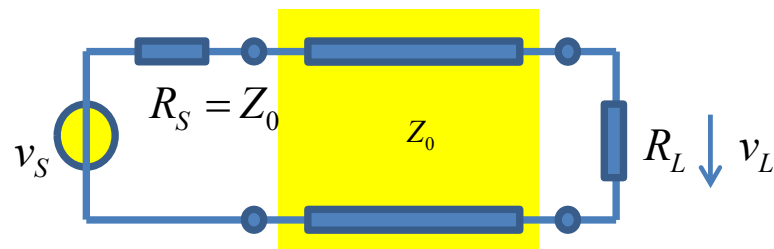
$$v_3 - Z_0 i_1 + Z_0 i_2 = 0 \quad \text{③}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} Z_0 \\ -2Z_0 \frac{R_2}{Z_0 + R_2} \\ -Z_0 \frac{Z_0 - R_2}{Z_0 + R_2} \\ 1 \\ 2 \frac{Z_0}{Z_0 + R_2} \\ \frac{Z_0 - R_2}{Z_0 + R_2} \end{bmatrix} i_{test}$$

存在反射，
但可能不
再是全反
射，而是
部分吸收，
部分反射

如何理解反射

要求理解反射概念



$t=0$ 时刻源端匹配，信源输出额定功率

$$P_{S,\max} = \frac{V_{s,rms}^2}{4R_S} = \frac{V_{s,rms}^2}{4Z_0}$$

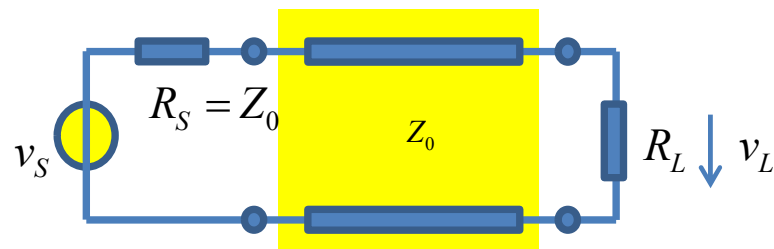
$t=\tau_0$ 时刻信号到达负载端

$$i_L(t) = \frac{v_S(t - \tau_0)}{R'_S + R_L} = \frac{v_S(t - \tau_0)}{Z_0 + R_L}$$

由于负载不匹配，负载实际吸收功率小于信源输出额定功率

$$P_L = I_{L,rms}^2 R_L = \frac{R_L}{(Z_0 + R_L)^2} V_{s,rms}^2$$

功率反射



$$P_{S,\max} = \frac{V_{s,rms}^2}{4Z_0}$$

t=0时刻源端匹配，信源输出额定功率

$$P_L = \frac{R_L}{(Z_0 + R_L)^2} V_{s,rms}^2$$

**t=τ₀时刻信号到达负载端
负载不匹配，负载实际吸收功率小于信源输出额定功率**

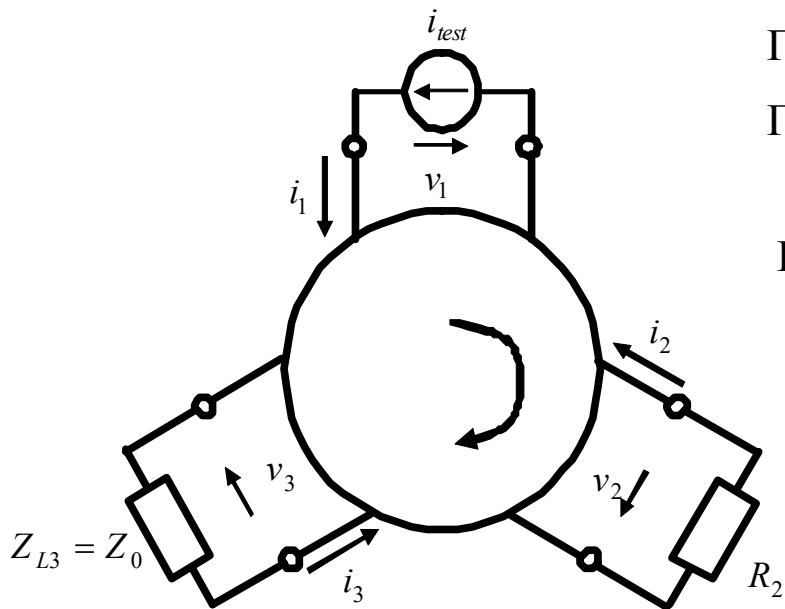
多余的功率反射回去，t=2τ₀时刻反向传输到信源，被信源匹配内阻吸收

反射功率

$$\begin{aligned} P_R &= P_{S,\max} - P_L = \frac{V_{s,rms}^2}{4Z_0} - \frac{R_L}{(Z_0 + R_L)^2} V_{s,rms}^2 \\ &= \frac{V_{s,rms}^2}{4Z_0} \left(1 - \frac{4Z_0 R_L}{(Z_0 + R_L)^2} \right) = P_{S,\max} \left(\frac{R_L - Z_0}{R_L + Z_0} \right)^2 = P_{S,\max} |\Gamma|^2 \end{aligned}$$

反射系数

信号功率是如何传输的？



$$\Gamma_2(R_2=0) = -1 \quad \text{开路短路}$$

$$\Gamma_2(R_2=\infty) = +1 \quad \text{则全反射}$$

$$\Gamma_2 = \frac{R_2 - Z_0}{R_2 + Z_0} \quad \text{反射系数}$$

$$|\Gamma_2|^2 = \frac{P_{R2}}{P_{I2}}$$

$$P_1 = v_1 i_1$$

$$= Z_0 i_{test} i_{test}$$

$$= Z_0^2 i_{test}^2 = P_S$$

端口1吸收信源释放的功率 P_S

$$P_2 = -(1 - \Gamma_2^2) Z_0 i_{test}^2$$

$$= -P_S + |\Gamma_2|^2 P_S$$

P_S 在端口2全部释放，但负载不匹配，故而反射了 $\Gamma_2^2 P_S$ ，重新被环形器端口2吸收

$$P_3 = v_3 i_3$$

$$= -|\Gamma_2|^2 Z_0 i_{test}^2$$

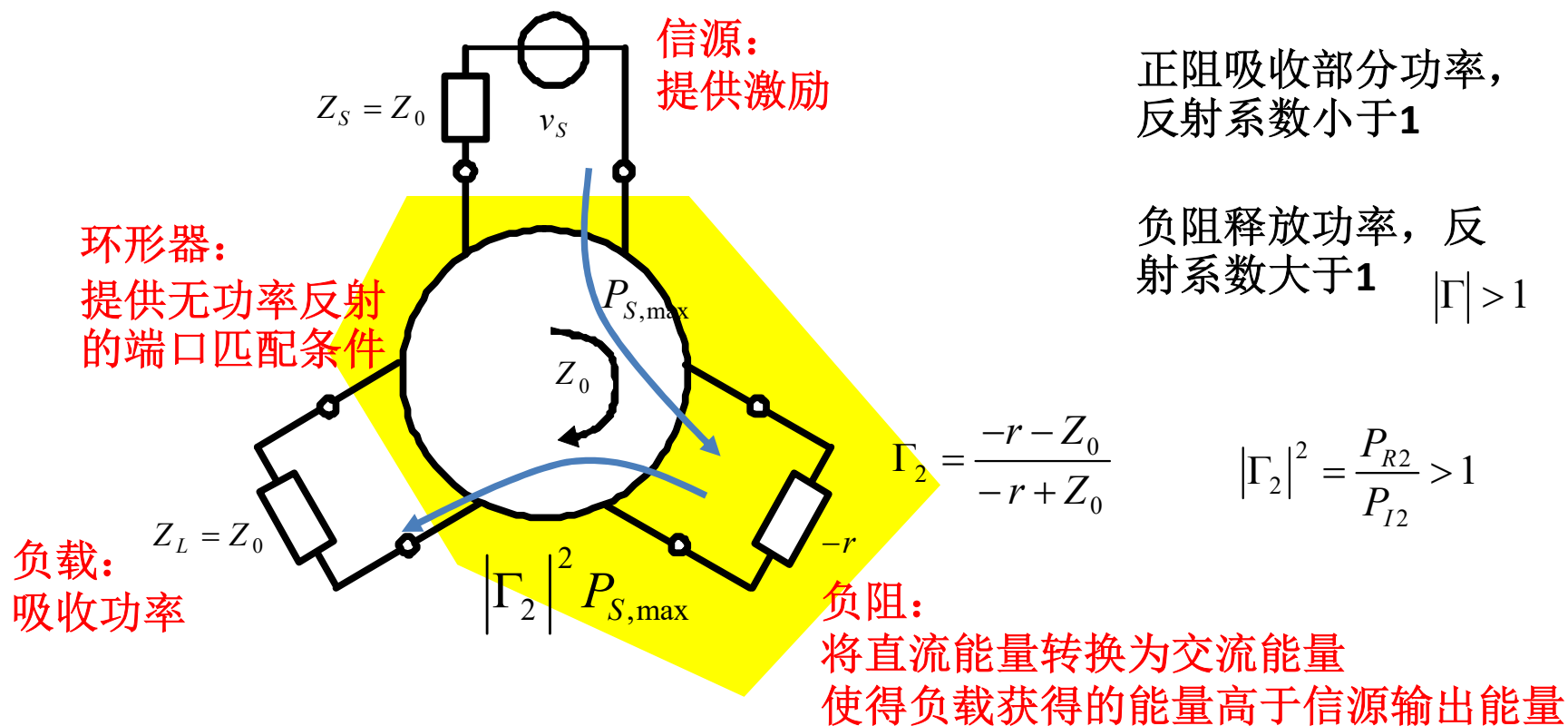
$$= -|\Gamma_2|^2 P_S$$

从端口2吸收的 $\Gamma_2^2 P_S$ 功率全部从端口3释放，为端口3匹配负载吸收

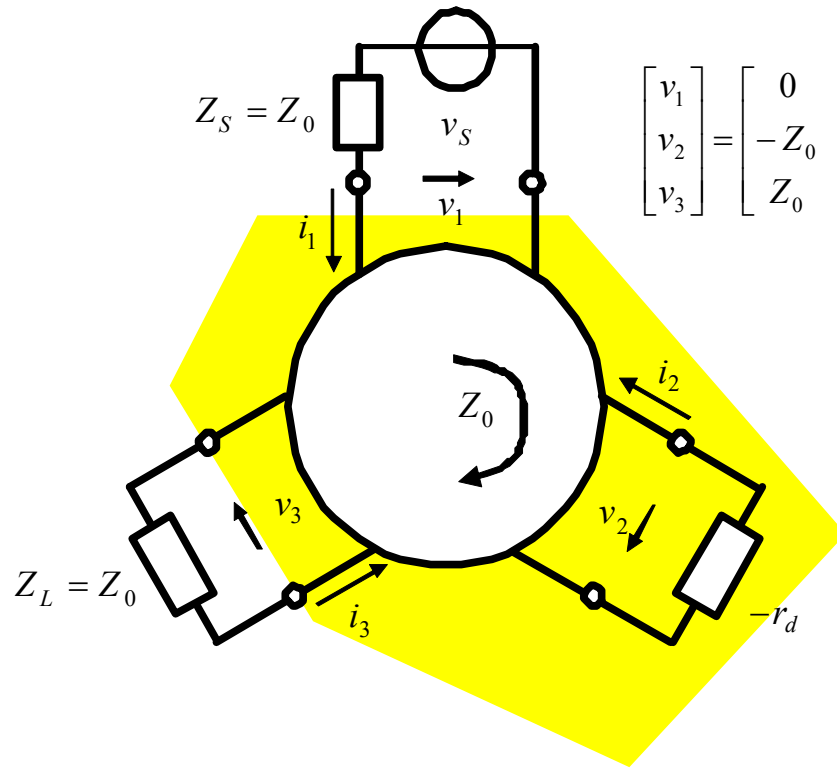
$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} Z_0 \\ -\frac{2R_2 Z_0}{Z_0 + R_2} \\ -\frac{Z_0 - R_2}{Z_0 + R_2} Z_0 \\ 1 \\ \frac{2Z_0}{Z_0 + R_2} \\ \frac{Z_0 - R_2}{Z_0 + R_2} \end{bmatrix} i_{test} = \begin{bmatrix} Z_0 \\ -(1 + \Gamma_2) Z_0 \\ \Gamma_2 Z_0 \\ 1 \\ 1 - \Gamma_2 \\ -\Gamma_2 \end{bmatrix} i_{test}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

反射型负阻放大器



$$P_L = |\Gamma_2|^2 P_{S,\max} = \left| \frac{Z_0 + r}{Z_0 - r} \right|^2 P_{S,\max} = G_T \cdot P_{S,\max} = G_{p\max} \cdot P_{S,\max}$$



$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 & Z_0 & -Z_0 \\ -Z_0 & 0 & Z_0 \\ Z_0 & -Z_0 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

$$v_1 = Z_0 i_2 - Z_0 i_3$$

$$v_2 = Z_0 i_3 - Z_0 i_1$$

$$v_3 = Z_0 i_1 - Z_0 i_2$$

环行器元件约束

$$v_2 = r_d i_2$$

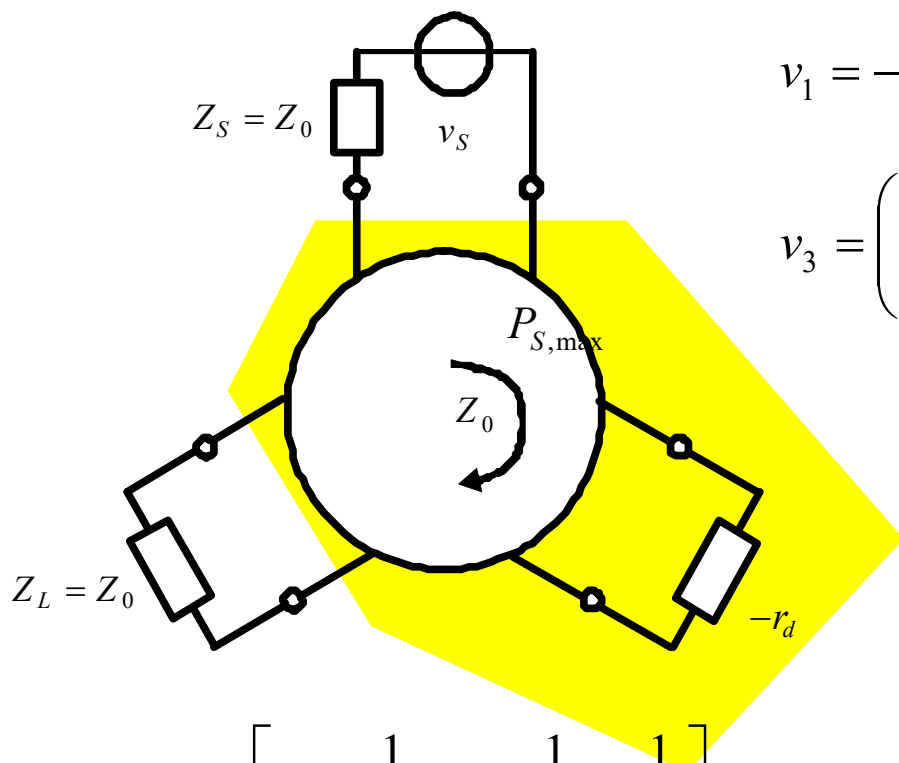
端口2接负阻：负阻约束

$$v_2 = Z_0 i_3 - Z_0 i_1 = r_d i_2$$

$$i_2 = \frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1$$

$$v_1 = Z_0 i_2 - Z_0 i_3 = Z_0 \left(\frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1 \right) - Z_0 i_3 = -\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0 \right) i_3$$

$$v_3 = Z_0 i_1 - Z_0 i_2 = Z_0 i_1 - Z_0 \left(\frac{Z_0}{r_d} i_3 - \frac{Z_0}{r_d} i_1 \right) = \left(\frac{Z_0^2}{r_d} + Z_0 \right) i_1 - \frac{Z_0^2}{r_d} i_3$$



$$v_1 = -\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0 \right) i_3$$

$$v_3 = \left(\frac{Z_0^2}{r_d} + Z_0 \right) i_1 - \frac{Z_0^2}{r_d} i_3$$

$$Z_0 = 250\Omega, r_d = 292\Omega$$

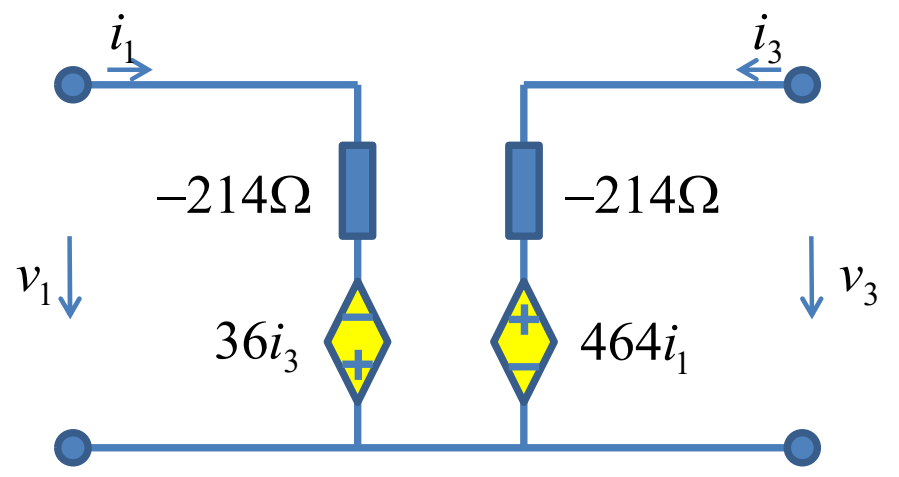
$$\mathbf{z} = \begin{bmatrix} -\frac{Z_0^2}{r_d} & \frac{Z_0^2}{r_d} - Z_0 \\ \frac{Z_0^2}{r_d} + Z_0 & -\frac{Z_0^2}{r_d} \end{bmatrix} = \begin{bmatrix} -214 & -36 \\ 464 & -214 \end{bmatrix} \Omega$$

非互易网络

$$\mathbf{y} = \mathbf{z}^{-1} = \begin{bmatrix} -\frac{1}{r_d} & \frac{1}{Z_0} & \frac{1}{r_d} \\ \frac{1}{Z_0} & \frac{1}{r_d} & -\frac{1}{r_d} \end{bmatrix}$$

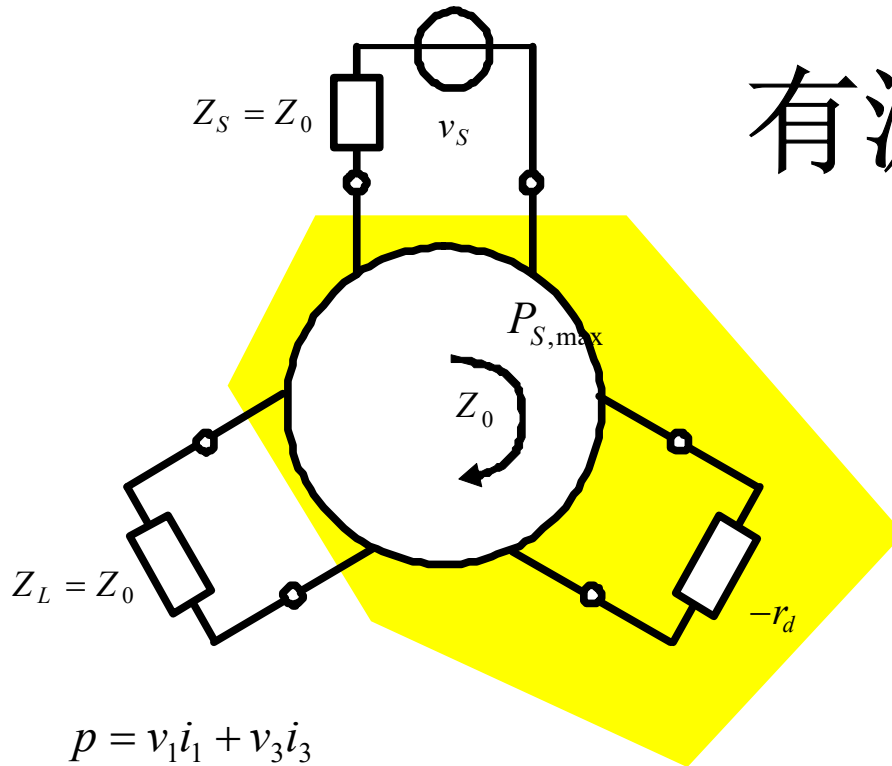
$$Z_{01} = \sqrt{\frac{z_{11}}{y_{11}}} = Z_0 = Z_{in1} (R_{L3} = Z_{03})$$

$$Z_{03} = \sqrt{\frac{z_{33}}{y_{33}}} = Z_0 = Z_{in3} (R_{L1} = Z_{01})$$



通过环行器，可以实现双端同时匹配

有源性



$$\mathbf{z} = \begin{bmatrix} -\frac{Z_0^2}{r_d} & \frac{Z_0^2}{r_d} - Z_0 \\ \frac{Z_0^2}{r_d} + Z_0 & -\frac{Z_0^2}{r_d} \end{bmatrix}$$

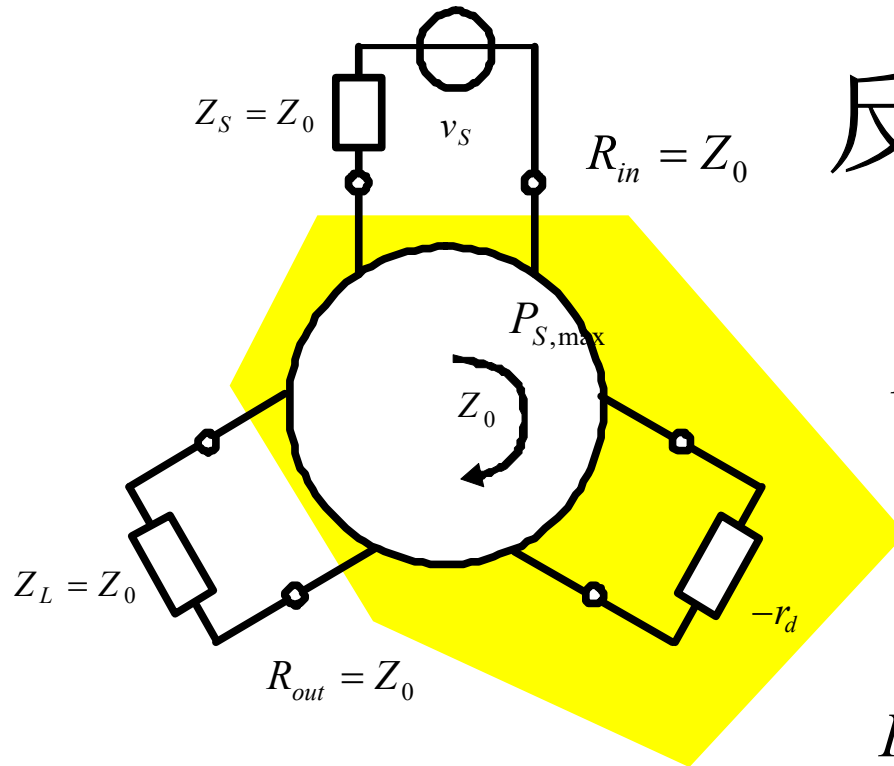
$$\begin{aligned} p &= v_1 i_1 + v_3 i_3 \\ &= \left(-\frac{Z_0^2}{r_d} i_1 + \left(\frac{Z_0^2}{r_d} - Z_0 \right) i_3 \right) i_1 + \left(\left(\frac{Z_0^2}{r_d} + Z_0 \right) i_1 - \frac{Z_0^2}{r_d} i_3 \right) i_3 \\ &= -\frac{Z_0^2}{r_d} i_1^2 - \frac{Z_0^2}{r_d} i_3^2 + 2 \frac{Z_0^2}{r_d} i_1 i_3 \\ &= -\frac{Z_0^2}{r_d} (i_1 - i_3)^2 < 0 \\ &= -\frac{v_2^2}{r_d} < 0 \end{aligned}$$

环行器+负阻：环行器为无损网络，二端口网络向外释放的纯功率全部由内部负阻提供

只要端口电流之差不为0，只要有电压加载到负阻两端，负阻即向外输出功率，故有源

$$v_2 = Z_0 i_3 - Z_0 i_1$$

反射型负阻放大器



$R_{in} = Z_0$ 端口1吸收了信源的额定功率，而无反射，故而其输入阻抗为 Z_0

输出端接匹配负载无功率反射回信源，这种情况下输入电阻为 Z_0

$R_{out} = Z_0$ 端口1信源内阻为特征阻抗时，3端口进入的任何功率全部被吸收，这种情况下输出电阻为 Z_0

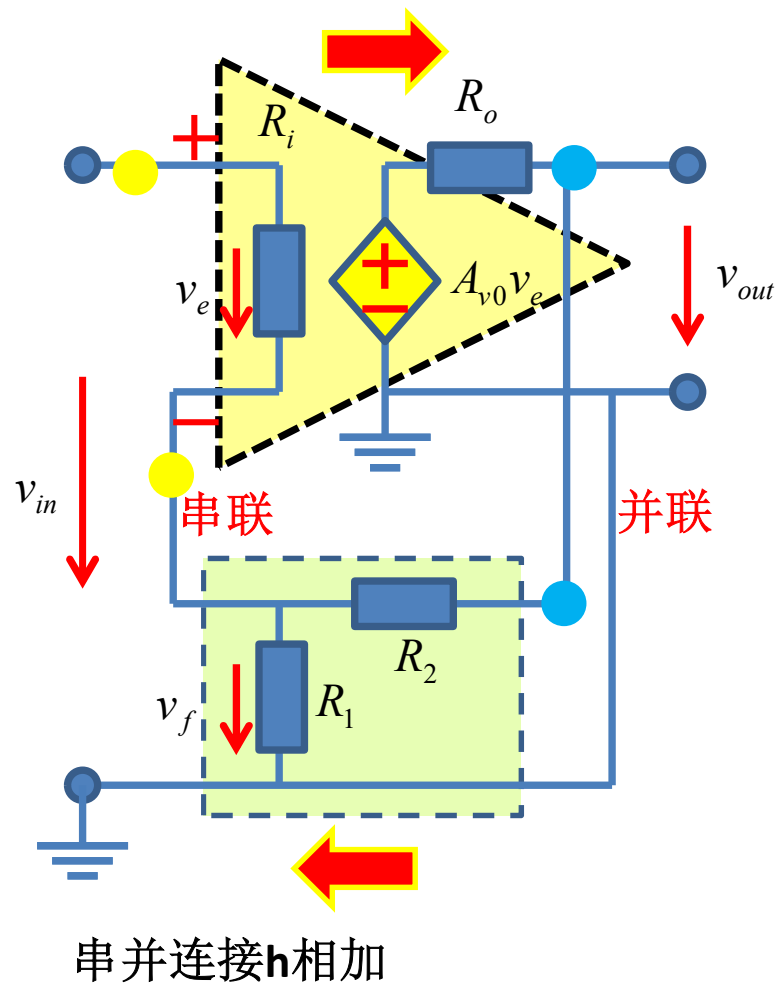
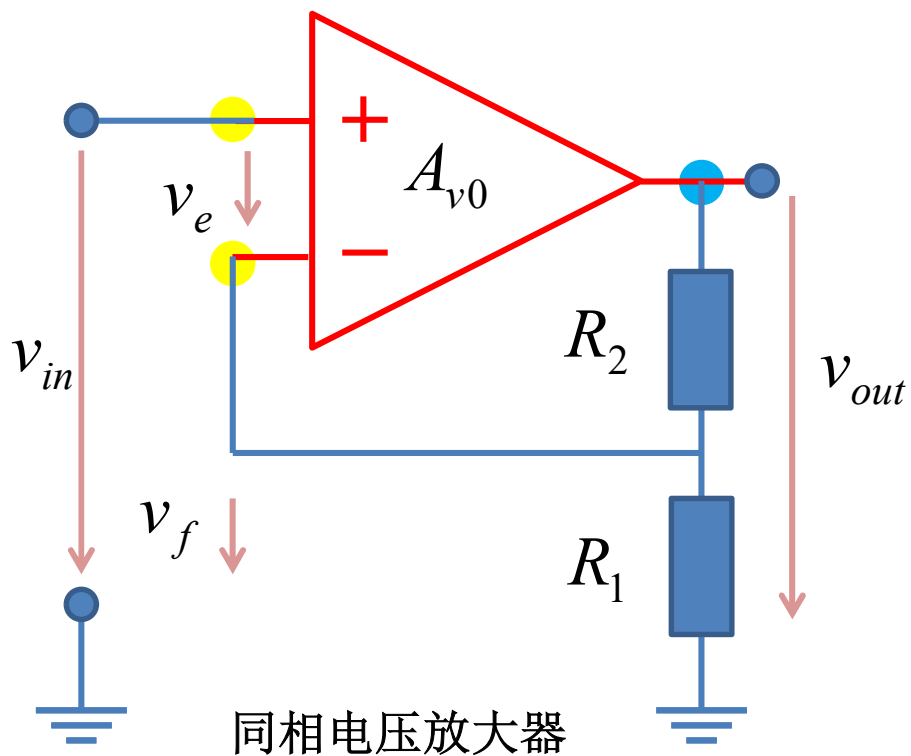
$$G_T = \frac{P_L}{P_{S,\max}} = |\Gamma_2|^2 = \left(\frac{-r_d - Z_0}{-r_d + Z_0} \right)^2 = \left(\frac{Z_0 + r_d}{Z_0 - r_d} \right)^2 > 1$$

功率增益 >1 ，放大器

只要给出合理的电路解释，电路设计就变得简单明了
给不出电路解释，就无法给出原理性清晰的电路设计

有源则可实现功率放大

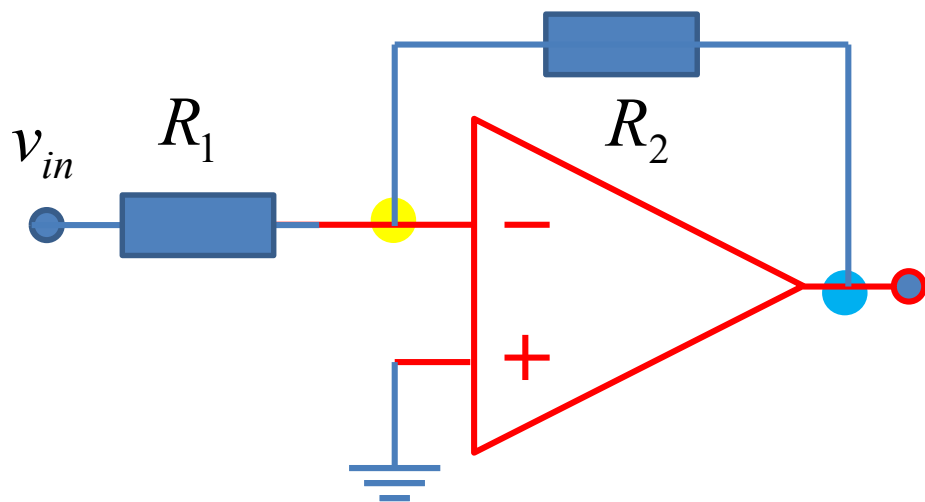
作业8 二端口网络连接关系分析



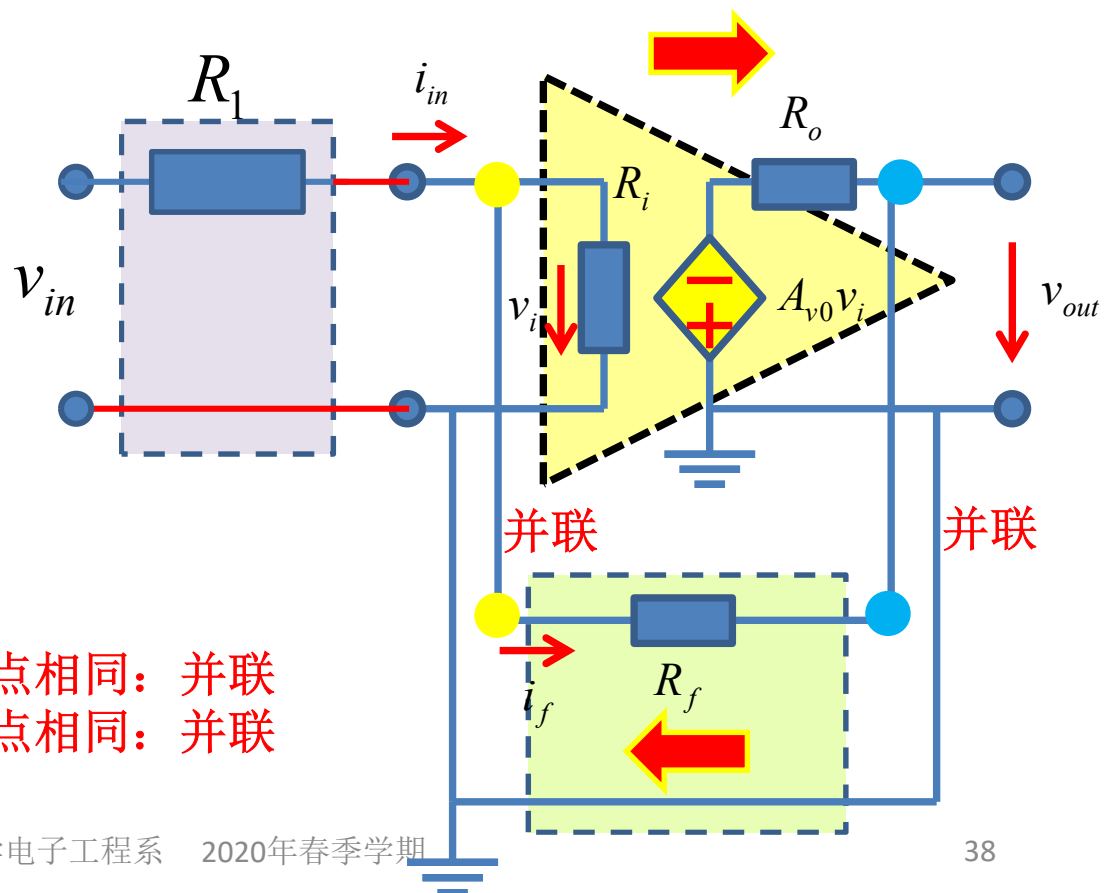
反馈网络输出点和放大网络输入点不同：串联
 反馈网络输入点和放大网络输出点相同：并联

并并连接

并并连接 y 相加

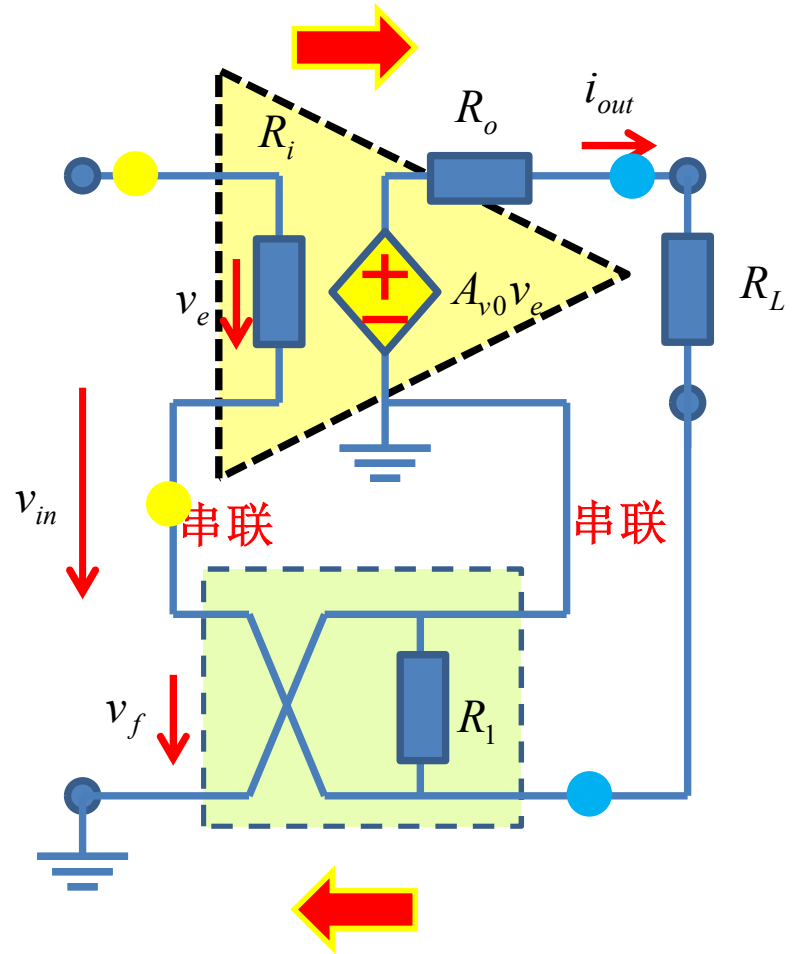
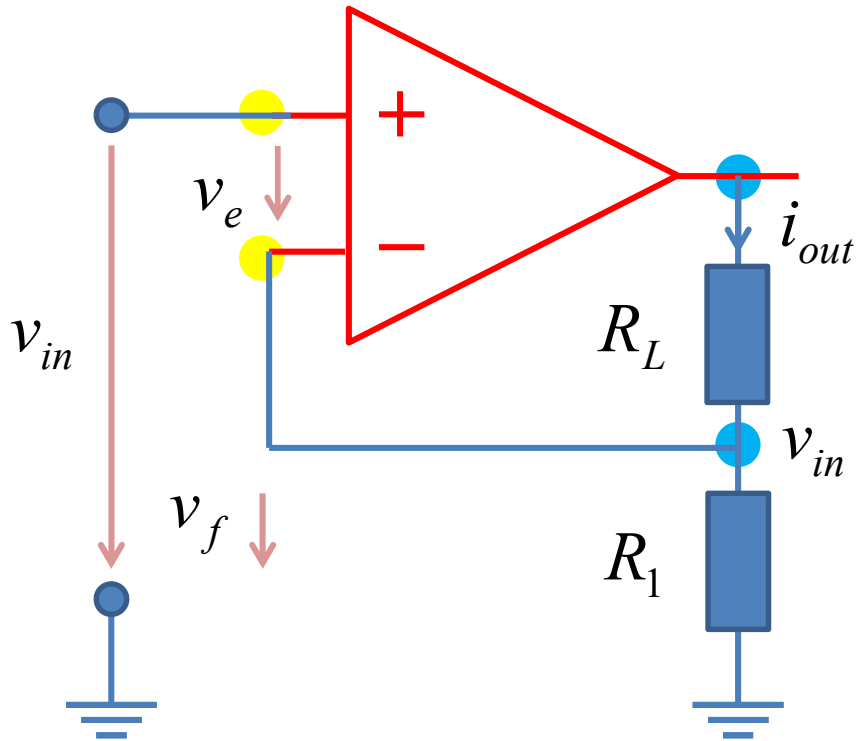


反相电压放大电路



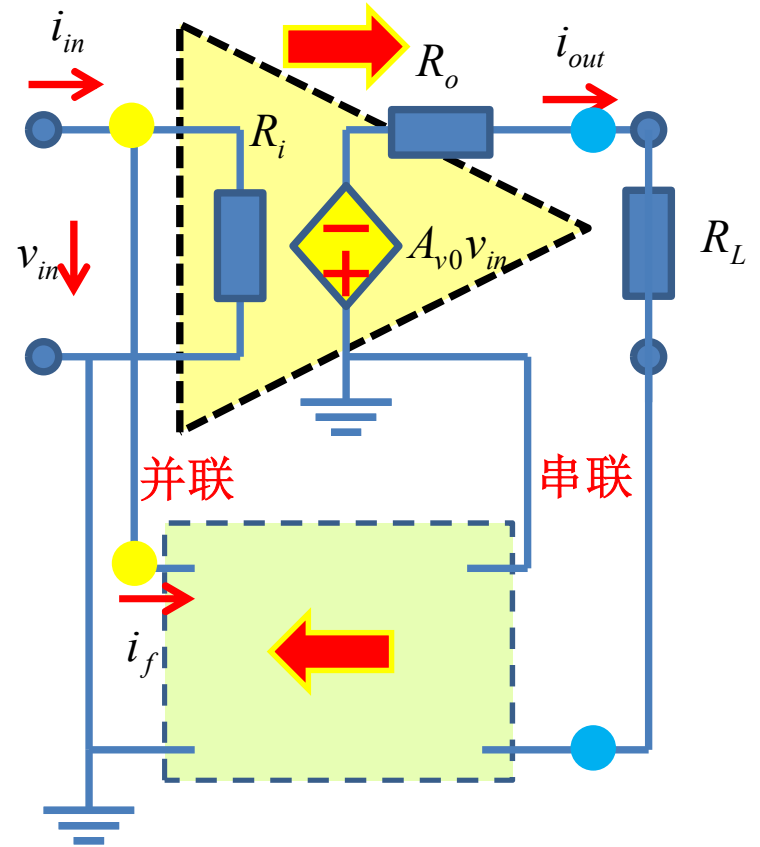
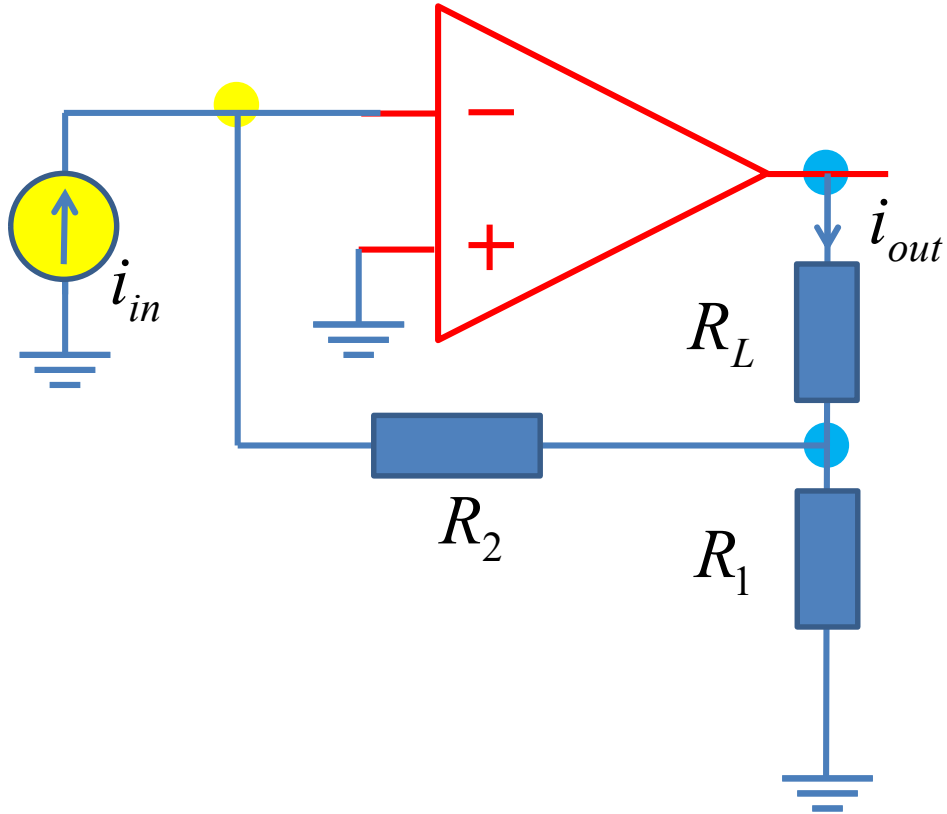
反馈网络输出点和放大网络输入点相同：并联
 反馈网络输入点和放大网络输出点相同：并联

串串连接z相加



反馈网络输出点和放大网络输入点不同：串联
 反馈网络输入点和放大网络输出点不同：串联

并串连接g相加

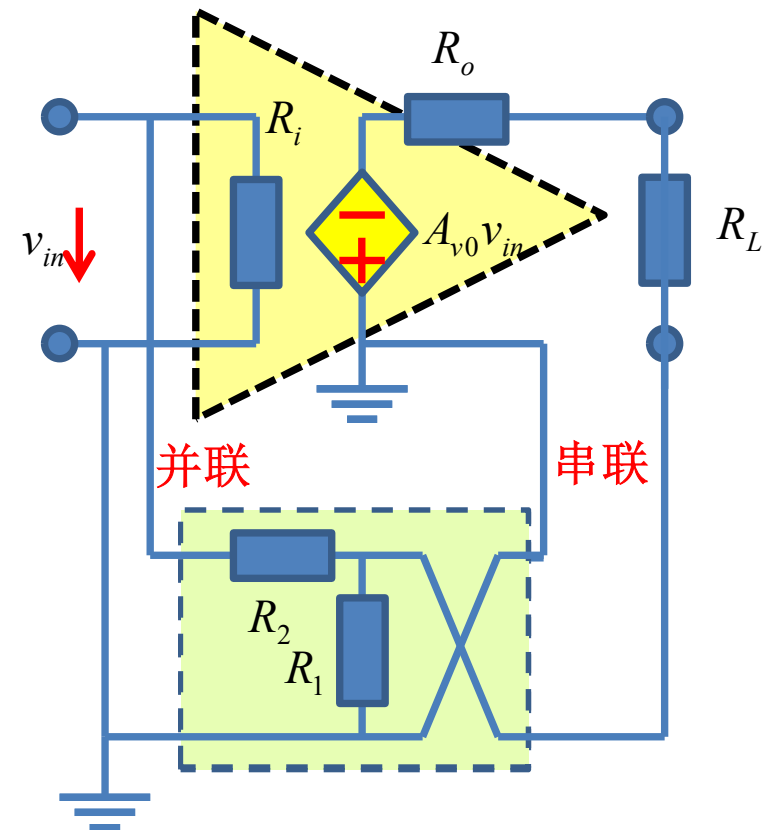
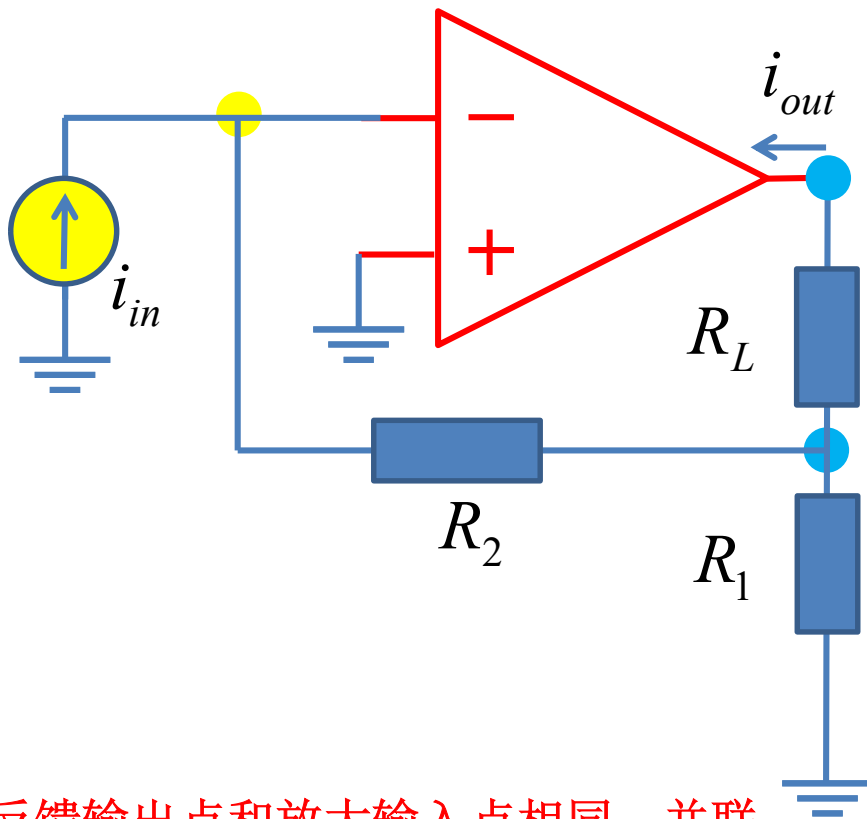


反馈网络输出点和放大网络输入点相同：并联
 反馈网络输入点和放大网络输出点不同：串联

作业8 二端口网络连接（选作）

- 确认并画出两个二端口网络的连接关系
- 获得两个二端口网络的合适参量，根据网络连接关系求总网络参量
 - 并串连接 g 相加，则分别求 g 参量，再相加
- 求逆，考察 $A_{v0} \rightarrow \infty$ 时，四种连接关系接近哪种理想受控源？
 - 并串连接 g 相加， g 求逆获得 h ，考察是否接近理想流控流源？
 - ...

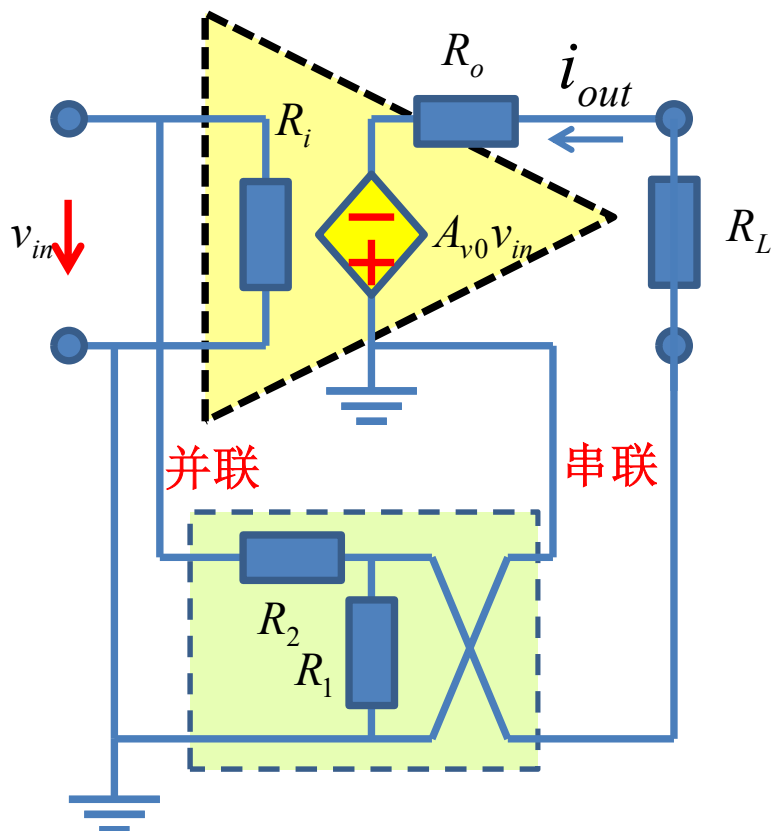
以并串连接为例：反馈网络



反馈输出点和放大输入点相同：并联
反馈输入点和放大输出点不同：串联

纯数学分析： 并串连接g相加

$$\begin{bmatrix} i_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ i_2 \end{bmatrix}$$



$$\mathbf{g}_A = \begin{bmatrix} G_{in} & 0 \\ -A_{v0} & R_{out} \end{bmatrix} \quad \mathbf{g}_F = \begin{bmatrix} \frac{1}{R_1 + R_2} & \frac{R_1}{R_1 + R_2} \\ -\frac{R_1}{R_1 + R_2} & \frac{R_1 R_2}{R_1 + R_2} \end{bmatrix}$$

$$\eta = \frac{R_1}{R_1 + R_2}$$

$$\mathbf{g}_{AF} = \mathbf{g}_A + \mathbf{g}_F$$

$$= \begin{bmatrix} G_{in} & 0 \\ -A_{v0} & R_{out} \end{bmatrix} + \begin{bmatrix} \frac{1}{R_1 + R_2} & \eta \\ -\eta & R_1 \parallel R_2 \end{bmatrix}$$

$$= \begin{bmatrix} G_{in} + \frac{1}{R_1 + R_2} & 0 \\ -A_{v0} - \eta & R_{out} + R_1 \parallel R_2 \end{bmatrix} + \begin{bmatrix} 0 & \eta \\ 0 & 0 \end{bmatrix}$$

对数学方程的电路解释

开环放大与理想反馈

如果不给电路解释，就纯粹成了数学分析，无法给后续电路进阶---电路设计提供帮助，要想能够快速给出电路设计方案，必须充分理解对数学方程的电路解释

$$\mathbf{g}_{AF} = \mathbf{g}_A + \mathbf{g}_F = \begin{bmatrix} G_{in} & 0 \\ -A_{v0} & R_{out} \end{bmatrix} + \begin{bmatrix} \frac{1}{R_1 + R_2} & \eta \\ -\eta & R_1 \parallel R_2 \end{bmatrix}$$

$$= \begin{bmatrix} G_{in} + \frac{1}{R_1 + R_2} & 0 \\ -A_{v0} - \eta & R_{out} + R_1 \parallel R_2 \end{bmatrix} + \begin{bmatrix} 0 & \eta \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} g_{in} & 0 \\ -A_{i0} g_{in} r_{out} & r_{out} \end{bmatrix} + \begin{bmatrix} 0 & F_i \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} r_{in} & 0 \\ A_{i0} & g_{out} \end{bmatrix}^{-1} + \begin{bmatrix} 0 & F_i \\ 0 & 0 \end{bmatrix}$$

$$r_{in} = \frac{1}{G_{in} + \frac{1}{R_1 + R_2}}$$

$$r_{out} = R_{out} + R_1 \parallel R_2$$

$$A_{i0} = (A_{v0} + \eta) r_{in} g_{out}$$

$$F_i = \eta$$

并串负反馈 流控流源

$$\mathbf{g}_{AF} = \begin{bmatrix} g_{in} & 0 \\ -A_{i0}g_{in}r_{out} & r_{out} \end{bmatrix} + \begin{bmatrix} 0 & F_i \\ 0 & 0 \end{bmatrix} = \mathbf{g}_{Ao} + \mathbf{g}_{iF} \quad \mathbf{h}_{Ao} = \begin{bmatrix} r_{in} & 0 \\ A_{i0} & g_{out} \end{bmatrix}$$

$$\begin{aligned} \mathbf{h}_{AF} &= \mathbf{g}_{AF}^{-1} = \begin{bmatrix} g_{in} & F_i \\ -A_{i0}g_{in}r_{out} & r_{out} \end{bmatrix}^{-1} = \frac{1}{g_{in}r_{out}(1+A_{i0}F_i)} \begin{bmatrix} r_{out} & -F_i \\ A_{i0}g_{in}r_{out} & g_{in} \end{bmatrix} \\ &= \frac{1}{1+A_{i0}F_i} \begin{bmatrix} r_{in} & -F_i \frac{r_{in}}{r_{out}} \\ A_{i0} & \frac{1}{r_{out}} \end{bmatrix} \stackrel{\text{单向化条件}}{\approx} \begin{bmatrix} r_{inf} & 0 \\ A_{if} & \frac{1}{r_{outf}} \end{bmatrix} = \frac{1}{1+A_{i0}F_i} \mathbf{h}_{Ao} \end{aligned}$$

单向化条件: $\left| \frac{A_{i0}F_i r_{in} g_{out}}{(1+A_{i0}F_i)^2} \right| = A_{i0}F_i r_{inf} g_{outf} \ll \left| R_S + r_{inf} \right| \cdot \left| G_L + g_{outf} \right|$

$$R_S \gg A_{i0}F_i r_{inf} \approx r_{in} \quad R_S \gg r_{in} = \frac{1}{G_{in} + \frac{1}{R_1 + R_2}} \approx R_1 + R_2$$

$$G_L \gg A_{i0}F_i g_{outf} \approx g_{out} \quad R_L \ll r_{out} = R_{out} + R_1 \parallel R_2 \approx R_1 \parallel R_2$$

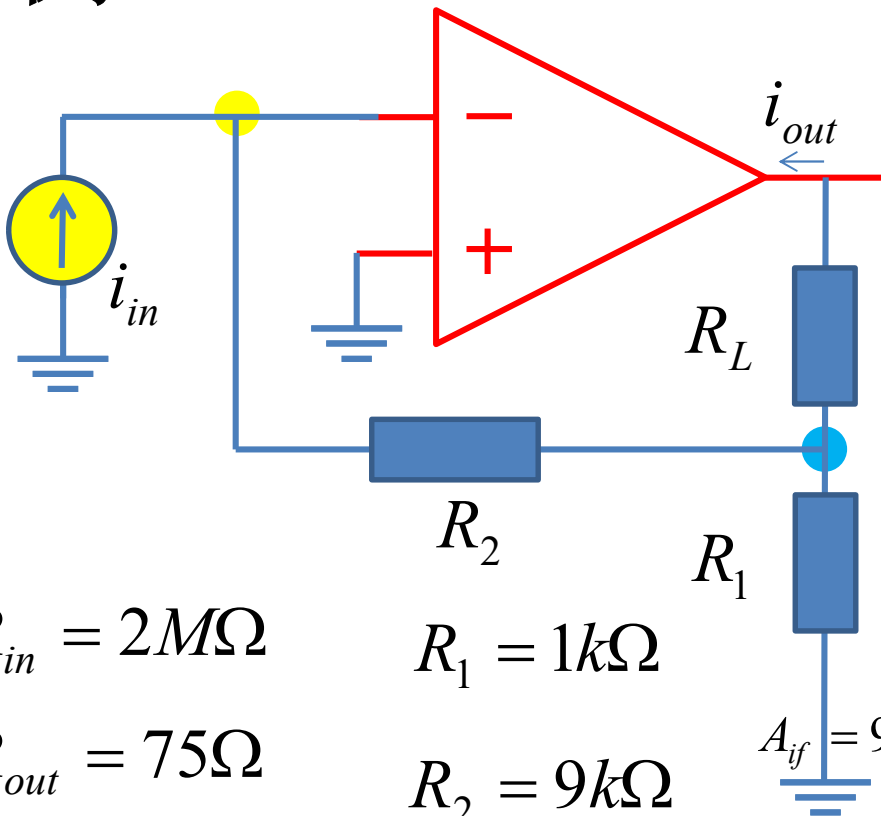
$$R_S G_L \gg A_{i0}F_i r_{inf} g_{outf} \quad \frac{R_S}{R_L} \gg \frac{1}{A_{v0}\eta} = \frac{1}{A_{v0}} \left(1 + \frac{R_2}{R_1} \right) \quad \text{最后一条单向化条件很容易满足}$$

数值例

$$\mathbf{g}_A = \begin{bmatrix} G_{in} & 0 \\ -A_{v0} & R_{out} \end{bmatrix} = \begin{bmatrix} 0.5\mu S & 0 \\ -200000 & 75\Omega \end{bmatrix}$$

$$\mathbf{g}_F = \begin{bmatrix} \frac{1}{R_1 + R_2} & \frac{R_1}{R_1 + R_2} \\ -\frac{R_1}{R_1 + R_2} & \frac{R_1 R_2}{R_1 + R_2} \end{bmatrix} = \begin{bmatrix} 0.1mS & 0.1 \\ -0.1 & 900\Omega \end{bmatrix}$$

$$\mathbf{g}_{AF} = \mathbf{g}_A + \mathbf{g}_F = \begin{bmatrix} 0.1005mS & 0.1 \\ -200000.1 & 975\Omega \end{bmatrix} = \begin{bmatrix} 0.1005mS & 0 \\ -200000.1 & 975\Omega \end{bmatrix} + \begin{bmatrix} 0 & 0.1 \\ 0 & 0 \end{bmatrix} = \mathbf{g}_{A0} + \mathbf{g}_{iF}$$



$$\mathbf{h}_{A0} = \mathbf{g}_{A0}^{-1} = \begin{bmatrix} 9950\Omega & 0 \\ 2041077 & 1.0256mS \end{bmatrix} \quad F_i = 0.1$$

$$A_{i0} = 2041077 \quad r_{in} = 9.95k\Omega$$

$$\mathbf{h}_{AF} = \mathbf{g}_{AF}^{-1} \quad r_{out} = 975\Omega$$

$$= \begin{bmatrix} 0.04875\Omega & 4.999973 \times 10^{-6} \\ 9.999951 & 0.005025\mu S \end{bmatrix}$$

$$\approx \begin{bmatrix} 0.04875\Omega & 0 \\ 9.999951 & \frac{1}{199.006M\Omega} \end{bmatrix}$$

$$A_{if} = 9.999951 = \frac{A_{i0}}{1 + A_{i0}F_i} \quad r_{inf} = 0.04875\Omega = \frac{r_{in}}{1 + A_{i0}F_i}$$

$$R_{in} = 2M\Omega$$

$$R_1 = 1k\Omega$$

$$R_{out} = 75\Omega$$

$$R_2 = 9k\Omega$$

$$A_{v0} = 200000$$

$$R_L = 1k\Omega$$

$$R_S \gg r_{in} = 9.95k\Omega$$

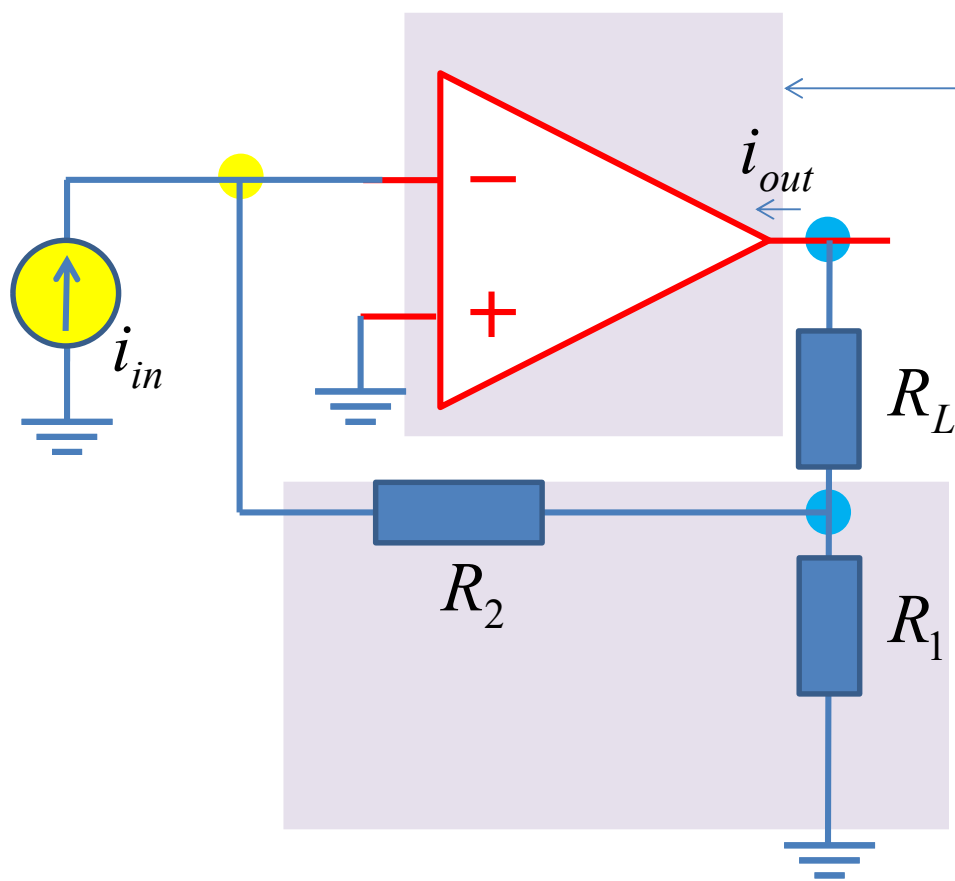
$$r_{outf} = 199M\Omega = (1 + A_{i0}F_i)r_{out}$$

$$R_L \ll r_{out} = 975\Omega$$

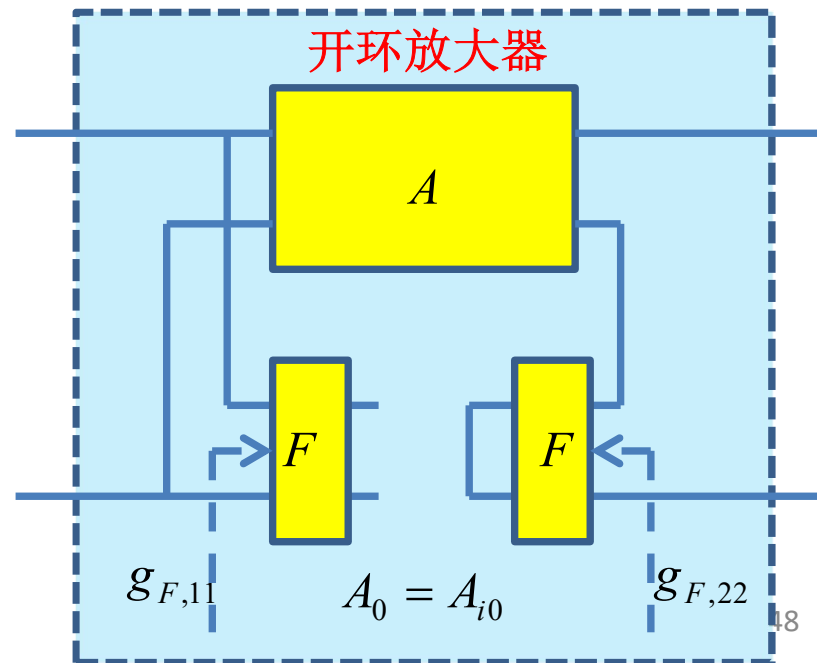
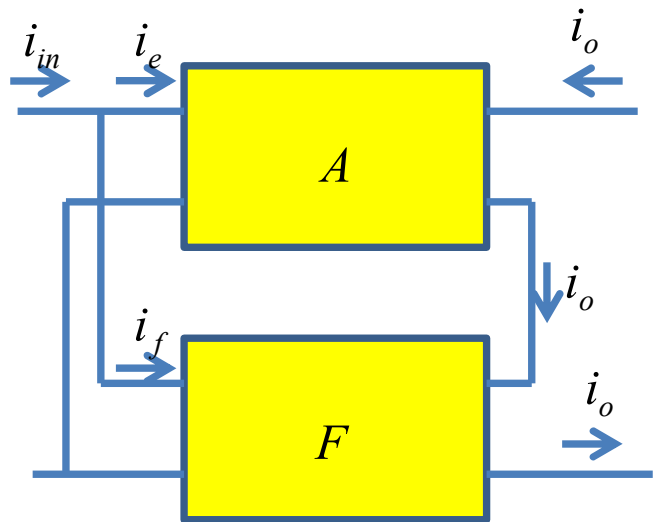
$$R_L \ll A_{v0}\eta R_S = 20000R_S$$

抛弃数学分析，直接进行电路操作

有些晶体管电路求网络参量显得简单问题复杂化
直接分析则显得极度简单

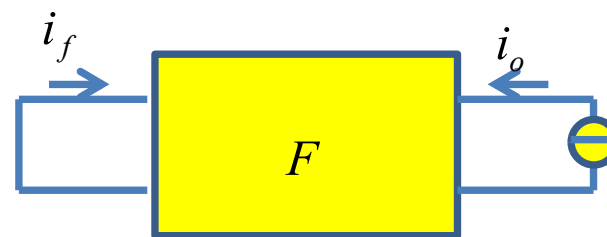


有时反馈网络和晶体管放大器网络是一体的，无法分离，单独求晶体管网络的网络参量显得困难或多此一举



$$\mathbf{g}_{A,openloop} = \begin{bmatrix} g_{A,11} & 0 \\ g_{A,21} & g_{A,22} \end{bmatrix} + \begin{bmatrix} g_{F,11} & 0 \\ g_{F,21} & g_{F,22} \end{bmatrix}$$

$$\approx \begin{bmatrix} g_{A,11} & 0 \\ g_{A,21} & g_{A,22} \end{bmatrix} + \begin{bmatrix} g_{F,11} & 0 \\ 0 & g_{F,22} \end{bmatrix}$$

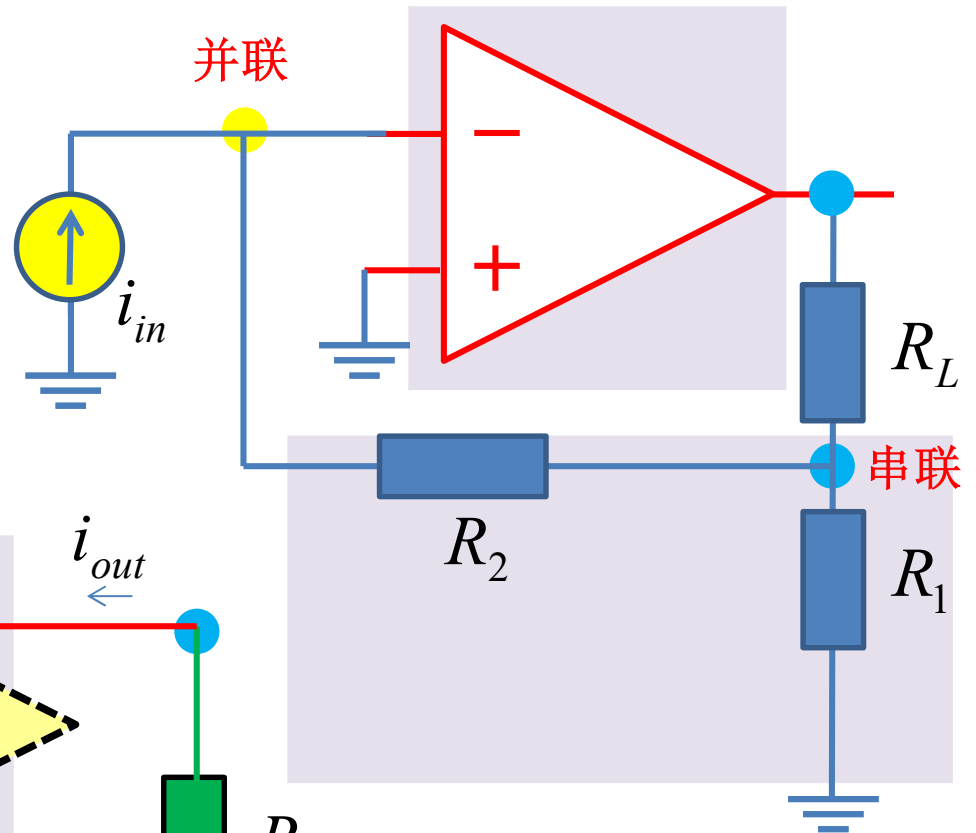
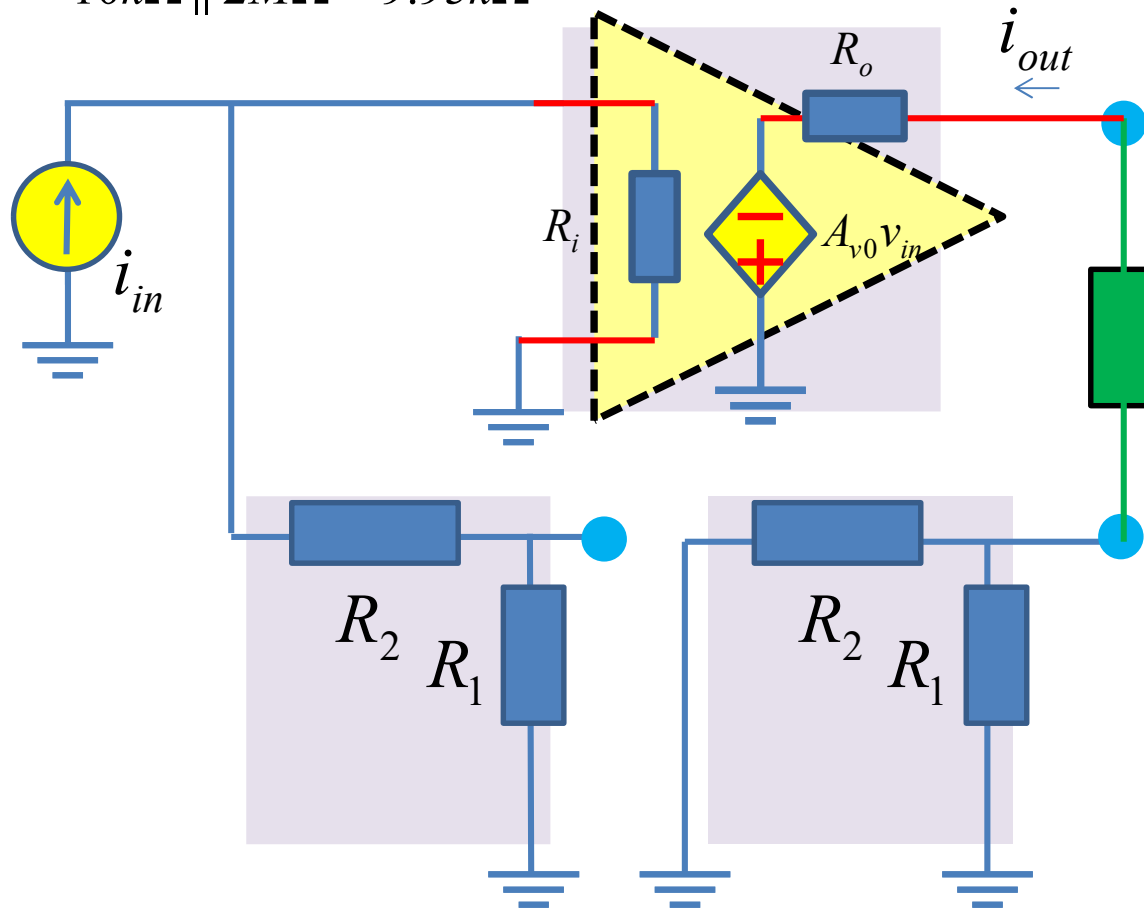


$$\mathbf{g}_{F,ideal} = \begin{bmatrix} 0 & F \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & g_{F,12} \\ 0 & 0 \end{bmatrix}$$

开环放大器

$$r_{in} = (R_2 + R_1) \parallel R_i$$

$$= 10k\Omega \parallel 2M\Omega = 9.95k\Omega$$



$$r_{out} = R_2 \parallel R_1 + R_o$$

$$= 900\Omega + 75\Omega = 975\Omega$$

$$A_{i0} = i_N / i_{in} = \frac{v_{TH}}{r_{out}} \bigg/ \frac{v_{in}}{r_{in}}$$

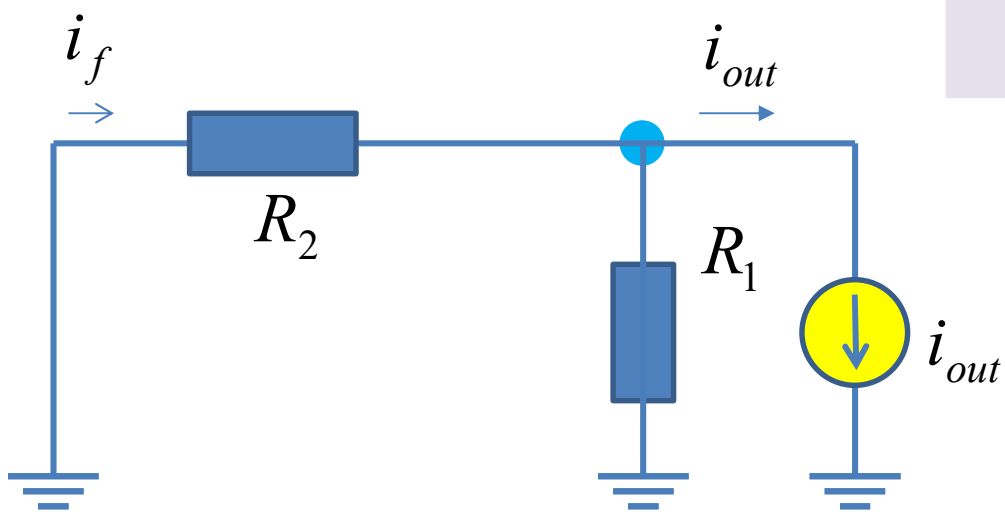
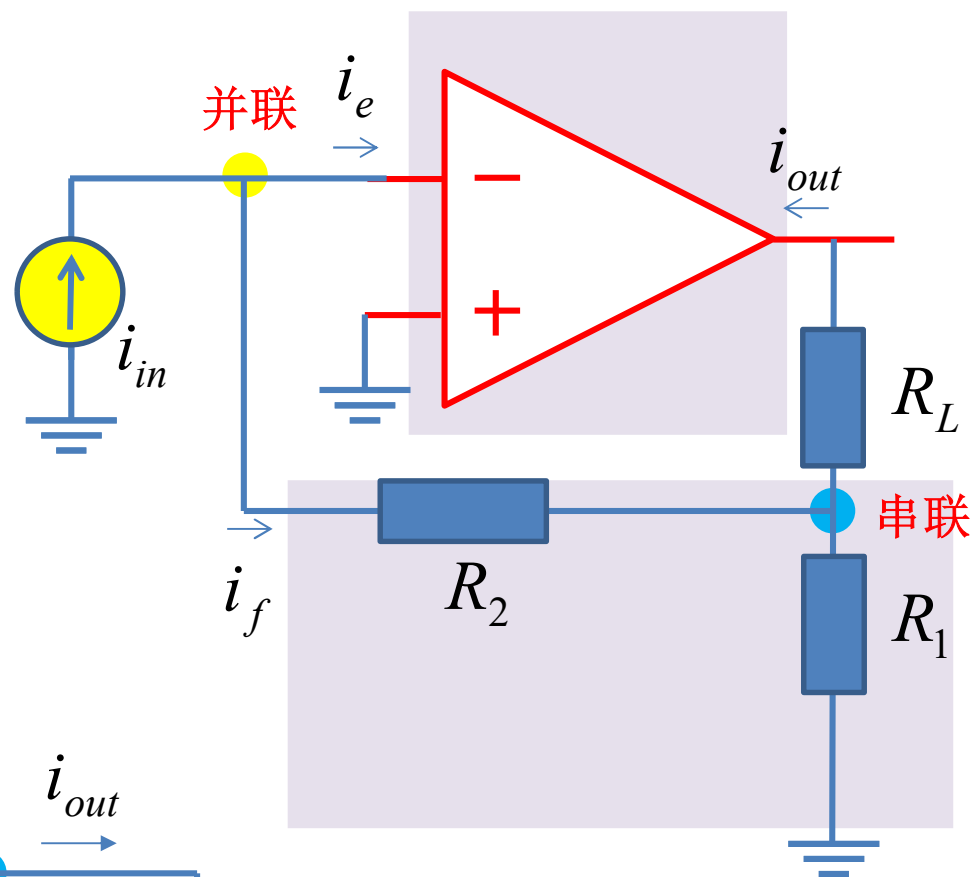
$$= A_{v0} \frac{r_{in}}{r_{out}} = 200000 \times \frac{9950}{975}$$

$$= 2041025$$

2041076/2041077

反馈系数

$$F_i = \frac{i_f}{i_{out}} = \frac{G_2}{G_1 + G_2} = \frac{R_1}{R_1 + R_2} = 0.1$$



闭环放大器

$$r_{in} = (R_2 + R_1) \parallel R_i = 10k\Omega \parallel 2M\Omega = 9.95k\Omega$$

$$r_{out} = R_2 \parallel R_1 + R_o = 900\Omega + 75\Omega = 975\Omega$$

$$A_{i0} = A_{v0} \frac{r_{in}}{r_{out}} = 200000 \times \frac{9950}{975} = 2041025$$

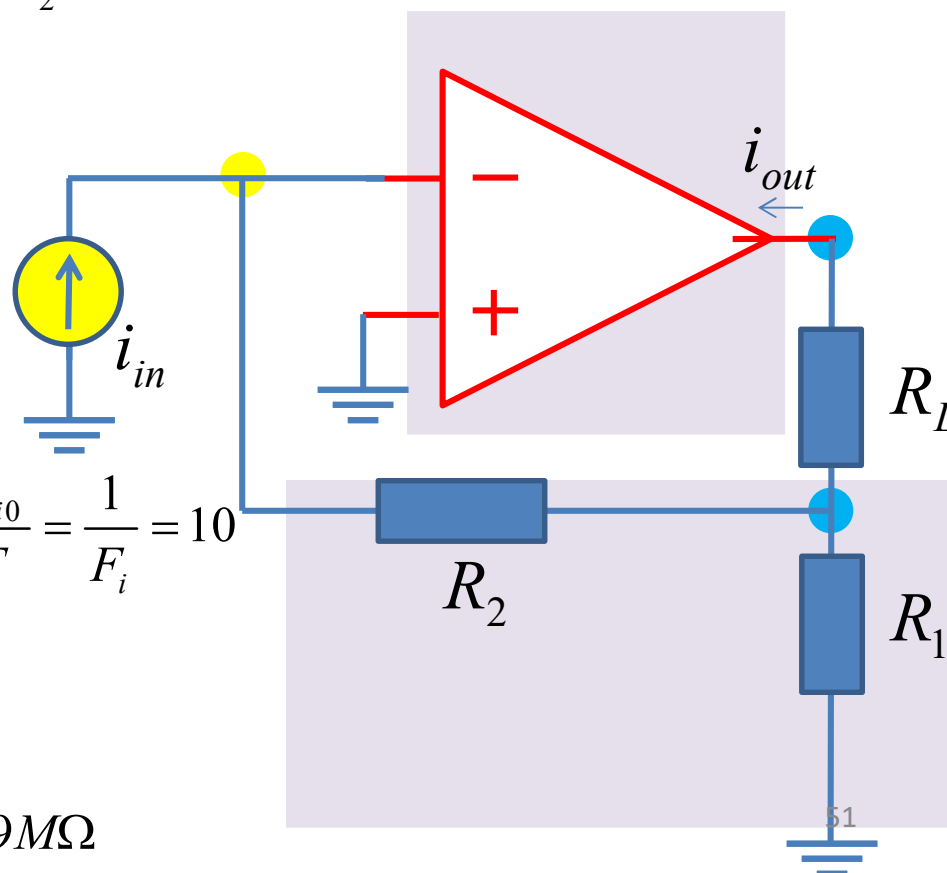
$$F_i = \frac{i_f}{i_{out}} = \frac{G_2}{G_1 + G_2} = \frac{R_1}{R_1 + R_2} = 0.1$$

$$T = A_{i0} F_i = 204103$$

$$A_{if} = \frac{A_{i0}}{1 + T} = \frac{2041025}{204104} = 9.999951 \approx \frac{A_{i0}}{T} = \frac{1}{F_i} = 10$$

$$r_{inf} = \frac{r_{in}}{1 + T} = \frac{9.95k\Omega}{204104} = 48.75m\Omega$$

$$r_{outf} = r_{out} (1 + T) = 975\Omega \times 204104 = 199M\Omega$$



直接对负反馈放大电路进行电路操作

- 练习：对第8题的其他三种放大形式
 - 获得开环放大器
 - r_{in}
 - r_{out}
 - A_0
 - 获得反馈系数
 - F
 - 获得闭环增益： $T=A_0F$
 - 获得闭环放大参数
 - 串联阻抗放大 $(1+T)$ 倍
 - 并联阻抗减小 $(1+T)$ 倍
 - 闭环增益减小 $(1+T)$ 倍，深度负反馈，近似等于 $1/F$

第8讲 非线性电路分段线性化分析

作业1: 直流电阻和交流电阻

- 假设某二极管伏安特性在很大范围内都满足指数律关系
 - 该二极管的反向饱和电流 I_{S0} 为**10fA**
 - 给出直流电流为**0.1mA**, **1mA**, **10mA**时对应的直流电压, 以及该直流工作点上的直流电阻和微分电阻
 - 分析直流电阻和微分电阻的变化规律

$$i_D = I_{S0} \left(e^{\frac{v_D}{V_T}} - 1 \right)$$

i_D (mA)	v_D	R_D	r_d
0.1			
1			
10			

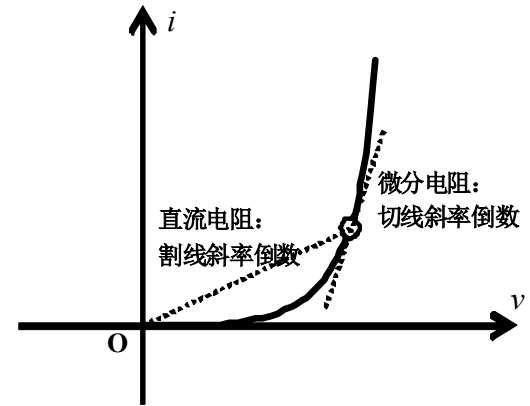
$$i_D = I_{S0} \left(e^{\frac{v_D}{v_T}} - 1 \right) \quad e^{\frac{v_D}{v_T}} = 1 + \frac{i_D}{I_{S0}}$$

$$v_T = \frac{kT}{q} = 26mV$$

$$v_D = v_T \ln \left(1 + \frac{i_D}{I_{S0}} \right) \quad I_{S0} = 10 fA$$

$$i_D = 0.1mA, 1mA, 10mA$$

$$v_D = \dots$$



非线性电阻的特征：电阻阻值和工作点有关

$$\frac{di_D}{dv_D} = \frac{I_{S0}}{v_T} e^{\frac{v_D}{v_T}}$$

$$= \frac{i_D + I_{S0}}{v_T} \approx \frac{i_D}{v_T}$$

i_D (mA)	v_D	R_D	r_d
0.1	0.5987V	5.987kΩ	260Ω
1	0.6585V	658.5Ω	26Ω
10	0.7184V	71.84Ω	2.6Ω

电流大幅变动，电压几乎不变：恒压等效的基础

$$r_d \ll R_D$$

$$r_d = \frac{dv_D}{di_D} = \frac{v_T}{I_D}$$

微分电阻很小，小信号的电压波动导致较大的电流波动

$$R_d = \frac{V_D}{I_D} \approx \frac{0.7V}{I_D}$$

二极管导通恒压源模型，但二极管本质是耗能的非线性电阻

$$i_D = I_{S0} \left(e^{\frac{v_D}{V_T}} - 1 \right)$$

交直流分析

$$i_D = f(v_D)$$

$$v_D = V_{D0} + v_{ac}$$

$$i_D = I_{D0} + i_{ac}$$

$$i_D = f(v_D) = f(V_{D0} + v_{ac}) = f(V_{D0}) + f'(V_{D0})v_{ac} + \frac{f''(V_{D0})}{2!}v_{ac}^2 + \dots \quad \text{Taylor展开}$$

$$\approx f(V_{D0}) + f'(V_{D0})v_{ac} = I_{D0} + i_{ac} \quad |v_{ac}| \text{很小} \quad \text{高阶项影响可忽略不计}$$

$$= f(V_{D0}) + \frac{v_{ac}}{r_d}$$

$$I_{D0} = f(V_{D0})$$

直流分析：非线性分析

只要交流信号足够小

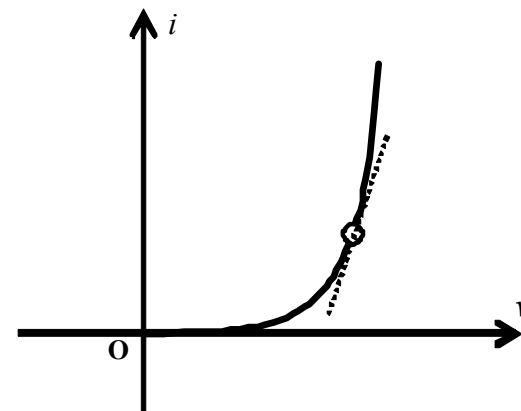
$$i_{ac} = f'(V_{D0})v_{ac} = \frac{v_{ac}}{r_d}$$

交流小信号线性分析

直流非线性分析和交流小信号线性分析可以分开分别进行

微分电阻

- **Differential Resistance**
 - 微分电阻
- **Incremental Resistance**
 - 增量电阻
- **Dynamic Resistance**
 - 动态电阻
- **Small Signal Resistance**
 - 交流小信号电阻



$$r_d = \frac{dv_D}{di_D} \quad \text{微分电阻}$$

$$i = I_0 + \Delta i$$

$$v = V_0 + \Delta v = V_0 + r_d \Delta i$$

$$r_d = \frac{\Delta v}{\Delta i} \quad \text{增量电阻}$$

$$i = I_0 + i_{ac}(t)$$

$$v = V_0 + v_{ac}(t) = V_0 + r_d i_{ac}(t)$$

$$r_d = \frac{v_{ac}(t)}{i_{ac}(t)} \quad \begin{array}{l} \text{动态电阻} \\ \text{交流电阻} \end{array} 56$$

交直流功率

$$v_D = V_{D0} + v_{ac} \quad i_D = I_{D0} + i_{ac} \approx f(V_{D0}) + \frac{v_{ac}}{r_d}$$

$$\begin{aligned} P_D &= \overline{p_D} = \overline{v_D i_D} = \overline{(V_{D0} + v_{ac})(I_{D0} + i_{ac})} \\ &= \overline{V_{D0} I_{D0} + v_{ac} I_{D0} + V_{D0} i_{ac} + v_{ac} i_{ac}} \\ &= V_{D0} I_{D0} + \overline{v_{ac} I_{D0}} + \overline{V_{D0} i_{ac}} + \overline{v_{ac} i_{ac}} \\ &= V_{D0} I_{D0} + \overline{v_{ac} i_{ac}} = P_{DC} + P_{AC} \\ &\approx V_{D0} I_{D0} + r_d \overline{i_{ac}^2} = I_{D0}^2 R_D + I_{ac,rms}^2 r_d \end{aligned}$$

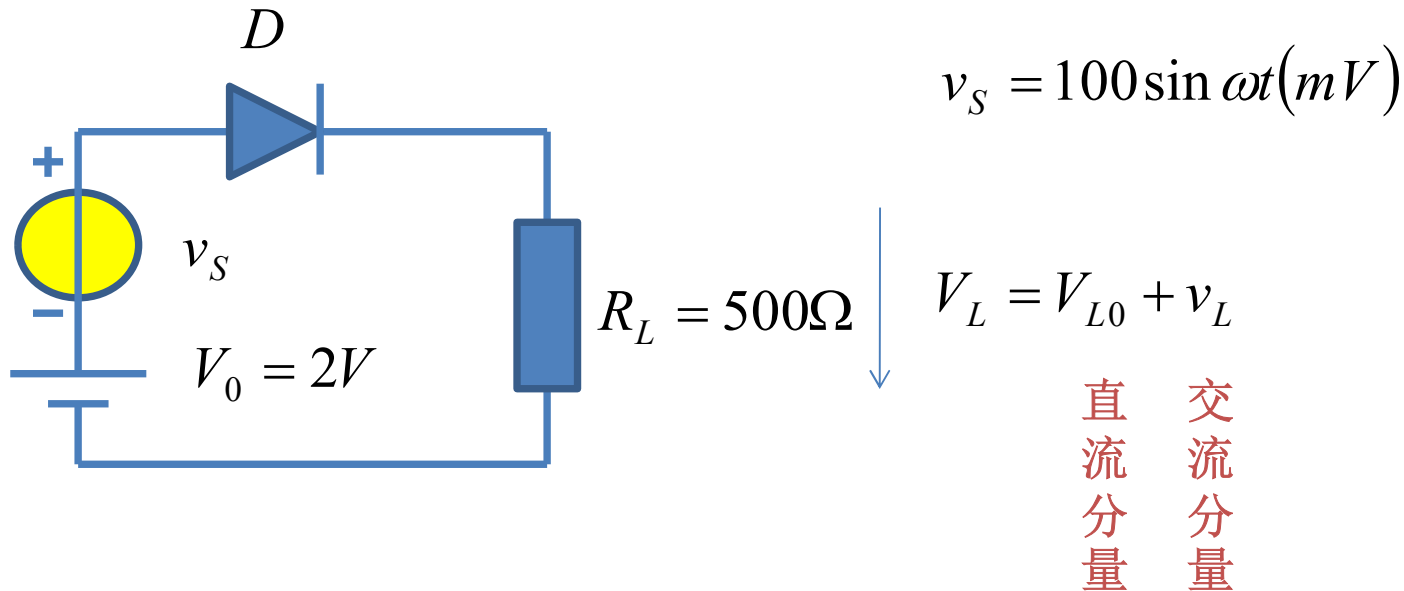
直流电阻可用于表述直流功率大小，
在信号处理中没有什么地位

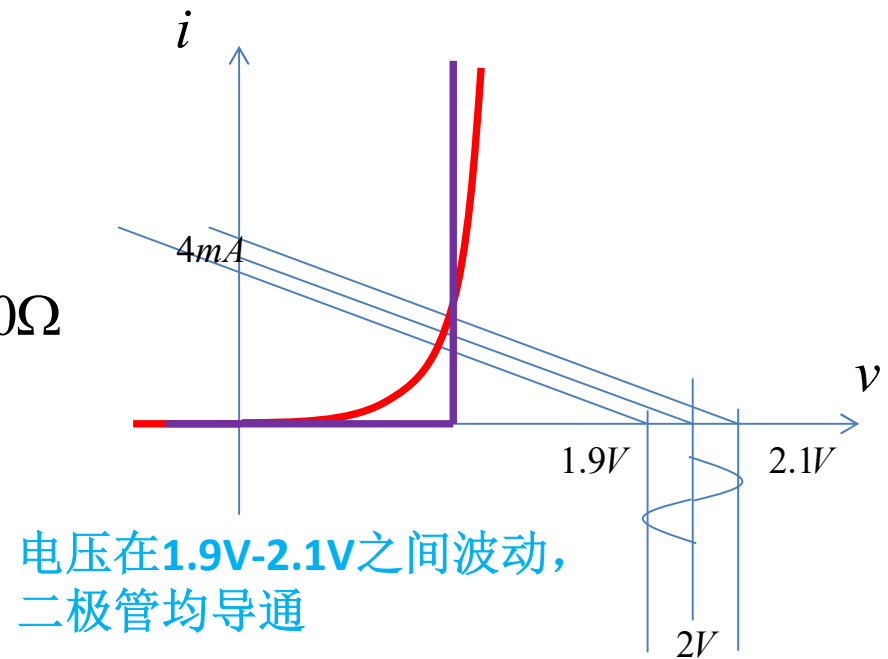
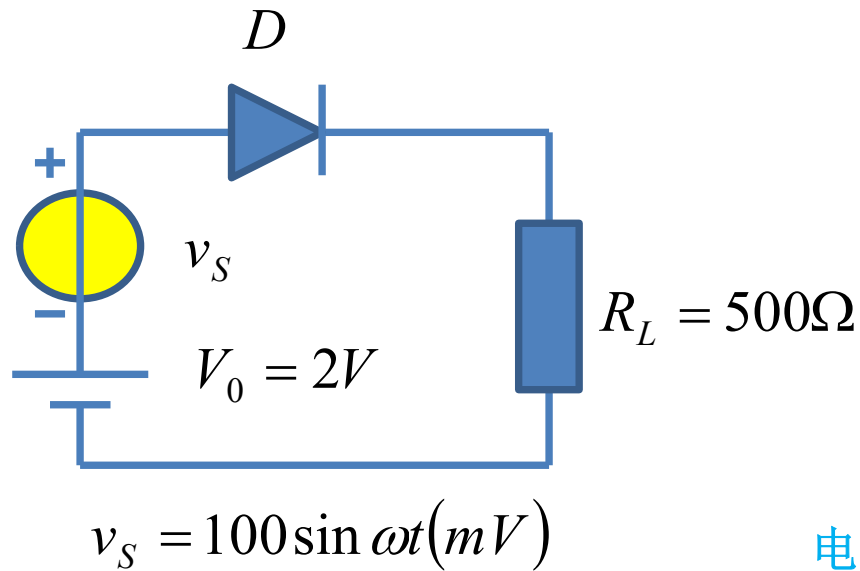
交流电阻（微分电阻）不仅可用于
表述交流功率大小，同时可用于
表述交流压流的线性转换关系

微分元件在非线性电路
分析中具有重要的地位

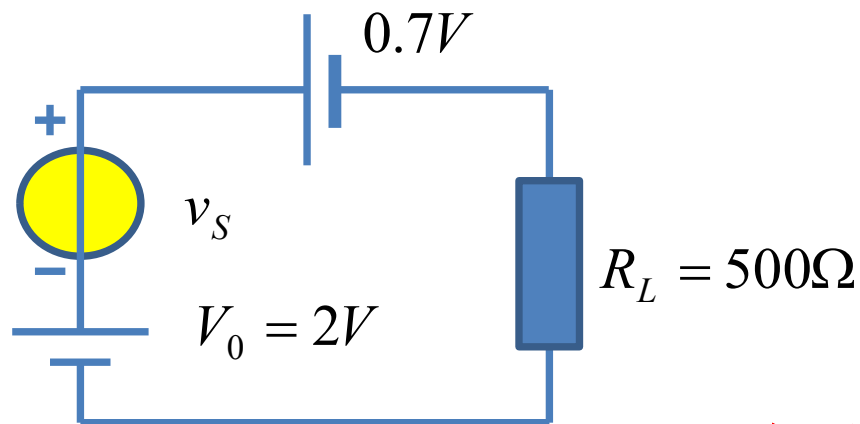
作业2：二极管导通恒压模型的应用

- 采用导通**0.7V**恒压源模型，分析如下电路，给出输出电阻上的电压大小





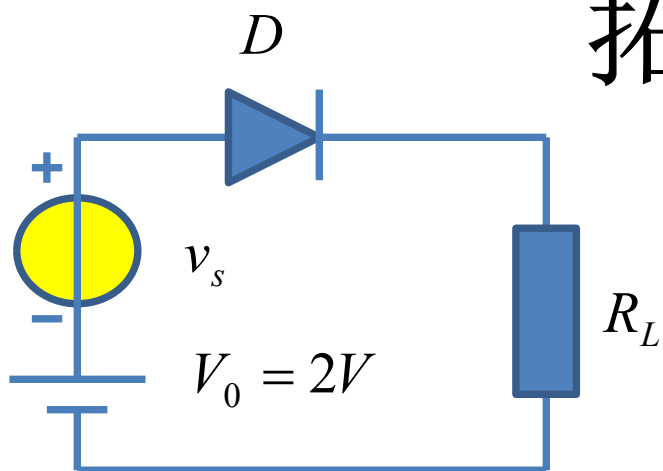
第一步，确认二极管的**导通**、截止状态！第二步，用折线模型替代



$$\begin{aligned}
 V_L &= V_0 - V_{D0} + v_S \\
 &= 1300 + 100 \sin \omega t (mV) \\
 &= V_{L0} + v_L(t)
 \end{aligned}$$

0.7V恒压源模型分析结论！快速，误差有多大？

拓展分析：交直流分析



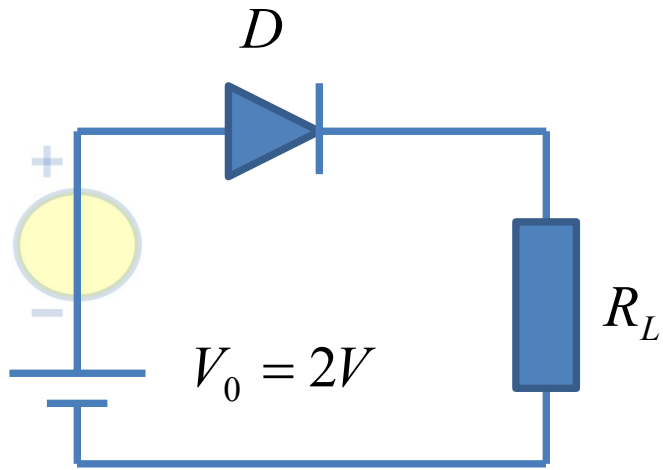
$$\begin{aligned}v_D &= V_0 + v_s(t) - (V_{L0} + v_l(t)) \\ &= (V_0 - V_{L0}) + (v_s(t) - v_l(t)) \\ &= V_{D0} + v_d(t)\end{aligned}$$

假设 $v_d(t)$ 足够小

$$i_D = f(v_D) = f(V_{D0} + v_d(t)) \approx f(V_{D0}) + \frac{v_d(t)}{r_d} = I_0 + i_d(t)$$

$$I_0 = f(V_{D0}) \quad \text{直流非线性分析}$$

$$i_d(t) = \frac{v_d(t)}{r_d} \quad \text{交流小信号线性分析}$$



$$f(v) = I_{S0} \left(e^{\frac{v}{v_T}} - 1 \right)$$

直流分析

$$I_0 = f(V_{D0}) = f(V_0 - V_{L0}) = f(V_0 - I_0 R_L)$$

$$I_0 = I_{S0} \left(e^{\frac{V_0 - I_0 R_L}{v_T}} - 1 \right) \Rightarrow I_0 = \frac{V_0 - v_T \ln \left(1 + \frac{I_0}{I_{S0}} \right)}{R_L}$$

2V 500Ω
10fA 26mV

可牛顿拉夫逊迭代法
数值求解

简单迭代格式

$$V_{D0} = v_T \ln \left(1 + \frac{I_0^{(3)}}{I_{S0}} \right) = 0.6837V$$

$$V_{L0} = V_0 - V_{D0} = 1.3163V$$

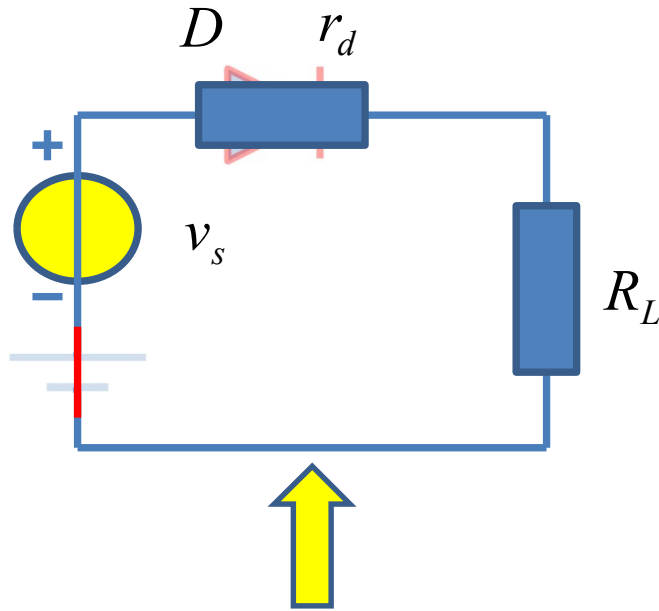
$$I_0^{(0)} = \frac{V_0 - 0.7}{R_L} = \frac{2 - 0.7}{0.5k} = 2.6mA$$

$$I_0^{(1)} = \frac{V_0 - v_T \ln \left(1 + \frac{I_0^{(0)}}{I_{S0}} \right)}{R_L} = 2.6332mA$$

$$I_0^{(2)} = \frac{V_0 - v_T \ln \left(1 + \frac{I_0^{(1)}}{I_{S0}} \right)}{R_L} = 2.6326mA$$

$$I_0^{(3)} = \frac{V_0 - v_T \ln \left(1 + \frac{I_0^{(2)}}{I_{S0}} \right)}{R_L} = 2.6326mA$$

交流分析



$$\begin{aligned}v_D &= V_0 + v_s(t) - (V_{L0} + v_l(t)) \\ &= (V_0 - V_{L0}) + (v_s(t) - v_l(t)) \\ &= V_{D0} + v_d(t)\end{aligned}$$

$$i_d(t) = \frac{v_d(t)}{r_d} = \frac{v_s(t) - v_l(t)}{r_d}$$

$$r_d = \frac{v_T}{I_{D0}} = \frac{26mV}{2.6326mA} = 9.8762\Omega$$

$$v_l(t) = \frac{R_L}{R_L + r_d} v_s(t) = \frac{500}{500 + 9.8762} \times 100 \sin \omega t = 98.06 \sin \omega t (mV)$$

$$v_L(t) = V_{L0} + v_l(t) = 1316 + 98 \sin \omega t (mV) \quad \mathbf{v_d(t) \text{ 足够小, 故而交直流分析几乎精确}}$$

$$v_L(t) = 1300 + 100 \sin \omega t (mV) \quad \mathbf{\text{分段折线模型误差小于} 2\%, \text{ 而且原理性更强, 因而对于大多数二极管电路, 我们更喜欢用分段折线模型}}$$

二极管小信号分析

- 当二极管电流在**mA**量级时，微分电阻 **$10^1\Omega$** 量级，和**k Ω** 量级负载电阻相比，一般可以忽略不计，此时二极管小信号电阻可抽象为**0**，二极管模型直接采用**0.7V**恒压源模型进行交直流分析即可

$$r_d = \frac{v_T}{I_{D0}} = \frac{26mV}{1mA} = 26\Omega$$

- 当二极管电流在 **μA** 量级时，微分电阻在**10k Ω** 量级，和**k Ω** 量级负载电阻相比，其影响不能忽略不计，此时加流小信号分析中必须将二极管微分电阻考虑在内
 - 如BJT的BE结微分电阻 **r_{be}** ，小信号模型中一般都需要考虑在内